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**Aircraft Design Optimisation
Conceptual Evaluation of a Three-lifting Surface
Turbo-fan Airliner**

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the degree of Doctor of Philosophy**



To my mother and my father,

Áurea and Fernando

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SUMMARY

Today's high competitiveness in the airline industry urges for the development of even more efficient transport aircraft. In many cases lower operating costs are the key to survival. Although the introduction of emerging advanced technologies has shown improvements both in safety levels and performance, with the associated reductions in costs, the search for more economical aircraft must also take into consideration changes in current design practice. The study of novel configurations is a contribution to this view.

In this research project, advantage was taken from multidisciplinary synergism to design and optimise conventional and three-surface configuration commercial aircraft, to satisfy the same mission and operational requirements. An integrated conceptual design synthesis approach was employed where typical aeronautical disciplines, as well their complex interrelations, were taken into account. All these considerations, together with both cruise and field performance, and static stability and control requirements, resulted in different baseline configurations of the two concepts, although sharing the same fuselage and the same technology standard, but with different Maximum Take-off Weights (MTOW), lifting surfaces, turbo-fan engine sizes, and economics. After coupling the design synthesis program to a gradient based numerical minimization routine, optimisation of these designs was performed for minimum Direct Operating Costs (DOC) and minimum MTOW, and their performance and economics were compared on an equal basis. Trade-off studies were conducted on all aircraft for 1000 through 3000 NM design mission ranges while keeping the same fuselage size, lifting surface planform shapes and same static longitudinal stability margin (inherently stable designs), as obtained for the respective datum designs (Range = 1250 NM).

Thus, using the same comprehensive design tool, built on the same primary assumptions, and using the same analytical methods and principles which include many real life considerations, a systematic and consistent study of both design concepts was conducted. The potential merits of a realistic three-surface transport design were clearly established, when comparison was made with an equivalent mission conventional twin turbo-fan airliner. Within the usual limitations of any initial conceptual design study, it appears that the concept of the three-lifting surface transport can effectively improve in terms of performance and direct operating costs, when compared to conventional aircraft designed for the same operational environment and mission profiles, and may show a promising future.

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NOTATION

A	lifting surface aspect ratio
A_1	compressibility drag parameter in the drag divergence Mach number correlation
A_2	compressibility drag parameter in the drag divergence Mach number correlation
$a = \frac{dC_L}{d\alpha}$	lift curve slope
a_{ij}	coefficients of the stability and control matching real linear equations derived for the computation of the canard and tail volume coefficients
b	lifting surface span
b_i	coefficients of the stability and control matching real linear equations derived for the computation of the canard and tail volume coefficients
C	production cost or force parallel to the fuselage longitudinal reference axis
CEF	cost escalation factor
C_D	aerodynamic drag coefficient
C_{D_c}	compressibility drag coefficient
C_{D_f}	parasite drag coefficient due to trailing edge flaps
C_{D_M}	drag rise coefficient due to Mach number
C_{D_i}	induced or vortex drag coefficient
C_{D_p}	parasite drag coefficient
$C_{D_{p0c}}$	canard free aircraft parasite drag coefficient
$C_{D_{p0w}}$	wing free aircraft parasite drag coefficient
C_{D_r}	lifting surface profile drag correction term
C_f	turbulent flat plate skin friction coefficient
C_L	aerodynamic lift coefficient

C_m	pitching moment coefficient
$C_{m_{b_{c_L}}} = a_{c_L} \bar{V}_c \tau_c$	canardvator power, at landing conditions in ground effect
$C_{m_{b_{e_L}}} = a_{t_L} \bar{V}_t \eta_t \tau_e$	elevator power, at landing conditions in ground effect
C_1 and C_2	terms in the canard lift curve slope equation
\bar{c}	lifting surface mean aerodynamic chord
c_{c_r}	canard root chord at fuselage centreline
c_{vt_r}	vertical tail root chord
e	lifting surface Oswald efficiency factor
F_n	single engine thrust
F_{oo_c}	canard loading parameter
F_{Re}	Reynolds number correction factor
g	acceleration due to gravity
h_{loc}	horizontal tail location on vertical tail as a percentage of the vertical tail span
h_n	maximum fuselage nose depth
IR	annual average inflation rate
I_{YY}	aircraft moment of inertia in pitch
i	lifting surface incidence angle relative to the fuselage longitudinal reference line
K	component aerodynamic form factor
K_y	aircraft pitch radius of gyration
L	lift force
$l_{c_{cg}}$	canard moment arm referred to the aircraft c.g.
$l_{c_{cg_e}}$	distance of canard centre of gravity from fuselage nose apex
$l_{\bar{c}/4}$	canard moment arm referred to the wing mean aerodynamic quarter chord point

$l_{\bar{c}_{c/4}}$	distance of the canard mean aerodynamic quarter chord point from fuselage nose apex
$l_{\bar{c}_{htc/4}}$	distance of the horizontal tail mean aerodynamic quarter chord point from the fuselage nose apex
$l_{c_{xc/4}}$	distance of canard centreline quarter chord point from fuselage nose apex
l_{fus}	fuselage length
l_{tcg}	tailplane moment arm referred to the aircraft c.g.
$l_{t\bar{c}/4}$	tailplane moment arm referred to the wing mean aerodynamic quarter chord point
$l_{w_{xc/4}}$	distance of wing root quarter chord point from fuselage nose apex
M	Mach number or pitching moment
M_D	drag divergence Mach number
N	engine rotor speed or normal force
P	total air pressure
P_{ca}	percent corrected engine airflow
Q_p	aircraft production quantity
$q = \frac{1}{2} \rho V^2$	air stream flow dynamic pressure
RC	rate of climb
Re	Reynolds number
Re_1	Reynolds number per unit length
RS	sink rate
r_n	fuselage nose fineness ratio
S	lifting surface planform area or body wetted area (fuselage or nacelle)
SC_{FAX} or SC_{FAC}	supercritical aerofoil parameter used to shift the drag divergence Mach number

$\frac{S_c}{S_w}$	canard to wing area ratio
SFC	engine specific fuel consumption
SF_n	specific engine thrust
S_K	correction factors in the canard weight estimating relationship
$SM = \frac{dC_m}{dC_L}$	longitudinal static margin
s_f	wing or canard efficiency correction factor due to change in spanwise lift caused by flap deflection
T	total air temperature or total thrust
t/c	lifting surface average thickness to chord ratio
U_{LF}	aircraft ultimate load factor
V	air velocity or aircraft speed
V_s	aircraft stall speed
\bar{V}	tail or canard volume coefficient
W	weight
W_a	engine air weight flow rate
W_{ca}	corrected air mass flow rate
W_0	aircraft gross weight or aircraft maximum take-off weight (no distinction is made in the present study)
$\frac{W}{S}$	aircraft take-off wing loading
$w_{f_{ec}}$	fuselage width at the canard intersection
X_{LF}	normal load factor
$\bar{X}_{c\bar{c}}$	longitudinal distance of the canard mean aerodynamic chord leading edge point from canard centreline apex
$\bar{X}_{ht\bar{c}}$	longitudinal distance of the horizontal tail mean aerodynamic chord leading edge point from the tailplane centreline apex

$\bar{X}_{w\bar{c}}$	longitudinal distance of the wing mean aerodynamic chord leading edge point from wing centreline apex
x	longitudinal distance measured from the fuselage nose apex to some particular point, e.g., aircraft c.g., aircraft aerodynamic centre or lifting surface aerodynamic centre
\bar{x}	location defined as a fraction of the wing mean aerodynamic chord from its leading edge
$\bar{x}_{P_{min}}$	wing minimum pressure point in fraction of wing chord
\bar{Y}_{c_c}	spanwise distance of canard mean aerodynamic chord from fuselage centreline
z	vertical distance measured from the aircraft c.g. to the aircraft or lifting surface aerodynamic centre
α	lifting surface angle of attack
α_0	wing zero-lift angle of attack
α_{0c}	canard zero-lift angle of attack
γ	flight path angle
Δ	distance range or increment
δ	canard or elevator deflection angle or the total atmospheric pressure ratio to that at sea level static conditions
δ_{c0}	canardvator deflection angle at overall zero lift
δ_{e0}	elevator deflection angle at overall zero lift
ε	wing downwash angle at the horizontal tail
η	lifting surface efficiency defined as the ratio of the dynamic pressure experienced by the surface to that of the undisturbed free air stream
θ	total temperature ratio to that at sea level static conditions
$\dot{\theta}$	aircraft pitch rate
$\ddot{\theta}$	aircraft angular pitch acceleration
Λ	angle of sweep
$\Lambda_{P_{min}}$	sweep angle at the wing minimum pressure points

λ	taper ratio
μ	dry runway coefficient of rolling friction
ρ	air density
σ	empirical flap efficiency factor obtained as a function of flap deflection or air density ratio
τ	control effectiveness
ν	kinematic viscosity of air

Subscripts

<i>a</i>	available
<i>ac</i>	aircraft aerodynamic centre
<i>aft</i>	rearward
<i>app</i>	approach
<i>c</i>	canard or canardvator
<i>cg</i>	centre of gravity
<i>cl</i>	climb
<i>cr</i>	cruise
<i>c/4</i>	quarter chord point
$\bar{c}/4$	mean aerodynamic quarter chord point
<i>dir</i>	direct
<i>e</i>	elevator
<i>FN</i>	normal force
<i>f</i>	rolling friction
<i>flap</i>	flaps
<i>fus</i>	fuselage
<i>fwd</i>	forward
<i>ht</i>	horizontal tail
<i>i</i>	ith component

<i>jinc</i>	jet inclination at horizontal tail
<i>L</i>	landing flare
<i>le</i>	leading edge
<i>lg</i>	landing gear
<i>max</i>	maximum
<i>min</i>	minimum
<i>n</i>	engine inlet
<i>nac</i>	engine nacelle
<i>np</i>	neutral point
<i>Re</i>	Reynolds number
<i>r</i>	lift-off rotation, or root or radius of the assumed rotation circular arc path
<i>ref</i>	reference
<i>sl</i>	sea level International Standard Atmosphere (ISA) conditions
<i>sls</i> or 0	sea level static conditions
<i>t</i>	horizontal tail or lifting surface tip or take-off condition
<i>te</i>	trailing edge
<i>th</i>	engine thrust
<i>trans</i>	lift-off transition
<i>t0</i>	take-off condition
<i>vt</i>	vertical tail
<i>w</i>	wing
<i>wet</i>	wetted

...many things are obvious once someone has pointed them out,...

Professor E.M.L.Beale in "Introduction to Optimisation"

1 Introduction

1.1 Scope of the Study

The underlying reason for this doctoral research investigation stems from the fact that whilst many recent studies attempt to bring some light on the pros and cons of three-lifting surface aircraft concepts versus conventional tail-aft designs by studying different lifting surface arrangements, they do not produce practical realistic results other than some insight into the problem. A more pragmatic approach is needed and a tentative treatment of the problem is described in this thesis.

To succeed, a real world commercial aircraft has to comply with a set of requirements ranging from its ability to perform safely and efficiently a given mission or missions dictated by the market, its growth potential and operating flexibility to accommodate new markets, if necessary capitalizing on new technologies in order to ensure a long and economically competitive life, and conform with the regulations set by the airworthiness regulatory bodies. Under these premises in order to evaluate more effectively the differences posed by both concepts it seems appropriate and opportune to perform parametric and design optimisation preliminary studies on the two configurations. While using the same assumptions, technology levels and ground rules, both concepts are designed to meet a given set of mission and operational requirements, optimised by the same criteria, and their performance and economics compared on an equal basis.

Typical and established engineering methods used in conceptual preliminary design are utilized for the design synthesis which is coupled to a numerical minimization technique capable of finding the combination of significant design variables which optimise an appropriate performance index.

1.2 Research Objectives

The main research objectives were:

1. The development and validation of a computer technique for the conceptual design and optimisation of commercial jet-transport aircraft with respect to suitable functions of merit.
2. The evaluation of the potential advantages of the three-lifting surface configuration aircraft when compared to conventional tail-aft transport designs optimised for the same mission while satisfying the same set of performance constraints.
3. To achieve a better understanding on the complex coupling of the several relevant disciplines which are traditionally considered during the conceptual phase of jet transport vehicle configuration design.

1.3 Structure of the Thesis

This thesis comprises two distinct parts, the main text and the appendices.

The main text is made up of seven separate sections:

1. Chapter 1 introduces the subject of the present research work, explains the reasons for undertaking it and the objectives.
2. Chapter 2 presents a survey on previously published literature in the field and shows the significance of this work.
3. Chapter 3 defines the design criteria, methodology used and describes the conceptual design and analysis tools required for the development of the work with the modifications carried out and assumptions made to adequately model the three-lifting surface concept.
4. Chapter 4 formulates the design optimisation problem, introduces the reader to the numerical minimization technique employed and describes its operation with the design synthesis.
5. Chapter 5 reports the case study undertaken through several steps. Starting from the establishment of a hypothetical mission specification, it describes the initial parametric analysis, the development of the baseline aircraft for both concepts, their optimisation with respect to minimum Direct Operating Costs (DOC) and minimum Maximum Take-off Weight (MTOW), and the conducting of range trade-off studies to determine their relative merits. Results obtained are described and documented. Conclusions arrived at are included, and comments on the operation of the optimiser-design synthesis given.
6. Chapter 6 presents a general assessment of the work with a discussion on the methods used and results obtained. Suggestions for future work are given.
7. Finally Chapter 7 draws the main conclusions from the work.

Each chapter is 'self-contained' showing at its end the respective list of references.

All the eight appendices, placed after the main text, contain detailed information such as theoretical derivations, equations used, computer listings, results and figures required to justify and support the main text.

2 Literature Review

2.1 Aircraft Design and Optimisation

2.1.1 Aircraft Conceptual Design

Significant advances have been achieved in computerised aircraft conceptual and preliminary design. The continuing development of the related techniques and computer based systems reveals the lively interest that exists in the field and is well documented in the existing extensive literature. This remarkable progress, driven by the need of efficient means for rapidly assessing new aerospace systems, kept pace with the fast growing development of the digital computers since the early sixties. A historical account of the progress made so far is briefly given in the following pages.

Until about 1960 conceptual aircraft design studies were usually performed by highly competent and experienced designers^{1,2} using relatively simple methods based on systematic graphical techniques. These techniques embodying empirical statistically derived correlations of data from recent past designs included the use of special purpose slide rules, nomographs and overlay methods allowing for an initial rapid evaluation and parametric analysis of new aircraft concepts. Although these ingenious techniques provided a very limited view of the design problem they did develop an intuitive feeling for the sensitivity of a particular configuration to the principal design variables and constraints.

The introduction of the high-speed digital computers offered the aircraft designer a powerful framework enabling a virtually unlimited number of design variables to be changed while searching for the best configuration to meet a given need, that is, the space of design variables could be more exhaustively explored in contrast with the two, three variables a time allowed by the former graphical parametric techniques.

Initially, the computer was used to run self-contained disciplinary analysis programs developed by departmental specialists who were responsible for their accuracy and up-to-date capability. However to carry out the design, interchange of design information and personal contacts between these disciplines are essential and were very frequently done in a highly interactive, sequencing and cyclic manner as the design progressed. This process proved quite inefficient and error prone as the complexity of the vehicle increased, and bigger design staffs were required³. The increase in complexity and sophistication of modern advanced aerospace vehicles and the iterative nature of the design process entailed longer and longer design cycles therefore increasing costs and the risk of introducing obsolete products in the market. In addition, competitive pressures at the preliminary design level leading to proposal submission fostered requirements for higher speed of response and accuracy. Both these attributes enhance analytical capability for broad and exhaustive parametric evaluations and trade-off studies. These are essential steps for thoroughly learning about the design and improving or optimising it thus enhancing both the confidence in the solutions found, and the company competitive postures. Automating the design process by integrating all the pertinent disciplines into design synthesis programs offered a solution to the problems and needs just mentioned. Therefore, analysis programs or modules were integrated by commonality of

input and output keeping disciplinary responsibility for each module.

Development of design synthesis programs indeed improved the quality of the designs and also allowed for expanded design options while retaining the same cycle time, thus lowering the risk associated with product development⁴. Design information became more consistent, more credible, thorough enough and systematically organized and very importantly was available early in the design process improving decision making capability. It is worth noting that decisions taken at these early design stages have enormous cost implications at the later stages of the development process and during aircraft operation, yet the resources and money expended during the initial phases are usually relatively small⁵. About 70 to 80% of the total program cost is determined by the time the aeroplane concept is formulated⁶. Design innovation gained as well, although indirectly through reduced evaluation time.

2.1.2 Computerized Tools

To adequately explore the many design approaches suggested during the early definition of aerospace vehicle concepts and to select those that show significant promise for further study, most companies, agencies and some Universities have developed their computerized tools for conceptual and preliminary design. A representative list of these former and contemporary programs is given with their acronyms and originators:

- SYNAC - General Dynamics⁷
- CADE - McDonnell Douglas Corp.⁸
- CPDS - Boeing Co.^{9,10}
- ASSET - Lockheed California Co.⁴
- CAP - North American Rockwell Corp.⁴
- ASAP - Vought¹¹
- ACSYNT - NASA Ames^{5,15}
- TRANSYN - NASA Ames¹²
- IPAD - NASA Langley^{13,3}
- ODIN - NASA Langley¹⁴
- MVO - Royal Aerospace Establishment¹⁶
- VDEP - NASA Langley¹⁷
- GASP - NASA Ames¹⁸
- CDS - Rockwell International¹⁹
- CAPDA - Technische Universitat-Berlin^{20,21}
- ADAS - Delft University of Technology^{22,23}
- AAA - University of Kansas²⁴
- RDS - Conceptual Research Corp.²⁵

Most cover the initial concept and preliminary phases, others such as the NASA IPAD system^{13,3} tend to cover the total process including the detail design and manufacturing phases. However, more emphasis is here given to conceptual design tools for the present work is concerned with the concept feasibility study phase. The general arrangement adopted by most of these programs is similar, being the differences settled by the way the several modules are interconnected, the level of the detail and the emphasis on particular aircraft types.

ACSYNT appears the most sophisticated of all since its development started earlier in the mid sixties and it has been continuously pursued since then^{26,27}. This program offers multi-level design synthesis and analysis including very sophisticated structural and aerodynamic analysis codes. As a result a great amount of detailed design information is generated allowing for much more accurate insight and assessment of the actual aircraft at the preliminary design phase. It now features good graphical capabilities with an appropriately developed conceptual aircraft computer-aided drafting system (CAD) for the interactive and automatic generation of aircraft geometries.

CAPDA and ADAS are well developed computerized transport aircraft design systems which provide configuration design synthesis and analysis, parametric and sensitivity studies, multivariate optimisation and trade-off studies as well as multi-level analysis capabilities. Both programs are coupled with computer-aided drafting systems (CAD). These programs and AAA were developed in a university environment and their improvement and updating is a continuing process.

2.1.3 Numerical Optimisation Techniques

The importance of conducting sensitivity and trade-off studies is stressed during all design activities since it represents the traditional means to get a sound insight into the design and to find the 'best' combination of aircraft design parameters that meet given system requirements. This process, called optimisation, can be automated though it is usually augmented by manual trade-offs. Automated methods for aircraft configuration design optimisation are a natural extension of past parametric methods. Both approaches rely on the designer's experience and intuition for a first guess and both use iterative methods to improve this guess.

Optimisation, as it stands today, is a lively branch of applied mathematics particularly associated with operational research which, in turn, is concerned with decision making. Creating a new product involves making many decisions, which suggests that designing is viewed as a decision making process. Decision making has sometimes to be based on subjective and vague considerations where the experience and creativity of the designer are essential in making proper decisions, bringing new challenges and opportunities for innovations which may influence the success of the new aircraft. Nevertheless, instinct and intuition alone are not always a satisfactory way of making decisions, particularly when the quality of a solution to a practical complex problem involving a great many factors and constraints which strongly interact and entails considerable financial risk, such as happens in aircraft design. Once a mathematical model of the problem, here represented by an integrated vehicle synthesis program which may simulate many alternative designs within its limitations, is established, the 'best' or 'optimum' design can be identified with the aid of mathematical programming methods. 'Optimum' designs should be interpreted as such with regard to a chosen performance criterion, within the tolerance of the mathematical model describing it, and the subjective judgement of the designer.

2.1.3.1 Multivariate Optimisation

Recognizing the potential offered by numerical optimisation techniques, Boeing Company developed a general-purpose optimisation program called AESOP, 'Automated

Engineering and Scientific Optimization Program', starting in 1965 under the direction of D. S. Hague^{28,29}. This optimiser can drive up to 100 design variables, and an unlimited number of constraints may be employed through a penalty function. It has nine search strategies, which may be used singly or in combination, for sequentially solving a design problem. The employment of so many optimisation methods emphasizes the strong influence the characteristics of the design synthesis process may have on the suitable choice of the numerical technique^{9,30}. This program was widely applied to performance optimisation problems and to multidisciplinary design problems including hypersonic transports and the US space shuttle⁹. Silver and Ashley³⁰ present an excellent discussion on the methods used and problems encountered with their application, and also include a well annotated list of references.

In the same line of reasoning, the Royal Aerospace Establishment (RAE), in Britain, centered its attention on the development of computerized numerical optimisation techniques³¹, combined with aircraft design synthesis^{32,33}. The first version of the Multi-Variate Optimisation (MVO) program was developed for civil transports^{32,33,34,35} and subsequent parallel work culminated in the development of a program for military aircraft^{36,37}. Throughout this development the programs were continuously improved by the introduction of more accurate design relationships and restructured into a modular form. The original optimisation driver³¹ was successively replaced by more sophisticated versions^{38,39} and is the later numerical algorithm used in the present investigation.

Kirkpatrick and Larcombe⁴⁰ described the initial development of the MVO design optimisation program, presented and discussed some of the related experience gained and showed some example applications on rapidly assessing the effect on the optimum design of changes in the specified performance or of advances in aerodynamic, structural or engine technology. They also illustrated, based on ref. 41, how the 'full' benefits could be obtained from an advance in technology and concluded "the benefits obtained by a complete reoptimisation of the aircraft design are 'much greater' than those obtained by using the advance to alter just one or two of the aircraft design characteristics". Also, based on refs. 42 and 43, they showed the advantages of using a compound optimisation function instead of a single objective criterion. This compound optimisation function consists of a weighted figure of merit combining two or more aircraft parameters and it is used to improve the aircraft performance in one respect while not greatly degrading it in another. The technique may be used, in particular, in commercial transports, for example to enhance passenger comfort, stretch potential or operational flexibility at a minimum economic penalty.

While describing the analysis methods employed in the automated synthesis, Kirkpatrick⁴⁰ observed that "the mass estimation must be as accurate as possible, but it is also essential when an optimisation procedure is being used that the partial derivatives of the various component masses with respect to each design variable should reflect the true situation as accurately as possible". This point was also addressed by Vanderplaats¹⁵ when he remarked that it is very important to make the discipline modules as accurate as possible which is a fundamental concern in achieving a reliable design tool since the automated optimisation process tends to capitalize on any weakness in the analytical model and produce unrealistic designs or even diverge. Ensuring the accuracy and reliability of the discipline information can provide valuable design information on which to guide and base research and development decisions.

Brian Edwards⁴⁴ described some techniques for using MVO programs and how the optimisation method could be used to explore the aircraft design model and cultivate an insight into its characteristics. He stressed the importance of these tools in producing systematic sets of comprehensive consistent data from which a thorough understanding of the interaction between the contending effects within the model can be gained. ...

Research initiated at RAE has been pursued, extended and complemented by work done in the College of Aeronautics (CoA) at Cranfield, at Loughborough University, and British Aerospace.

To provide a suite of combat aircraft design synthesis modules⁴⁵, other MVO programs were developed at the CoA covering Canard Delta⁴⁶ and Advanced Short Take-off and Vertical Landing⁴⁷ (ASTOVL) configurations; and a similar program for Unmanned Aerial Vehicle⁴⁸ synthesis and optimisation was produced where the optimisation drivers were supplied by RAE.

At Loughborough University interest was directed towards the application of MVO methods to evaluate optimum short-haul flight profiles for turbopropeller aircraft⁴⁹. This work was subsequently extended through the integration of the separate aspects of preliminary design optimisation and flight profile optimisation leading to the development of a program called CASTOR (Commuter Aircraft Synthesis and Trajectory Optimisation Routine)⁵⁰ for the design/analysis and optimisation of twin-turboprop commuter aircraft of the conventional layout, flying multistage missions. This strategy helps the selection of the best available or projected design for a particular airline route-structure or permits the design of the 'best' solution tailored to that route-structure. More recently^{51,52}, this program was modified to account for turbo-fan engine data, fuselage pressurization, introduction of composite materials, changes in aircraft operational procedures and updated cost, allowing for the synthesis of optimum regional fan-jet transport aircraft. This later version of the Loughborough MVO program features a very versatile capability for rapidly performing parameter sensitivity and trade-off studies with the incorporation of the newly developed Peri-optimum subprogram which conducts a series of single passes through the synthesis model and automatically generates plots of the design surface around the optimum design point for chosen parameters. The programs were developed in support of industrial design studies performed by the project design team at Short Brothers (Belfast) Plc. and benefited from the close industrial collaboration that existed.

RAE multivariate techniques have been applied as well at British Aerospace in the development of MVO design synthesis/optimisation programs as described by Chacksfield⁵³ and more recently by Cousin and Metcalfe⁵⁴ with the TASOP (Transport Aircraft Synthesis and Optimisation Program) program which features high standard coding, structure, documentation and maintenance procedures enhancing its flexibility and response in terms of applicability to a wide variety of aircraft projects and design problems with improved quality and reliability.

Another interesting effort is represented by OPDOT⁵⁵ (Optimum Preliminary Design of Transports) program developed by Sliwa and Arbuckle, which integrates a constrained non-linear programming technique with a transport aircraft preliminary design routine. The program was written to expeditiously obtain answers for a study of the impact of active

controls upon transport aircraft⁵⁶. Using the same tool, other studies on medium-range transports followed. These included the evaluation of the influence of selecting different performance indices and constraints on the design⁵⁷, and the conceptual study and optimisation of a statically stable, subsonic, canard-configured transport aircraft⁵⁸. The later one was the first reported comprehensive design study of a subsonic, medium-range canard-configured transport aircraft.

Continuing interest on the initial design/optimisation of transport aircraft is shown by the development of similar computerised tools and their application in France and in the old U.S.S.R. as described in references 59 and 60.

2.1.3.2 Selection of Figures of Merit and Multiobjective Functions

The difficulty presented in selecting the appropriate figure of the merit in aeroplane configuration design and its importance have already been stressed and exemplified in many of the above reported investigations. A good illustration of its effect on aircraft optimum configurations is also presented and discussed by Jensen and al.⁶¹ who determined optimum designs of commercial and military cargo transports for seven different performance indices. They concluded that designs for minimum gross weight and D.O.C. show the smallest penalties relative to optimum solutions of the other figures of merit and that 'compromise' designs can be obtained by means of weighted combinations of performance indices.

However, by studying three different classes of subsonic commercial aircraft (short, medium and medium-to-long range) optimised for several different objective functions, Johnson⁶² concluded that the optimum configuration is strongly influenced by the prevailing economic conditions which also determine how much technology can be included on the aircraft. So, by optimising an aircraft for minimum gross weight and for minimum D.O.C. may result in quite different configurations as was shown by the effect of increasing the fuel price which, in this case, plays a much more important role in determining D.O.C. and therefore in defining its related configuration. Jacobson and Murphy⁶³ also illustrated this point of view and emphasized how deeply a change from the present low fuel cost to a high fuel cost environment could affect aircraft design and the airline's competitive position. Thus, Jensen's conclusion on minimum gross weight and D.O.C. designs will hold and should be interpreted in the light of the particular economical environment assumed in their study.

When using multiobjective functions, the relative influences of each individual performance index are significant for the designer. Investigation on the use of multiobjective optimisation methods for conceptual transport aircraft design where conflicting figures of merit are simultaneously considered and effectively combined was undertaken by Dovi and Wrenn⁶⁴. Later, by combining different figures of merit into a multiobjective function with the weighting of individual functions varied parametrically to obtain a series of multiobjective optimal solutions, Malone and Mason⁶⁵ showed the evolution of optimum designs from one objective function to another. This evolution provides insight into the importance of each figure of merit to alternate mission tailoring, structural trade-offs and considerations of growth, flexibility and adaptability potential. Additionally a more thorough understanding of the effects of the proper choice of the performance index can be gained.

2.1.4 Systematic Decomposition and Sensitivity Analysis of Complex Coupled Systems

As the design evolves into more detail and refinement, better geometrical representation of the configuration is required together with more accurate disciplinary analysis methods. This starts from the integration of a very flexible CAD design system in the concept design/optimisation program, if not already implemented for which CAAD⁶⁶ was the first computerized example, and the inclusion of more sophisticated analysis methods such as Computational Fluid Dynamics (CFD)⁶⁷ and Finite Element Methods (FEM)⁶⁸. With the integration of the NLRAERO panel code^{69,70} and a FE-analysis program⁷¹ respectively for aerodynamic and structural design and analysis, ADAS system is now becoming a very powerful, sophisticated and complex multi-level design environment for aircraft preliminary design optimisation.

However, due to the optimisation methodology used, this kind of sequential system while growing in complexity tends to obscure the conflicting trends and trade-offs which guide the design towards improvement, without providing visibility of the mutual influences among the diverse engineering and economic disciplines. Additionally it becomes computationally costly and less accurate as the finite differencing needed to generate the system sensitivity derivatives are performed on the entire system analysis in the form of total derivatives of the objective function with respect to each of the specified design variables. An alternative to this conventional approach was proposed by Sobieski⁷² at NASA Langley Research Centre and it is known as 'optimisation by decomposition'. This method is appropriate for systematic analysis and optimisation of large engineering systems such as aircraft by decomposition of the design process into a set of smaller, more manageable self-contained subproblems amenable to concurrent analysis. It is intended to particularly fit typical engineering organizations and take advantage of the modern technology of distributed computing and parallel processing. A distinction is made in reference 73 between a top-down hierarchic decomposition in which several levels of subproblems are considered, each depending on the input from a level above as described in ref. 72 and exemplified in ref. 74, and a non-hierarchic decomposition in which the subproblems are all interconnected at the same level⁷⁵. In the hierarchic decomposition, each subproblem contains its own optimisation while in the non-hierarchic decomposition, the optimisation is done at the entire system level, e.g. the system optimisation is treated as a single problem. The later approach is based on sensitivity analysis of a complex, coupled system which concurrently generates partial sensitivity derivatives in each individual discipline fully accounting for the interactions among the parts and the disciplines that govern the design. The system sensitivity design derivatives are computed simultaneously from the partial sensitivity derivatives of its parts for all the design variables of interest and provide a numerically precise and global comprehensive answer which may be used to improve the design by judgemental changes, and/or by formal optimisation. This is in contrast with the former conventional sequential process where the entire design sequence had to be repeated for each design variable perturbation in order to generate information for a finite difference and assess its influence on the design.

Sensitivity analysis offers a practical tool to answer the "what if" questions that arise in design providing visibility of the mutual influences among the engineering specialities, and decomposition into smaller, concurrently executable tasks enables interdisciplinary synergism to be exploited. This method addresses the very important qualitative aspects of the design process, usually dominated by quantitative computable considerations, by supporting human

intellect and judgement decisions through sensitivity data which also provide a means of communication between disciplines. Under this scheme, each specialist will know how his decisions will affect other coupled subsystems and the entire system. Thus great emphasis in this method is given to the control of interactions among disciplines and physical subsystems to improve the entire system performance.

These techniques accounting for interdisciplinary coupling have been mostly tested on preliminary and detail design problems⁷⁶. However, references 77 and 78 described the work undertaken at Rockwell towards the application of these techniques to the conceptual design of advanced fighters with emphasis on wing design within an industrial environment. Other example applications, deliberately kept at the conceptual design level, are presented in references 65 and 79 for the design of transport aircraft. The later one focuses on a three-lifting surface transport of the Boeing 777 class designed and optimised for minimum take-off gross weight where the locations and areas of the three lifting surfaces were taken as design variables. A more comprehensive and updated review on the experience obtained from the application of these methodologies is found in reference 80.

The problem of optimal design of aircraft has suggested other alternative approaches.

2.1.5 Genetic Algorithms

For handling problems with discontinuities and local minima, such as the present one, one of the methods that show promise is based on the so-called genetic algorithms⁸⁰. Genetic algorithms⁸¹ are a form of direct random search which simulates the improvement process based on Darwin's evolutionary theory. They start with many possible discrete solutions which are randomly distributed over the design space to create an initial population of designs. Each design member is represented by a bit-string which is a coded listing of the values of the design variables. A measure of fitness is evaluated for each member. The measure of fitness is a function of the degree of satisfaction of the constraints and of the objective function, or functions, whose extremum is sought. Then the members in the population are allowed to evolve through a process of natural selection, mating and crossover of genetic material, and mutation, using probabilistic operations borrowed from evolution theory. In crossover two individuals exchange part of their strings, so two children are generated as combinations of parts of the parents' strings. In mutation, individual bits of the string may be changed. Unlike natural evolution the total number of members in the population is kept constant. The parents are ranked according to the value of their fitness function, the higher the rank of a parent the higher its chance of being selected for reproduction. During the process parents are gradually replaced by better fit children through several generations and, due to the mutations, superior features may occur in some children to initiate a new line of evolution, improving the solution of the optimisation problem until convergence is obtained, or the process is stopped at a given stage of the evolution. A measure of convergence may be obtained from the difference between the fitness of the best member and the average fitness of the population.

These algorithms require only the values of the objective function. Their gradients, first or second derivatives, are not needed, consequently these methods are less susceptible to getting trapped in local extrema as happens with other nonlinear optimisation algorithms. Consequently genetic algorithms are especially effective in locating "interesting" regions

within the design space and therefore are more suitable for finding global minima. However, in the neighbourhood of an extremum point they are not as efficient as nonlinear programming methods in finding the exact values of the design variables and the use of a gradient-based search is then recommended^{80,81}. Thus application of a hybrid method is favoured.

As described, the process involves not only the survival of the fittest, but the elimination of the weak and it sounds a bit heartless. But optimisation implies discarding many designs, some of them interesting regarding their particular merits, in search of the "fittest", and this one is intended "to survive". This approach is intrinsically suitable to handle multiobjective problems. Reference 82 describes the minimum weight sizing of a business jet aircraft at the conceptual stage using a genetic algorithm. Other applications of these methods on aerospace-related engineering optimisation problems are discussed and illustrated in reference 83.

2.1.6 Knowledge-Based Strategies

Recently another approach to conceptual aircraft design using knowledge based strategies by means of inferential methods is becoming increasingly significant and shows relative success. These methods apply Artificial Intelligence⁸⁴ techniques in the development of computer Expert Systems which aim to emulate the problem-solving ability of human experts. These systems are explicitly based on capturing the proper knowledge and coding it into the form of condition-action rules. The rules are program declarative statements which infer a property of an object or of one set of objects from properties of other objects. Selection and execution of the rules are under the control of an "inference engine". Expert Systems adopt a symbolic programming approach which has proved convenient for the deductive reasoning process. However propositions and inference rules in Expert Systems are very often not known with certainty and this fact can pose a limitation in this type of systems. There are other difficulties associated with the development of these systems. They depend not only on the acquisition of adequate expertise but also on their updating and continuous maintenance requirements. Changing knowledge, fixing faults, verification and validation become increasingly difficult⁸¹ and this is a constant concern. One important goal in developing this kind of system is to retain the transparency of design decisions and the flexibility of the classical configuration design process. This approach emphasises interactivity in addition to providing design advice to the user.

At Cranfield, several studies leading to the development of Expert Systems for conceptual design have been performed. These studies started in 1984 with the development of the ADROIT (Aircraft Design by Regulation of Independent Tasks) system^{85,86}, a prototype program that conceptually designs the wing for high subsonic transport aircraft, which is still under development. A similar system for the design of a transport aircraft fuselage⁸⁷ was also developed and, more recently, a program for the overall configuration design of subsonic transport aircraft⁸⁸ has been completed. Application of these techniques elsewhere is described in references 89, 90, 91 and 92.

2.1.7 Combined Systems

A trend exists in combining several methods and techniques within one system in order to augment its flexibility in dealing with different problems or apply the most appropriate approach to a given multidisciplinary design optimisation problem. A system for aircraft concept design combining an expert system and a suite of optimisation methods including gradient-based and genetic algorithms is illustrated and problem applications are discussed by Kroo⁹². Another example incorporating similar techniques but developed for "ingenious" jet engine design named EnGENEous⁸¹ is used at General Electric.

2.1.8 The Teaching of Aircraft Project Design Methods

The important educational role provided by these integrated computer aids in teaching aircraft design and optimisation is also widely illustrated throughout the literature^{21,22,52,93,94} since Silver⁹⁵ first attempted to identify the best in light-aircraft in 1971, at Stanford University, as the topic of his Ph.D. dissertation.

2.2 The Three-lifting Surface Aircraft Concept

2.2.1 Some Practical Examples and Prospects

The concept of a three-lifting surface aircraft although very rarely implemented is not a new one. The Curtiss-Herring No.1 Reims Racer (1908), and the De Havilland Biplane No.2 (1909), illustrated respectively in figures 2.1 and 2.2, were two of the earliest attempts of the type ever flown⁹⁶. A very recent example is the Piaggio P-180 Avanti⁹⁷, shown in fig. 2.3, a business class turbo-propeller aircraft intended to offer enhanced comfort and performance as compared to current conventional competing turbo-props.

The aim was to produce an economic/advanced business aircraft. The need for a quiet and comfortable cabin, the use of large extensions of natural laminar flow on the fuselage and lifting surfaces for low drag, and the lowest possible weight target by exploiting interdisciplinary synergism, were the main design drivers. Essentially, its particular layout permits the positioning of the engines and propellers behind the cabin rear pressure bulkhead to minimize engine noise level, thus avoiding the weight penalties associated with the installation of noise insulating materials. Rearward positioning of the wing provides full stand-up headroom in the cabin as well as allowing for a reduced wing-fuselage interference drag which is favoured by an almost mid-wing installation. The relatively high aspect ratio wing and little sweep, $A=12.3$ and $\Lambda=0^\circ$ @ 15% chord, offers an aerodynamically efficient design at subcritical conditions. This feature, combined with a precise contour smoothing and very high quality skin surface finishing, and a cleaner pusher configuration with the propellers located well behind the wing, encourages laminar flow and leads to a high lift-to-drag ratio operation. The wing-mounted engine arrangement provides for a load relief effect and results in a lighter wing structure. Additional structural weight savings are achieved by synergetically combining three major load carrying components, e.g. the wing main spar in the fuselage, forms an integral aluminium alloy fail-safe structural unit with the rear pressure bulkhead and the main landing gear. Owing to the excessive rearward location of the wing, bearing in mind weight, balance, stability and control, the solution of combining a fore-lifting

surface together with a conventional tail was adopted. The canard helping the wing for lift generation also ensures aircraft longitudinal trim in favour of a higher trimmed overall lift. For a given longitudinal static stability margin this may also tend to reduce trim drag as usually produced in conventional inherently stable aeroplanes by the required tail down-load. This compromise appears to minimize cruise drag consequently reducing fuel consumption and the amount of fuel to carry for a given mission range. Pitch control is provided by the horizontal tail elevators while the canard auxiliary flaps (single slotted trailing edge flaps) are mechanically coupled with the main wing flaps, both working together as to offset any changes in trim. The end result, when compared to a conventional tail-aft aircraft designed to the same specification and using the same level of technology, would be a lighter aeroplane, probably equipped with less powerful, lighter and more economic engines because of lower maximum take-off weight and drag, thus offering better cruise performance and passenger appeal.

2.2.2 Previous Research

Many authors have recently investigated the advantages of using canards on aircraft configurations. Most of these studies were performed in the sequence of the early seventies energy crisis and subsequent trends in fuel costs whose increase adversely affects airline economics. The aim was to reduce aircraft overall drag to improve performance and decrease operating costs while increasing safety levels.

2.2.2.1 Two-lifting Surface Concepts

Several papers¹⁰⁰⁻¹⁰⁹ dealing with the subject of the minimum induced drag of two-surface aeroplanes, both of the tail aft and of the canard configurations, were based on Prandtl's biplane theory⁹⁸ and Munk's stagger theorem⁹⁹. Prandtl calculated the mutually induced drag of a multiplane in potential flow by assuming that the spanwise lift distribution on each surface was elliptical and integrated the product of the downwash and lift across the span. Munk proved that the total induced drag of a multiplane system remains unchanged if the lifting surfaces are displaced (staggered) relative to each other in the direction of flight as long as their spanwise lift distributions are preserved. Thus, the theory rests on the assumption of elliptically loaded lifting surfaces under the mutual influence of their downwash flow fields.

Naylor¹⁰⁰ demonstrated that if the tail of a conventional aeroplane is in the same plane as the wing (zero gap), then the minimum induced drag occurs when the tail load is zero. As for zero gap, Larrabee¹⁰¹ showed that the induced drag of canard and conventional configurations of equal span ratios is the same if the canard and tail are carrying equal but opposite trim loads. No consideration of longitudinal stability requirements was given in this study. However, McLaughlin¹⁰², in his comprehensive analysis on trimmed drag of conventional and canard aircraft where the effect of gap, span ratio, zero lift moment and static margin were assessed, found that their related static stability margins were considerably different. In fact, the canard design had an unstable static margin of about 0.1, while the conventional showed an excessively stable static margin of about -0.5. This author showed that the cruise drag of practical canard configurations is higher than that for conventional types with similar static margins which is due to the high canard loading that is required for trim. This same conclusion was also obtained by Keith and Selberg^{110,111}. After studying

conventional subsonic transport aeroplanes, Laitone¹⁰³⁻¹⁰⁶ concluded that if the tail is either above or below the plane of the wing (finite gap), then a slightly positive tail load (upload) would produce minimum induced drag which would be virtually the same than that obtained from a zero tail load. The reduction so obtained in induced and compressibility drag for typical aircraft would lead to potential fuel savings amounting to 5%. Shevell's¹⁰⁴ trimmed drag data confirmed these estimates. However, this condition can be attained at only one aft centre of gravity (c.g.) location on a tail-aft design, and cannot be achieved on a pure canard configuration which requires a further forward c.g. location for inherent static longitudinal stability.

Feistel and al¹⁰⁷, while performing wind tunnel experiments on canard-wing arrangements (no fuselage), found a 10% total induced drag reduction when compared with that predicted by the classical Prandtl-Munk theory which was due to favourable canard-wing interference effects. These measurements correlated well with estimates made from a vortex-lattice panel code and were explained and supported analytically by Butler¹⁰⁸ and Kroo¹⁰⁹. These authors, working independently in an attempt to extend the theory to include more realistic loading distributions, modified Prandtl's biplane induced drag equation to allow for changes in the main wing spanwise lift distribution imparted by the presence of the canard, to minimize the total induced drag. For a typical example, both determined reductions respectively in 6% and 10% of the total induced drag as predicted by the Prandtl-Munk theory which is consistent with the empirical trends found by Feistel.

2.2.2.2 Two- and Three-lifting Surface Concepts

Using the Prandtl-Munk theory, Butler¹¹² and Kendall¹¹³ compared the induced drag of two-surface and three-surface layouts.

After having studied an advanced fighter type design, Butler concluded that improvements of up to 20% in lift to drag ratio at high lift coefficients are theoretically possible on a three-lifting surface configuration by choosing the lift distribution among the surfaces to reduce total induced drag, while maintaining trimmed conditions at a specified static margin. In addition, since the effects of the downwash of the forward plane on the induced drag are not properly accounted for in the Prandtl-Munk approach, as already referred to above, then there is an additional induced thrust term which can lead to reductions of about 5% over the induced drag predicted by the theory.

Kendall^{113,114} showed that minimum induced drag can be achieved at any practical c.g. location on a modern three-surface aeroplane, such as the Piaggio P-180, if the forward and aft trimming surfaces have zero-gap, equal spans and when their opposite trim loads cancel each other. Consequently, in contrast with the limitations presented by the two-surface designs in sustaining minimum induced drag, there is no conflict between the requirements for minimum drag, longitudinal trim and positive static longitudinal stability, thus potential fuel savings relative to conventional and canard types may be expected in all cruise flight conditions. He concluded that the three-surface design can theoretically have a lower cruise trimmed drag than a conventional design which, in turn, is superior to the pure canard type. His results show reasonable agreement with the trends obtained by Butler for low to moderate lift coefficients.

Conventional, canard and three-surface high performance general aviation aircraft were investigated by Rokhsaz and Selberg¹¹⁵. A vortex lattice method was used to trim the aircraft and to compute its induced drag while a vortex panel code in combination with a momentum integral boundary layer method was employed to predict inviscid and viscous aerodynamic characteristics. Six and twelve seat configurations were considered. In each case, all aircraft were designed to the same specification with a stable static longitudinal margin of -0.38, assuming common fuselages, wings, vertical tails, engines and internal components. Canard and tailplane surface areas were assumed equal for the canard and conventional concepts, while for the three-surface configuration canard and tail areas were equal to one-half the size assumed in the former cases. Under trim conditions, Kendall's minimum induced drag criteria for the three-surface aircraft, i.e. same span canard and tailplane providing equal and opposite trim loads, was used to obtain the lifting surfaces design cruise incidences. For both payload cases, the conventional designs showed the highest lift to drag ratio followed closely by the three-surface and the canard aircraft. The aerodynamic differences found were not significantly large to support a clear selection on the best layout. However, the canard and three-surface aircraft, if carefully designed, could offer the prospect of a stall- and, hence spin-proof configuration. These authors demonstrated that the Prandtl-Munk theory underestimates the induced drag for the three-surface design which is the result of modifications on the assumed ideal elliptic wing spanwise load distribution due to aerodynamic coupling among the lifting surfaces (outboard shift of the wing's lift distribution due to the downwash directly behind, and upwash outboard of the canard).

Later on, aerodynamic trade-off studies on the six-place configurations were carried out¹¹⁶ where trimmed lift to drag ratios were analysed over a range of static margins, lifting surface area ratios and aspect ratios. Again, it was concluded that for lower stabilator aspect ratios the conventional aircraft provides the highest lift to drag ratio with the canard and the three-surface about equal where the conventional shows the least induced drag followed by the three-surface and then by the canard configuration. However, the differences are so small that configuration selection should be made in light of other considerations (stability and control, structures, safety, etc.).

A more recent investigation¹¹⁷, where induced drag predictions obtained from the Prandtl-Munk theory were compared against results produced by a vortex lattice method for non-elliptic (practical) loaded lifting surfaces of the six-place designs, confirmed the conclusions already drawn in the other two studies.

Kroo¹¹⁸ compared the relative performance of the three layouts (no fuselage considered) optimising the lift distribution of a system of multiple lifting surfaces at low speeds to any combinations of fixed total lift, trim with specified static margin and fixed structural weight. Profile drag and structural weight to resist bending moment are accounted for. His program models lifting surfaces using a discrete vortex Weissinger method with lift-dependent section profile drag. Induced drag estimates are based on Trefftz plane downwash. He concluded that conventional arrangements are generally more efficient than canard designs of identical weight and area. If the section maximum lift coefficient is constant spanwise, tail-aft configurations show greater maximum lift capability than canards of moderate aspect ratio. Relaxing static stability results in canard and conventional designs with similar performances. Three-surface layouts, assuming that the canard and tail have equal span and aspect ratio, achieve minimum drag when their spans are 20% of the wing span. This

minimum drag is slightly lower than for the canard and slightly higher than for conventional designs. However, the maximum lift coefficient is obtained for small canard and tail surfaces, thus providing an aerodynamic advantage with regard to the canard design and closely approaching the performance of a tail-aft aircraft. No obvious performance advantage over the conventional type was found for the three-surface concept.

To investigate how non-elliptical load distributions influence the lift, drag and static longitudinal stability of three-surface aircraft, Ostowari and Naik¹¹⁹ performed a series of wind-tunnel experiments using a typical business jet model. Comparisons were made with canard and conventional configurations. The effects of variations in canard size (although of fixed planform shape), canard and tail incidence angles, stagger and gap were assessed. The main wing and vertical tail remained the same, while the other components were allowed to move or change (fuselage length and canard size). Results showed that the three-surface has better lift and high lift drag characteristics than either the canard or tail-aft configurations, but the cruise drag is the highest. At cruise conditions, induced drag is highest for the canard and lowest for the conventional. A decrease in canard span on the three-surface offers better cruise performance and longitudinal stability characteristics, but has adverse effects on high lift drag. The conventional configuration has better cruise lift to drag ratio while the three-surface showed to be the least efficient. This order is reversed for high lift conditions.

At NASA Langley¹²⁰, wind-tunnel tests were also conducted on several advanced unconventional configurations including the types under review and revealed some important design considerations that influence their performance, efficiency and safety. These involved natural laminar flow retention, flow-field interactions among aircraft components, control surface and wing stall behaviour and power effects. Initial results pointed out the importance of recognizing the strong aerodynamic interactions originated from the unconventional placing of lifting and control surfaces as well as from the allocation of the propulsion system. Unconventional aircraft configurations may allow the designer to exploit more effectively the benefits from individual technology advances together with the potential advantages offered by particular arrangements of aircraft components.

In the sequence of the research outlined above and using the ADAS/ NLRAERO system, Middel^{69,70} investigated a family of derivative three-surface aircraft configurations, based on the Piaggio P-180 concept, evolving from a near-canard to a near-conventional design. The optimum sizing of lifting surfaces and wing location for minimum cruise trimmed drag was performed together with an assessment of the effect of cruise lift coefficient and c.g. travel on trim drag for a selected configuration. The analysis was limited to subcritical cruise conditions. Simplifying assumptions included were:

- the sum of canard and wing area were held constant ensuring that a given maximum lift coefficient could be attained (same stall speed) if the canard and wing maximum lift coefficient were the same;
- canard and tail volume coefficients referred to the aircraft c.g. were kept identical to ensure a given control pitching moment at low speeds (take-off rotation).

Cruise weight and c.g. location were computed using the semi-empirical methods of ref. 121 with fixed fuel and payload. A Lagrange optimisation technique is employed to optimise the lifting surfaces spanwise lift distribution for minimum drag, based on the Trefftz

plane formulation, on every configuration, subject to a given total lift ($L=W$) and trimmed conditions ($C_m=0$). So it is assumed that optimum circulation distributions are feasible through appropriate twist and camber of the lifting surfaces. The following conclusions were drawn:

- relaxing static stability requirements, the canard is favoured with regard to minimum cruise drag. The absolute minimum drag is achieved for unstable configurations only.
- the three-surface aircraft may be the best solution if a limited amount of static instability or low stability margin is allowed for.
- for an inherently stable design the conventional type may be the best option.
- for the case where the wing should be located aft of the passenger cabin for comfort, and a positive static margin is required, the three-surface should be considered.
- all stable designs show a tail download.
- changing the configuration from a near-conventional to a near-canard, while preserving the same static margin, increases drag in about 10%. By doing this, canard area increases, at the same time the main wing is moved rearwards with decreasing both wing and tail areas in order to satisfy the above design assumptions. For pitching moment equilibrium the canard lift contribution will increase and consequently its induced drag. Reducing the stability margin by 0.1 yields a drag decrease of about 4%.
- In most cases, the combined load of canard and tail have a positive contribution to the overall lift. This is in contrast with Kendall's^{113,114} and Rokhsaz and Selberg's¹¹⁵ assumption for minimum drag implying that this is achieved for equal and opposite canard and tail trimming loads (these authors, as referred to above, based their research on the assumption that the canard and horizontal tail would only contribute for pitching moment equilibrium). This condition strongly depends on aircraft layout arrangement and c.g. location. On the other hand it was shown that there is a value of the canard area for which the position of the main wing has little effect on the wing lift which suggests that the combined canard and tail lift is nearly constant being their lift differential used for trim.
- Apparently, the configurations having a smaller canard yield not only less drag at the design cruise condition, but also lower drag levels for different c.g.s and lift coefficient.
- Further, Middel concluded that "... one might select a three surface configuration over a conventional because of structural weight savings, despite the higher drag levels at the same weight." Also, "The application of three surface aircraft compared to the conventional aircraft is expected to find limited application unless static margin requirements are relieved. Depending on the level of instability, the three surface configurations might yield lower drag levels than a conventional aircraft."
- Finally, he added "The three surface aircraft principal advantage (minimizing trim drag over a centre of gravity and lift coefficient envelope), allows to yield lower drag levels, depending on the centre of gravity and lift coefficient envelope. It remains to be questioned however, if a conventional aircraft (having a lower drag level at the design centre of gravity and lift coefficient) is outperformed."

Trimming procedures were also investigated. Cruise drag was assessed for trimming with tailplane only, canard only, and both simultaneously. For the baseline (similar to P-180), it was concluded that trimming with the tailplane only is highly penalizing with regard to

drag. For extreme forward c.g. and high lift condition a large tail download may be required to obtain a given maximum lift, consequently an excessive angle of attack may lead to canard stall. For all conditions it was found that the best solution in terms of minimum cruise drag is achieved by trimming with the canard and tailplane in combination and that trimmed drag is nearly independent of c.g. location for which the largest feasible shift is possible.

The above conclusions were obtained by assuming constant lifting surfaces planform parameters such as aspect ratio, sweep, taper ratio, and dihedral. However, additional research was conducted on the effects of canard taper and aspect ratio variations. A change in canard taper ratio from 0.2 to 1.0 causes a 1% increase in drag while an increase in aspect ratio from 3 to 10 produces a 2% drag decrease. Providing the c.g. is kept fixed, static margin and the location of the neutral point are very sensitive to changes in canard aspect ratio. In fact, for the same variation in aspect ratio, a typical variation in static margin from 0.0 to 0.25 was found. This suggests that this parameter may be effectively used to fine tune the aircraft static stability margin.

2.2.2.3 Three-lifting Surface Project Designs

The benefits gained in terms of performance, passenger comfort and ride quality are also apparent from the selection of the three-surface concept in the design of commuter and general aviation aeroplanes. This was shown by Roskam in his design studies reported in references 122, 123 and 124. Although the conclusions address specific types of aircraft, they are believed to be of a more general application.

2.2.3 Assessment of the Previous Research

As described above, there has been a vigorous debate within the technical community concerning the suitability of these types of unconventional aircraft in outperforming current conventional designs in use. They range from simple theoretical analytical investigations of a pure aerodynamic nature, where the fuselage was usually neglected and where issues such as longitudinal stability and viscous drag were rarely incorporated, to more complete evaluations including considerations of longitudinal stability and controllability, longitudinal trim, profile drag, aircraft weight, centre of gravity location and shift, and main landing gear location. The first kind, by applying simple methods such as the classical Prandtl-Munk theory and, or their extensions such as those by Laitone, Kroo or Butler to account for the non-elliptical load distribution on the main wing, focused on the minimization of the overall induced drag by systematically studying different lifting surface arrangements with arbitrarily chosen lifting surface areas. Although backed-up by some aerodynamic wind-tunnel experimentations, whose results provided useful scope for assessing the range of validity of theoretical results as obtained from different aerodynamic analysis approaches, mostly for two lifting surface arrangements without fuselage, it was felt that very little empirical information on realistic unusual designs remained to ensure a rapid and reliable means for an unquestionable configuration selection. Thus, this was the reason for pursuing with the second more exhaustive kind of studies such as those by Selberg and Middel. They took into account far more considerations into play and used rather more sophisticated tools such as the aerodynamic vortex lattice and panel analysis methods to reduce the level of uncertainties, likely to occur when dealing with novel configurations from which no empirical data exists, and treated the design problem as a truly multidisciplinary task.

The trends found by Kendall, Rokhsaz and Selberg, and later on obtained from the experiments conducted by Ostowari and Naik, are somewhat misleading. They showed that comparisons between the three concepts is a far more complex problem, and that simplifying assumptions and procedures, usually accepted in the conceptual design of wing-aft tail configurations, are not completely satisfactory when applied on unconventional configurations if an accurate assessment of their relative merits is sought. Bearing in mind Middel's thorough assessment for sizing the lifting surfaces of the generalised designs, a more realistic basis for comparison was achieved. In fact, in his approach, Kendall's conditions for minimum induced drag were relaxed, and the lifting surfaces mutual aerodynamic interferences, together with fuselage effects, were taken into account. These aerodynamic interactions are likely to considerably change the lift distribution on the forward wing of pure canard and three-surface configurations. Considerations of weight and balance, and stability and control were also included by means of maintaining a given stall speed and the same take-off rotation control criterion in his family of designs. Fuselage aerodynamic interaction (fuselage-canard and fuselage-main wing interferences) was determined by Middel of being of the same order as the canard-main wing interference. Its importance on the aircraft overall aerodynamics increases as the canard span tends to be smaller relative to the fuselage diameter. These influences are due not only to the local downwash/upwash effects on the main wing flow field, but also by a greater departure from the assumed elliptical shape of the canard lift distribution for smaller canard span to fuselage diameter ratios. Of course, for smaller wing span to fuselage diameter ratios, the overall aerodynamic efficiency will degrade further.

All these mutual aerodynamic couplings and influences considerably impacts the actual overall lift distribution to maintain pitching moment and weight equilibrium when compared to that of a system of uncoupled lifting surfaces. This also makes current initial profile and induced drag predictions less reliable for unconventional designs, in the absence of appropriate experimental data. Consequently, these aerodynamic effects on the overall lift distribution may change considerably the longitudinal stability behaviour of the complete configuration, as predicted (for example, it is not as simplistic as just adding the isolated fuselage pitching moment derivative with regard to lift to assess the aircraft longitudinal static stability), which brings difficulties in the determination of the neutral point, producing uncertainties on the actual stability margin. An effect of these mutual aerodynamic interferences is the high sensitivity experienced by the static margin to changes in canard aspect ratio, as found by Middel.

On the other hand, as shown in ref. 120 and exemplified in the Piaggio P-180, there are benefits arising from the wise adoption of particular design solutions which may be integrated, synergetically enhancing the overall aerodynamic and structural efficiencies for improved performance and operating costs, while ensuring good flying qualities, operational flexibility and safety.

Hence, to adequately assess and achieve a fair comparison among these different concepts, realistic preliminary design studies should be performed to a given specification under the rules of an airworthiness certification body, adopting an identical technology level and optimised to a given performance index. Uncertainties due to the present lack of appropriate empirical data should be reduced through suitable wind tunnel tests to be conducted on models of the canard and three-surface initial concepts in order to correctly

account for practical effects. It is the author's belief that more conclusive results would be obtained in this way even at a conceptual design detail level. This is consistent with Roskam's⁹⁶ red, white and blue team approach as the "only way to find out which configuration 'best' meets a given set of design requirements." Following this methodology, Arbuckle and Sliwa⁵⁸ conducted optimal conceptual designs of both canard and conventional configurations of a statically stable subsonic medium-range transport. Each configuration was evaluated and optimised on the basis of an economic index of interest to airlines. For the type of aircraft in consideration, his research identified two critical problems for canard configurations, the fore-plane high-lift requirement for trim and the main landing gear longitudinal location. Results suggested that conventional configurations are economically superior to canard configurations for this class of aeroplane, and that a possible alternative could be a three-lifting surface configuration. This solution would allow to solve those design problems while preserving the specific benefits inherent to both configurations.

2.2.4 The Present Research Project

The present investigation adopts this same comprehensive and integrated approach, excluding the experimental tests as proposed above, in evaluating three-surface and conventional jet-transport aircraft designed to the same mission and optimised for minimum Direct Operating Costs (DOC) and minimum Maximum Take-off Weight (MTOW). Although not using the sophisticated aerodynamic tools as utilized by Middel in his studies, a design synthesis program was set up and coupled to a gradient based numerical minimization routine where the typical disciplines of aerodynamics, weights and balance, propulsion, performance and static stability and control as well as economics, at a level adequate to preliminary design work, were taken into account. Three-surface concept design assumptions include balancing the aircraft weight by canard and wing lift, trim and pitch control obtained by simultaneous use of canard and tailplane assuming that both surfaces ensure equal trim/control pitching moment. Inherent longitudinal static stability margin of -0.1 is assumed on every design where the engines are sized for take-off, climb and cruise conditions. The fuselage is fixed by the seat arrangement while the lifting surface areas and planform geometric parameters are allowed to change until the minimum value of the figure of merit is achieved. This is in contrast with the fixed lifting surface planform shapes adopted on other studies. Details of the design synthesis tool and the research methodology pursued are described in Chapters 3 and 5.

Figure 2.4 shows a panelled view of Roskam's¹²⁴ promising Advanced Personal Transport and figs. 2.5 and 2.6, reproduced from references 125 and 126, illustrate other visionary future transport designs. All these examples reflect the existing live interest and expectations raised by the potentialities of the concept of the three-lifting surface configuration when applied to transport aircraft.

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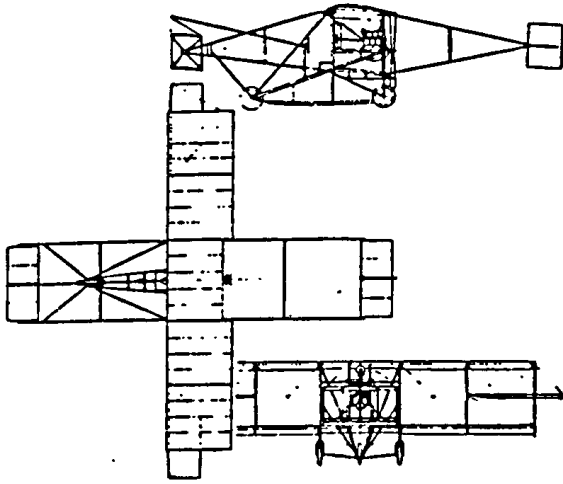


Fig 2.1 - Curtiss Herring No.1 Reims Racer
(from Ref. 96)

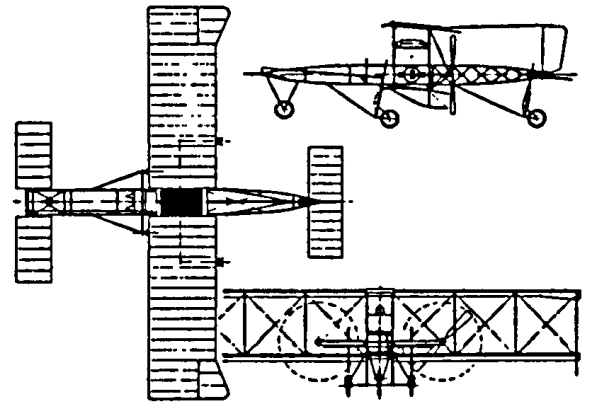


Fig 2.2 - De Havilland Biplane No.2
(from ref. 96)

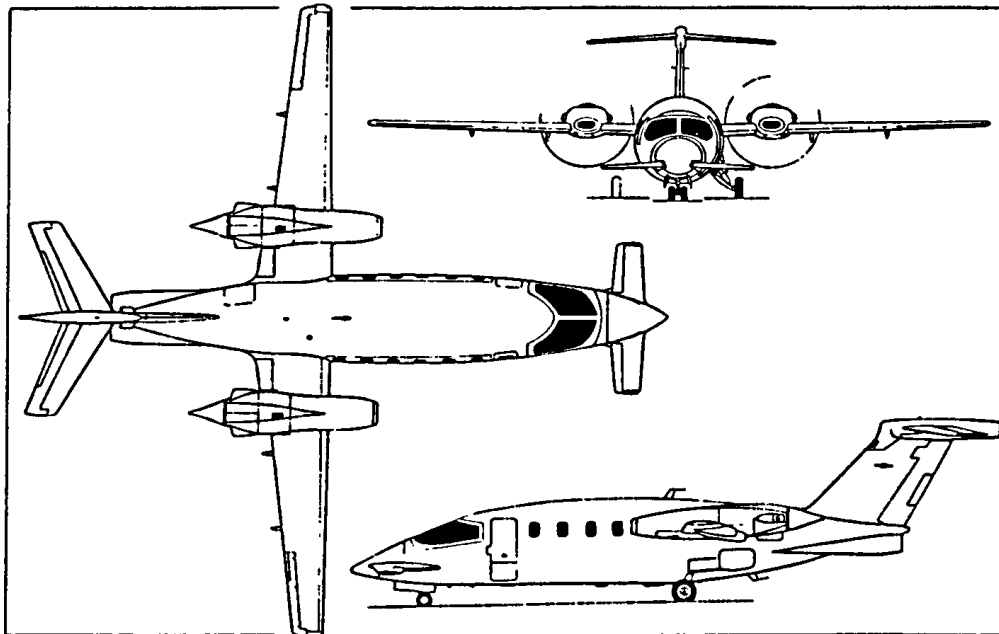


Fig 2.3 - Piaggio P-180 Avanti business transport (from ref. 97)

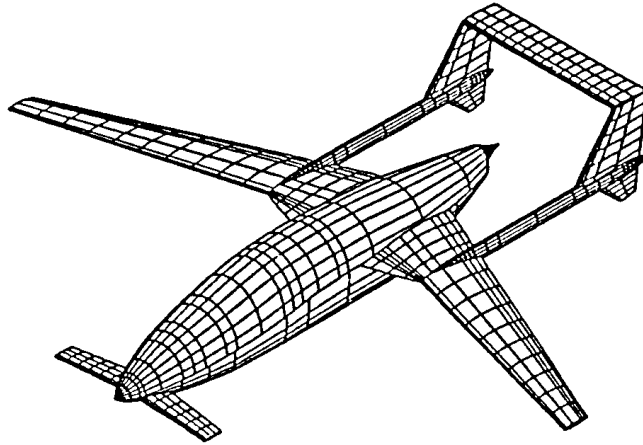
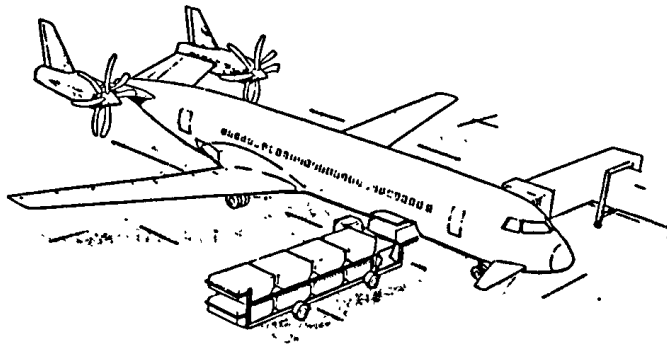


Fig 2.4 - Roskam's Advanced Personal Transport (from ref 124)



THE FUTURE ?

Fig 2.5 - Saab visionary efficient shorthaul aircraft (from ref 125)

3 Design Criteria, Methodology and Special Design Tools

3.1 Design System Philosophy, Concept and Evolution

The objective of the conceptual design phase is to arrive at the most efficient configuration for a given mission specification, while satisfying structural, performance and environmental requirements. This involves the simultaneous study of several potential configurations which must be considered iteratively through extensive analysis and comparison on the grounds of global characteristics, usability and work-off studies. The most promising concept is then identified and eventually refined during the preliminary and detailed design phases which may follow.

It is recognized that the experience and judgement of the designer plays an essential role in the decision-making process. The designer must retain the flexibility and responsibility to make changes in the design as the project evolves and requirements change.

A further specific feature is the use of a modular design approach. In the early years of the design process, the aircraft is divided into several functional modules. This provides space for the designer to explore different configurations and to make changes as required. The modules are then integrated into a complete aircraft configuration through synthesis in the preliminary design phase.

It is also recognized that the design of the aircraft must be integrated with the propulsion system. The engine and its associated systems are considered as part of the aircraft design.

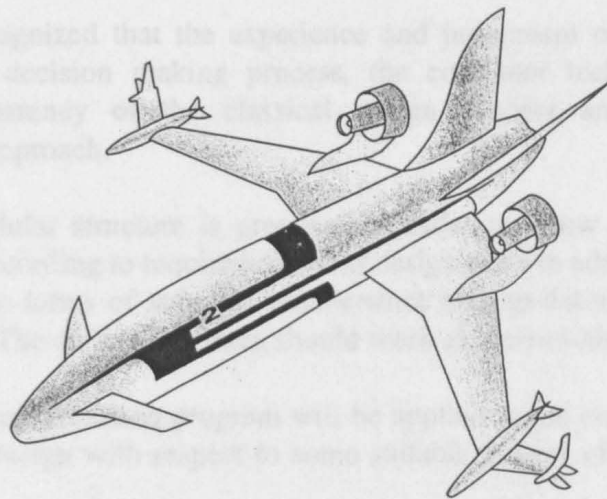


Fig 2.6 - Airbus Industrie's E2 advanced concept, a 220-260 seat, medium/long range transport (from ref 126)

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3 Design Criteria, Methodology and Conceptual Design Tools

3.1 Design System Philosophy, Concept and Structure

The objective of the conceptual design phase is the search for the most efficient configuration for a given mission specification while satisfying operational, performance and airworthiness requirements. This implies the comprehensive study of several potential configurations which must be consolidated iteratively through successive analysis and compared on the grounds of global characteristics, sensitivity and trade-off studies. The most promising concept is then identified and eventually refined during the preliminary and detailed design phases which may follow.

Since it is recognized that the experience and judgement of the designer plays an essential role in the decision making process, the computer technique must retain the flexibility and transparency of the classical design process and therefore reflect an engineering-oriented approach.

A flexible modular structure is proposed in order to allow for easy control of the computing sequence according to required different design tasks in addition to providing space for future extensions in terms of software maintenance and up-dating, range of applications and other capabilities. The design synthesis should work as a stand-alone program if required.

A constrained minimisation program will be applied to the configuration synthesis in order to optimise the design with respect to some suitable figures of merit.

A general flow chart adopted for the synthesis integrated optimisation system is illustrated in Figure 3.1. As shown, the system will include four main modules:

- the Parametric Analysis module
- the Configuration Concept Design module
- the Engineering/ Economic Evaluation module
- the Optimiser

The Parametric Analysis module relies heavily on statistical methods allowing for a first estimate of aircraft take-off, empty and fuel weights. In addition a design space in terms of the thrust loading versus wing loading plot, where all the mission, performance and airworthiness requirements are met is suggested, providing a consistent and realistic set of input data to the subsequent configuration synthesis/ analysis iterations. Take-off gross weight sensitivity studies with respect to mission, aerodynamic and propulsion parameters are also performed and some indication of the technology levels involved is obtained together with some feeling on the critical parameters which drive the design. A prototype of the module was developed following the preliminary sizing method presented by Roskam in his "Airplane Design" volume, Part I¹, and was shown to be working properly. This module will only need as input a mission specification together with assumptions on some empirical and technology related parameters to produce a preliminary sizing of the required wing and engine(s), in terms of wing area and maximum static thrust, providing the assumptions are sound and

attainable.

The Configuration Design module and the Engineering/ Economic Analysis modules can be fairly well represented by the flow chart shown by Howe in his lecture note DES 8108^{2,3}, and reproduced here as Figure 3.2, the Structure and Aeroelastic modules being excluded in this approach.

The Configuration Design module to define the aircraft geometry and component allocation was devised and initial development undertaken, following mainly Roskam's methodology as shown in "Airplane Design", Part II ¹.

The Engineering/ Economic Analysis module was originally intended to include the programs identified in section 3.2.

The program RQPMIN, Recursive Quadratic Programming Minimisation⁴, developed by the Royal Aerospace Establishment to solve the nonlinear constrained minimization problem will constitute the optimisation driver.

3.2 Available Disciplinary Analysis Programs

Some analysis programs suitable for initial aircraft design work have been developed, used and up-dated by past M.Sc. and Ph.D. students, in the College of Aeronautics (CoA), and have been shown to produce results within acceptable levels of accuracy for the purpose concerned. Hence, in order not to re-invent or duplicate work, it was initially intended to adapt and integrate these programs into the system under study. These programs were:

- MASS-ESTimation, developed by Sarrazin⁵ in 1987;
- DELTADD, initially developed by Frosst⁶ in 1981 and Sarrazin⁵ and subsequently rewritten and improved by Hartland⁷ and Howe;
- FLTANAL, developed by Pasaribu⁸ in 1991;
- ACCOST, developed by Pasaribu⁸ in 1991;
- MITCHELL, developed by Mitchell⁹ and modified for the CoA by Theophilou¹⁰ in 1983.

MASS-ESTimation is a component mass breakdown prediction method based on empirical formulae obtained mainly from CoA lecture notes DES 8515 and 8336².

DELTADD is based on the Delta method, an empirical drag build-up estimation technique developed by Lockheed in 1978¹¹, which is able to predict the total configuration drag polar within a CL range of 0.0 to 0.6 or buffet onset and a speed range of $0.2 < M < 2.0$. This program deals with high lift devices which is an improvement on the original method of ref 11.

FLTANAL is a program written to perform flight mission analysis of subsonic transport aircraft. It calculates fuel weight, time and range covered during the climb, cruise and descent legs of the flight profile as well as the reserve fuel.

ACCOST is another program written for the estimation of subsonic transport aircraft and engine costs and is based on methods presented by Nicolai¹², Roskam¹ and Maddalon¹³.

The core of both FLTANAL and ACCOST programs was obtained from the OPDOT program developed by Sliwa and Arbuckle¹⁴ in 1980.

MITCHELL is a program to predict the stability and control characteristics of subsonic aircraft⁹, developed at the Royal Aircraft Establishment in 1973. The primary sources of data used in this program were the ESDU data sheets.

3.3 Initial Work

A careful evaluation of the disciplinary analysis tools just mentioned above revealed that considerable software development work would be required in order to adapt, streamline and integrate them into an adequate synthesis program to perform realistic preliminary designs of conventional and unconventional three-surface transports as described in 3.1.

For the purpose, a modified version of the MASS-ESTimation program named MASS program was developed in fortran to replace the existing one in basic in order to make possible easy integration with the remaining routines, all of them written in fortran. MASS program differs from the original one mainly in that it computes the fuel weight needed during the range, hold and diversion legs of the mission profile by using the appropriate Breguet equations while assuming user guessed fuel weight fractions for the remaining mission legs. MASS-EST, as it stands, requires user input proportions for fuel burned up to the start of cruise and during the cruising phase. Although this former program was written for a wide scope of aircraft types, MASS is restricted to initial component mass predictions of subsonic narrow body jet transport aircraft. Future extensions to accommodate new types were made easy by the adoption of a highly modular and structured programming style.

MITCHELL program has benefited from an extensive revision driven by the high frequency that running problems were encountered where many of the results, if any, were doubtful, consequently precluding its intended use within the design synthesis program. These problems were mostly associated with the several syntax errors encoded which have been cleared out improving its acceptability and portability. It is worth mentioning that now the program can run on an IBM PC or other compatible platform. Some minor corrections were made to the logic, for example to the calculation of one of the longitudinal stability derivatives, i.e., the non-dimensional force derivative due to velocity increment along OZ^9 , Z_w , as well as to the all-moving tail model algorithm used for the computation of the low speed handling characteristics.

It should be noted that the tools referred to in 3.2 are not design but disciplinary analysis programs whose purpose concerns the estimation of the mass, aerodynamic, flight performance, stability and control characteristics of possible conventional configurations as well as their associated costs, assuming a given engine cycle. They should be adequately interrelated through a Configuration Design module able to systematically change design variables until a solution consistent with the requirements is met. To this end a Configuration module was partially developed as stated before which would potentially lead to a preliminary

component sizing and allocation, where considerations of weight and balance, stability and control, field performance and required cruise altitude and range within the FAR Part 25 requirements were taken into account.

The fuselage sizing is relatively straightforward for a given passenger seating and baggage arrangement with allowances for the flight deck, doors, emergency exits, toilets, galleys and cabin crew seats providing no transonic or supersonic area rule is used and it is kept fixed throughout the iterations. Only the lifting surfaces geometries and respective locations are allowed to change while the several design criteria are satisfied along the synthesis process. It may happen that the wing no longer accommodates the mission fuel between the main spars for very long ranges in which case an increment to the wing area is input and the overall process restarted.

By initially locating the centre of gravity corresponding to the operating empty mass at 25% of the wing mean aerodynamic chord (usually at 25-30% MAC¹⁵), a mass balance routine was devised for the estimation of the most critical fore and aft centre of gravity locations based on two extreme loading conditions with all seats, baggage bins and fuel tanks filled respectively forward and aft that point. The design load condition is estimated as well, assuming the maximum take-off mass .

In face of the elaboration implied in the methods used by the existing modules, it was thought convenient and thus more credible, to incorporate the physics of take-off and landing in special purpose analysis subroutines for the field performance evaluation instead of the more simple empirical correlations suggested by Loftin¹⁶, and already included in the initial Parametric Analysis module.

An initial estimate of the tail sizing was implemented using typical tail volume coefficients taken from actual similar mission aircraft. Subsequent refinement would be achieved by iterating among the mass, balance and stability and control modules in order to satisfy required longitudinal and directional static stability and control criteria consistent with the allowable centre of gravity travel. After the flight performance analysis has been done, including all the mission phases from starting up the engine(s) to shut down, further checks on the maximum take off mass is required by repeating the overall process again and again until convergence, and showing then a consistent set of relevant data which describes the configuration. At this stage a first assessment of the aircraft costs including the Research, Development, Testing and Evaluation (RDT&E) and Operating Costs is possible using ACCOST.

It is well known that significant gains¹⁷ can be achieved by designing aircraft for reduced inherent longitudinal stability or even with some degree of instability which are artificially made stable by the introduction of an appropriate highly reliable and redundant feedback Stability Augmentation System (SAS) which will confer the required de-facto stability and handling qualities. This concept allows for significant reduction of the tail size and surface wetted areas thus directly reducing its associated structural mass, skin friction drag, and consequent fuel mass. The lower stability margin will entail a reduction of the trim drag which is most significant at low speeds with flaps deployed, due to the reduction in the required trim downward tail load, providing higher values for the CL_{max}, and hence improving the take-off and landing performance. So, more payload can be carried for the

same aircraft or performance enhanced by fuel reduction or range increase, driving the operating costs to lower levels. The use of a SAS will incur a corresponding single significant initial cost. When considering big capacity aircraft this is not important compared with their initial price and ready economical advantages associated with its implementation, but the same is not so clear for small ones where its market competitiveness may be seriously impaired. Following this reasoning the study will focus on inherently stable commercial aircraft to carry 50 passengers which may correspond to an initial cost of no more than US\$20 million. Providing that benefits can be obtained from a similar mission three-surface configuration, this concept could be further explored for this class of aircraft assuming that for a given level of technology the improvement through the introduction of a SAS on conventional configurations is not economically feasible. Of course similar study conclusions could be obtained from the two different configuration aircraft both equipped with a SAS in order to preserve the same basis for comparison.

Using the Parametric Analysis module a preliminary sizing of a subsonic turbo-fan airliner to carry 50 passengers over a range of 1250 NM was performed and has shown that a powerplant consisting of two engines, each one rated to a minimum of about 8000 Lb maximum installed static thrust, would be enough, as described in 5.2 and Appendix C. This level of propulsion power would need to be implemented in the FLTANAL routine since it is not representative of the engines already modelled in the program.

Once the Configuration Design module, the mass balance, the field performance evaluation routines and the propulsion model had been concluded and incorporated into the synthesis procedure, the complete design system would be tested, fine tuned if necessary, and validated against a known similar aircraft, and full integration with the numerical optimisation technique obtained. At this stage it would only allow for the conceptual design and optimisation of conventional tail-aft jet transports and a complete review and modification would be required to include the design criteria, implications and contributions of the additional fore lifting surface, typical of the new concept in consideration, in order to properly account for its multidisciplinary effects on the design.

The integration and adaptation of these separate programs clearly represented a major task.

3.4 Switching to GASP

3.4.1 Introduction

During the time of developing this study the author was fortunate in getting involved on an Unmanned Aerial Vehicle System Research & Development work¹⁸, under an University/ Industry joint project initiated in Portugal, aimed to fulfil the need for a cost-effective system for civil observation and reconnaissance missions. The initial vehicle concept design study leading to the first of a series of configurations studied was performed by the author together with Brederode, his former teacher and Professor of Aerodynamics at the Instituto Superior Tecnico (IST), Lisbon University. To facilitate the initial study, some software tools were acquired including the NASA "General Aviation Synthesis Program" (GASP)¹⁹.

This program developed on a CDC computer was not easily portable to other computer systems requiring conversion to run on the Hewlett Packard 9000, Series 730 workstations in use at the IST. Also several most difficult modifications and validations were needed to properly model and synthesise the type of aerial vehicle envisioned. This requirement represented a very time-consuming task even for an experienced engineer with adequate background and expert knowledge and thus it was not of much practical use, at least for the initial months of the project. Nevertheless the program represented a very powerful and comprehensive tool for the purposes of the present research investigation and a change to it was justifiable under the circumstances explained in section 3.3.

The origins of GASP date back to 1973^{20,21}, and it was developed for several years by engineers at NASA Ames Research Center to conduct aircraft preliminary designs and rapid parametric studies. The program has been used by several Companies and Universities and is under continuing development.

The program comprises several disciplinary modules conveniently interrelated into a computational flow and integrated in a way to produce consistent results of novel designs that are as accurate as the methods implemented, the assumptions made and the input data used. It includes several design options for the synthesis of a wide variety of aircraft types ranging from small single piston or rotary engine propelled general aviation up to twin turboprop/turbofan powered corporate or transport type aircraft.

GASP is a useful tool for comparing configurations, assessing aircraft performance and economics, performing trade-off and sensitivity studies, and assessing the impact of advanced technologies on aircraft performance and economics. The original program may be operated either in batch or interactive graphics mode although the version in use only runs in batch mode.

3.4.2 Program Structure

The synthesis program consists of a control module and distinct technology modules representing the six pertinent technical disciplines as represented in figure 3.4. Each of the technology modules is composed of one or more separate computer subroutines and the input data to each module may be either the user input or the output from another module. The integration ensures that the results comprise the effects of the multidisciplinary interrelations maintaining data consistency and method compatibility, and leading to significant reductions in both effort and task flow time with configuration results more free from errors since these are restricted to the input data, provided the methods are satisfactory and reliable.

A brief description of the engineering methods used is now given:

Geometry

The module computes the dimensions of the aircraft components. Typical input consists of the number of passengers to be carried, cabin layout, wing and tail surfaces aspect ratio, taper ratio, sweep, aerofoils thickness ratios, fuselage nose and tail fineness ratios and vertical locations of wing and horizontal tail. The cabin is assumed to be of circular cross section and tail surfaces are initially sized using historical trend equations. Geometric data

such as component areas, lengths, angles, etc are obtained and eventually used by other modules.

Aerodynamics

The module computes lift, drag coefficients and lift curve slope. Lift coefficient is obtained as the sum of a term proportional to angle of attack and an increment due to high lift devices. Lift curve slope is a function of aspect ratio, Mach number and sweep, including ground effect. Drag coefficient is determined as the sum of profile drag, increments due to the high lift devices, landing gear and compressibility whenever applicable and the vortex drag, including ground effect. The input consists of the aircraft geometry, flight conditions and related configuration providing, in addition to the above data, the drag polars for cruise, take-off and landing conditions.

Propulsion

As already stated, a large variety of powerplants can be simulated from reciprocating/ rotary engines up to turboprop/ fan engines. The module determines the engine size and performance to satisfy both cruise and take-off requirements. From the specific engine performance data, thrust and fuel flow is computed for any flight condition.

Weight and Balance

Inputs to this module consist of a first estimate of the maximum take-off weight and payload, with details of aircraft geometry and empirical weight trend coefficients. Statistical equations for component weight prediction developed in ref. 22 are used and the wing is located so that the aircraft is in balance for the centre of gravity travel and for a desired value of the static margin. An option to resize the horizontal tail is provided. Although ref. 22 concerns in particular V/STOL type aircraft, the correlations imported to GASP are based on statistical regression analysis performed on data from several types of existing aircraft. The adequacy of their application is controlled by the user by assigning appropriate values to the weight trend coefficients to adapt the basic equations to a particular application.

Mission Performance

Mission segment legs such as taxi, take-off, climb, cruise, descent and landing are analysed and total fuel, including reserves, and range determined. The module provides options for the calculation of engine out, accelerate/ stop distance, best rate of climb, high speed climb and other characteristics. For a required range the aircraft size is approached within a specified range tolerance.

Economics

This module computes flyaway and operating costs. Flyaway cost is obtained by summing estimates of labor, material and purchased equipment costs including overhead, tooling, sales and profit both for the manufacturer and the dealer. Operating costs include fuel, oil, inspection and maintenance, insurance, depreciation, crew costs, taxes, and the direct and indirect operating costs are combined to give the total operating cost as a function of the

annual utilization rate.

Figure 3.5 represents the GASP program design procedure.

In view of the changes adopted, the synthesis integrated optimisation system as constructed has evolved as shown on figure 3.3, being the Parametric Analysis module excluded from the optimisation cycle, for simplicity, and the Configuration Design and the Engineering/ Economic Evaluation modules replaced by the GASP program.

3.5 Extensions to the Three-Lifting Surface Configuration

This section describes the modifications implemented in the GASP source code in order to properly simulate the contributions of a canard surface upon the overall vehicle design. As long as the changes are introduced the methods and methodologies incorporated in the original program are reviewed together with descriptions of a few additions included for the sake of completion. For any details not shown in the present text, the reader is referred to ref. 19.

GASP is composed of 65 computer subroutines from which the subset used in this study employs 55 plus a new utility one created by the author and called 'Cramer'. These subroutines are grouped by specialities and are listed in figure 3.6. Figure 3.7 shows an updated listing of the subroutines which may be called by the indicated subroutine.

3.5.1 Design Procedure followed by GASP program

Input data includes the general concept of the aircraft being designed in terms of payload, performance criteria, mission profile, geometric characteristics, technology factors relating to structures and materials, propulsion and aerodynamic concepts together with a first guess of the maximum take-off weight and wing loading and several options controlling the sizing criteria.

The computation as represented in figure 3.5 starts with the calculation of the aircraft geometric parameters needed by the aerodynamics, propulsion, weight and performance modules. An initial evaluation of the flap aerodynamic performance is done. The performance module is used to compute the engine size and the required wing loading to satisfy the specified cruise conditions and the landing and take-off field performance including the airworthiness requirements for take-off, climb and balked landing (the present study considers a vehicle under FAR Part 25 requirements).

Weight and balance computations follow together with the empennage sizing for a required longitudinal static margin and satisfying desired stability and control criteria. At this stage a first configuration is obtained where the main component sizes/ weights and respective allocations are completely defined. The configuration is then subject to a full performance analysis from the taxi up to the descent phase until reaching an altitude of 1500 ft over the destination airport. Take-off engine out and accelerate-stop distance conditions are simulated and the cruise conditions at the specified speed, normal power and best specific range cases are considered. Both take-off and landing field performance are recomputed and mission fuel

weight and block time obtained.

A check on range is done and the overall calculation repeated until the maximum tolerance of 1% on the desired value is satisfied. Once this convergence is reached cost computations are performed and a full printout of every important design parameters and results produced.

3.5.2 Changes introduced in GASP code

3.5.2.1 General

The version of the program received, while very complete in its formulation, didn't account in its computations for the influence of the wing pitching moment coefficient. Furthermore the tail sizing criteria using stability and control considerations assumed only the controls free and no option for controls locked was implemented. The present study focuses on an airliner where hydraulic boosted flight controls are anticipated so the latter capability would be useful. Also some influences such as those due to the engine jet efflux inclination on stability and the pitching moment required to rotate the aircraft at lift-off were not accounted for in the stability and control equations. All the above limitations were overcome by implementing the related capabilities in the program as described later. In addition a switch enabling the new developed part of the program was included in the input file to allow for the synthesis of unconventional three-lifting surface configurations.

The general GASP design procedure as implemented and shown in section 3.5.1 is kept unchanged. The consideration of another lifting surface complicates the problem and simplifications were allowed in order to reduce both computational effort and costs during the optimisation runs. The main simplification concerns the design criteria adopted which limits the range of configurations to be studied.

While studying conventional subsonic transport aeroplanes, Laitone²³ concluded that if the tail is out of the wing plane (above or below), then a zero tail load would produce minimum induced drag. However this condition can be achieved at only one aft c.g. location for an inherently longitudinal stable aircraft. This c.g. location should be behind the wing-body aerodynamic centre as to create a couple to balance the nose down zero-lift moment, thus leaving the tail unloaded. A good design should allow for this condition during cruise, for time periods as long as possible, by minimizing the c.g. shift produced by the fuel consumption. For the three-lifting surface concept, it is assumed that the above condition is attained in cruise and the tail is unloaded, i.e., both canard and wing balance the aircraft weight. So, by extrapolating Laitone's conclusion on minimum induced drag in conventional configurations for this case, it implies that for the same overall lift the lifting surface sizes will be minimized. It is usually difficult during the flight to maintain this ideal c.g. location for minimum induced drag. Unless the fuel c.g. is always lying on the aircraft zero-fuel c.g., and other influences such as crew or passenger movement are eliminated, it is unlikely c.g. excursions are avoided during flight. So, trimming and control surfaces are required. One can intuitively suggest that cruise longitudinal trim drag could be minimized when trim conditions, other than the ideal one for conventional configurations, are kept by employing two small trimming surfaces, one of them being a fore-plane, instead of only one large rear horizontal tail, for the same desired minimum static margin. From the above a design criteria

for the canard/ tail sizing is devised that assumes both surfaces will provide equal trim/control pitching moments and thus both will contribute to the aircraft longitudinal trim and control. They will perform differentially to achieve the required trim and control pitching moments. Thus it is assumed that the tail will contribute to the trim condition in cruise but will not influence the additional lift required to balance weight. Because of this, it is also assumed that the horizontal tail induced drag is negligible, hence it will not be evaluated in GASP computations. This also applies to the conventional designs. Another simplification is that the canard and wing have the same lift coefficient in cruise, thus assuming identical aerodynamic loadings, i. e., the overall aircraft lift will be proportionally distributed by both surface planform areas. All these assumptions are considered reasonable as a first order approximation as far as the initial design is concerned and should be verified at later stages of the design. As stated above the design approach will reduce the range of the three-lifting surface configurations to those with canard/ wing area ratios, say between 0.145 and 0.175. Pure canard configurations can not be evaluated. So, in addition to complementing the wing for providing lift, the canard will be constrained to ensure that it provides only half the required minimum control power. This may reflect the interdisciplinary complexity of the design procedure implemented since all the lifting surfaces are sized at the same time to satisfy stability and control requirements and also to meet the mission, certification and performance constraints.

3.5.2.2 Specific Changes

3.5.2.2.1 Geometry

As briefly described in section 3.4 and figures 3.6 and 3.7, this module computes the initial main aircraft component sizes, determines their initial allocations and other geometric data needed by the other disciplinary modules. It consists of one subroutine called "SIZE".

The fuselage sizing procedure is unchanged which means that both conventional and unconventional designs will show the same basic fuselage for the same accommodation arrangement, the difference being set by the sizing of an additional foreplane and its allocation relative to the overall configuration layout. From a given canard to wing area ratio and for a specified canard location, "SIZE" will only split the statistical conventional tailplane volume coefficient in two, one for the horizontal tail and one for the canard. Assuming that in level unaccelerated flight conditions the lift contributions from both the canard and wing are proportional to the respective areas, i.e., both the aerodynamic loadings remain the same while the tail is kept unloaded (except for trim purposes), it is possible to perform an initial sizing of the three-lifting surfaces. "SIZE" does not locate the wing for weight balance and stability. This is done later on by the subroutines "WEIGHT" and "TAIL", it only sketches the configuration for further refinement.

Figure 3.8 shows the canard/ wing location geometry. Equations used are detailed in Appendix B.

3.5.2.2.2 Aerodynamics

The aerodynamic model implemented in GASP was modified to include the contributions from the canard surface. The respective module is made up of the eight

subroutines listed in figures 3.6 and 3.7, each one performing a specific function as follows:

CTAER	- determines required lift and drag coefficients in cruise flight,
AERO	- computes the equivalent flat plate areas, wetted areas and the parasite drag for the basic aircraft in the cruise configuration,
DRAG	- computes induced drag coefficient, in ground effect whenever applicable, compressibility drag coefficient and the total aircraft drag coefficient with or without flaps and landing gear deployed,
AEROUT	- produces the drag polars both for low and high speed conditions,
CLIFT	- determines the wing alone lift coefficient or angle of attack,
FLAPS	- estimates aircraft maximum lift coefficient, lift and drag increments for several flap types and settings and flap weights,
EODRAG	- evaluates the drag increment due to engine failure,
APPFLP	- estimates approach flap deflection.

Significant changes were only introduced in the drag related computations involving subroutines AERO and DRAG. Minor changes relating to the switch of the reference area, originally the gross wing area, to that defined as the sum of the canard and the wing gross areas, used for the new concept, were included in subroutines CTAER and FLAPS.

A brief description of the aerodynamic drag model is given in order to illustrate the approach used in simulating the canard drag contribution. This follows the procedure of GASP.

In the 'clean' configuration, the aircraft aerodynamic drag coefficient may be represented by the sum of parasite drag, lift induced drag and compressibility drag coefficients:

$$C_D = C_{D_p} + C_{D_i} + C_{D_c}$$

or

$$C_D = \sum_i C_{D_{p_i}} + C_{D_{p_w}} + C_{D_{p_c}} + C_{D_{i_w}} + C_{D_{i_c}} + C_{D_{c_w}}$$

It will be assumed that the air flow at the canard and wing is not incurring any energy losses due to interference with the fuselage boundary layers or canard wake, in this way showing the same dynamic pressure as that of the undisturbed free stream air. So the related efficiencies are taken as unity. Another simplification concerns the compressibility drag which is assumed as originated only by the wing being the component with the lower drag divergence Mach number.

Detailing the several contributions, drag may be expressed as:

Generalized component parasite drag coefficient, $C_{D_{pi}}$

$$C_{D_{pi}} = \frac{K_i C_{f_i} S_i}{S_{ref}} = \frac{K_i C_{f_i} S_i}{S_w} \frac{1}{(1 + S_c/S_w)}$$

with $C_{f_i} = C_{f_{Re=10^7}} F_{Re_i}$

where K_i is the i th component aerodynamic form factor,

$C_{f_{Re=10^7}}$ is the Mach number dependent flat plate skin friction coefficient evaluated at a reference Reynolds number of 10^7 and obtained as shown next:

$C_{f_{Re=10^7}}$	M
0.002944 - 0.0001760 M	$M < 0.4$
0.002990 - 0.0003125 M	$0.4 \leq M \leq 0.92$
0.002700	$M > 0.92$

$F_{Re_i} = \left(\frac{\log Re_i}{7}\right)^{-2.6}$ is the Reynolds number correction term for the i th component

derived from the Prandtl-Schlichting turbulent flat plate skin friction equation. For the purposes of Reynolds number computation, the characteristic length is the body length for fuselages and nacelles and the mean aerodynamic chord for wings and other surfaces,

S_i is the i th component area (fuselage, nacelle, and lifting surfaces wetted areas),

$S_{ref} = S_c + S_w = S_w \left(1 + \frac{S_c}{S_w}\right)$ is the reference area.

Wing and Canard parasite drag coefficient, $C_{D_{pw}}$ and $C_{D_{pc}}$

The wing and canard parasite drag contributions are computed in a similar way but are factored by a correction term C_{D_r} to reflect its dependency on the lift coefficient. C_{D_r} represents the ratio of the actual clean wing/ canard profile drag at some lift coefficient to the profile drag of the wing/ canard at the angle of attack for minimum profile drag. Typical values are represented in figure III.1.2 of ref. 19. As stated above, the tailplane will contribute to trim by producing some lift. However, during cruise flight, it may be small. Thus, its induced drag is assumed negligible and tail lift dependent drag contributions will not be predicted in GASP evaluations, for simplicity.

The wing parasite drag coefficient may be written as:

$$C_{D_{pw}} = \frac{K_w C_{f_w} S_w C_{D_r}}{S_{ref}} = K_w C_{f_w} C_{D_r} \frac{1}{(1+S_c/S_w)}$$

and the canard parasite drag coefficient:

$$C_{D_{pc}} = \frac{K_c C_{f_c} S_c C_{D_r}}{S_{ref}} = K_c C_{f_c} C_{D_r} \frac{S_c}{S_w (1+S_c/S_w)}$$

Since the same aerofoil is chosen both for the canard and wing and that lift coefficient on both surfaces is assumed to be the same for a given flight condition, C_{D_r} will take the same value depending only on the actual lift coefficient.

Induced drag coefficients, $C_{D_{iw}}$ and $C_{D_{ic}}$

Wing induced drag coefficient may be written as:

$$C_{D_{iw}} = \frac{C_L^2}{\pi e_w A_w} \frac{1}{(1+S_c/S_w)}$$

and the canard induced drag coefficient:

$$C_{D_{i_c}} = \frac{C_L^2 S_c}{\pi e_c A_c S_w} \frac{1}{(1 + S_c/S_w)}$$

Assumptions made were as already noted above concerning to:

- no losses of dynamic pressure in the inflow air stream and
- same lift coefficient on both surfaces.

The wing Oswald efficiency factor is obtained empirically¹⁹ by:

$$e_w = \frac{1}{1.035 + 1.19 A_w \left(\frac{C_{D_{P_w}}}{\cos^2 \Lambda_{w_{c/4}}} + C_{D_{P_{0_w}}} \right)}$$

where $C_{D_{P_w}}$ is the wing parasite drag coefficient as obtained above,

$C_{D_{P_{0_w}}} = \sum_i C_{D_{P_{i}}} + C_{D_{P_e}}$ is the wing free aircraft parasite drag coefficient,

A_w is the wing aspect ratio,

$\Lambda_{w_{c/4}}$ is the wing quarter chord sweep angle.

and the canard Oswald efficiency factor is determined using the same empirical approach:

$$e_c = \frac{1}{1.035 + 1.19 A_c \left(\frac{C_{D_{P_c}}}{\cos^2 \Lambda_{c_{c/4}}} + C_{D_{P_{0_c}}} \right)}$$

where $C_{D_{P_c}}$ is the canard parasite drag coefficient as obtained above,

$C_{D_{P_{0_c}}} = \sum_i C_{D_{P_{i}}} + C_{D_{P_w}}$ is the canard free aircraft parasite drag coefficient,

A_c is the canard aspect ratio,

$\Lambda_{c_{c/4}}$ is the canard quarter chord sweep angle.

Aircraft compressibility drag coefficient, $C_{D_{c_w}}$

This contribution is represented by:

$$C_{D_{c_w}} = K_w \Delta C_{D_M}$$

where K_w is the wing form factor

and ΔC_{D_M} is given by¹⁹ :

$$10(M - M_D)^3 \text{ if } M > M_D \text{ or}$$

$$0, \quad \text{otherwise}$$

The drag divergence Mach number, M_D is defined as:

$$M_D = A_1 + A_2 C_L + 0.08 SC_{FAX}$$

where SC_{FAX} is the supercritical aerofoil parameter which may be input as SC_{FAC} to shift the drag divergence Mach number of the aerofoil. It may take values ranging from 0 to 1 (figure III.1.3 of ref 19).

A_1 and A_2 are compressibility drag parameters which depend on the wing and aerofoil geometries as well as on the wing pressure distributions.

These compressibility parameters are computed using the following empirically derived expressions:

$$A_1 = [1 + 0.0033(4\Lambda_{P_{min}} - 3\Lambda_{t/c_{Max}})] [1 - 1.4t/c - 0.06(1 - \bar{x}_{P_{min}})] - 0.0368$$

and

$$A_2 = -0.33(0.65 - \bar{x}_{P_{min}}) [1 + 0.0033(4\Lambda_{P_{min}} - 3\Lambda_{t/c_{Max}})]$$

where $\bar{x}_{P_{min}}$ is the wing minimum pressure point in fraction of wing chord (taken as 0.30),

$\Lambda_{P_{min}}$ is the sweep angle at the wing minimum pressure points, expressed in degrees,

$\Lambda_{t/c_{Max}}$ is the sweep angle at the wing maximum thickness points, expressed in degrees,

t/c is the wing average thickness to chord ratio computed by equation III.1.2 in ref 19.

The sweep angles are obtained as follows:

$$\Lambda_{P_{min}} = \arctan\left[\tan\Lambda_{c/4} - \frac{4(\bar{x}_{P_{min}} - 0.25)(1-\lambda)}{A_w(1+\lambda)}\right]$$

and

$$\Lambda_{t/c_{Max}} = \arctan\left[\tan\Lambda_{c/4} - \frac{4(\bar{x}_{t/c_{Max}} - 0.25)(1-\lambda)}{A_w(1+\lambda)}\right]$$

where $\Lambda_{c/4}$ is the wing quarter chord sweep angle,

λ is the wing taper ratio,

$\bar{x}_{t/c_{Max}}$ is the wing maximum thickness point in fraction of wing chord (taken as 0.40 for a supercritical aerofoil).

Equations included in the AERO and DRAG subroutines other than the ones just presented are detailed in Appendix B.

3.5.2.2.3 Propulsion

Although the propulsion model is unchanged, it is worth describing the methodology used and how the module operates. Propulsion system performance is calculated during engine sizing and whenever aircraft performance is evaluated. Engine performance methodology is based on tabulated performance data for specific engine cycles. The active module consists of subroutines related to turbojet/ turbofan engines (figures 3.6 and 3.7) and the routines used with their respective functions are shown next:

ENGSZ	- determines the engine size which is expressed in terms of rated sea level static airflow;
ENGINE	- determines engine performance as a function of the flight altitude, Mach number and engine power setting. Engine performance is described by thrust, airflow, fuel flow, specific thrust, percent corrected airflow and thrust specific fuel consumption;
NACDG	- computes nacelle parasite drag during engine sizing and performance calculations;

ENGDT5 - provides propulsion system performance data for the General Electric CF-34 turbo-fan engine allowing it to be scaled up or down in order to simulate a similar cycle powerplant of arbitrary size.

This engine cycle was selected for the thrust level envisioned in the design study. This same engine powers the Canadair Regional Jet which is a similar capacity transport.

The engine is first sized to match cruise drag with an excess cruise thrust to ensure a specified margin of rate of climb will be available. To satisfy required take off distance, or one engine out requirements on the aircraft rate of climb (FAR-Part 25), an engine resizing is done. Engine nacelle geometry is a function of engine size, therefore it is computed while sizing the engine. During this process, which is iterative, nacelle drag is accounted for as an aerodynamic force rather than a penalty on engine performance (this alternative option is also available in GASP).

The scaling of a particular reference engine to match the required cruise thrust is based on the assumption that at a given Mach number, altitude and engine power setting, the specific thrust, SF_n , the specific fuel consumption, SFC, and the percent corrected airflow, P_{ca} , of the scaled engine are the same as for the unscaled engine. Once ENGSZ establishes the sea level static airflow, the scaled engine performance at the specified operating point follows immediately:

Airflow

$$W_a = W_{a_{sls}} P_{ca} \frac{\delta}{\sqrt{\theta}}$$

Thrust

$$F_n = SF_n W_a$$

Fuel Flow

$$W_F = SFC * F_n$$

where $W_{a_{sls}}$ is the ISA sea level static conditions airflow,

$P_{ca} = \frac{W_{ca}}{W_{a_{sls}}}$ is the percent corrected airflow required to convert the engine corrected

airflow to the corresponding rated sea level static airflow,

$W_{ca} = W_a \frac{\sqrt{\theta}}{\delta}$ is the corrected airflow,

SF_n is the specific thrust expressed in $[Lb_{thrust}/Lb_{air}/sec]$,

SFC is the specific fuel consumption expressed in $[Lb_{fuel}/HR/Lb_{thrust}]$,

$\delta = \frac{P}{P_0}$ is the total pressure to SLS pressure ratio,

$\theta = \frac{T}{T_0}$ is the total temperature to SLS temperature ratio,

Subscript '0' stands for sea level static conditions.

The engine performance data contained in ENGDT5 consists of corrected thrust, corrected airflow and corrected fuel flow tabulated as functions of engine power setting and flight Mach number. Typically, engine power setting is expressed as either the ratio of turbine inlet temperature to the engine face total temperature ($T5/T2$) or the percent corrected rotor speed ($N/\sqrt{\theta}/N_{Max}$). The relationships are illustrated schematically in figure 3.9 where the effect of altitude is contained implicitly in the ratios of total temperature and total pressure to sea level static values of these parameters (θ and δ), in terms of which the "corrected" values of thrust, airflow and fuel flow can be found.

3.5.2.2.4 Weight and Balance

The Weight and Balance module has undergone extensive modifications, namely in subroutines WGHT and TAIL to permit the design and analysis of the new concept. As shown in figures 3.6 and 3.7, it is composed of six subroutines, and the ones used with their purposes follow:

DLOAD	- determines the minimum design speeds and structural load factors in accordance with FAR regulations Parts 23 and 25,
WGHT	- computes the weights of the structural components, flight controls and payload and locates the wing for balance purposes, compromising the CG travel obtained from loading considerations with the allowable limits set out by the stability and control requirements,
TAIL	- determines the sizes of the horizontal and vertical tails based on stability and control considerations,
ENGWGT	- estimates the engine(s) weight(s),
WFIXEU	- determines the weight of the fixed equipment and fixed useful load.

A simplified computational flow for subroutine WGHT is shown in figure 3.10.

The weight of the aircraft structure, flight controls, engines, fixed equipment and useful load are estimated using historical trend equations¹⁹.

Canard structural weight is estimated using the same semi-empirical relationship as developed for the wing from Torenbeek's approach²⁶ and a regression analysis shown in figure V.1.14¹⁹. This correlation takes into account the material required to resist the root bending moment due to lift in a specified flight condition and does not include the weight of the high lift devices. Whilst the wing flap weight is computed in subroutine FLAPS, the weight of the

canard high lift devices will not be evaluated for simplicity, and because it may be assumed negligible in the present initial design approach.

3.5.2.2.4.1 Aircraft Balance

The wing is initially located based on default historical tail volume coefficients. Following the loading rules and solving the equations for weight moment equilibrium, the aircraft centre of gravity and the related forward and rearward positions are determined. Stability and control (S&C) is evaluated in "TAIL" so that the forward control limit falls at the c.g. at the most forward loading condition. Tail moment arms and areas are then recomputed in order to satisfy the c.g. range as well as other required longitudinal and lateral stability and control requirements. This process is iterated until the tail area converges to an acceptable tolerance which is 0.4 sqft difference in successive horizontal tail areas, in the present case. The code now allows for sizing of the canard by introducing canard parameters in terms of a volume coefficient, as used on conventional layouts, to the three-surface configuration. Basically, the procedure now implemented is the same as originally, the only difference resides on the assumptions made, already mentioned above, and on the additional complexity added due to the wing area variation which happens while refining the canard and the tailplane areas, keeping the canard/ wing area ratio constant throughout a complete design synthesis run.

Assuming there is no cargo compartment in the aircraft, the loading conditions are:

Most Forward Load Condition

- Pilots,
- All seats forward of c.g._r are filled by passengers and respective over-head baggage,
- All fuel tanks forward of c.g._r are full⁽¹⁾.

Most Aft Load Condition

- Pilots,
- All seats aft of c.g._r are filled by passengers and respective over-head baggage,
- All fuel tanks aft of c.g._r are full⁽¹⁾.

Design Load Condition

- Pilots,
- Maximum number of passengers loaded in forward seats and respective overhead baggage,
- Design fuel load contained in wing and fuselage tanks (if any).

3.5.2.2.4.2 Canard and Tail Sizing

Canard and tail sizing is governed by critical longitudinal and lateral stability and control requirements set up by the regulatory authorities. Methods used in the modified "TAIL" subroutine reflect the FAR requirements and within the program limitations the sizing

¹If fuel forward of c.g._r (or aft of c.g._r) is less than minimum fuel, here assumed as 20% of wing fuel tank capacity, add fuel to the next most forward (or aft) fuel tank until minimum fuel load is reached.

criteria ensures the following:

Horizontal tail and canard

- meeting a specified longitudinal static margin;
- the ability to trim the aircraft maximum lift coefficient in the landing configuration, in ground effect;
- the ability to rotate the aircraft in the take off configuration.

Vertical tail

- meeting a specified directional static stability requirement;
- the ability to maintain the minimum control speed for twin engine aircraft.

In addition to including the necessary logic for the sizing of the three surfaces in the new configuration, the conventional configuration horizontal tail sizing procedure was replaced by a new one, more structured, providing new options for the controls locked and controls free cases and accounting for the contributions from the wing pitching moment, the thrust jet inclination and the rotational control pitching moments in the stability and control equations.

Longitudinal stability and control (stick-fixed) equations as applied to the three-lifting surface aircraft were derived from basic principles and are shown in Appendix A. The formulation implemented in "TAIL" to size the horizontal tail and the canard is based on these equations and is described below.

3.5.2.2.4.2.1 Conventional Configuration

To satisfy the requirements for longitudinal stability and control listed above the stability equation and the pitching moment equilibrium equation were combined in order to determine the minimum tail volume coefficients to satisfy both cruise stability and landing trim, and cruise stability and lift off rotation. The most critical of the two is taken and the required tailplane area, span and moment arm are computed.

Equations A7 and A4 with appropriate adjustments are used and shown next:

- Cruise Stability

For a required static margin and c.g. range, the aircraft forward c.g. position is determined by evaluating the neutral point and the aft c.g. locations as follows:

$$\bar{x}_{np} = \bar{x}_{cg_{dC_m/dC_L=0}} = \bar{x}_{ac} - \sum_i \left(\frac{dC_m}{dC_L} \right)_i - \frac{a_i}{a_w} \bar{V}_i \eta_i \left(1 - \frac{d\epsilon}{d\alpha} \right)$$

$$x_{cg_{aft}} = x_{np} - SM \quad ,$$

thus,

$$\bar{x}_{cg_{aft}} = \bar{x}_{cg_{aft}} - \Delta \bar{x}_{cg}$$

where,

\bar{x}_{np} is the aircraft neutral point location as fraction of wing mean aerodynamic chord,

\bar{x}_{ac} is the aircraft aerodynamic centre location as fraction of the wing mean aerodynamic chord,

$\sum_i \left(\frac{dC_m}{dC_L} \right)_i = \left(\frac{dC_m}{dC_L} \right)_{fus} + \left(\frac{dC_m}{dC_L} \right)_{nac} + \left(\frac{dC_m}{dC_L} \right)_{th_{dir}} + \left(\frac{dC_m}{dC_L} \right)_{th_{jinc}}$ is the sum of the fuselage, nacelles and powerplant installation contributions to stability,

a_w and a_t are the wing and tailplane lift curve slopes,

$\bar{V}_t = (\bar{x}_{cg} - \bar{x}_t) \frac{S_t}{S_w}$ is the tail volume coefficient,

\bar{x}_{cg} is the aircraft c.g. location as fraction of the wing mean aerodynamic chord,

\bar{x}_t is the tailplane aerodynamic centre location as fraction of the wing mean aerodynamic chord,

S_t is the tailplane planform area,

S_w is the wing planform area,

$\eta_t = \frac{q_t}{q}$ is the dynamic pressure ratio at the tail to that of the undisturbed free air stream,

$\frac{d\epsilon}{d\alpha}$ is the rate of change of wing downwash at the horizontal tail with angle of attack,

SM is the specified longitudinal static margin,

$\bar{x}_{cg_{aft}}$ is the rearward location of the c.g. as fraction of the wing mean aerodynamic

chord,

$\Delta \bar{x}_{cg}$ is the c.g. range as fraction of the wing mean aerodynamic chord,

$\bar{x}_{cg_{fwd}}$ is the forward c.g. location as fraction of the wing mean aerodynamic chord.

- Landing Flare and Lift-off Rotation

To evaluate the horizontal tail volume coefficient the equation for pitching moment equilibrium is used:

$$C_{m_{cg}} = C_L(\bar{x}_{cg} - \bar{x}_{ac}) + \sum_i C_{m_i} + a_t \alpha_t \bar{V}_t \eta_t = 0$$

resolving for \bar{V}_t it becomes

$$\bar{V}_t = \frac{C_L(\bar{x}_{ac} - \bar{x}_{cg}) - \sum_i C_{m_i}}{a_t \alpha_t \eta_t}$$

where,

$\sum_i C_{m_i}$ is the sum of the various pitching moment contributions,

$\alpha_t = \alpha_w - \varepsilon - i_w + i_t + \tau_e \delta_e$ is the tailplane angle of attack,

α_w is the wing angle of attack,

ε is the wing downwash angle at the horizontal tail,

i_w and i_t are the wing and tailplane incidence angles,

$\tau_e = \frac{d\alpha_t}{d\delta_e}$ is the elevator control effectiveness,

δ_e is the elevator deflection.

For the two critical control cases, the tail volume coefficients are obtained by replacing the corresponding parameters, ground effects included, in the above equation as detailed below:

Landing Flare

$$\bar{V}_{t_L} = \frac{C_{L_{\max L}}(\bar{x}_{ac_L} - \bar{x}_{cg_{fwd}}) - (C_{m_{ac}} + C_{m_{flap}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th_{dir}}} + C_{m_{th_{jinc}}})_L}{a_{t_L} \eta_{t_L} (\alpha_{w_L} - \epsilon_L - i_w + i_t + \tau_e \delta_{e_{\max}})}$$

Lift-off Rotation

$$\bar{V}_{t_r} = \frac{C_{L_r}(\bar{x}_{ac_r} - \bar{x}_{cg_{fwd}}) - (C_{m_{ac}} + C_{m_{flap}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th_{dir}}} + C_{m_{th_{jinc}}} + C_{m_{ig}} - C_{m_{I_{YY}}})_r}{a_{t_r} \eta_{t_r} (\alpha_{w_r} - \epsilon_r - i_w + i_t + \tau_e \delta_{e_{\max}})}$$

where,

$C_{m_{ac}}$ is the wing pitching moment coefficient,

$C_{m_{flap}}$ is the flap pitching moment coefficient,

$C_{m_{fus}}$ is the fuselage pitching moment coefficient,

$C_{m_{nac}}$ is the nacelles pitching moment coefficient,

$C_{m_{th_{dir}}}$ is the propulsion direct thrust pitching moment coefficient,

$C_{m_{th_{jinc}}}$ is the propulsion jet-induced downwash at the tail pitching moment coefficient,

$C_{m_{ig}}$ is the landing gear pitching moment coefficient,

$C_{m_{I_{YY}}}$ is the pitching moment coefficient contribution due to the aircraft inertia resistance to rotation,

L and r subscripts stand for landing flare-out and lift-off rotation.

Using the greatest of the tail volume coefficients obtained, the following geometric data is determined:

$$\text{Tailplane area, } S_t = \frac{\bar{V}_t S_w \bar{c}_w}{l_{t_{cg}}}$$

$$\text{Tailplane span, } b_t = (A_t S_t)^{1/2}$$

$$\text{Tailplane moment arm, } l_{t_{q4}} = l_{t_{cg}} + (\bar{x}_{q4} - \bar{x}_{cg_{aft}}) \bar{c}_w$$

where, $l_{t_{cg}} = (x_{cg} - x_t)$ is the tailplane moment arm referred to the aircraft c.g.,

and $l_{t_{q4}} = (x_{q4} - x_t)$ is the tailplane moment arm referred to the wing mean aerodynamic quarter chord point.

3.5.2.2.4.2.2 Three-Surface Configuration

Again, to meet the longitudinal S&C requirements, the stability and the pitching moment equilibrium equations as presented in Appendix A were combined to determine the minimum canard and tail volume coefficients consistent with both cruise stability and landing trim, and cruise stability and lift-off rotation. The most critical of the two volume coefficient combinations is adopted and the canard and tailplane areas, spans and moment arms readily obtained.

Equations A7, A39, A42 and A47 and A48 with appropriate adjustments and arrangements are implemented and presented below:

- Cruise Stability

Similarly to the conventional concept case, the aircraft forward c.g. position is determined by evaluating the neutral point and the aft c.g. positions for a given static margin and c.g. range:

$$\bar{x}_{np} = \bar{x}_{ac} - \sum_i \left(\frac{dC_m}{dC_L} \right)_i - \frac{a_c}{a_w} \bar{V}_c - \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right)$$

thus,

$$\bar{x}_{cg_{fwd}} = \bar{x}_{np} - SM - \Delta \bar{x}_{cg}$$

where, $\sum_i \left(\frac{dC_m}{dC_L} \right)_i$ is defined as in the conventional configuration case,

a_c is the canard lift curve slope,

$\bar{V}_c = (\bar{x}_{cg} - \bar{x}_c) \frac{S_c}{S_w}$ is the canard volume coefficient,

\bar{x}_c is the canard aerodynamic centre location as fraction of the wing mean aerodynamic chord,

S_c is the canard planform area.

- Landing Flare and Lift-off Rotation

Equations A39/ A47 and A42/ A48, derived from the equation for pitching moment equilibrium assuming that the fore-plane and the horizontal tail contributions to the overall pitching moment are equal, give the forward c.g. location in terms of the tail and the canard parameters respectively. Both may be written in the following form for the two flying conditions considered:

$$\bar{x}_{cg_{fwd}} = \bar{x}_{ac} - \frac{2}{C_L} a_t \alpha_t \bar{V}_t \eta_t - \frac{1}{C_L} \sum_i C_{m_i}$$

and,

$$\bar{x}_{cg_{fwd}} = \bar{x}_{ac} - \frac{2}{C_L} a_c \alpha_c \bar{V}_c - \frac{1}{C_L} \sum_i C_{m_i}$$

where, $\alpha_t = \alpha_w - \varepsilon - i_w + i_t + \tau_e \delta_e$ is the tailplane angle of attack,

$\alpha_c = \alpha_w - \alpha_{0_c} - i_w + i_c + \tau_c \delta_c$ is the canard angle of attack,

α_{0_c} is the canard zero-lift angle of attack,

i_c is the canard incidence angle,

$\tau_c = \frac{d\alpha_c}{d\delta_c}$ is the canardvator control effectiveness,

δ_c is the canardvator deflection.

Two systems of real linear equations are obtained, concerning the landing flare-out and the nose wheel liftoff rotation situations while ensuring longitudinal static stability in cruise, by combining individually the above stability derived equation with the two later control equations. The canard and tailplane volume coefficients are found through the solution to these systems of equations that are shown next:

Cruise Stability and Landing Flare

$$a_{11_L} \bar{V}_{c_L} + a_{12_L} \bar{V}_{t_L} = b_{1_L}$$

$$a_{21_L} \bar{V}_{c_L} + a_{22_L} \bar{V}_{t_L} = b_{2_L}$$

Replacing for the appropriate parameters that include the ground effects the coefficients of the equations are defined:

$$a_{11_L} = \left(-\frac{a_c}{a_w}\right)_{cr}$$

$$a_{12_L} = \left[-\frac{a_t}{a_w} \eta_t \left(1 - \frac{d\varepsilon}{d\alpha}\right)\right]_{cr} + \frac{2}{C_{L_{max_L}}} a_{t_L} (\alpha_{w_L} - \varepsilon_L - i_w + i_t + \tau_e \delta_{e_{max}}) \eta_{t_L}$$

$$a_{21_L} = a_{11_L} + \frac{2}{C_{L_{max_L}}} a_{c_L} (\alpha_{w_L} - \alpha_{0_c} - i_w + i_c + \tau_e \delta_{e_{max}})$$

$$a_{22_L} = \left[-\frac{a_t}{a_w} \eta_t \left(1 - \frac{d\varepsilon}{d\alpha}\right)\right]_{cr}$$

$$b_{1_L} = [-\bar{x}_{ac} + \sum_i \left(\frac{dC_m}{dC_L}\right)_i + SM + \Delta \bar{x}_{cg}]_{cr} + [\bar{x}_{ac_L} - \frac{1}{C_{L_{max_L}}} \sum_i C_{m_{i_L}}]$$

$$b_{2_L} = b_{1_L}$$

where, $\sum_i \left(\frac{dC_m}{dC_L}\right)_{i_{cr}} = \left[\left(\frac{dC_m}{dC_L}\right)_{fus} + \left(\frac{dC_m}{dC_L}\right)_{nac} + \left(\frac{dC_m}{dC_L}\right)_{th_{dir}} + \left(\frac{dC_m}{dC_L}\right)_{th_{jinc}}\right]_{cr}$

$$\sum_i C_{m_{i_L}} = (C_{m_{ac}} + C_{m_{flap}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th_{dir}}} + C_{m_{th_{jinc}}})_L$$

Cruise Stability and Lift-off Rotation

$$a_{11,r} \bar{V}_{c_r} + a_{12,r} \bar{V}_{t_r} = b_{1,r}$$

$$a_{21,r} \bar{V}_{c_r} + a_{22,r} \bar{V}_{t_r} = b_{2,r}$$

Identically, using the appropriate parameters that account for the ground effects the coefficients of these equations are:

$$a_{11,r} = a_{11,L}$$

$$a_{12,r} = \left[-\frac{a_t}{a_w} \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right) \right]_{cr} + \frac{2}{C_{L_r}} a_t (\alpha_{w_r} - \varepsilon_r - i_w + i_t + \tau_e \delta_{e_{\max}}) \eta_t$$

$$a_{21,r} = a_{11,L} + \frac{2}{C_{L_r}} a_c (\alpha_{w_r} - \alpha_{0_c} - i_w + i_c + \tau_c \delta_{c_{\max}})$$

$$a_{22,r} = a_{22,L}$$

$$b_{1,r} = \left[-\bar{x}_{ac} + \sum_i \left(\frac{dC_m}{dC_L} \right)_i + SM + \Delta \bar{x}_{cg} \right]_{cr} + \left[\bar{x}_{ac,r} - \frac{1}{C_{L_r}} \sum_i C_{m_i,r} \right]$$

$$b_{2,r} = b_{1,r}$$

where, $\sum_i C_{m_i,r} = (C_{m_{ac}} + C_{m_{fap}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th,dar}} + C_{m_{th,jinc}} + C_{m_{ig}} - C_{m_{TY}})_r$

The solutions to these systems of equations are obtained using the Cramer's rule which is implemented in the new "Cramer" subroutine included in the program.

The critical canard and tailplane volume coefficients to consider are those whose sum provides a higher value. Once this is done geometric data such as the canard and tail areas, spans and moment arms are determined:

Tail

$$\text{Tailplane moment arm, } l_{t_{cg}} = l_{t_{q4}} + (\bar{x}_{cg_{aft}} - \bar{x}_{c/4}) \bar{C}_w$$

$$\text{Tailplane area, } S_t = \frac{\bar{V}_t S_w \bar{c}_w}{l_{t_{cg}}}$$

$$\text{Tailplane span, } b_t = (A_t S_t)^{1/2}$$

Canard

$$\text{Canard moment arm, } l_{c_{cg}} = l_{c_{cgA}} + (\bar{x}_{c_{cgA}} - \bar{x}_{c/A}) \bar{c}_w$$

$$\text{Canard area, } S_c = \frac{\bar{V}_c S_w \bar{c}_w}{l_{c_{cg}}}$$

$$\text{Canard span, } b_c = (A_c S_c)^{1/2}$$

Finally, a first order approximation of the canardvator deflection is given by equation A44 reproduced next:

$$\delta_{c_{\max L}} = \frac{C_{m_{\delta_{eL}}}}{C_{m_{\delta_{cL}}}} \left(\delta_{e_{\max}} + \frac{\alpha_{tL}}{\tau_e} \right) - \frac{(\alpha_c - \alpha_{0c})_L}{\tau_c}$$

where, $C_{m_{\delta_{eL}}} = a_{tL} \bar{V}_t \eta_t \tau_e$ is the elevator power, at landing conditions in ground effect,

$C_{m_{\delta_{cL}}} = a_{cL} \bar{V}_c \tau_c$ is the canardvator power, at landing conditions in ground effect,

$\alpha_{tL} = \alpha_{wL} - \epsilon_L - i_w + i_t$ is the horizontal tail angle of attack at landing in ground effect,

$\alpha_{cL} = \alpha_{wL} - i_w + i_c$ is the canard angle of attack at landing in ground effect.

Most of the canard related aerodynamic derivatives are obtained using the same DATCOM type methods as implemented in GASP and used to estimate the tailplane aerodynamic derivatives¹⁹.

As far as the vertical tail is concerned, GASP original procedure¹⁹ is kept unchanged and is applied to both concepts as it stands.

Equations other than the ones shown above and incorporated in subroutines WGHT and TAIL are detailed in Appendix B.

3.5.2.2.5 Mission Performance

The Mission Performance module requires consideration of propulsion, aerodynamics and weight characteristics so the interaction between the subroutines within the program becomes quite complex. It is composed of thirteen subroutines as shown in figures 3.6 and 3.7 and those actually used with their purpose are listed below:

PERFRM	- defines the mission profile and controls the mission computations,
TAXI	- computes the fuel consumption during ground idle,
TAKOFF	- models the take-off manoeuvre up to a specified altitude,
ACCEL	- models the aircraft rectilinear acceleration at constant altitude between mission segments,
CLIMB	- simulates a constrained climb,
XRANGE	- performs cruise range computation,
DESCND	- computes the descent performance,
DLAND	- models the landing manoeuvre,
DERIV	- determines derivatives and checks constraints for the TAKOFF routine,
ASPEED	- determines speed at specified power for equilibrium horizontal flight,
CEILNG	- computes the engine-out service ceiling or the rate of climb for a specified altitude,
RGBAL	- controls the aircraft resizing process to meet the specified range or endurance within a tolerance of 1%.

To ensure consistency with the new reference area adopted for the simulation of the three-surface aircraft, the module was modified to include minor changes in the subroutines TAKOFF, ACCEL, CLIMB, DESCND, DLAND, DERIV, CEILNG and RGBAL, which are reflected in the equations shown in Appendix B.

As stated previously, the mission performance module is used to determine the engine size and the wing loading necessary to meet the specified performance constraints and to compute the amount of fuel required for the mission.

The mission profile consists basically of 6 segments:

- taxi,
- take-off,
- climb,
- cruise,
- descent,
- landing

where straight level flight acceleration is assumed and computed by ACCEL between take-off and climb and climb and cruise.

3.5.2.2.5.1 Taxi

For an input taxi time and runway altitude, assuming the engines at idle thrust, the TAXI routine returns the corresponding burned fuel weight.

3.5.2.2.5.2 Take-off

TAKOFF computes the take-off field performance assuming a sequence of events starting from the beginning of the take-off run up to a specified height as follows:

- initiate ground roll and accelerate,
- rotate,
- lift-off,
- begin landing gear retraction at 50 ft (retraction time assumed = 7 sec),
- distance to an altitude of 35 ft,
- distance to an altitude of 50 ft,
- begin flap retraction at 400 ft (retraction rate assumed = 3.333 degrees/ sec),
- end of take-off at a specified altitude.

For twin engine aircraft the optional engine-out take-off performance can be evaluated. This consists of a continued take-off to an altitude of 50 ft with a failed engine and an accelerate-stop distance consisting of:

- initiate ground roll and accelerate,
- engine failure,
- remove power,
- apply brakes,
- stop aircraft.

The take-off manoeuvre is analysed at maximum engine thrust by integrating the equations of motion for velocity, flight path angle, distance and altitude, using a time interval of 0.2 sec. After the take-off distance has been obtained, the engine size can be varied to satisfy a required take-off field constraint.

3.5.2.2.5.3 Climb

Three types of climb trajectory can be simulated by CLIMB with either maximum thrust or maximum continuous thrust settings and constrained by the pitch angle and the maximum FAR equivalent airspeed at altitudes below 10 000 ft:

- at maximum rate of climb,
- at maximum allowable operating speed,
- at a specified equivalent airspeed.

A point performance technique at required altitude intervals is used for the climb trajectory computation and the engine can be sized so that the aircraft meets the FAR engine-out climb requirements. As already referred to in the Propulsion section, the engine sizing will also take into consideration that enough thrust is available at cruise conditions to meet a prescribed rate of climb.

3.5.2.2.5.4 Cruise

Cruise performance, range and cruise fuel weight is computed by XRANGE using the Breguet range equations for three fuel capacities and three cruise Mach number conditions:

Fuel Capacities:

- Maximum available fuel weight (minimum payload),
- Minimum available fuel weight (maximum payload)
- Design available fuel weight.

Mach Numbers:

- Specified cruise Mach number,
- Normal thrust Mach number,
- Maximum specific range Mach number.

Altitude is assumed fixed, during cruise flight.

3.5.2.2.5.5 Descent and Landing

DESCND computes the descent performance constrained by the cabin de-pressurization rate, the fuselage angle and the maximum FAR equivalent speed under 10 000 ft altitude.

The landing field performance is modelled in DLAND by a sequence of four events:

- a glide approach from 50 ft altitude,
- a circular flare to touchdown at constant load factor and velocity,
- a ground roll delay before braking,
- a braked ground roll with or without application of thrust reversers.

If a specified landing distance constraint is not met an iteration on wing loading is performed until the constraint is satisfied. This involves the recomputation of the geometry, aerodynamics, weights and performance.

3.5.2.2.6 Economics

As shown in figures 3.6 and 3.7, the Economics module is composed of two subroutines performing the following tasks:

- | | |
|---------------|---|
| GACOST | - computes the engine and the airframe costs as well as the direct operating cost (DOC) of the aircraft, |
| AFCOST | - computes the Research, Development, Testing and Evaluation (RDT&E) costs, the detailed airframe production costs and the initial aircraft cost. |

Once the sizing process is completed, this module is called to evaluate the economic worth of the aircraft. GACOST makes use of the engine and airframe cost estimating relationships (CER) developed by Anderson²⁷ and the Boeing 1977 DOC methodology²⁹. RDT&E costs are estimated using a Rand type of formulation based on the airframe weight and cruise Mach number and the detailed airframe production cost is evaluated based on CERs developed by Beltramo²⁸ in AFCOST. All these costs are corrected to 1993 using a cost escalation factor (CEF) based on an average annual inflation rate of 8%.

The direct operating cost is defined as the sum of the flight crew salary, fuel and oil costs and taxes, insurance, direct maintenance costs involving both the airframe and engines maintenance, maintenance burden costs and depreciation.

Crew salary is a function of the aircraft maximum take-off weight, cruise speed and trip block time. Annual insurance cost is assumed to be 5% of the initial aircraft cost. Airframe direct maintenance costs are composed of material costs and labour costs, and are functions of the airframe weight, flight time, and labour rate of pay. Engines direct maintenance costs are made up of material and labour costs, and are functions of the engine maximum sea level static thrust, number of engines, flight time, and labour rate. Maintenance burden is assumed to be twice the direct maintenance labour costs. Aircraft depreciation is dependent on its initial purchase cost, the estimated spares factor assumed here as 6% of that cost, the number of years in operation and its residual value.

Changes have only been incorporated in subroutine AFCOST in order to reflect the canard cost in the airframe production costs. The estimating correlation used is the same as used for the wing production cost and is presented in Appendix B.

3.5.2.2.7 Utilities

The last group of subroutines displayed in figure 3.6 consists of a library of numerical methods which may be called by the other subroutines and which typically perform a numerical function. Those used and their role are as follows:

TPALT	- computes the atmospheric properties or altitude, whichever is applicable,
OUTPUT	- prints the geometric data, weights, aerodynamic, and cost results of the design,
Cramer	- computes the solution of a system of real linear equations using the Cramer's rule,
BIV	- performs linear interpolation in two independent stored variables,
INTS	- performs the numerical integration by finite differences of a system of simultaneous first-order differential equations. These equations are defined in subroutine DERIV.
ITRLN	- performs linear interpolation in one independent stored variable,
ITRMHW	- finds a zero of a function using the Newton-Raphson method.

These subroutines were employed without modifications except Cramer which was purposely developed to assist the computation of the canard and horizontal tail volume coefficients in the new TAIL routine.

3.6 Limitations of the Design Model

The design model is a mathematical abstraction of the envisioned real system. It contains the underlying physics of the aircraft design, including aerodynamics, weights propulsion, performance, etc. Its accuracy depends on how accurately it models reality. The mathematical model requires inputs from the real world and the results must be continuously compared with real world results, from which appropriate calibration may be provided.

In the initial conceptual design phase, when no information exists other than the mission and technology level requirements and the operational and certification criteria, the best way to proceed is to rely on statistically derived data from past experience and on empirical and semi-empirical disciplinary analysis methods to formulate a first approach to the solution. Of course statistical data and empirical analysis methods will only be reliable for some well ordered classes of aircraft and for the more usual conventional tail-aft configurations for which they apply and any extrapolations will incur in some degree of error due to incorrect modelling or insufficiency of data. Overall the results of a design study can only be as accurate as the data and the analysis methods on which it is based.

While it is true that historical data and empirical methods allow the reproduction of existing aircraft at their actual technology level with an acceptable degree of accuracy, they also permit the assessment of the impact produced by the introduction of new technologies, or the adoption of radical different configurations, on the performance and costs of new aircraft after appropriate inputs, modifications and adjustments have been made to the synthesis/analysis procedures. Thus extrapolation from past experience is frequently needed in spite of the risks involved, providing these are carefully and adequately controlled. It seems to be the only reasonable way to study new concepts when no specific detailed data is available.

As referred to in Chapter 2, most of the existing synthesis programs for conceptual design are automated forms of the traditional manual design procedures with more or less flexibility dependent on whether they present high or low degree of modularity, open-ended structure and interactivity with the designer. The usual result of these procedures, whether automated or not, are design concepts that will permit the selection of the few most promising ones for more detailed study rather than a very comprehensive and refined good preliminary design. GASP program can be classified as a modular, open-ended, not-interactive synthesis program and represents the mathematical abstraction of the design used in the present work.

Interactivity would be particularly helpful in the development of the baseline design needed to initiate the iterative trial-and-error design procedure by allowing flair and innovation, as well as involving the designer directly with the design process; and afterwards, during the optimisation process as explained later in Section 5.4, and for rapidly performing the trade-off studies shown in Section 5.5. Although interactivity is desirable it would not be achieved unless innovation is allowed by the existing disciplinary analysis modules as well as by the synthesis procedures implemented in GASP. In fact the different modules should be prepared and re-written in such a flexible way as to permit an arbitrary geometry to be analysed, probably generated by a conceptual CAD system as exemplified by CDS^{30,31} or a more advanced version of RDS-CAD³². The inclusion of more disciplinary modules reflecting different design criteria or new assumptions to cope with creativity would be useful as would

an interactive engine with suitable controllers to allow running the analysis modules independently, or in combination as appropriate to the problem to be solved, or to the aims of a particular design investigation. Probably the integration with a commercial relational data-base would enhance the design environment by providing better storage of intermediate and final results with the potential for incorporating a commercially available CAD and Graphical systems.

Fortunately, in contrast with the difficulty presented when handling combat aircraft^{33,34,35,36}, the geometry of a subsonic transport aircraft can be formulated in terms of relatively straightforward equations from which the computer can derive the baseline design. This is implemented in the GASP geometric module for the conventional transport, and in order to develop the three-surface baseline concept the only change consisted of the addition of a lifting fore-plane together with the definition of its location on the fuselage and the inclusion of the initial tail/canard sizing criteria, as was already shown in Section 3.5. This latter section also reflects the considerable additional changes that were required in the disciplinary modules to produce the needed improvement in terms of innovation and creativity capacity within GASP, although of limited scope. In addition to conventional concepts, the program can now synthesize the three-surface concepts of the particular type already described (with canard/wing area ratios limited to values within 0.145 and 0.175). It will not evolve readily, for example, a canard configuration or other exotic concepts.

With regard to the accuracy of the results, the disciplinary areas where more uncertainties are posed usually correspond to the weights, aerodynamics and cost predictions. This is especially true for GASP. The Propulsion module contains actual tabulated engine performance data for current turbofan engines and the Performance module, which computes the flight profile, mission fuel required, block time, engine size and the wing loading, is quite elaborate and grounded on physical principles. This will produce results as realistic and as accurate as the weight and aerodynamic predictions provided by the respective modules.

Since it was proposed the study of the impact of a configuration change rather than that due to the introduction of new technologies, it was decided to adopt technology levels reflecting the mid-seventies period for which these modules were developed, calibrated and validated. It seems that the important issue here is to compare different concepts using the same assumptions, design criteria and ground rules.

The GASP weight predictions are usually accurate to within 10% for the maximum take-off weight as shown in ref. 21 which is typical of most conceptual design tools^{5,37,38}, assuming the other discipline modules are providing precise information. Since the canard will complement the wing for lift generation it is assumed that similar structural concepts are adopted for both components, thus justifying the use of the same Torenbeek's semi-empirical weight estimating relationship²⁶ as utilized for the wing. However the canard weight is not computed for simplicity, it being assumed that it is negligible at this initial stage of the design.

An accurate performance assessment requires a good prediction of the aircraft aerodynamic characteristics. GASP Aerodynamics module embodies empirical and statistical aerodynamic analysis methods^{19,39} and appears to give acceptable results for conventional designs. This is shown in Appendix G where low speed and high speed drag polars for two

different conventional aircraft configurations are compared with those obtained using the CoA DELTADD program. Based on a Lockheed empirical drag build-up estimation technique¹¹, this program is well known by its good results obtained at the early stages of preliminary design. The version now in use deals with flap systems while the original one did not.

The airlines operating costs are generally divided into Direct Operating Costs (DOC) and Indirect Operating Costs (IOC). DOC broadly comprises the costs associated with flying operations, maintenance and depreciation of flight equipment while IOC include the operator's other costs such as maintenance and depreciation of ground properties and equipment, servicing, administration and sales. Thus aircraft IOC strongly depends on the particular airline organization and managerial policy and is not under the control of the designer. On the other hand, several factors influencing DOC are directly related to the aircraft concept and operational characteristics and as such fall under the designer's control. This makes it a more attractive and convenient criterion for conceptual design economic evaluation. The Economics module as implemented in GASP consists of a systematic statistically based cost estimating procedure based on several sources, as referred to in section 3.5, whose main purpose is to provide a consistent means for comparing the operating economics of competing designs under a standard set of conditions. The corresponding results are useful for establishing first-order trends as required in the initial design stages, and not for comparing absolute levels of DOC with actual operating aircraft. The reasons are that standardized methods do not consider factors such as fleet mix and size, route structure, actual en-route winds, component commonality with other aircraft in the fleet, serviceability, reliability, variations in crew salary, labour rates and fuel costs, all of which will vary from one operator to another and can have a significant impact on costs. To give some idea about the accuracy of such methods, it is worth mentioning that the airframe production costs needed for the evaluation of the aircraft initial cost are computed using the cost estimating relationships developed by Beltramo and al²⁸ who demonstrated a precision within 4%, for two commercial transport aircraft (F-28 and DC-10-10) assuming a 10% manufacturer's profit, when actual component and system weights were used in the calculations.

Since the primary use of a conceptual design tool is the comparison of configurations resulting from different concepts being evaluated, changes of mission or performance requirements, varying levels of technology, relative trade-offs and trends are more important than the absolute precision of predicting a performance index. Whereas GASP absolute predictive capabilities are expected to be marginal, the accuracy of the relative comparisons of designs is expected to be good.

The above arguments suggest that the methods employed, including the modifications made which incorporate accepted engineering practices, simplifications and assumptions, often needed at the initial preliminary design stages, will ensure acceptable results for conceptual design work providing caution is exercised on their applicability and appropriate empirical correction factors are applied where necessary. Historical data blended with empirical or semi-empirical analysis techniques when adequately applied, and cautiously extrapolated, provide a measure of the feasibility of novel concepts within real world constraints.

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SYNTHESIS INTEGRATED OPTIMISATION

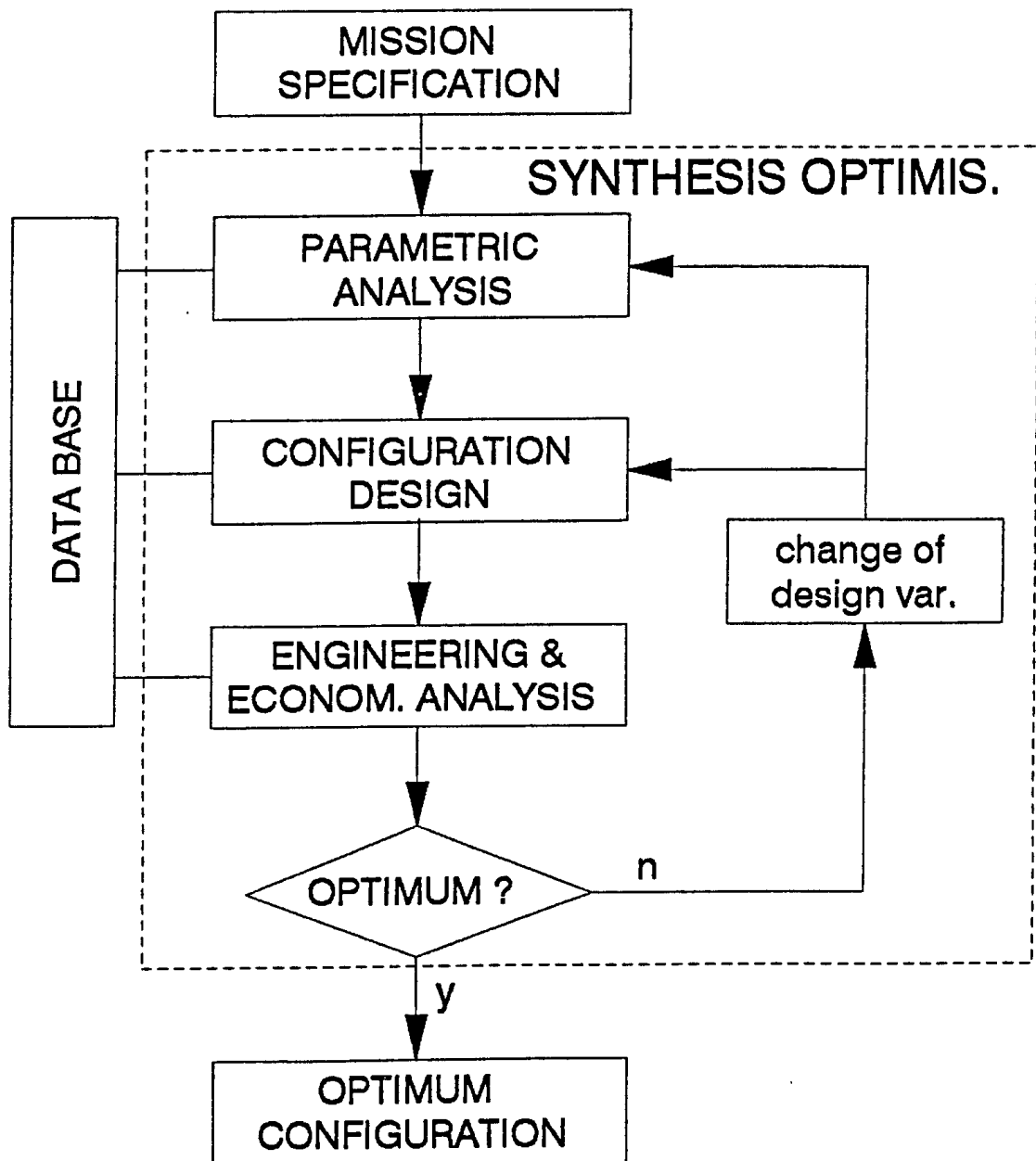


Fig 3.1 - Design Synthesis and Optimisation System Initial Flow-chart

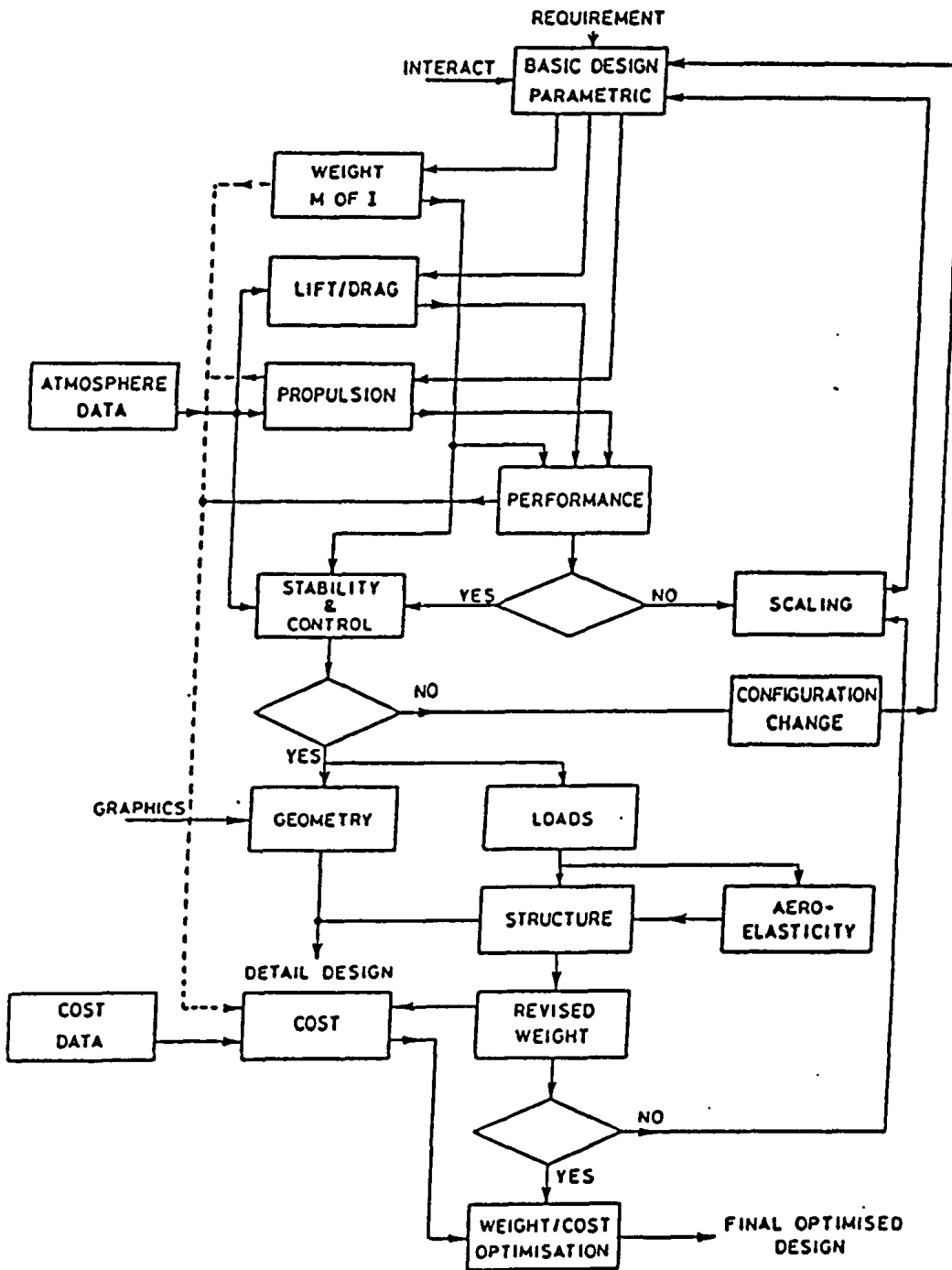


Fig 3.2 - Flow-chart of Project Design Process (reproduced from reference 3)

SYNTHESIS INTEGRATED OPTIMISATION

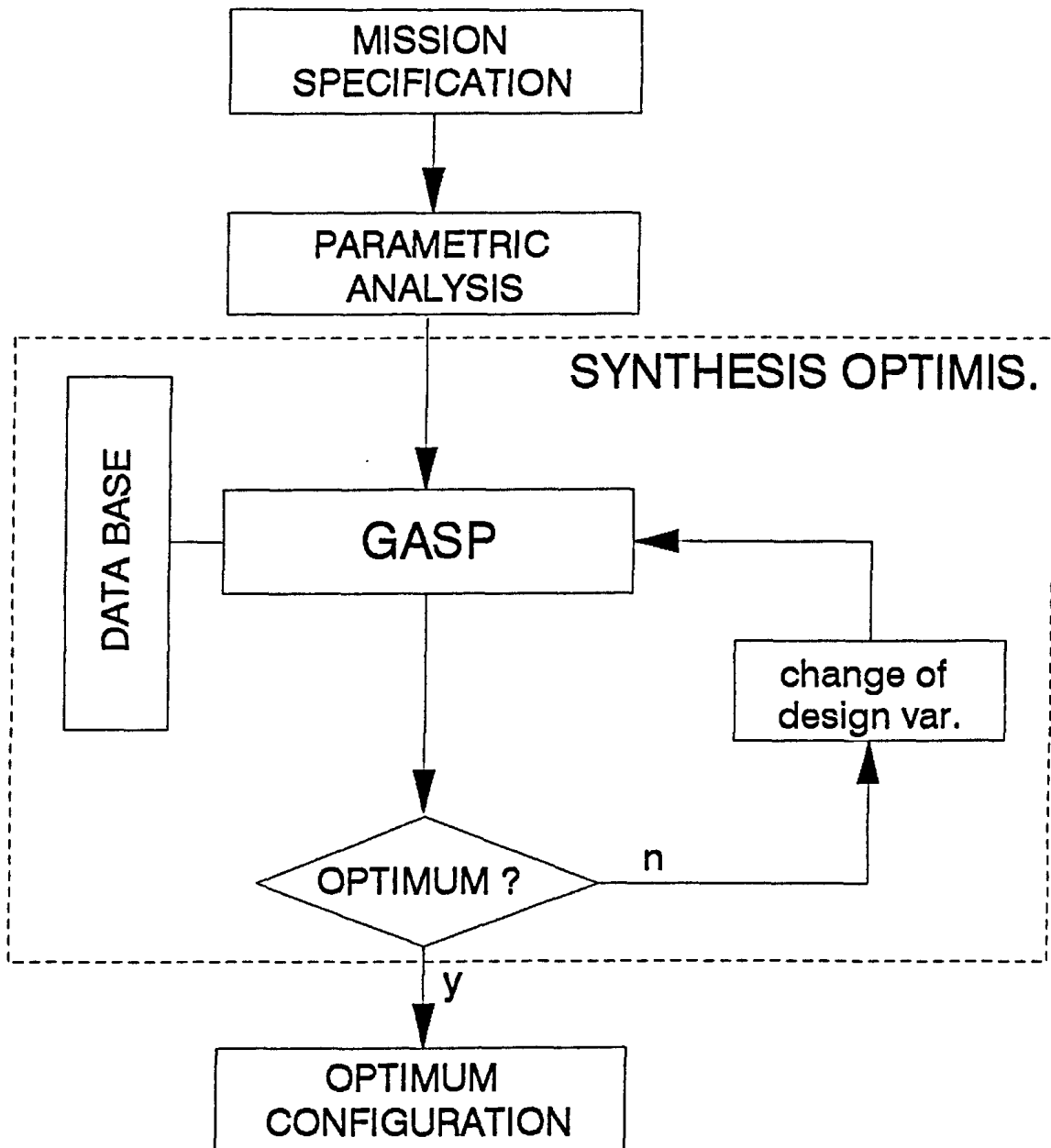


Fig 3.3 - Design Synthesis and Optimisation System Actual Flow-chart

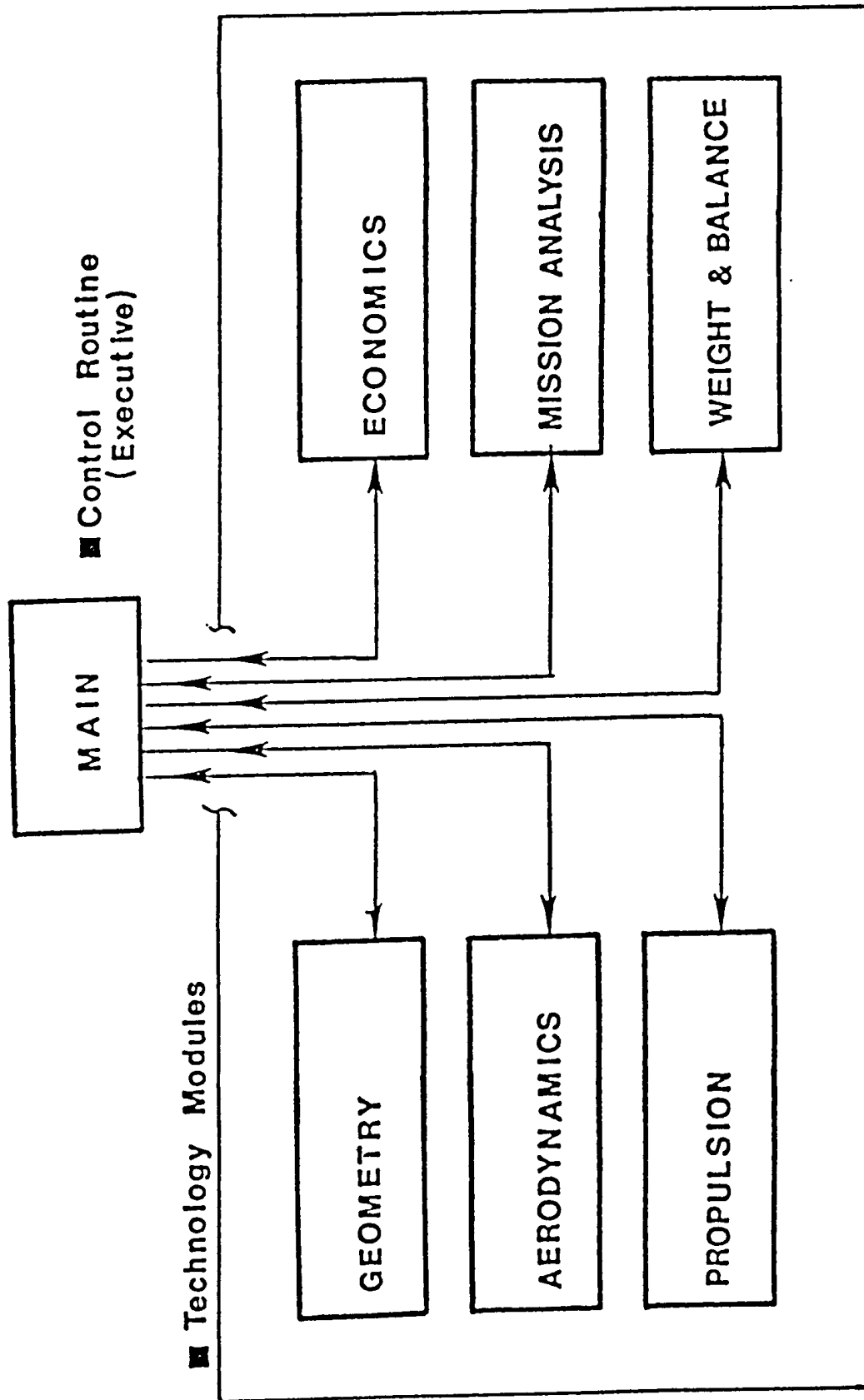


Fig 3.4 - GASP Program Structure
(reproduced from reference 19)

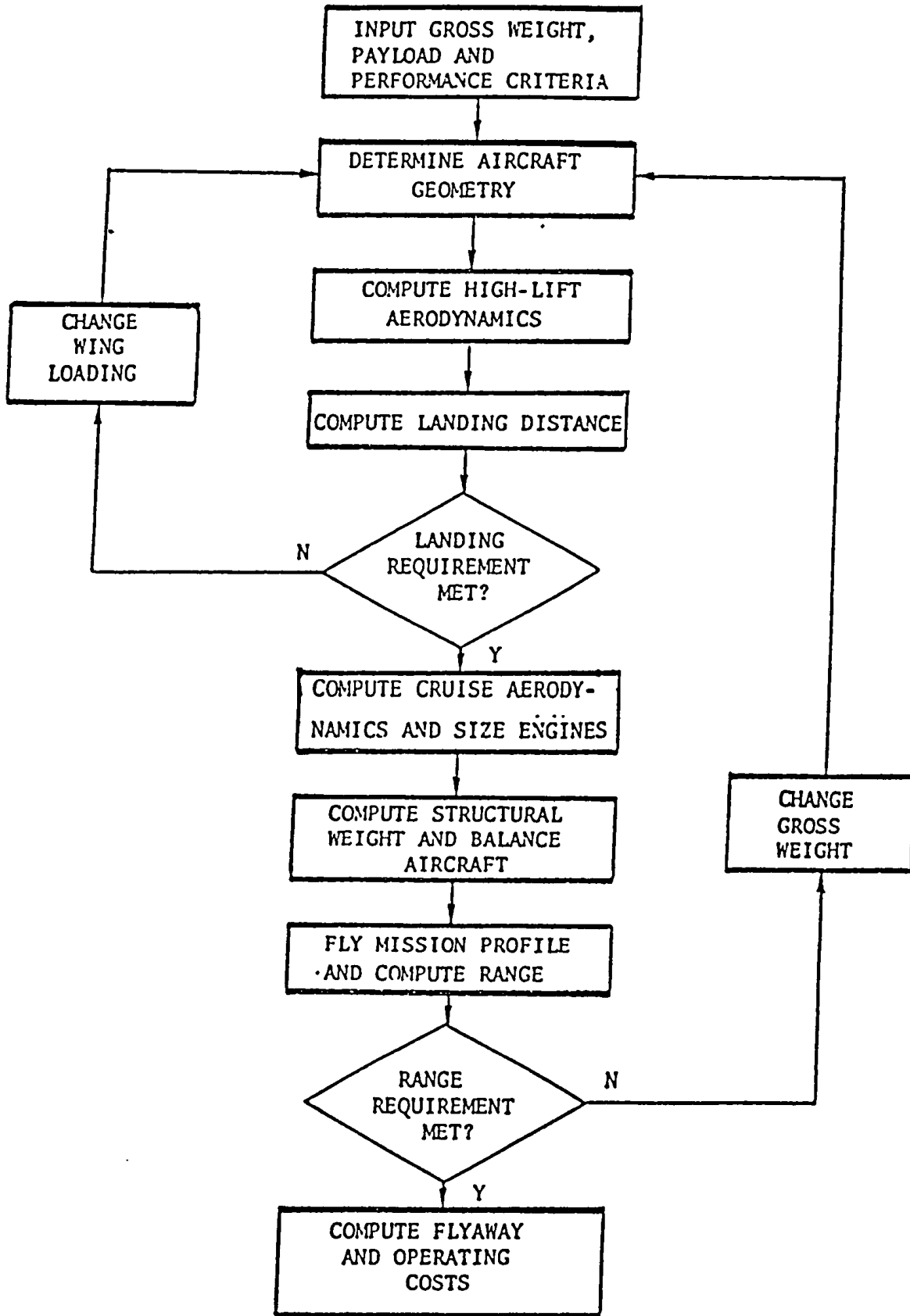


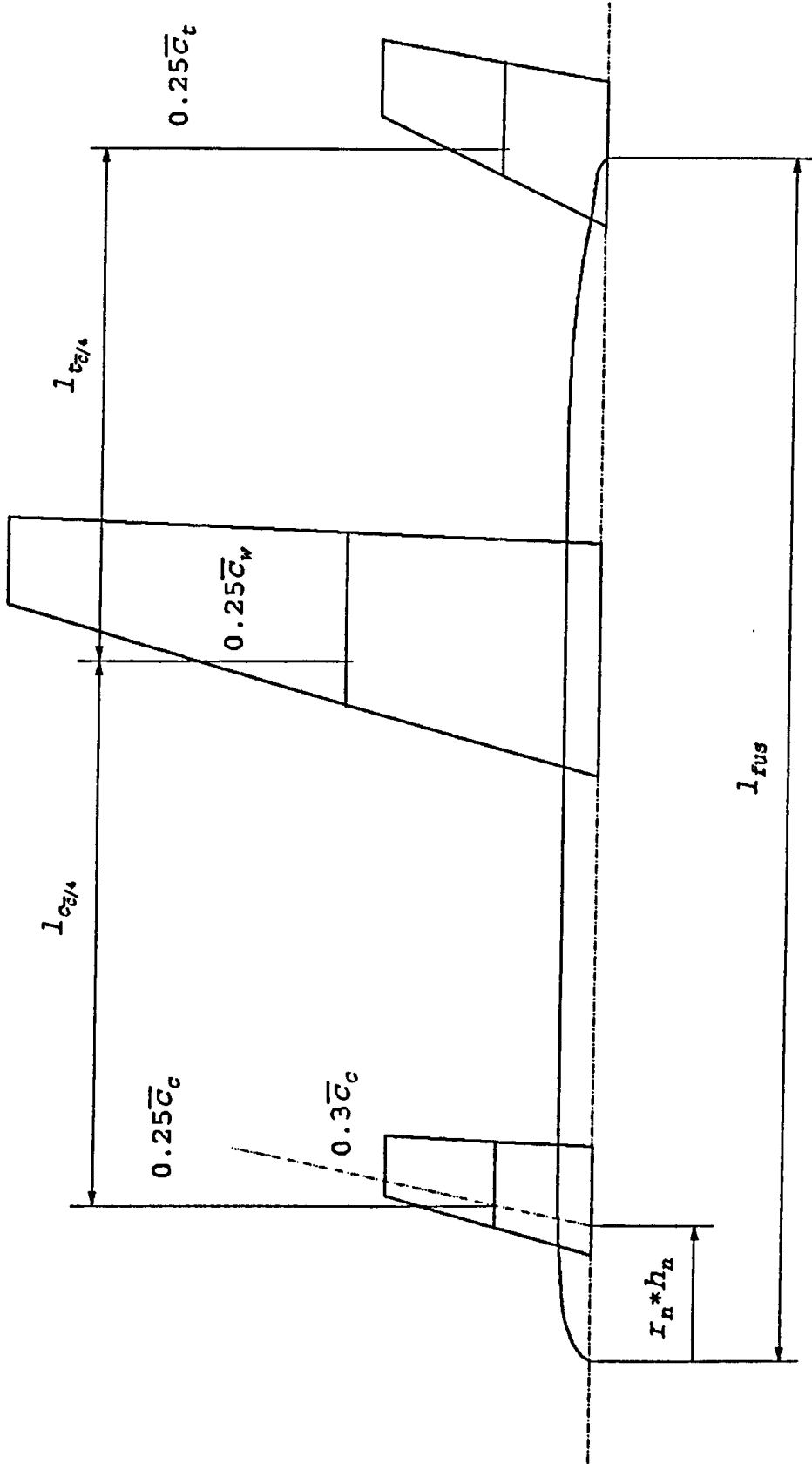
Fig 3.5 - Typical GASP Computational Flow
(reproduced from reference 19)

Purpose	Control	Geometry	Aerodynamics	Propulsion	Weight & Balance	Performance	Economics	Utilities
Program	MAIN							
Subroutines		SIZE	CTAER	ENGINE	DLOAD	PERFRM	GACOST	TPALT
			AERO	ENGSZ	WGHT	TAXI	AFCOST	OUIPUT
			DRAG	ENGD11	TAIL	TAKOFF		Cramer
			AEROUT	ENGD12	WFIXEU	CLIMB		BIV
			CLIFT	ENGD13	WTREAT	ACCEL		INTS
			FLAPS	ENGD14	ENGWGT	XRANGE		IIRLN
			EODRAG	ENGD15		TURN		IIRMHW
			APPFLP	ENGD16		DESCND		MAXMHW
				ENGD17		DLAND		BISC
				ENGD18		DERIV		MAPS
				ENGD1T		ASPEED		STORE3
				NACDG		CEILING		
				HOPWSZ		RGBAL		
				RCWSZ				

Fig 3.6 - GASP Subroutines

Program		Subroutines called														
Control	MAIN	SIZE	CTAER	AEROUT	FLAPS	ENGSZ	WGHT	ENGWGT	PERFRM	XRANGE	DLAND	RCBAL	GACOST	OUTPUT	MAPS	
Subroutines																
Geometry	SIZE	TPALT														
Aerodynamics	CTAER	AERO	DRAG	CLIFT	TPALT											
	AERO	ITRLN														
	DRAG	DRAG	CLIFT	FLAPS												
	AEROUT	TPALT	BIV	ITRLN												
	CLIFT	FLAPS	ITRMHW													
	FLAPS	ITRMHW														
Propulsion	ENGINE	ENGDT1	ENGDT2	ENGDT3	ENGDT4	ENGDT5	ENGDT6	ENGDT7	ENGDT8	ENGDTT	NACDG	ITRMHW				
	ENGSZ	DRAG	EODRAG	APPFLP	ENGINE	ENGWGT	PERFRM	TURN	CEILING	TPALT						
	ENGDT1	BIV	ITRLN													
	ENGDT2	BIV	ITRLN													
	ENGDT3	BIV	ITRLN													
	ENGDT4	BIV	ITRLN													
	ENGDT5	BIV	ITRLN													
	ENGDT6	BIV	ITRLN													
	ENGDT7	BIV	ITRLN													
	ENGDT8	BIV	ITRLN													
	ENGDTT	ITRLN														
	NACDG	BIV	ITRLN													
	HOPWSZ	ITRLN														
RCWSZ	BIV	ITRLN														
Weight & Balance	DLOAD	CTAER	ENGINE	ENGSZ	DLOAD	TAIL	WFIXEU	WTREAT	ENGWGT	ASPEED	TPALT					
	WGHT	CLIFT	ENGINE	TPALT	Cramer	BIV	ITRLN									
	TAIL	ITRLN														
	WFIXEU	ENGINE	HOPWSZ	RCWSZ												
Performance	TAXI	TAKOFF	CLIMB	ACCEL	XRANGE	TURN	DLAND									
	TAXI	ENGINE	TPALT													
	TAKOFF	DRAG	CLIFT	EODRAG	ENGINE	DERIV	TPALT	INTS								
	CLIMB	DRAG	CLIFT	ENGINE	TPALT											
	ACCEL	CTAER	DRAG	ENGINE	TPALT											
	XRANGE	CTAER	ENGINE	ACCEL	DESCND	ASPEED	TPALT	ITRMHW								
	TURN	DRAG	ENGINE	TPALT												
	DESCND	DRAG	CLIFT	ENGINE	TPALT	ITRMHW										
	DLAND	AERO	DRAG	CLIFT	ENGINE	TPALT										
	DERIV	DRAG	CLIFT													
	ASPEED	CTAER	ENGINE	TPALT	ITRMHW											
	CEILING	DRAG	ENGINE	TPALT												
	RCBAL	SIZE	CTAER	AEROUT	FLAPS	ENGSZ	WGHT	ENGWGT	PERFRM	OUTPUT						
Economics	GACOST	ENGINE	ASPEED	AFCOST	TPALT											
	AFCOST															
Utilities	TPALT	AERO	CLIFT	WFIXEU	TPALT											
	OUTPUT															
	Cramer															
	BIV	DERIV														
	INTS															
	ITRLN															
	ITRMHW															
	MAXMHW															
	BISC															
	MAPS															
STORE3																

Fig 3.7 - GASP Program and Subroutines



(Note: see also fig B1)

Fig 3.8 - Initial Canard/ Horizontal Tail Sizing

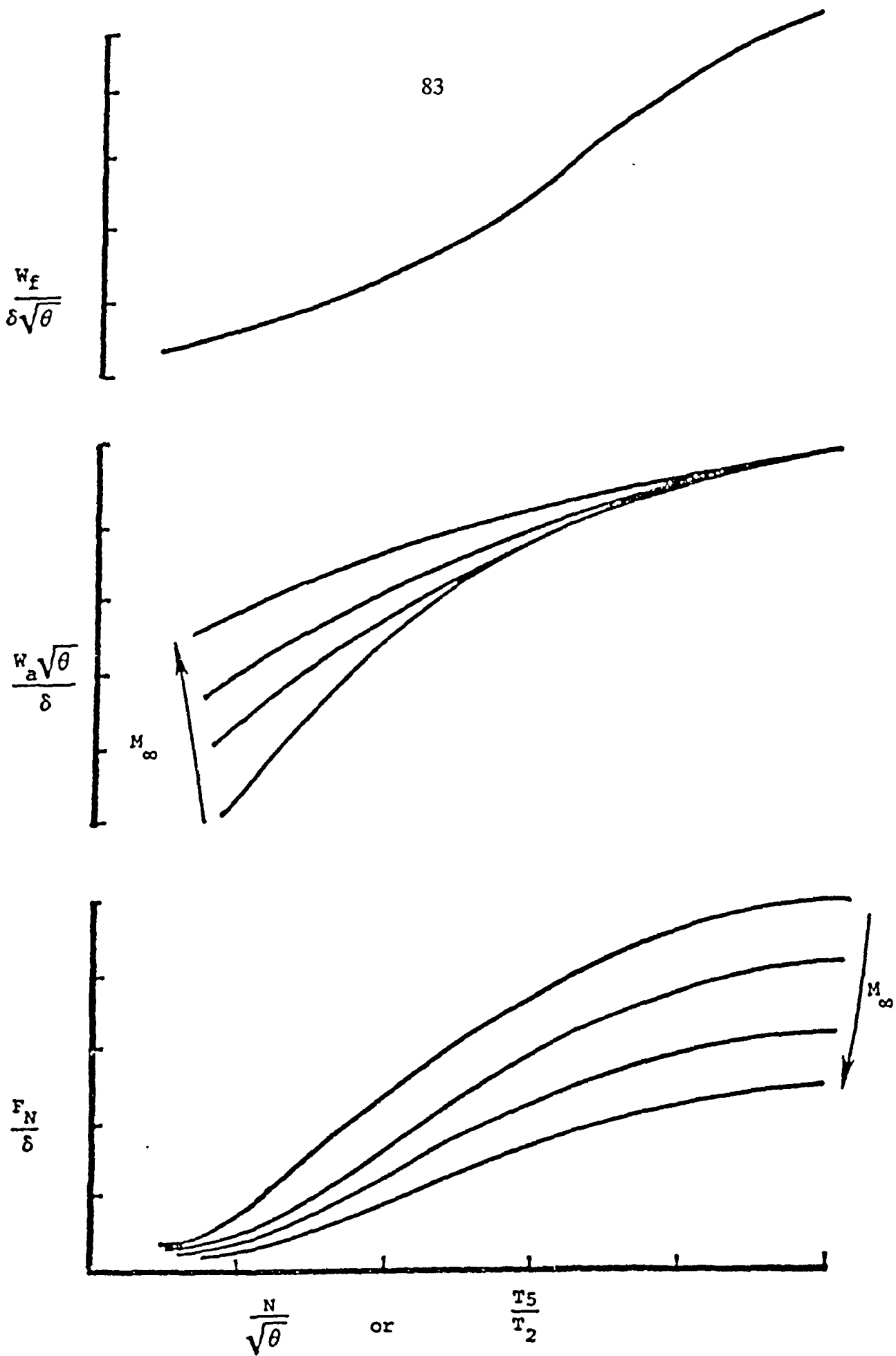


Fig 3.9 - Engine Performance
(reproduced from reference 19)

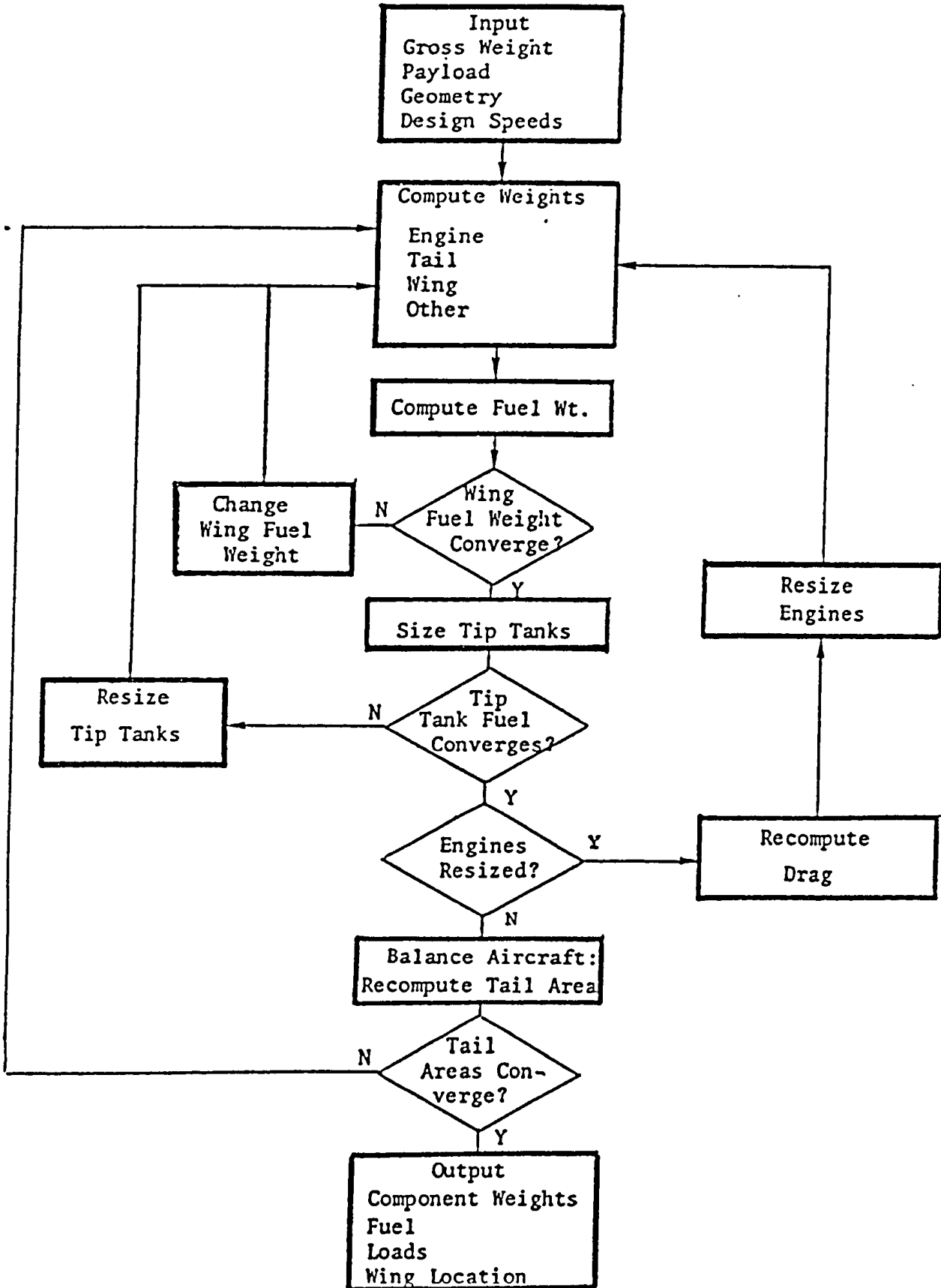


Fig 3.10 - Simplified Flow-chart for Subroutine WGHT
(reproduced from reference 19)

4 Optimisation

4.1 Problem Formulation and Minimization Technique Employed

Optimisation involves finding the best answer to a problem. Once a mathematical model of the problem has been built a suitable numerical method for finding maxima or minima may be applied. Many numerical methods of this kind generally known as mathematical programming techniques were developed in the last forty years. A more general mathematical programming problem may be formally stated as:

$$\begin{array}{lll}
 \text{minimize} & f(x) & \\
 \\
 \text{subject to} & g_i(x)=0 & (i = 1, \dots, m'), \\
 \\
 \text{and} & g_i(x) \leq 0 & (i = m'+1, \dots, m), \\
 \\
 \text{with} & L_j \leq x_j \leq U_j & (j = 1, \dots, n)
 \end{array}$$

where $f(x)$ is the objective function,

$g_i(x)$ are the constraint functions,

$x \in R^n$ is a design vector,

x_j are the problem independent variables,

and L_j and U_j are the lower and upper variable limits, respectively.

The functions $f(x)$ and $g_i(x)$ may be non-linear and the independent variables are simple lower and upper bounded.

A general purpose non-linear constrained optimisation program named Recursive Quadratic Programming MINimization (RQP MIN), developed at the Royal Aerospace Establishment (R.A.E.)⁸ intended, in particular, to perform aircraft design optimisation studies was available in the College of Aeronautics and thus it was used in the present project. As mentioned in chapter 2, the package has been extensively used in other research studies namely at R.A.E.¹, at Loughborough University of Technology⁵ and in the CoA^{2,3,4} and appears to produce good results.

The program can handle problems with up to 75 constraints and up to 50 variables. It can solve unconstrained optimisation problems as well, however limits on the independent variables must always be specified. It is assumed that the problem functions (objective and

constraints) are twice continuously differentiable. If any of the functions are linear the code takes advantage of the fact. However if all the problem functions are linear a dedicated linear programming technique is recommended for computational efficiency. As with any other mathematical programming technique the program may also be used to find the maximum of the objective function by minimising the symmetric of the objective function. The program has modular architecture comprising nearly 90 subroutines and is written in ANSI Standard Fortran 77.

The algorithm of RQPMIN is based on the Lagrange-Newton approach which implies that a stationary point of the Lagrangian function is evaluated by Newton's method⁶. This method differs from other similar methods in that it does not use a penalty function to force global convergence. Skrobanski⁷ introduces the new concept of pseudo-feasibility which assumes a trial point is rejected if the square root of the sum of the squares of the constraints is greater than the radius of pseudo-feasibility. This radius, initially defined as a relatively large figure, will only be reduced when necessary. Very often the radius of pseudo-feasibility is kept unchanged throughout the minimization process.

The numerical method is detailed in ref. 7 and ref. 8 describes its application and operation as well as the associated progress reports, diagnostic messages and detailed output.

As illustrated by the problem statement the numerical technique deals with a set of mathematical entities which can be identified as:

- External Variables (EV) - user application initial input or default design variables
- Independent Variables (IV) - external variables at the disposal of the optimisation driver
- Dependent Variables (DV) - variables evaluated as functions of the external and independent variables
- Objective Function (OF) - chosen figure of merit or cost function to be minimized or maximized by the optimiser
- Equality Constraint (EC) - function which must be satisfied by the solution. This constraint remains active throughout the optimisation process.
- Inequality Constraint (IC) - function which must be satisfied by the problem solution. This function will be active whenever it is not met by the solution vector.

4.2 Optimiser-Design Synthesis Operation

In order to set up the design optimisation system, two subroutines, USERF and USERD as well as an input data file, RQPMIN.DAT must be provided by the user. USERF will define the OF, the IVs, the ECs, and the ICs, call the design synthesis program and must return the values of the problem functions at a given point x . USERD will define the analytical derivatives of the problem functions (OF, EC and IC), only possible when explicit dependence of the problem functions on design variables is known, and return the respective values at that point. A dummy USERD should be supplied if all differentiation is to be done by finite differences. RQPMIN.DAT contains the initial values of the IVs, the upper and lower bounds and the scale factors of the IVs, the OFs, the ECs and the ICs. Scale factors are introduced to normalise their values to near unity ensuring a proper operation of the

mathematical programming algorithm. Finally a number of command and assignment keywords are included to control the operation and tune the performance of RQPMIN. Examples of these user written subroutines and input files are shown in Appendix E for the optimisation studies done.

RQPMIN starts checking for possible errors in the input file and if everything is fine proceeds with the optimisation. An initialization phase follows during which USERF and thus the GASP synthesis program are called for a number of times similar to the number of independent variables used to evaluate the objective and the constraint functions. The IVs are varied one a time allowing RQPMIN to decide on which initial search direction to head in by the end of this phase. Then a series of feasibility steps may begin where the IVs are automatically changed while the program searches for a feasible path subject to the constraints in order to start minimizing the objective function. If a feasible path is not found, the program will stop with the message 'no further progress possible' and a new set of initial IVs should be tried by the user. When a feasible path is located, a series of minimization steps is performed until a minimum of the objective function is found, satisfying the constraint functions within the prescribed tolerances and meeting the method convergence criteria.

Three types of convergence may occur:

- A - the program has located a point at which the estimated distances to the minimum of the objective function and to the minimum of the sum of the squares of the constraint functions are less than the specified tolerances;
- B - the program has located a point at which the estimated distance to the minimum of the sum of the squares of the constraint functions is less than the specified tolerance and a value of the objective function sufficiently smaller than the current value cannot be found;
- C - the program has located a point at which the estimated distance to the minimum of the sum of the squares of the constraint functions is less than the specified tolerance and no independent variables exist.

It should be noted that none of the convergence types guarantees that the numerical technique has found a valid solution nor the 'no further progress possible' message means that the run has failed. It is possible that the program stops at a saddle point of the objective function or if this function represents a design surface with many hills and valleys it can suggest that a point in a less deep valley has been found and thus it has converged on a local minimum. To check for these problems the program should be re-started from different initial design points.

During its operation, RQPMIN produces progress reports and warnings which are sent to the user's terminal and an output file. The frequency of the progress reports is controlled by a keyword given in the input file and their context relates to the successive stages of the optimisation process:

- initialization context;
- feasibility step context;

- minimization step context;
- changing to central differences context;
- final call to user routine context.

The output file consists of five sections from which two are optional:

- listing of input file (optional);
- Analysis of input file data and control parameters;
- Starting point;
- Intermediate output (optional);
- final output.

Appendix E shows the RQPMIN.RES output files for the relevant optimisations performed (1st solutions, as defined in section 5.4) where all sections are included except the first optional one. There follows a description of these sections:

Analysis of input file data and control parameters - consists of a list of all the input variables and functions in normalised format, and the RQPMIN control parameters including the default values.

Starting point - lists the initial values of the variables and problem functions in a normalised format.

Intermediate output - lists the best values of the variables and problem functions in a normalised format as found at given stages of the optimisation. The corresponding values of the Lagrange multiplier estimates, the partial derivatives of the Lagrangian function, the norms of the active constraints and the values of the various convergence criteria are also listed. This optional section is included if this information is required by the user and is activated through input control parameters specifying when it should start (iteration number) and its frequency (after how many iterations).

Final output - is similar to the intermediate output and printed when the program stops.

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5 The Case Study

5.1 The Mission Requirement

Chapter 1 introduced the reader to the topic and scope of the present investigation. It is not intended to generate optimum configuration initial designs with the aim of future production and commercialisation in response to an eventual market need or opportunity, to compete with similar type existing aircraft for the same slice of the market, but only to study potential advantages eventually offered by the usually named Three-lifting Surface configuration aircraft. In this view a very simple mission profile for a commercial transport aircraft is sought in order to base the conceptual optimum design of a familiar tail-aft configured design or conventional one and a new unconventional one. This relatively simple flight profile, although already sufficiently elaborate, will not consider any turn manoeuvres nor any air traffic control (ATC) impositions. The standard alternate airport diversion leg or any additional mission alternatives or scenarios usually considered during every serious potential aircraft initial study are not considered as well. This simplification is quite fair for that it seems not to invalidate or compromise the realistic conclusions and trends that were expected to draw.

A Turbo-fan jet transport aircraft to carry economically 50 passengers across a distance of 1250 nautical miles on a regular basis is envisioned. It was designed for a yearly utilization of 3200 hours during an expected life time of 15 years. The mission specification is summarized as follows:

Payload:	50 passengers each one at 175 lbs and 25 lbs of baggage;
Crew:	2 pilots and a cabin attendant each one at 175 lbs and 25 lbs of baggage;
Range:	1250 NM to destination (with 45 minutes of fuel reserves at cruise conditions);
Cruise altitude:	35000 ft for the design range;
Cruise Mach number:	0.8 at cruise altitude;
Climb:	direct to 35000 ft at maximum take-off weight;
Field length:	FAR Part 25 take-off field length of 6000 ft at an altitude of 5000 ft and a 95 degree F day; FAR Part 25 landing field length of 5000 ft at an altitude of 5000 ft and a 95 degree F day. (Landing performance at a landing to maximum take-off weight ratio of 0.94)
Power-plants:	two turbo-fan engines;
Pressurization:	8000 ft cabin at 40000 ft altitude;
Technology level:	conventional (no advanced technologies considered other than wing/canard supercritical aerofoil technology);
Certification Base:	FAR Part 25.

5.2 Parametric Analysis and the Initial Design

An initial parametric analysis has been performed using a Preliminary Sizing (PreSiz) program, purposely developed by the author as mentioned in Chapter 3, in order to select a credible initial design point for the subsequent GASP analysis/ synthesis evaluations. The program is based on Roskam's rapid sizing method as shown in his "Airplane Design"¹, Part I volume. Appendix C presents the input file used together with the results obtained. A brief description of the input design data is enclosed as well. The output file consists of four parts:

- the mission specification which has been analysed;
- the results of the maximum take-off, empty and fuel weight predictions;
- a sensitivity study report of the maximum take-off weight due to variations of payload, empty weight, range, endurance, cruise speed, specific fuel consumption and lift to drag ratio;
- the low speed drag polar estimations for several wing loadings and wing aspect ratios and performance tables to account for fieldlength, FAR climb, cruise speed and direct climb requirements.

Table 5.1 includes a summary of the main results obtained. Figure 5.1 illustrates the design space in terms of a thrust to weight versus wing loading diagram, where the selected initial design point for which all requirements are met is identified, laying on the intersection of the take-off and the landing performance constraints. This plot clearly shows that the design is determined not only by the two fieldlength constraints but also by the FAR Part 25 engine-out missed approach climb requirement. This is in contrast with the most usually considered 2nd segment climb requirement, and by the direct climb to cruise height requirement.

The matching results to note are:

Maximum take-off weight	= 44076 lbs
Empty weight	= 24698 lbs
Fuel weight	= 8558 lbs

Maximum lift coefficients:

Take-off CL _{max}	= 2.45
Landing CL _{max}	= 3.25

Wing aspect ratio	= 8.3
-------------------	-------

Take-off wing loading	= 83.75 lb/sqft
Wing area	= 526.3 sqft
Take-off thrust to weight ratio	= 0.345
Engine maximum static take-off thrust	= 7603 lbs

5.3 The Baseline Designs

Having brought the initial guess to the right order, two baseline concepts were evolved using the modified GASP synthesis program.

5.3.1 General Considerations

In order to better understand the implications of adding a foreplane to the aircraft the basic geometry is kept the same. So effects due to configuration changes, e.g., low and high wing, wing mounted and fuselage podded engines, will not be reflected in the results.

Examples of existing aircraft that could approximately meet the present requirement are the VFW-Fokker 28 and the Canadair CL-601 Regional Jet². Both aircraft have a low clean wing, fuselage mounted engines and a T-tail. This is the basic configuration to be adopted in the study. The aft fuselage engine installation is favoured because of the reduction in the risk of ingestion of debris at take-off and taxiing, little asymmetric thrust after engine failure, and a clean wing. Another significant reason is related to avoiding air flow disturbance likely to occur at the engine intakes due to the canard wake and tip vortices in the new configuration, if they are podded on the wing.

The fuselage is to be kept as small and compact as possible within acceptable limits consistent with comfort standards, required performance and operating costs in a way not to affect adversely the aircraft's earning capacity. A cylindrical mid-section is chosen and the general dimensions are determined by the passenger seat layout. Four-abreast seats at a pitch of 31 in and a one aisle arrangement is selected and allowances for the flight deck, passenger doors, one galley, one toilet, nose and tail cones are made.

To achieve high subsonic cruise Mach numbers consistent with low wing and canard weights, supercritical aerofoil technology is adopted with a modest rearward sweep on both lifting surfaces. Powerful double slotted Fowler flaps³ are initially selected to obtain the high maximum lift coefficients at take-off and landing needed to comply with the field performance requirements, allowing for the expected wing loading.

According to the thrust level required, about 8000 lb per engine, the General Electric CF 34 turbofan cycle, as used currently on the Canadair Regional Jet, is selected and adequately scaled during the GASP runs.

It is assumed the basic airframe is manufactured of conventional aluminium alloy materials, so all the weight trend coefficients employed in the weight prediction correlations will adequately reflect this decision. There is no need to simulating the employment of new advanced materials such as fibre-reinforced plastic composite materials. This remark extends also to any other class of advanced technologies since a comparison of two different configurations, using the same technologies and both designed according to the same ground rules, is what is needed in order to find their relative merits.

In terms of static stability it is required that both concepts have a stable longitudinal static margin of $SM = 10\%$ mac and directional stability with the yaw-moment derivative with respect to sideslip of $dC_n/d\beta = 0.002$ per degree.

The direct operating costs are calculated based on the following assumptions:

- Total Research, Development, Testing and Evaluation predicted by a Rand derived formulation (historical average number of prototype aircraft assumed);
- market potential demand of 500 aircraft of the type;
- year of costs calculations = 1993;
- annual average inflation rate of 8%;
- airframe production cost including 10% profit;
- yearly utilization of 3200 hours;
- flight crew and cabin attendants annual gross salary, including pension, overtime, subsidies and travelling computed as functions of take-off gross weight and cruise speed giving values about US\$185000 for the captain, 80% of this figure for the 1st officer and 35% for the cabin attendant, which relates roughly to current practice (these are predicted very closely by GASP correlations);
- avionic equipment cost of 4 million US dollars;
- fuel and oil costs at 85 US cents/ US gallon plus taxes worth 4.5% fuel costs;
- insurance of 0.5 % flyaway price per annum;
- maintenance labour cost of US\$23 dollars per man-hour;
- maintenance burden at 200% of the direct maintenance labour cost;
- depreciation determined as the total investment, including 6% airframe price on spares, over 15 years to 10% residual value;
- no landing fees nor average net cost of finance considered.

Noise characteristics are of prime importance if restrictions are to be avoided in the use of the aircraft. These shall meet the requirements set in FAR Part 36. These issues are not accounted for in this thesis, the reason being that the most important single factor to reduce the level of noise is the engine bypass ratio which is under the control of the designer. It is influenced not only by its design, but by its installation in a nacelle and by the aircraft design itself giving necessary take-off and landing performances (steepest take-off and approach flight paths, for example). Other measures may be used to reduce noise both at the engine design level and with proper integration with nacelles equipped with acoustic lining and/or splitter plates in the inlet and exhaust³. The selected power-plants have a high bypass ratio of 6.3², so providing adequate integration with the aircraft is achieved, noise is unlikely to cause any problems and there is already experience with the Canadair Jet with its relatively low noise level². Under these circumstances it is acceptable to neglect noise evaluations at this stage.

5.3.2 GASP Input Data and Baseline Solutions

The parameters composing the GASP input file, organised by their respective disciplinary groups, are listed below with the proposed values for the initial trial configurations, both conventional and unconventional. Additional parameters related to the modifications done in GASP, as described in Chapter 3, are shown in italics and the appropriate program control options are included as well.

Geometry

General data

Engine cycle indicator - General Electric CF 34	5
<i>Conventional (0) or Three-Lifting Surface concept (1) (option)</i>	
take-off gross weight (initial guess) [lb]	44050
take-off wing loading (initial guess) [lb/sqft]	83
number of passengers	50
design cruise Mach number	0.8
design cruise altitude [ft]	35000
number of engines	2

Fuselage data

seats abreast in fuselage	4
seat width [in]	20
number of aisles	1
aisle width [in]	19
seat pitch [in]	31
length of flight deck plus passenger door allowance [ft]	11.22
mean fuselage diameter minus nose cone max. diameter [ft] (\approx windscreen height)	2.47
fuselage nose cone fineness ratio	1
fuselage tail cone fineness ratio (assuming allowances for galley, toilet and rear passenger door)	3.2

Nacelle

nacelle drag assumed as part of aircraft drag (option)	1
length of pylon attachment for fuselage mounted engines [ft]	10

Wing

wing aspect ratio	8.3
wing tip thickness to chord ratio	0.10
wing root thickness to chord ratio	0.13
wing taper ratio	0.20
sweep of wing 1/4 chord [degrees]	14.5
wing incidence to fuselage horizontal datum line [degrees]	2

Canard

<i>canard aspect ratio</i>	<i>5.5</i>
<i>canard thickness to chord ratio</i>	<i>0.10</i>
<i>canard taper ratio</i>	<i>0.50</i>
<i>sweep of canard 1/4 chord [degrees]</i>	<i>15</i>
<i>canard incidence to fuselage horizontal datum line [degrees]</i>	<i>2</i>

canard to wing area ratio 0.145

Horizontal tail

location of tailplane on vertical fin as a fraction of fin span 1
 tailplane aspect ratio 4
 tailplane thickness to chord ratio 0.10
 tailplane taper ratio (initial value) 0.55
 sweep of tailplane 1/4 chord [degrees] 27.5

Vertical tail

fin aspect ratio 1
 fin thickness to chord ratio 0.12
 fin taper ratio 0.70
 sweep of fin 1/4 chord [degrees] 50.5

Aerodynamics

number of points in wing/ canard profile drag table 12
 values of C_L in wing/canard profile drag table:
 -1.0, -0.6, -0.4, -0.2, 0, 0.1, 0.2, 0.4, 0.6, 0.8, 1, 1.2
 normalized wing/canard profile drag values in wing/canard profile drag table:
 2.400, 1.466, 1.221, 1.066, 1.005, 1.000, 1.005, 1.046, 1.138, 1.333, 1.743, 2.718
 increment in overall drag coefficient 0.0015
 increment in equivalent flat plate area of fuselage [sqft] 0.2
 shift in drag divergence Mach number due to supercritical aerofoil design 0.75
 increment in wetted area/wing area 0
 wing zero lift angle of attack [degrees] -1.6
 program computes increment in drag coefficient due to engine out (option) -1
 maximum clean basic wing lift coefficient at reference conditions⁴ 1.2
 altitude for Reynolds number calculation (field conditions) [ft] 5000
wing pitching moment coefficient -0.06
canard aerodynamic form factor (control value) -1
canard zero lift angle of attack [degrees] -1.0

Flaps

number of flap segments per wing panel 1
 fraction of wing span without flaps due to wing mounted engines 0
 double slotted Fowler flaps (selection) 7
 take-off flap deflection [degrees] 15
 landing flap deflection [degrees] 40
 flap chord to wing chord ratio 0.30
 flap span to wing span ratio 0.75

Propulsion

engines sized for cruise, take-off and climb (option)	2
FAR Part 25 turbine propulsion sizing requirements (option)	1
engine power setting during take-off, maximum power (option)	5
engine power setting during climb, maximum climb power (option)	7
engine power setting during acceleration, maximum power (option)	5
take-off field altitude [ft]	5000
increment in take-off ambient temperature above ISA standard day [degree F]	36
required rate of climb at cruise conditions [fpm]	50
required take-off distance to 35 ft (not constrained)	99999
engine face sea level static Mach number	0.5
engine face hub/tip ratio	0.437
ratio of cruise weight to maximum take-off gross weight (for engine sizing)	0.97
engine out service ceiling required [ft]	0
input maximum static thrust for one engine (if engine known) [lb]	0
inlet pressure recovery factor	1

Weights

weight trend coefficient of engine installation, fraction of dry engine	0.135
weight trend coefficient of landing gear, fraction of gross weight	0.038
main gear weight fraction of landing gear weight	0.8
weight trend coefficient of engine nacelle, fraction of dry engine	0.338
weight per passenger including luggage [lb]	200
wing/canard strut attachment point, fraction of semi-span (for cantilever wing/canard = 0)	0
incremental control group weight [lb]	0
weight trend coefficient of horizontal tail	0.18
weight trend coefficient of vertical tail	0.22
weight trend coefficient of wing and canard, excluding high lift devices	133.4
location of main gear on wing, fraction of wing semi-span	0.25
engine c.g. fraction of fuselage length (for fuselage mounted engines)	0.75
c.g. of fuselage and contents, fraction of fuselage length	0.45
transport design structural category, FAR Part 25 (used to determine allowable load factors and design speeds)	3
maximum operating design flight speed, structural [mph]	685
weight trend coefficient of fuselage	107
weight trend coefficient of cockpit controls	20
weight trend coefficient of fixed wing controls	0.43
weight of stability augmentation system [lb]	0
engine c.g. in relation to the leading edge of the wing mean aerodynamic chord (mac),as a fraction of mac, for wing mounted engines, positive aft	0
wing/canard c.g. with respect to mac quarter chord point, fraction of mac	0.2
aircraft c.g. with respect to mac quarter chord point, fraction of mac	0
fuselage pressure differential in order to maintain an 8000 ft cabin at 40000 ft altitude [psi]	8.2
location of engines on wing (on fuselage = 0)	0

weight trend coefficient for fuel system	0.02
fraction of total theoretical wing volume used for wing fuel	0.43
program computes fwd and aft c.g. limits and sizes canard and, or horizontal and vertical tail for stability and control	2
incremental structural weight [lb]	0
dry weight of one engine, function of engine size [lb]	0
engine specific weight [lb/lb _{Thrust}]	0.16
weight of one nacelle, function of engine size [lb]	0
nacelle weight to nacelle surface area ratio [lb/sqft]	2.287
weight of one pylon, function of engine size [lb]	0
factor for turbofan engine pylon weight	0.7
nacelle length to diameter ratio	3

Stability and Control (Canard and/or Tail Sizing)

<i>controls free (0) or controls locked (1) (option)</i>	1
pitching moment coefficient about centre of gravity due to all engines during landing (direct thrust effect only)	0
aircraft static margin, fraction of mac	0.1
elevator chord to horizontal tail chord ratio	0.35
maximum up elevator deflection, negative for trailing edge up (degrees) -25	0
tailplane incidence angle relative to fuselage horizontal datum line (degrees)	0
vertical position of thrust line relative to c.g., positive for thrust below c.g.	0
distance of main wheel contact point aft of mac leading edge, fraction of mac	0.52
low wing position on fuselage	0
required directional stability of aircraft, function of take-off gross weight and wing span [degree ⁻¹]	0.002
rudder chord to vertical tail chord	0.30
ratio of minimum control speed to stall speed in take-off configuration	0.99
maximum rudder deflection [degrees]	25
<i>canardvator chord to canard chord ratio</i>	0.35
<i>jet-flow inclination contribution to the aircraft longitudinal static stability</i>	0.03

Performance

Taxi

time spent taxiing before take-off and after landing [hr]	0.1666
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Take-off

program computes full mission (option)	1
program computes engine-out and acceleration/ stop distance (option)	0
maximum allowable fuselage floor angle [degrees]	15
altitude at start of mission [ft]	5000
maximum load factor during take-off rotation	1.1
estimate of time required to rotate aircraft during take-off [sec]	3.5
increment of engine failure decision speed above stall [kt]	5

increment of take-off rotation speed above engine failure decision speed [kt]	5
ratio of allowable lift-off speed to stall speed	1.1
coefficient of rolling friction	0.02
coefficient of braking friction	0.4
increment in take-off ambient temperature above ISA standard day [degree F]	36
terminal altitude for take-off segment [ft]	500

Climb

climb at maximum rate of climb (option)	1
altitude increment during climb [ft]	1000

Cruise

cruise flown at speed at normal rated cruise power, for cost and range calculation (option)	1
hold wing loading fixed during range balance (option)	0
required fuel reserve, fraction of 45 min	1
required design range [NM]	1250
off-design mission altitude [ft]	25000
off-design specified Mach number	0.5
maximum take-off gross weight scale factor for range balance iterations (default function of gross weight and range)	0.80

Landing

landing weight as a fraction of gross weight (option)	2
increment in landing ambient temperature above ISA standard day (degree F)	36
time delay for brake and reverse thrust application during landing (sec)	1
wing height above ground during ground run (ft)	5.5
required landing distance (not constrained)	99999
altitude of landing field (ft)	5000
ratio of landing weight to maximum take-off gross weight	0.94
ratio of approach speed to stall speed	1.3
maximum allowable rate of sink during approach [ft/min]	1000
ratio of reverse thrust to idle thrust during landing	0
ratio of touchdown speed to stall speed	1.15
obstacle height (ft)	50
landing touchdown sink rate (ft/sec)	3
landing flare load factor	1.2

Costs

additional equipment cost as a function of base cost (option)	1
year of cost calculation	1993
cost of avionic equipment (million US\$)	4
aircraft utilization per year (hr/annum)	3200
fuel cost (US\$/US gallon)	0.85

insurance as a fraction of flyaway price per annum	0.005
maintenance burden factor	2
aircraft residual value as a fraction of initial value	0.10
aircraft depreciation period [years]	15
production quantity	500
maintenance labour cost (US\$/man-hour)	23
annual average inflation rate	0.08

It is worth noting that the canard related parameters are only used if the unconventional concept design synthesis option is used.

The above GASP input data list was employed on both the concept baseline designs and for the optimisations. However some small changes were required. These were concerned with the concept option actually taken, the three-surface configuration initial lifting surface loading required to obtain the same result as found for the conventional aircraft in the baseline design case, and with the convergence adjustable weight scale factor which is arbitrarily changed to approximate the configuration design range closer to the required range. The latter may be changed for other reasons to be explained in section 5.4.

Appendix D includes the detailed GASP results for the two baseline configurations while table 5.1 summarizes the main results obtained including those found during the initial parametric analysis. Figures 5.2 and 5.3 show the airliner three view sketches corresponding, respectively, to the classical and to the three-surface designs. The sketches were produced using Raymer's RDS-Student CAD program⁵.

5.4 The Optimised Designs

5.4.1 General Considerations

The search for the best feasible design must be based on a quantifiable criterion, single or compounded, usually called the figure of merit. The performance index, the cost function or the objective function describing the design problem lend themselves to quantification. In commercial aviation the most commonly used are the Direct Operating Costs (DOC) at the design range or the Maximum Take-off Weight (MTOW). For the airlines the former forms a more relevant criterion since it reflects the aircraft economic potential^{8,9}. Both objective functions are used in the present study.

5.4.2 Setting up the Tool

The optimisation technique has three main functions:

- Receive the results from the synthesis evaluation and interpret the data in the light of the previous design iterations;
- Decide which design variables should be perturbed, how large the perturbations should be, and repeat the design synthesis with the new design variables;

- Find whether the chosen perturbations succeed in moving towards the optimum solution, and repeat the iterations until the optimisation of the objective function has been achieved or the search has proved to be fruitless.

As described in Chapter 4 and shown in Appendix E, the user written subroutines USERF and USERD, and the RQPMIN.DAT file were developed following the recommendations set in ref. 6. This reference should be consulted for any details not presented here. USERF assigns the design independent variables, calls the design synthesis program, and defines the objective and the selected constraint functions.

The independent variables chosen for the optimisations, both for the conventional and the three-surface configurations, are listed below where the additional variables related with the latter one are in italics (the adopted variable lower and upper bounds as shown in the RQPMIN.DAT input file are also included):

wing loading [lb/sqft]	[80,105]
wing aspect ratio	[8,10]
wing quarter chord sweep angle [degrees]	[11,35]
wing taper ratio	[0.16,0.31]
horizontal tail aspect ratio	[3.8,4.3]
horizontal tail quarter chord sweep angle [degrees]	[20,35]
vertical tail aspect ratio	[0.8,1.2]
vertical tail quarter chord sweep angle [degrees]	[40,53]
<i>canard aspect ratio</i>	<i>[4,8]</i>
<i>canard quarter chord sweep angle [degrees]</i>	<i>[10,35]</i>
<i>canard taper ratio</i>	<i>[0.16,0.7]</i>
<i>canard incidence angle [degrees]</i>	<i>[0,3]</i>
<i>canard over wing area ratio</i>	<i>[0.145,0.175]</i>
<i>engine c.g. location as a fraction of fuselage length</i>	<i>[0.75,0.85]</i>

The constraint functions reflect the low speed field performances and cruise performance boundary limits of the design space in the form of inequalities. These functions and their extreme values are:

FAR Part 25 take-off distance [ft]	(maximum value = 6000)
FAR Part 25 landing distance [ft]	(maximum value = 5000)
approach speed [knots], EAS	(maximum value = 125)
cruise Mach number	(minimum value = 0.76, maximum value = 0.86)

The objective function, either DOC or MTOW, is defined according to the criterion the design is to be optimised for.

Since no analytical derivatives exist for the problem functions, that is the objective and constraint functions with respect to the design variables, a void USERD subroutine is included and the driver will evaluate them by finite differences whenever necessary.

The starting point, or initial estimate of the solution, for all the optimisations performed and defined in the optimiser input file, corresponds to that of the baseline

configurations. These are feasible designs satisfying all the constraints as obtained with GASP when working as a stand-alone program, and described in the previous section.

5.4.3 Optimisation Results

Several local "optimum" solutions were obtained either for minimum DOC and minimum MTOW for both concepts. Generally speaking convergence of the numerical algorithm was achieved within 6% and 4% of the lowest obtained figure of merit, respectively, for the conventional and for the three-surface configurations. Most convergences were of the B type, although many A type were obtained while optimising the three-surface design for minimum weight. No C type convergence occurred.

For all the cases considered figure E1, in Appendix E, summarises the "best" solutions obtained at this stage and calls them 1st solutions. Listings of the next closest to the "best" are included as well, and are named 2nd and 3rd solutions. In addition to the values corresponding to the initial and the convergence point design variables and respective functions, objective and constraints, information on the convergence type, CPU time and number of function evaluations (nfe) per run is given. (nfe) corresponds to the number of times the GASP program was called by RQPMIN. Several "optimum" solutions achieved show the complex nature of the design surface, which is typical of complex practical engineering systems design problems where multiple local optimum solutions are usually found. This may be an advantage since it allows the designer additional freedom to select the most suitable solution among many other "good" solutions. This behaviour was previously explained in Chapter 4 when the convergence criteria were introduced. However a recommendation was then given for checking purposes to re-start the optimisation from a different starting point. It was found during the initial trial runs, after setting up the system, that the convergence of the numerical method was very sensitive to the slightest change in the initial design variables, and on their lower and upper bounds. To keep the starting point virtually unchanged in terms of the RQPMIN interface, it was decided to change, in successive optimisation runs, the weight scale factor in the GASP input file which controls the precision in the synthesis range-balance iterations. Effectively this produces slightly different results from the design program and acts as if the optimisation actually started from a different starting point. This was the procedure used for checking the optimum design point result and search for better results.

Detailed GASP result listings of the two optimised configurations, both for minimum DOC and minimum MTOW, are also included in Appendix E, while table 5.1 presents a summary of their main characteristics together with the initial parametric analysis results and the baseline designs data. Figures 5.4, 5.5, 5.6 and 5.7 show the airliner three view sketches corresponding to the four optimised designs. A comparison of the cruise drag polars obtained for the baseline and minimum DOC datum designs is illustrated in fig 5.13.

5.4.4 Method Idiosyncrasy and Graphical Displays

Optimum results were obtained only with difficulty. The reasons as understood by the author were due to several factors, some of them may be attributed to:

- the complexity of the engineering design model itself, in particular where the three surface design case is concerned. When trying to match the three lifting surfaces sizing with the required stability and control requirements, for some combinations of the design variables, the process diverged and as a result the solution was lost.

- numerical difficulties associated with the mathematical technique itself. While trying to find or adjust the direction of a feasible path, for instance, during the evaluation of function derivatives at a point where the design surface has sharp ridges or saddle points, it was found that it produced wrong perturbations on the design variables used in the next iteration.

- inability of the minimization package to identify bad moves, and thus in discarding wrong steps in the light of sudden surges of the figure of merit. A 'memory' capability, if implemented, would significantly improve the performance of the mathematical programming method by reducing markedly the number of iterations to convergence and computation time.

- difficulties associated with meeting the method convergence criteria which are intimately related with the characteristics of the design surface topology. Proper tolerances to the problem functions had to be carefully chosen in a way so as not to compromise meaningful results or making convergence impossible. There were cases where the program converged on a solution by numerically violating one of the constraints (for example, all the three optimum local solutions as determined for the minimum MTOW three-surface configurations, as shown in Appendix E, fig E1). Doubts on the proper operation of RQPMIN arose. In one case, it happened however that a particular design point had been previously assessed by the optimiser during the process of minimization without satisfying the convergence criteria. Later, convergence was achieved on the very same design point, which suggested that the minimum solution of the objective function had been determined, with a probably very tight tolerance. Although, in view of the accuracy of a design synthesis model for initial preliminary studies, the tolerance used and the magnitude of the constraint violation were considered of no significance for practical purposes, and the result acceptable.

5.4.5 A Quest for Transparency and Efficiency in the Design Optimisation Process

An appropriate graphics capability would be useful to allow the user to monitor the optimisation progress and stop it when no improvement on the performance index is experienced. Histories of the objective function, constraint functions and design variables are a convenient way of learning more about the design problem, draw conclusions and help the designer's decision making. To illustrate some advantages of using graphical displays and the insights gained concerning the problem behaviour, together with the particular behaviour of RQPMIN, some comments are appropriate on to the historical diagrams contained in Appendix F. For illustrative purposes this Appendix shows the convergence histories of the problem functions and design variables for the direct operating costs optimisation cases (first solutions) performed on both configurations.

In the case of the conventional configuration, figure F1, and in spite of the apparent randomness or noise in the engineering processes, the numerical method is seen to fail to converge for three times before actually stopping on the method "optimum" solution. If a close analysis on the progress of the objective and constraint functions, as well as on the design variables controlled by the algorithm is exercised, it will be concluded that iteration number 487 corresponds virtually to the same point as the final convergence. Deliberately stopping the process at that point or on iterations numbers 386, 577 and 718 solutions very close to the optimum design solution would be determined, since they tend to stabilize after those points before the occurrence of sudden large excursions whose probable explanation is given above. Other comments can be drawn in particular to the evolution of the MTOW. In fact, the history of the objective function diagram shows a very close reduction trend on the MTOW, although this is more prone to wild variations in contrast to the small randomness experienced by the DOC function. This behaviour may be explained in part if not a great difference exists on the best solution when the optimisation is performed with regard to the minimum MTOW. The constraint history diagrams show that none of them were violated, so they remained inactive during the complete run and could be ignored. Thus this particular problem could be treated such as any simpler unconstrained problem, reducing the computational effort and time. Looking at the design variables' evolution, it can be noticed that the wing loading increases until reaching iteration number 216 after which it remains almost constant on its upper bound up to when convergence is achieved. It means that this variable could have been assigned a fixed value at that point, reducing the number of design variables to be optimised. This action would help problem simplification, and speed up the design optimisation process without affecting its result, and with minimum computational costs.

Similar considerations can be expressed by looking at the historical diagrams related to the optimisation of the three-surface concept with respect to minimum DOC, as shown on figure F2. The objective function and the MTOW curves display very similar reduction trend patterns, reinforcing the same feeling that no major difference would be produced by choosing any performance index between the two. The constraints' histories suggest that cruise Mach number could be ignored since it does not influence the optimisation process. The FAR Part 25 take-off distance requirement is the critical one and both the landing distance and the approach speed are very close to their imposed limit boundaries. A close look at the design variables suggests that the wing quarter chord sweep could have been ignored since it stabilizes on about the same value after iteration number 336 as was assumed for its starting value. After iteration number 386 the optimisation could be stopped. All the function and variable values seemed to converge and stabilize very closely to the "optimum" converged point until an abrupt departure occurred at iteration number 415, violating all the three critical constraints, and leading to another subsidence towards stable values at about iteration number 561. At this point the program could again be stopped before the mathematical convergence criteria were satisfied.

The difficulty associated with the selection of the tolerances on the objective and constraint functions required by the convergence criteria, and referred to above, was detected while optimising the three-surface concept to minimum MTOW. This case, corresponding to the last column of table 5.1, is not illustrated by historical diagrams. Here the system converged at iteration number 1348 on a solution, violating the take-off distance constraint. This solution had virtually occurred previously at iteration number 1000 without satisfying

the convergence criteria. This fact may suggest that the convergence is not easily satisfied due to a very small tolerance imposed on the problem functions. On the other hand it appears that there is some inconsistency in the coding of the convergence criteria, since convergence actually occurred while violating one of the constraints. It is the author's opinion that theoretically convergence shouldn't have occurred because, numerically speaking, the solution is unfeasible.

An interactive design optimisation capability, such as exemplified by IDESIGN software⁷, would considerably improve the visibility of the design optimisation process. Owing to increased transparency, design contending effects become more clear, improving the designer's understanding as well as his learning process. This helps the user to refine the problem formulation and to accelerate the optimum design. Additionally, any potential numerical difficulties in the optimising algorithm may be identified.

5.4.6 Reflection on the Performance Index and Optimum Results

The considerations made above concerning the adoption of the performance index, DOC or MTOW, can be substantiated by the results on table 5.1 where the conventional design optimised for both figures of merit show the same DOC while the respective MTOWs are close within 0.15%. However for the unconventional case, the DOCs are within 1.1% and the MTOW results differ by 1.2%. It is the author's opinion that the latter differences may turn out to be irrelevant if a better local result could be achieved for the three-surface aircraft optimised for minimum weight. It should be noted that in this particular case the minimum weight came up slightly higher than the weight obtained for the minimum DOC optimisation, reflecting the local nature of the optimum results rather than the desired global or absolute optimum.

The results obtained at this stage enable one to say that optimisations performed for minimum DOC or minimum MTOW produce approximately the same optimum design solutions for each concept (assuming the design range of 1250 NM and the adopted economic assumptions).

5.5 Range Trade-off Studies

To assess the relative worth of the several designs obtained thus far, a series of range trade-off studies was conducted for design ranges, ranging from 1000 to 3000 nautical miles at 250 NM intervals.

These studies were performed using GASP program with input files related to the baseline and to the optimised configuration solutions, the only difference being the required design range. The aircraft families so obtained maintain the same take-off wing loading and the same overall geometry as the datum aircraft (Range=1250 NM), thus, for the particular case in consideration the transports look alike apart for the lifting surface areas which increase with weight. No restrictions were imposed on the take-off and landing field lengths. Tables 5.2, 5.3, 5.4, 5.5, 5.6 and 5.7 include the main characteristics of these designs.

Plots of DOC and MTOW versus range were prepared for both the conventional and the three-lifting surface configurations (baseline and optimised designs) related to the conventional datum and are shown for each case on figures 5.8.1, 5.8.2, 5.9.1, 5.9.2, 5.10.1 and 5.10.2. Benefits on DOC and MTOW of the unconventional design with respect to the corresponding classical one are shown on figures 5.8.3, 5.9.3 and 5.10.3.

DOC and MTOW range trade-offs for the configurations optimised for minimum DOC are presented in figures 5.11.1 and 5.11.2 and compared to the baseline design curves. All results are normalised to those of the baseline conventional datum design. Benefits on DOC and MTOW of the minimum DOC configurations with regard to the conventional and to the three-surface baseline designs are shown respectively on figures 5.11.3 and 5.11.4. The same for the minimum MTOW configurations is illustrated in figures 5.12.1 and 5.12.2, 5.12.3 and 5.12.4, respectively.

5.5.1 Baseline Designs

As stated above, the wing loading on both baseline configurations was kept unchanged, $W/S = 83 \text{ lb/sqft}$, while generating the aircraft families to meet the required design ranges. Taking into account the particular range in consideration all designs satisfy all the other initial requirement constraints with the exception of the three-surface aircraft synthesised for a design range of 3000 NM, which marginally exceeds the FAR Part 25 Take-off field length by 1.05% ($= 6062.9 \text{ ft}$).

Figure 5.8.1 shows that the conventional designs offer a minimum DOC for a design range of 1500 NM which increases parabolically for both lower and higher ranges. The three-surface design shows a similar trend with a minimum DOC at a design range of 1750 NM, corresponding to a DOC saving of 5.5% with regard to that of the same range conventional design (fig 5.8.3). This graph, fig 5.8.1, shows that whilst the three-surface design DOC is more sensitive at shorter ranges than the conventional one, it offers clear advantage for higher ranges since its DOC curve shows smaller differences with regard to range than that of the conventional design. Ultimately, at a range of 3000 NM, the three-surface baseline offers a saving in DOC of about 7.9% as seen on figure 5.8.3 which turns out to correspond roughly to an annual saving of nearly US\$315000, assuming the cost assumptions employed are accepted. Figure 5.8.3 shows that, for the baseline designs, DOC benefit can be obtained from the operation of a three-surface configuration which increases linearly from a minimum of 4.1% at a design range of 1000 NM up to nearly 8% at 3000 NM range. With regard to the M.T.O.W for all ranges considered the unconventional design MTOW is lower than that for its conventional counterpart as seen on figure 5.8.2. Comparing both concepts with the conventional baseline datum ($R = 1250 \text{ NM}$), MTOW growths of 40.3% and 30.2% respectively for the conventional and for the three-surface designs at a design range of 3000 NM are visualized. Roughly speaking and in a similar manner as for the DOC, it can be said that the difference in weight increase with range results in a weight reduction of about 7.2% being achieved for the three-surface at the upper extreme design range simulated. At the datum range its weight benefit is about 4.5%.

5.5.2 DOC and MTOW Optimised Designs

The search for the best compromise consistent with the initial mission specification,

satisfying field and cruise performance, stability and control requirements and also meeting the FAR regulations while minimizing the DOC or the MTOW, would probably entail a change in wing loading on every case driven by RQPMIN. In fact, for the design datum range ($R=1250$ NM), tables 5.4 through 5.7 show that the minimum DOC or minimum MTOW is achieved by an increase of the wing loading corresponding to a decrease in the aircraft lifting surface areas and respective weights, at an expense of the aircraft field performance.

Tables 5.4 and 5.6, for the conventional optimised designs, show that the "optimal" corresponds to a wing loading of 105 lb/sqft which is the upper limit imposed on this design variable, as indicated in section 5.4. This limit was chosen for empirical reasons assuming it represents already a relatively high value for practical purposes when compared to that adopted on equivalent type aircraft (Ex.: Fokker F28 W/S = 85.88 lb/sqft; Canadair RJ 100 W/S = 80.82 lb/sqft and RJ 100 ER W/S = 86.87 lb/sqft).

Tables 5.5 and 5.7 related to the three-surface optimisation show that the "optimal" is constrained by the FAR take-off field length without approaching the upper wing loading bound. When conducting the range trade-off studies the field length constraints were relaxed, i.e. unconstrained, since they do not seem to change the objective of the research in a meaningful manner. This led to easing and speeding up the several design synthesis runs. In this way it is shown in the same tables, that for ranges above the specification range all the unconventional designs violate the take-off field length while the conventional designs only violate it for ranges equal or above 2250 NM. The maximum violation occurs for the three-surface optimised for minimum MTOW at a design range of 3000 NM with a take-off field length of 6660.8 ft which corresponds to 11% above the specification value. Having in mind the required range, this difference may turn to be insignificant in practical terms.

Regarding the optimised designs trade-offs, figures 5.9 and 5.10 deserve the same qualitative considerations as developed above for the baseline studies shown on figure 5.8. The effect of the range trade-offs performed with the MTOW optimised designs on the DOC, figure 5.10.1 may seem strange. Recalling that the three-surface DOC curve grows faster for lower ranges than happens for the conventional counterpart, it is not surprising that the two curves may intercept for some particular designs. For this design case DOC penalties are experienced by the unconventional designs (fig 5.10.3). According to the curves on figures 5.9 and 5.10, the conventional optimised design has a minimum DOC occurring between the design ranges of 1500 and 1750 NM, while for the three-surface it happens at a range of 1750 NM, as for the baseline. In agreement with these trends, a maximum of 3.5% DOC benefit is obtained by the three-surface design with respect to the DOC optimised classical concept at a design range of 3000 NM. This roughly corresponds to an annual saving per aircraft of US\$134000, assuming the cost assumptions made are realistic. For the DOC optimised configurations range trade-offs, an almost linear growth on DOC benefit is offered by the three-surface concept from 0.4% (1000 NM range) up to 3.5% (3000 NM range). For the MTOW, the three-surface optimised designs show weight advantages with respect to the conventional optimised configurations for all ranges considered, 3.45% average weight benefit for the DOC optimised range trade-off designs and 2.43% average weight benefit for the MTOW optimised range trade-off designs, as shown respectively on figures 5.9.2, 5.9.3 and 5.10.2, 5.10.3.

5.5.3 Optimised versus Baseline Designs

Figures 5.11 and 5.12 provide a convenient way of comparing the optimised designs with the corresponding design range baselines and to assess both the inherent potential benefits offered by the drastic configuration change due to the inclusion of a fore-plane as well as the power of the mathematical programming techniques.

In fact, a first inspection of figures 5.11.1 and 5.12.1, show that a most significant contribution to the overall gain comes from the simple switch of the baseline conventional configuration to an equivalent three-lifting surface one in contrast with the result obtained from its optimisation. This is illustrated by the wide spacing displayed by the two baseline designs range trade-off curves, while maintaining the same take-off wing loading. The one for the baseline unconventional design almost mixes up with the corresponding optimised designs curves. Considering the conventional datum design (R=1250 NM) as a base for comparison, the corresponding three-surface baseline shows a benefit in DOC of 4.7% (fig 5.8.3) while the DOC optimised designs, tail-aft and three-surface show respectively 6.1% and 6.4% DOC advantage (fig 5.11.3). This means that, for the design range concerned, performing a DOC optimisation on the classical baseline design will give only an advantage of about 1.4% in relation to the three-surface baseline (not optimised). On the other hand, if the three-surface baseline is optimised for DOC this advantage would turn to be about 1.7%. For the datum range, and assuming the cost figures as reasonable predictions, it can be said that the three-surface baseline will show annual DOC benefits per aircraft of nearly US\$172100 while its optimised version will represent a saving of about US\$233900 with respect to the tail-aft baseline configuration. The optimised conventional one presents an intermediate annual saving, for this study (DOC optimisation) of about US\$224650. When performing MTOW optimisations, the optimised three-surface transport does not show the "best" DOC result as the latter case. This is claimed by the minimum weight conventional configuration (fig 5.12.1). The reason is probably because the MTOW minimization runs conducted on the three-surface design were unable to locate a better minimum MTOW solution, as explained before at the end of section 5.4.

At increasing design range, DOC benefits claimed by the three-surface designs are more noticeable since this concept is less sensitive in terms of DOC for higher ranges than the tail-aft concept, as shown before. Thus at a design range of 3000 NM, taking the conventional baseline design at this range as a base for comparison, the corresponding three-surface baseline shows a benefit in DOC of 7.9% (fig 5.8.3), as referred to above, while the DOC optimised designs, tail-aft and unconventional one show respectively 7.6% and 10.9% DOC advantage (fig 5.11.3). These figures mean that for the design range considered, performing a DOC optimisation on the classical baseline design gives a penalty of about 0.3% with respect to the three-surface baseline (not optimised). On the other hand if the three-surface baseline is optimised for DOC the advantage would be increased to 2.9%. In fact a three-surface airliner optimised for minimum DOC and to fly a distance of 3000 NM would represent roughly an annual saving of about US\$432000 per aircraft when compared to the initial baseline conventional design for the same range, assuming the cost assumptions and utilization rate employed are close to reality. It is interesting to see that for design ranges at, or above, 2750 NM the conventional aircraft optimised both for minimum DOC and minimum MTOW experiences higher DOC than the corresponding design range three-surface baseline designs as shown on figures 5.11.1, 5.11.4, 5.12.1 and 5.12.4.

Regarding the MTOW, the three-surface baseline airliner generally offers weight advantages with respect to the conventional optimised configurations at design ranges above the datum range as observed on figures 5.11.2, 5.11.4, 5.12.2 and 5.12.4. For all design ranges considered, the optimised unconventional transports display the lowest MTOW, 8% weight saving at 1250 NM design range and 8.9% weight saving at 3000 NM design range when compared to the same range tail-aft baseline concept (figs. 5.11.2 and 5.11.3). With respect to the three-surface baseline concept these weight savings are respectively 3.7% and 1.8% (figs. 5.11.2 and 5.11.4). These gains were taken from the minimum DOC unconventional solutions since these were the best solutions found for this configuration based on the minimum DOC rather than on minimum weight, as noted above and referred to in section 5.4.

5.6 Concluding Remarks

It was shown that DOC and MTOW benefits are evident when switching from a conventional tail-aft configuration to a same mission equivalent three-surface aircraft design, assuming the same wing loading is kept on both concepts. Further more it was found that DOC benefits increase linearly with design ranges which nearly double from a range of 1000 NM up to 3000 NM. Although MTOW increases with design range, weight savings are also experienced. These increase from 4.2% at 1000 NM range, up to 7.2% MTOW saving at 3000 NM design range.

When optimising the above designs it is observed that improvement on the figures of merit is obtained, but a major general gain, comparable to that obtained from the optimised tail-aft configuration, is produced simply by the adoption of the concept under study. It is interesting to note that the canard equipped version is less cost sensitive at longer ranges than the equivalent classical concept. It may be observed that the marginal gains determined by the conventional one, optimised for medium haul, are offset and turn to be cost penalties with regard to the three-surface baseline design for long ranges (equal to or above 2750 NM). On the other hand, while optimising the three-surface concept, sensible gains both on DOC and MTOW are demonstrated with respect to its baseline design for all design ranges analysed, and have greater impact on cost savings achieved for higher ranges (figs. 5.11.1 and 5.11.4). Annual economies in DOC per airliner amounting to roughly US\$233900 at 1250 NM design range and US\$432000 at 3000 NM design range with regard to the classical baseline concept are possible, providing the cost assumptions used in the studies are credible.

From the design study results, within the usual limitations of any initial conceptual design study but in the present case including many real life considerations that quantitatively are important ingredients for any realistic study, it appears that little doubt exists on the inherent achievable benefits when replacing a conventional design by an equivalent mission twin turbo-fan airliner of the three-lifting surface type.

It is worth noting that the conclusions here are based on a more complex approach than used by others and reported in Chapter 2. It is the author belief that within the time constraints of the present research, a comprehensive, consistent and systematic design study has been conducted on the topic, and the results are of a conclusive nature regarding the merits of such a potential unusual commercial turbofan airliner.

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Thrust-to-Weight vs Wing Loading Diagram

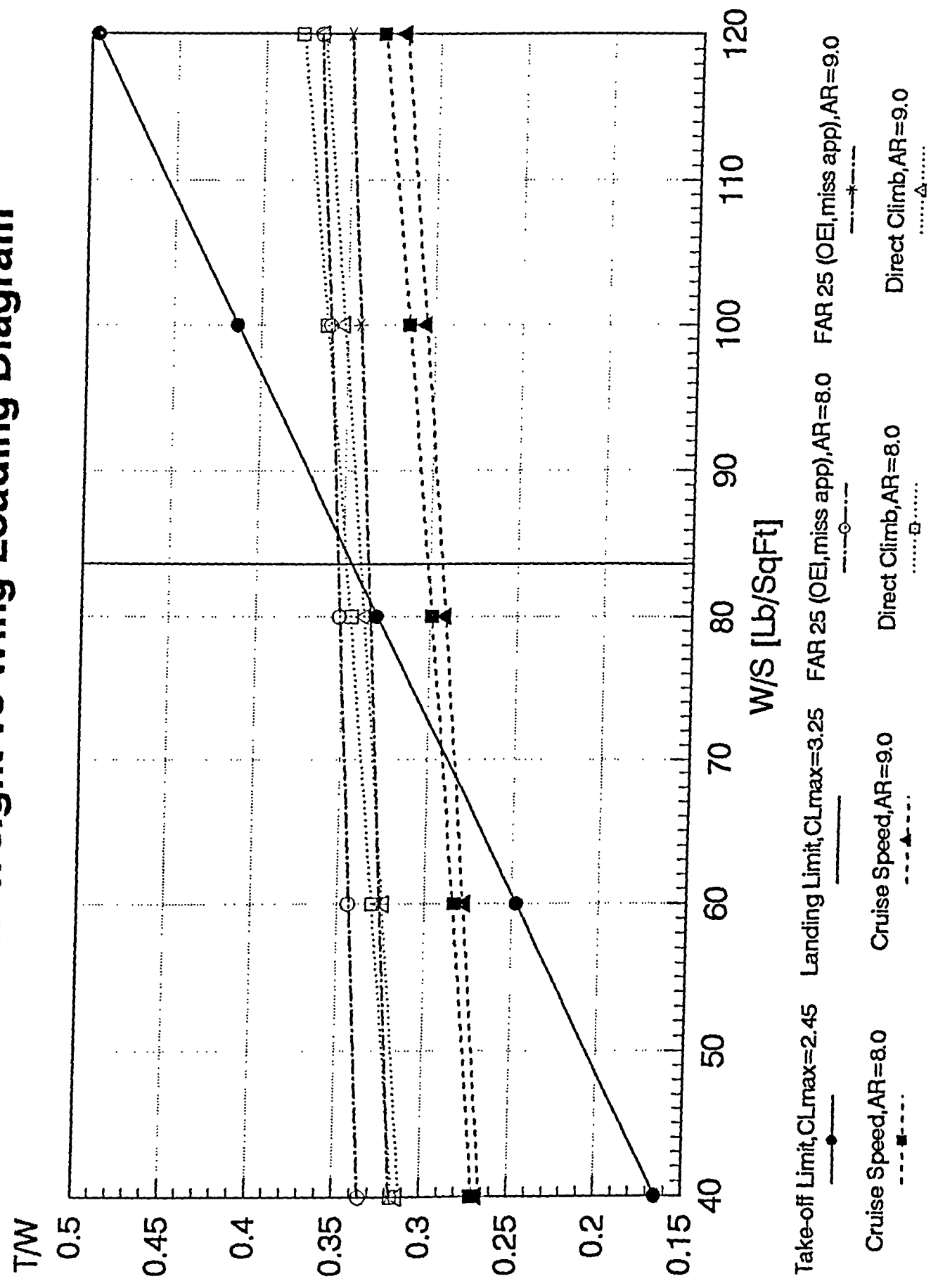


Fig 5.1 - Design Constraint Diagram

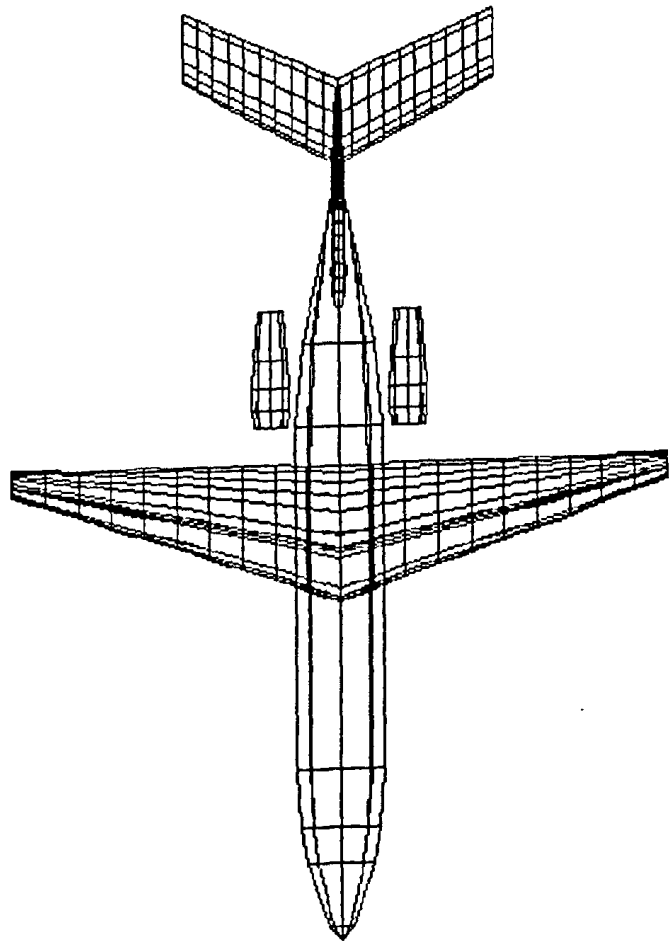
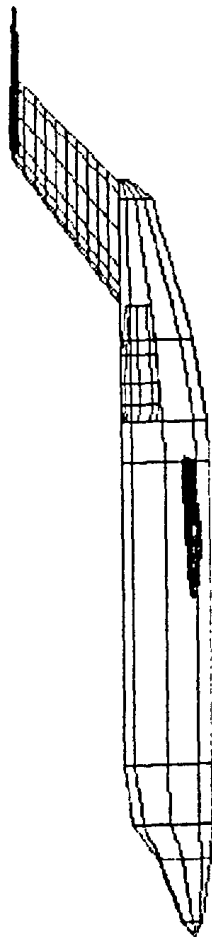
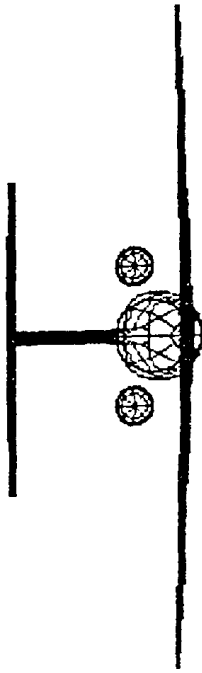


Fig 5.2 - Conventional Baseline Configuration

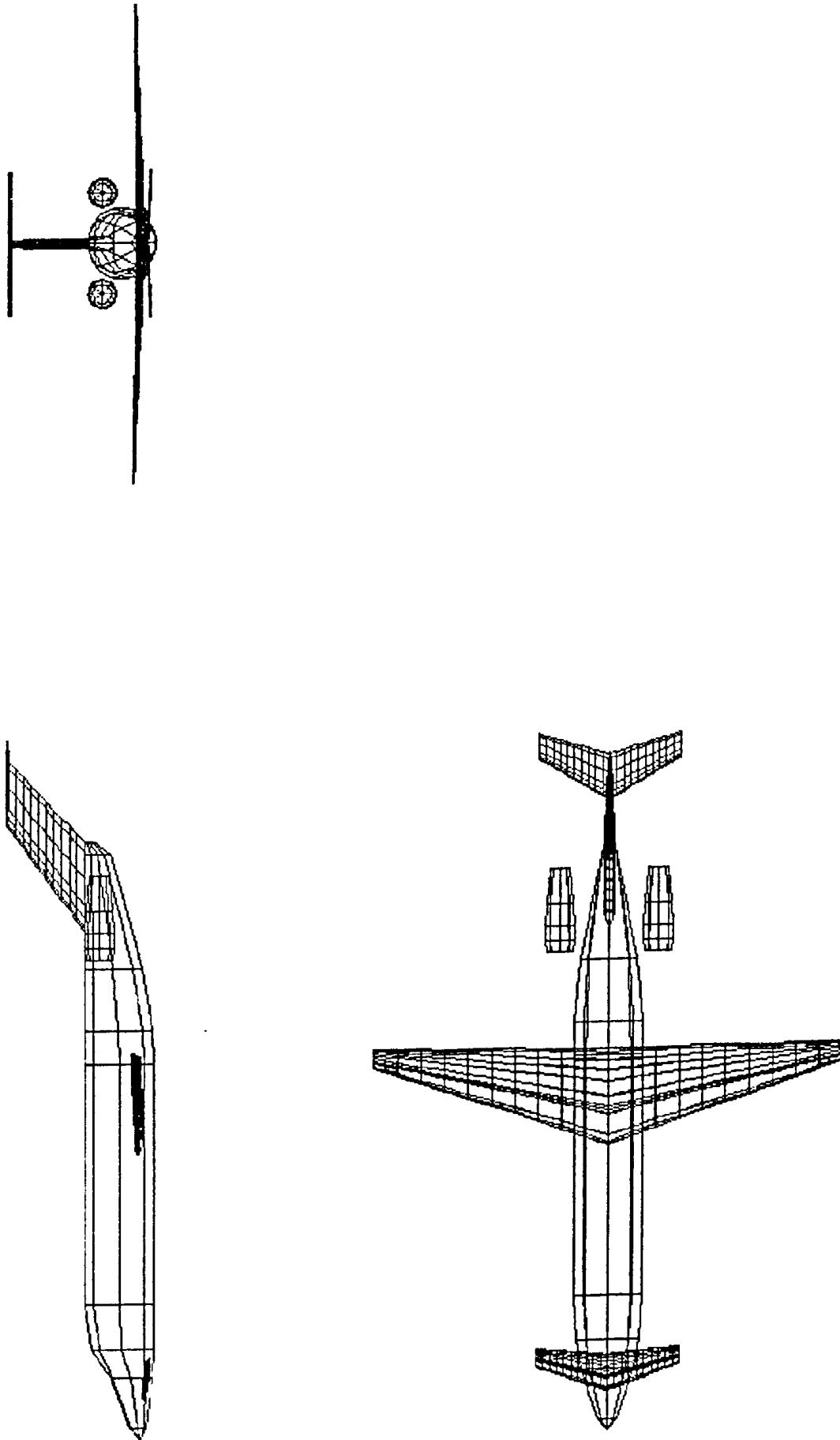


Fig. 5.3 - Three-Lifting Surface Baseline Configuration

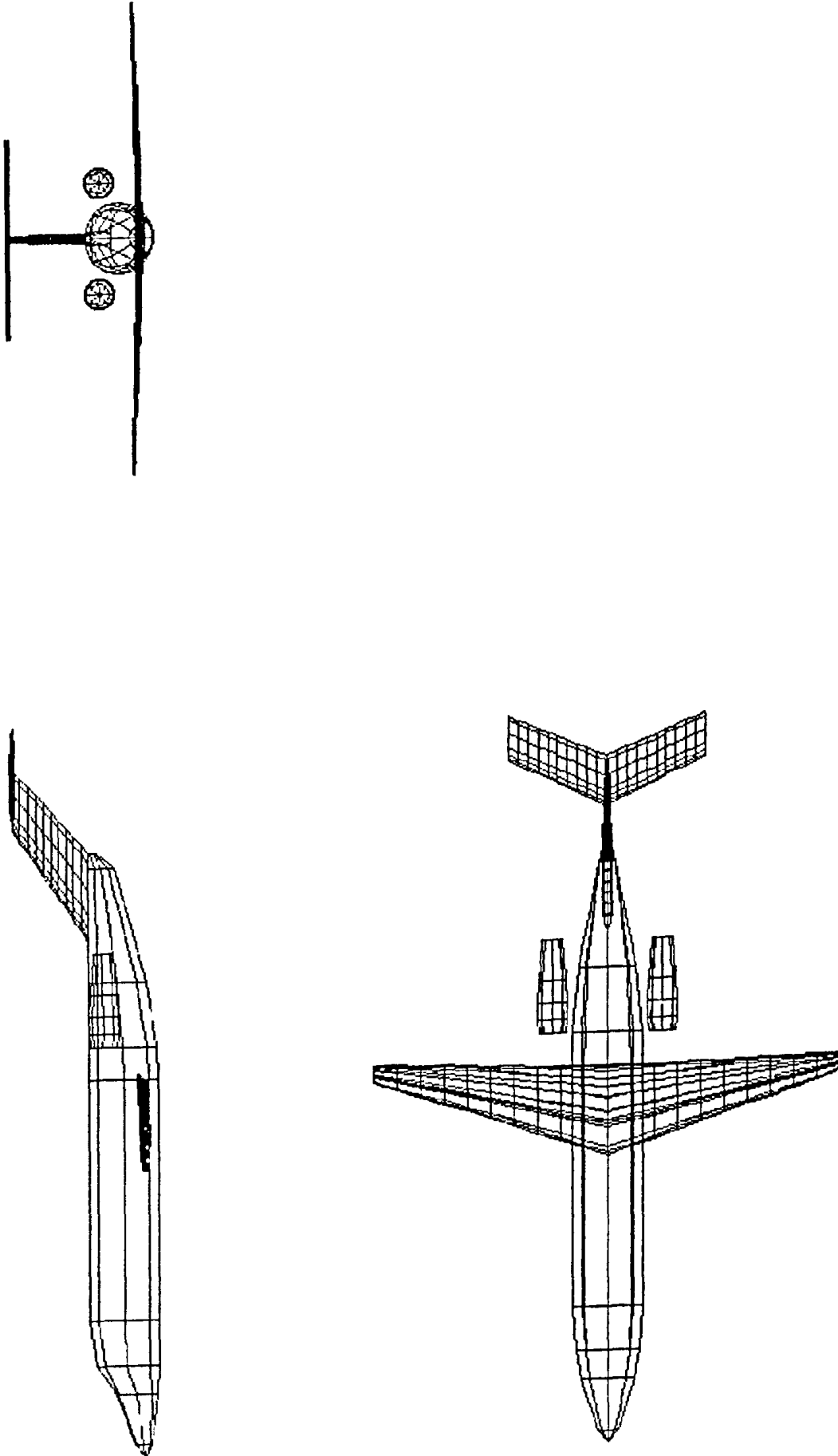


Fig 5.4 - Conventional Configuration optimised for minimum D.O.C.

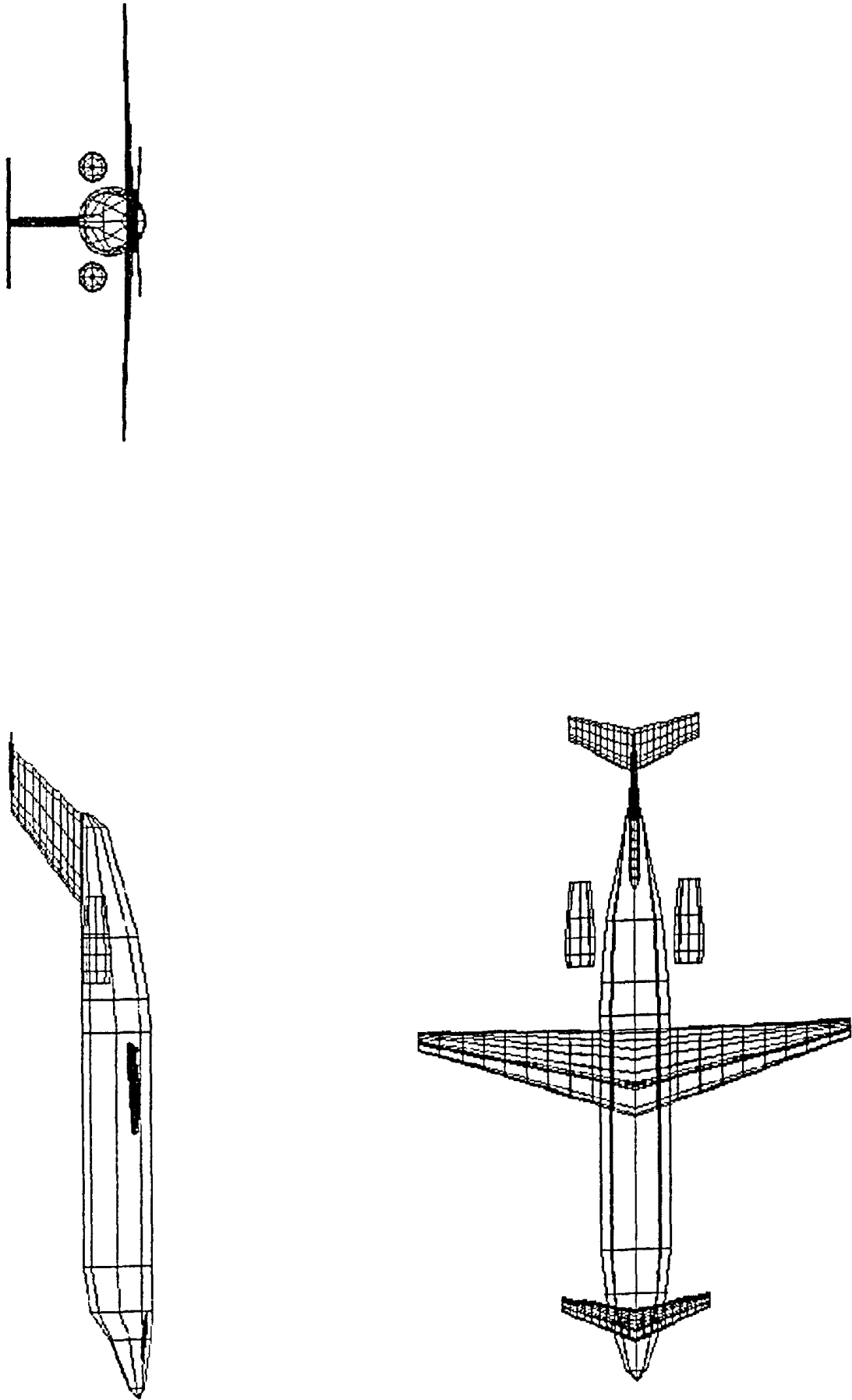


Fig 5.5 - Three-Lifting Surface Configuration optimised for minimum D.O.C.

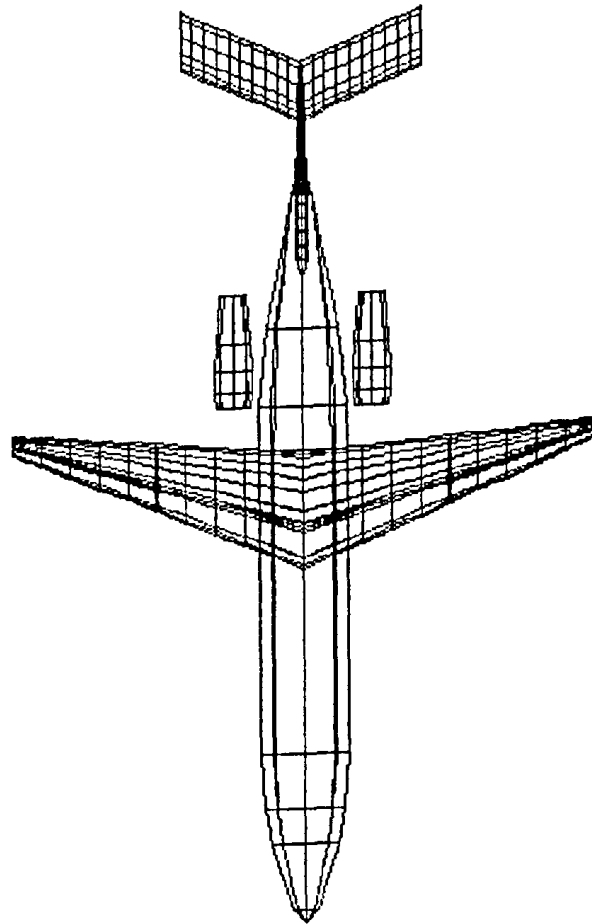
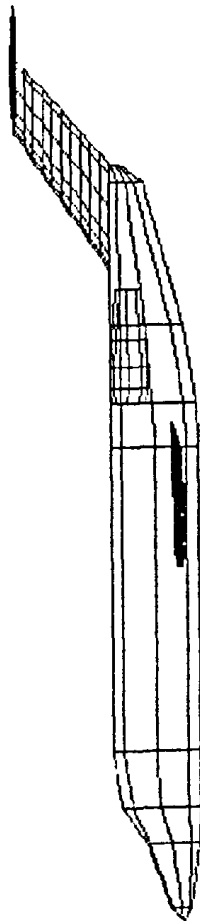
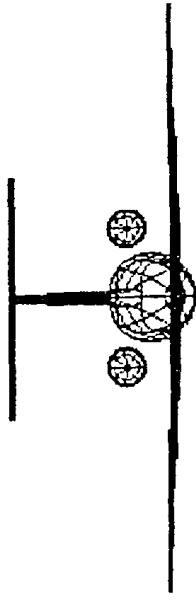


Fig 5.6 - Conventional Configuration optimised for minimum M.T.O.W.

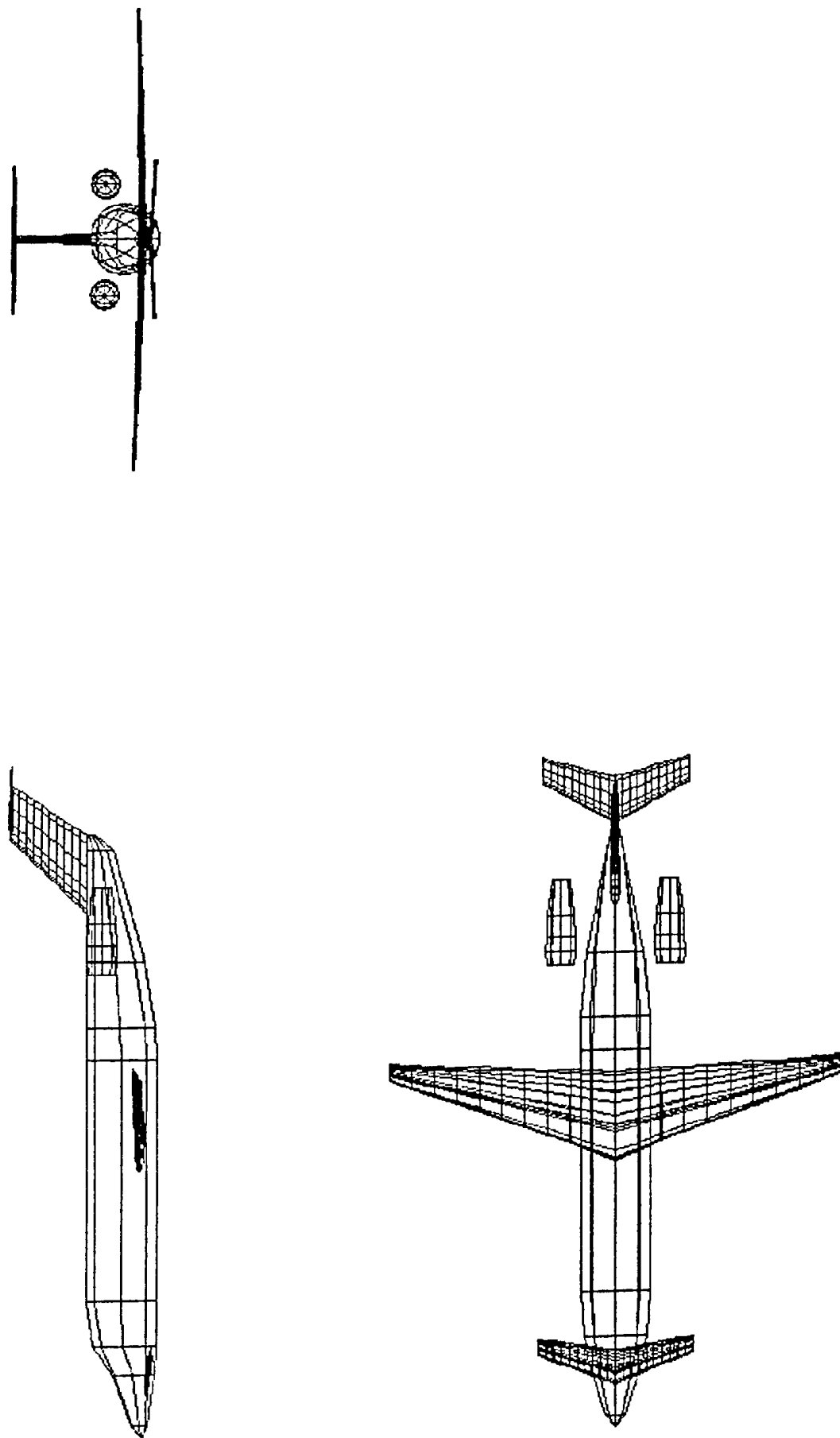


Fig 5.7 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.

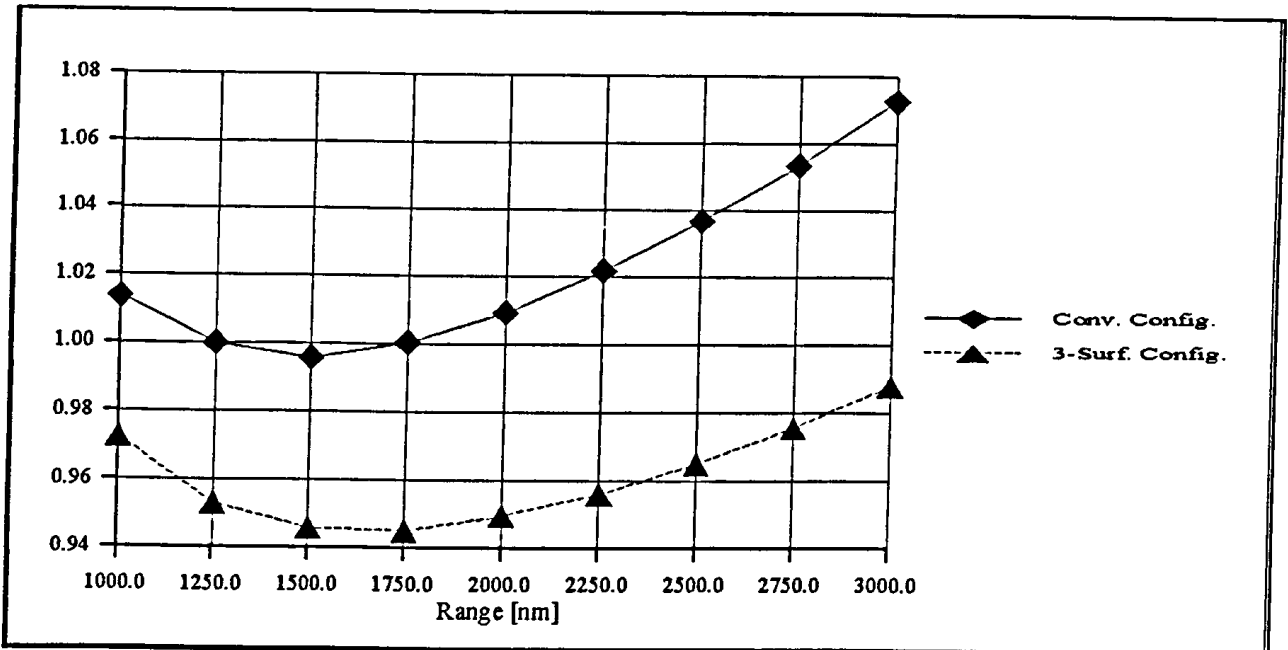


Fig 5.8.1 - Direct Operating Costs - Range Trade-off for the Baseline Configurations

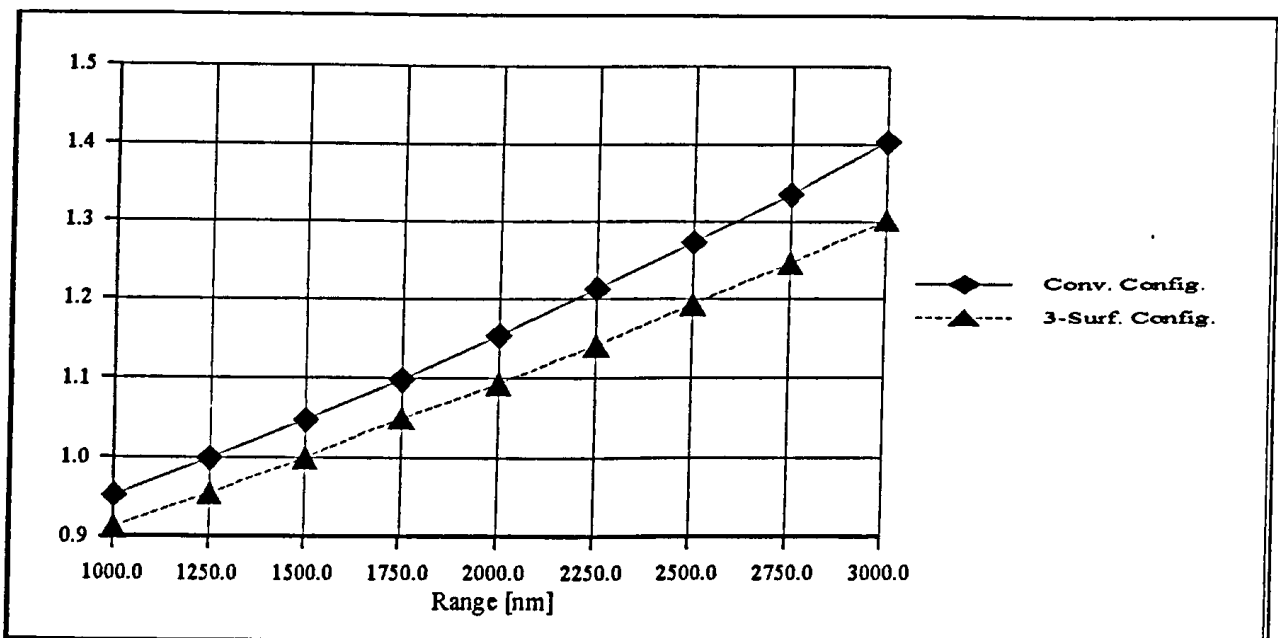


Fig 5.8.2 - Maximum Take-off Weight - Range Trade-off for the Baseline Configurations

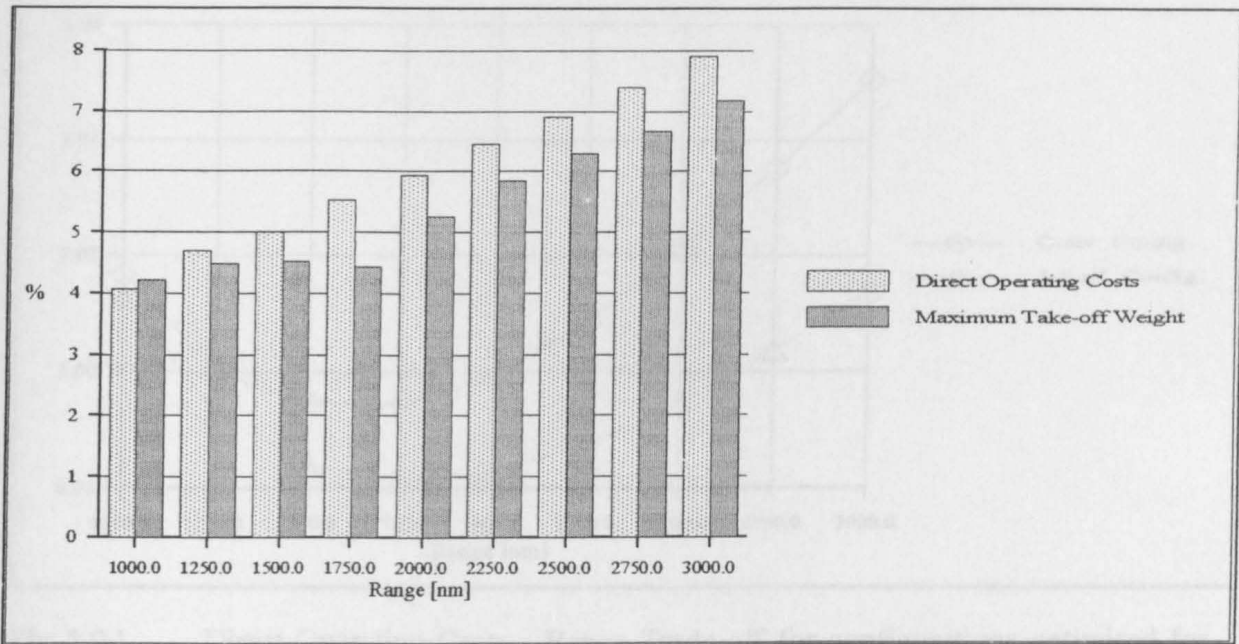


Fig 5.8.3 - Three-Surface versus Conventional Configurations Benefits (Baseline Designs)

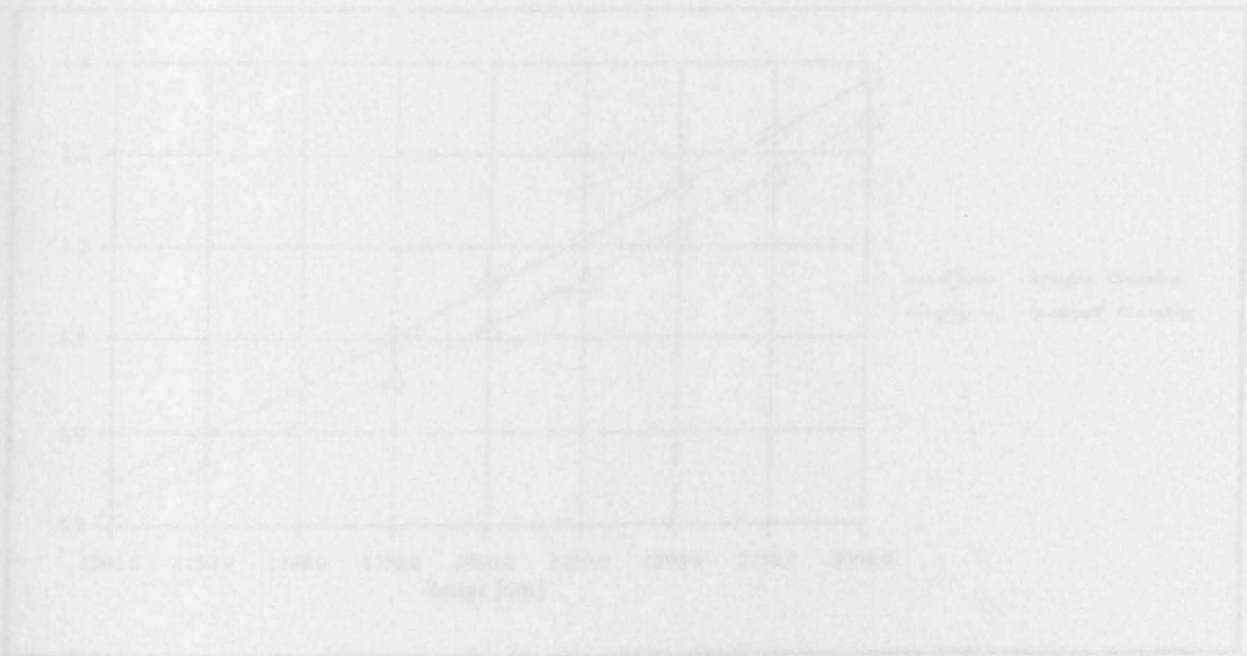


Fig 5.8.2 - Maximum Take-off Weight - Fuel Burn Rate for configurations optimized for minimum DOC.

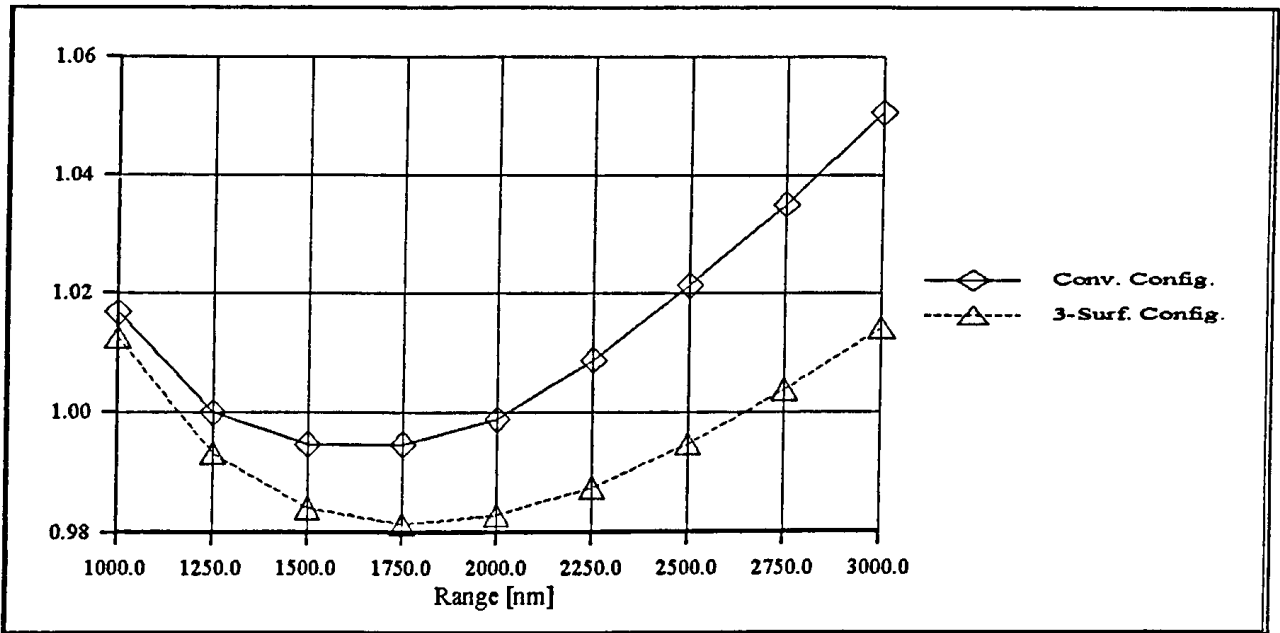


Fig 5.9.1 - Direct Operating Costs - Range Trade-off for configurations optimised for minimum D.O.C.

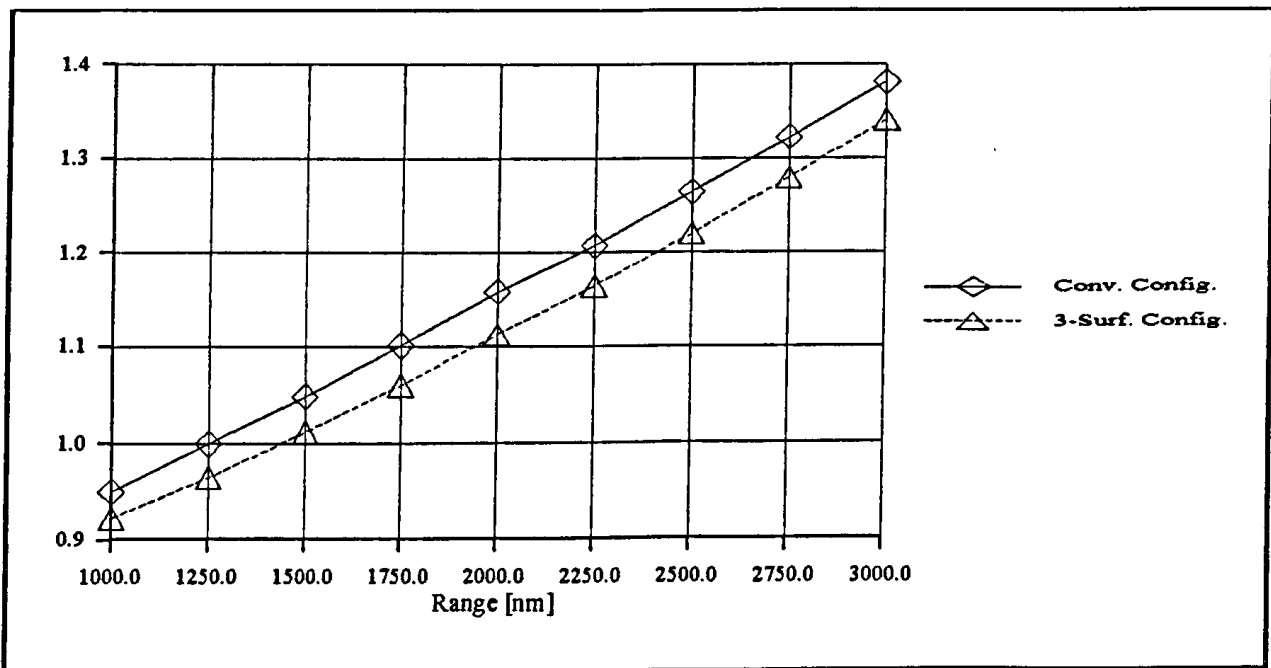


Fig 5.9.2 - Maximum Take-off Weight - Range Trade-off for configurations optimised for minimum D.O.C.

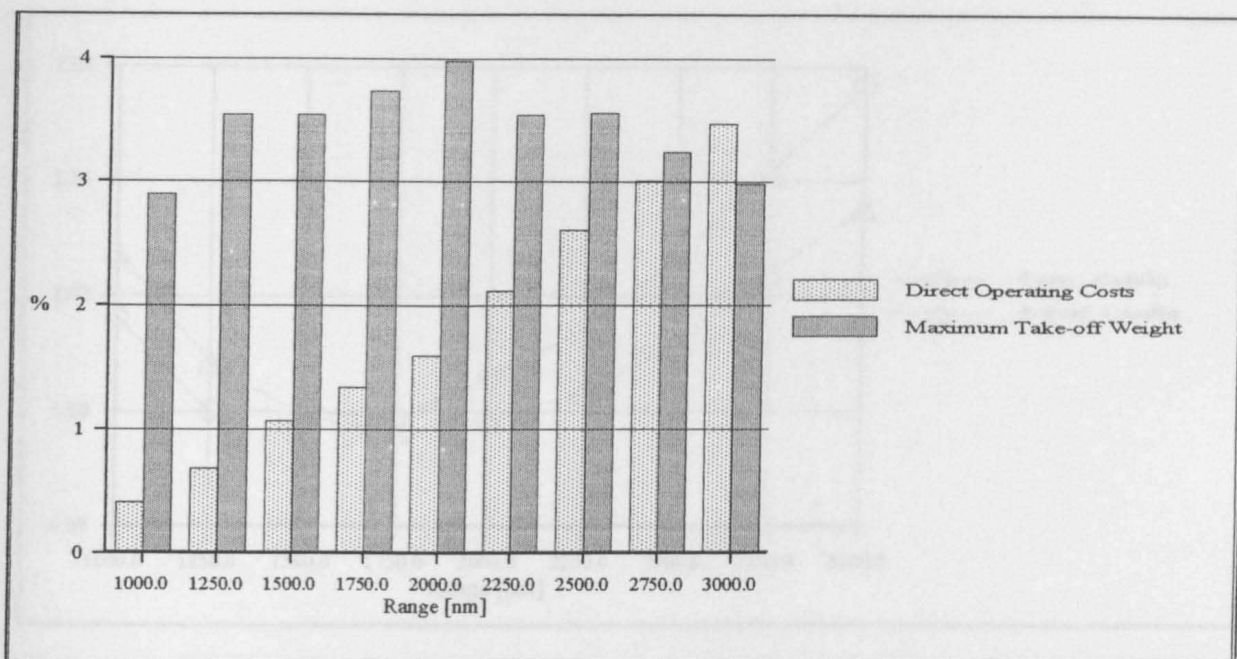


Fig 5.9.3 - Three-Surface versus Conventional Configurations Benefits (Configurations optimised for minimum D.O.C.)

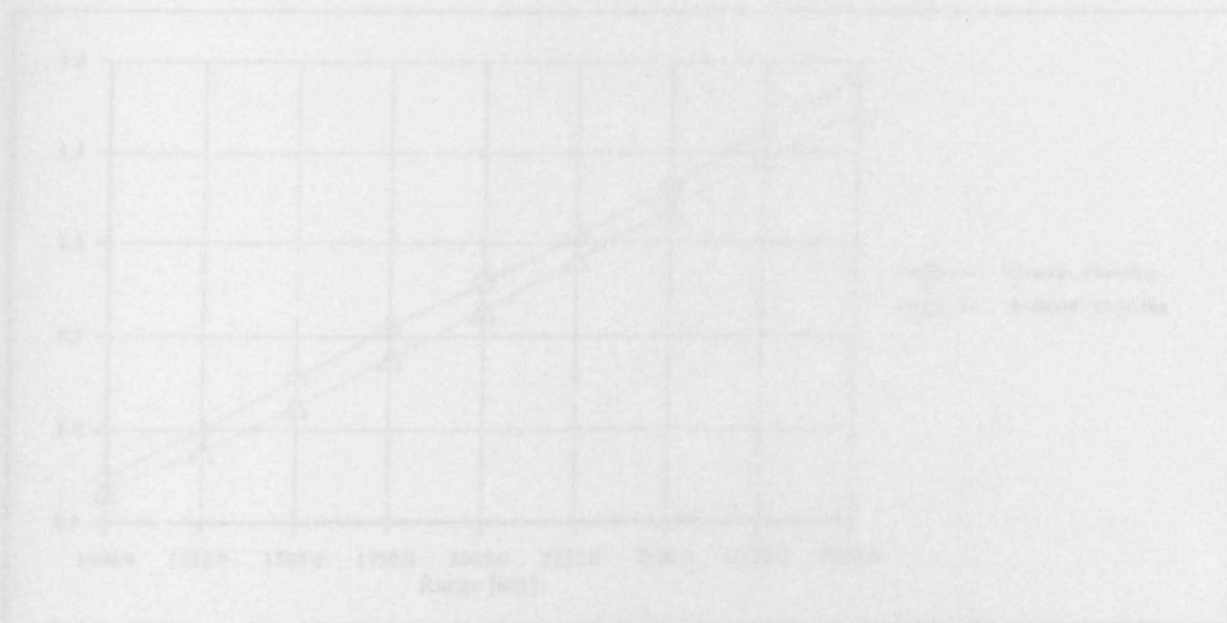


Fig 5.10.2 - Maximum Take-off Weight - Range Take-off for configurations optimised for minimum M.T.O.W.

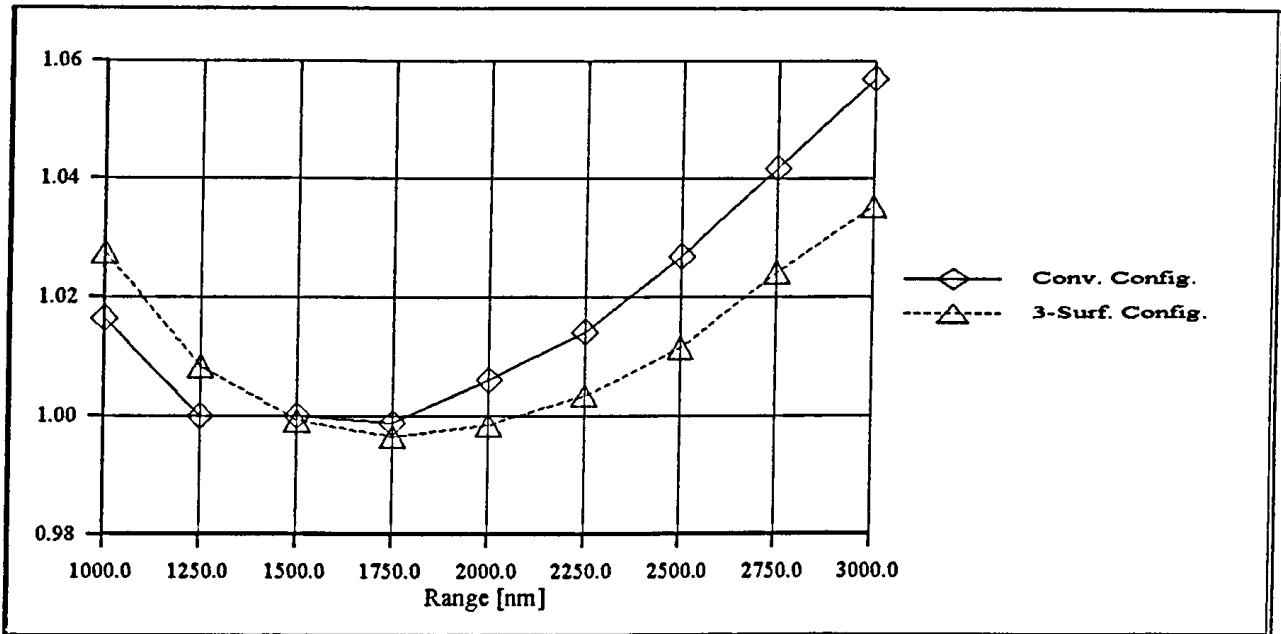


Fig 5.10.1 - Direct Operating Costs - Range Trade-off for configurations optimised for minimum Max. Take-off Weight

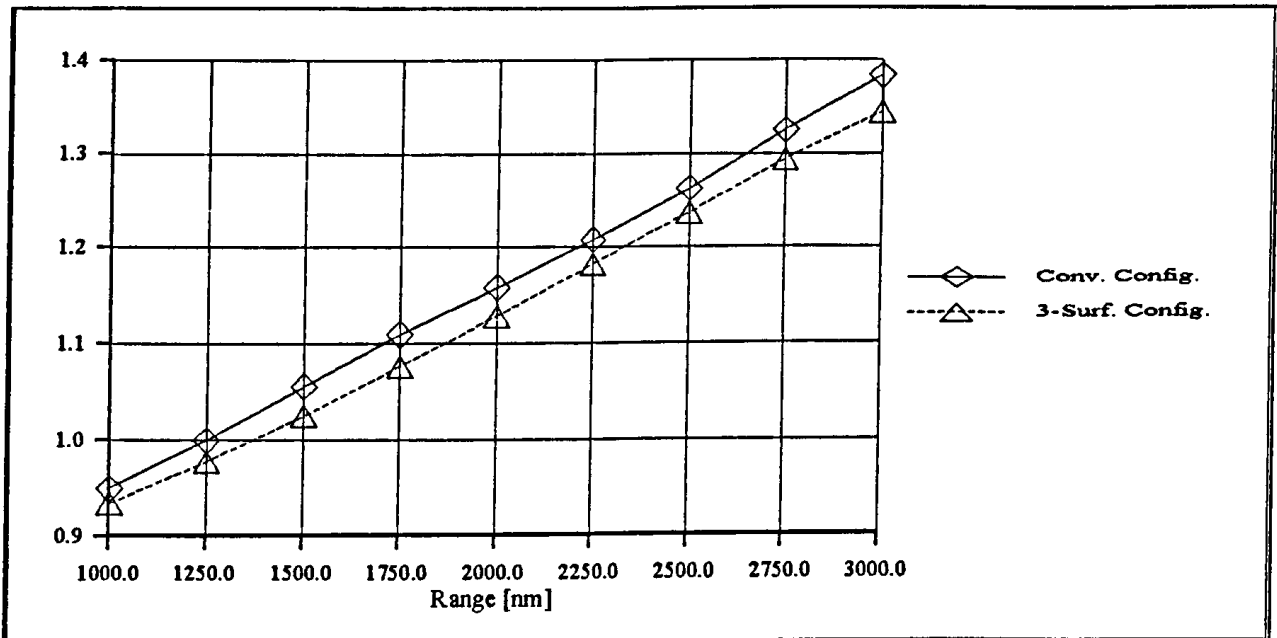


Fig 5.10.2 - Maximum Take-off Weight - Range Trade-off for configurations optimised for minimum Max. Take-off Weight

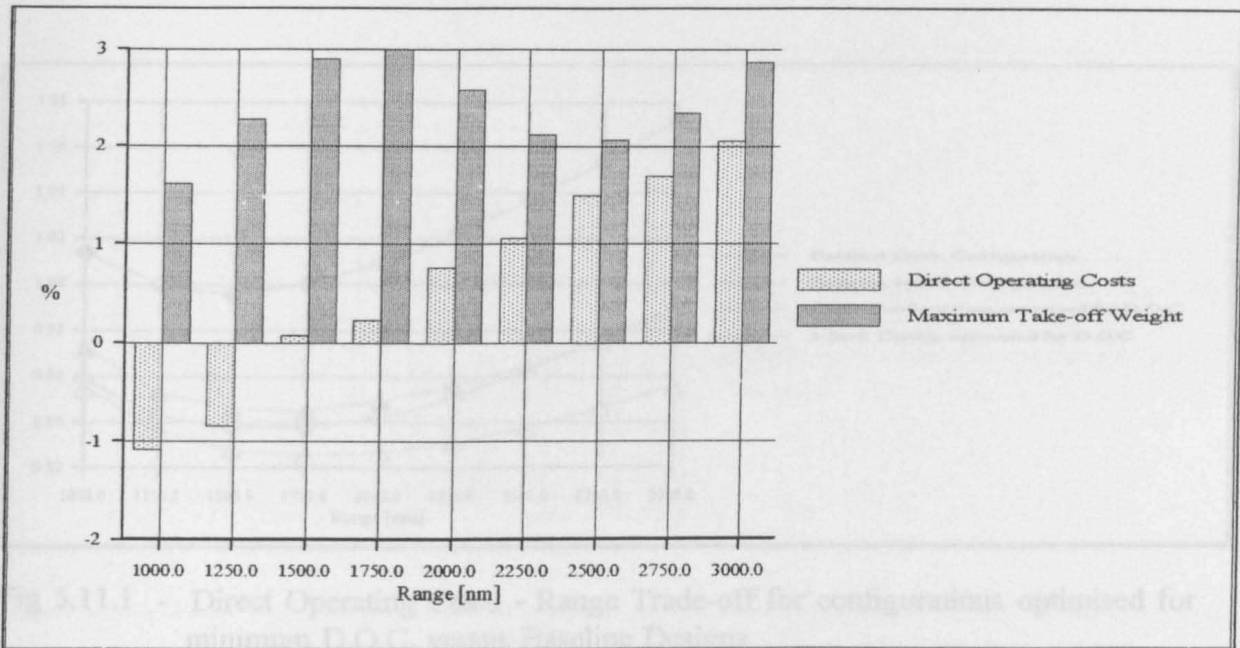


Fig 5.10.3 - Three-Surface versus Conventional Configurations Benefits (Configurations optimised for minimum Max.Take-off Weight)

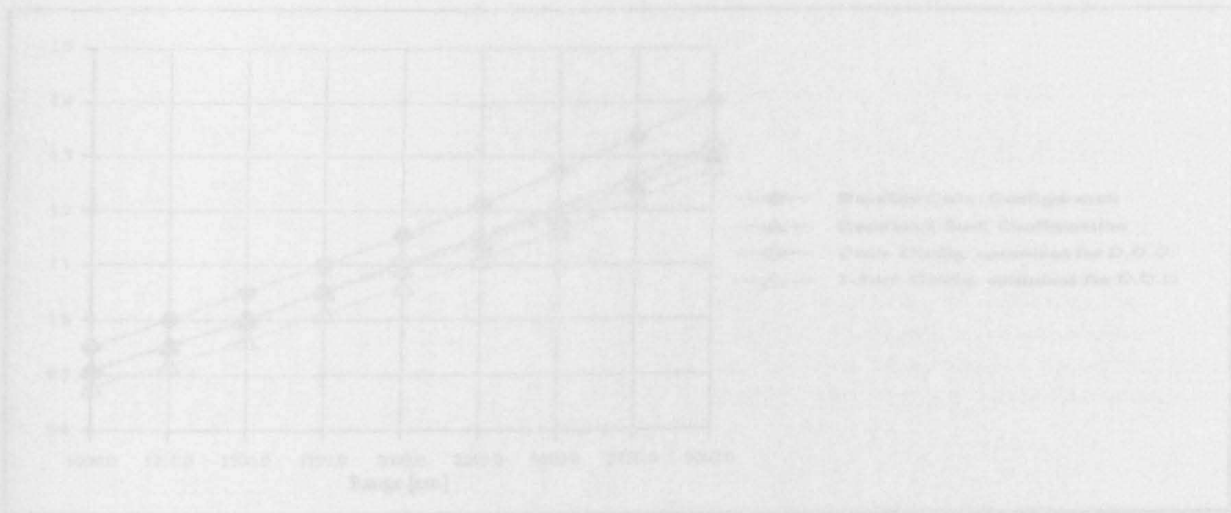


Fig 5.11.2 - Maximum Take-off Weight - Range Trade-off for configurations optimized for minimum D.O.C. versus Baseline Design

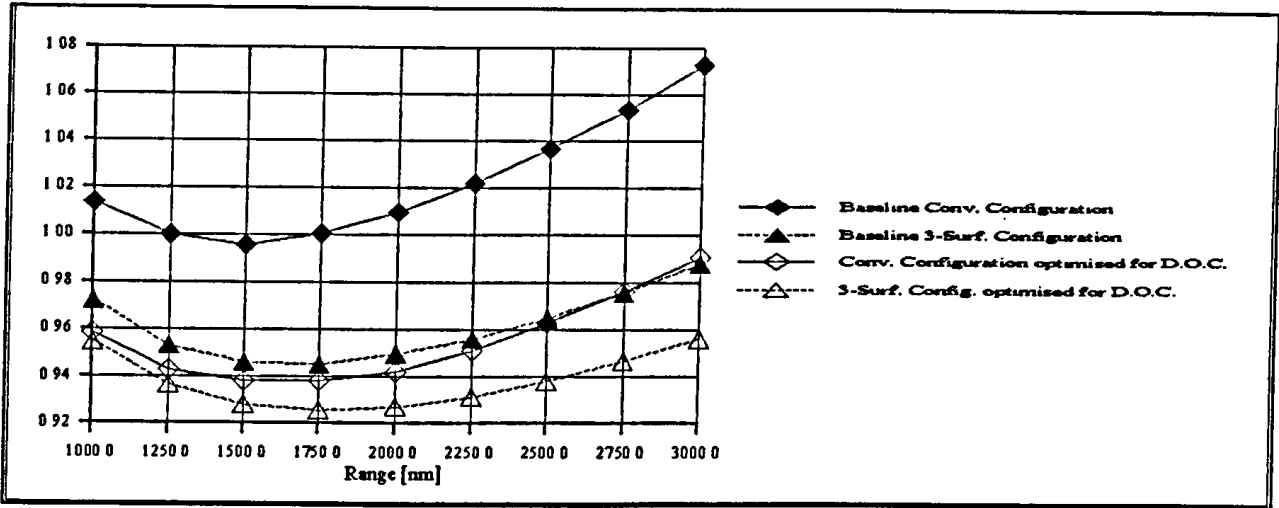


Fig 5.11.1 - Direct Operating Costs - Range Trade-off for configurations optimised for minimum D.O.C. versus Baseline Designs

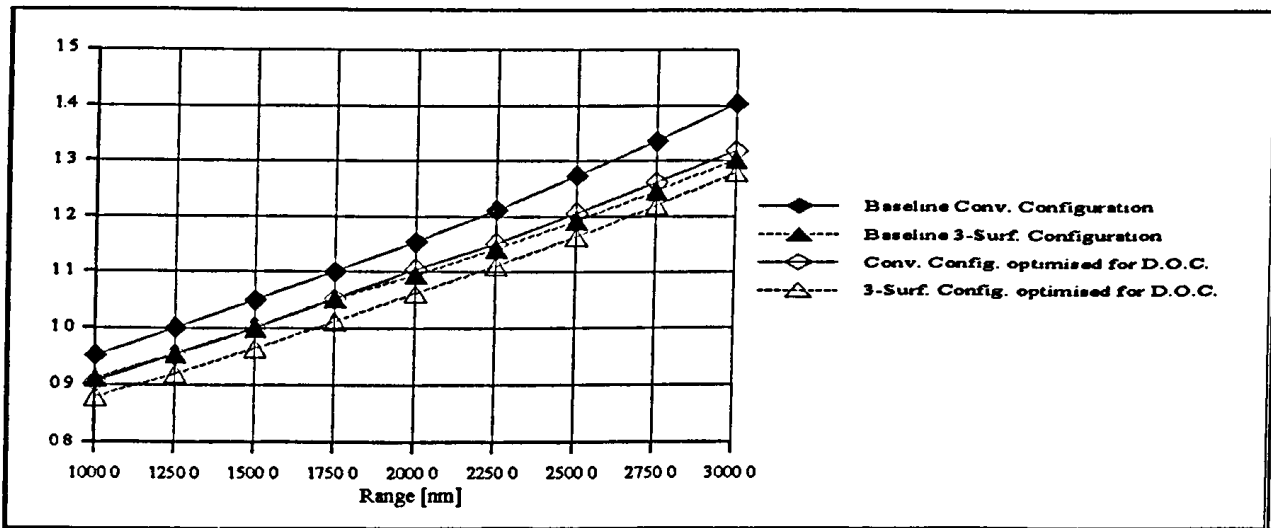


Fig 5.11.2 - Maximum Take-off Weight - Range Trade-off for configurations optimised for minimum D.O.C. versus Baseline Designs

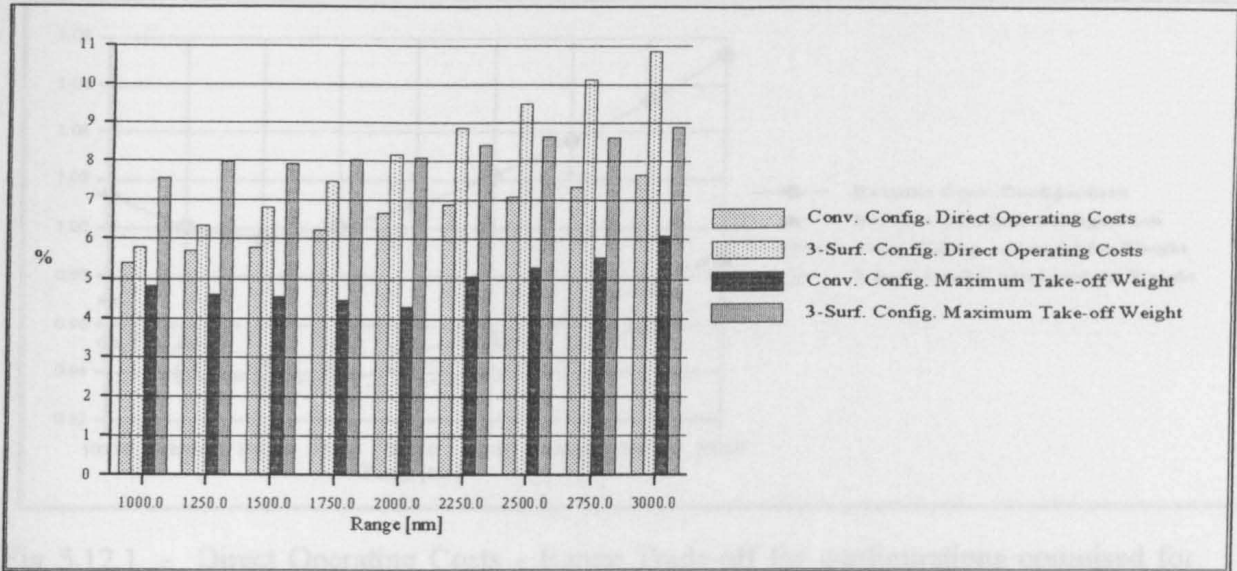


Fig 5.11.3 - Benefits of Configurations optimised for minimum D.O.C. with regard to the Conventional Baseline Design

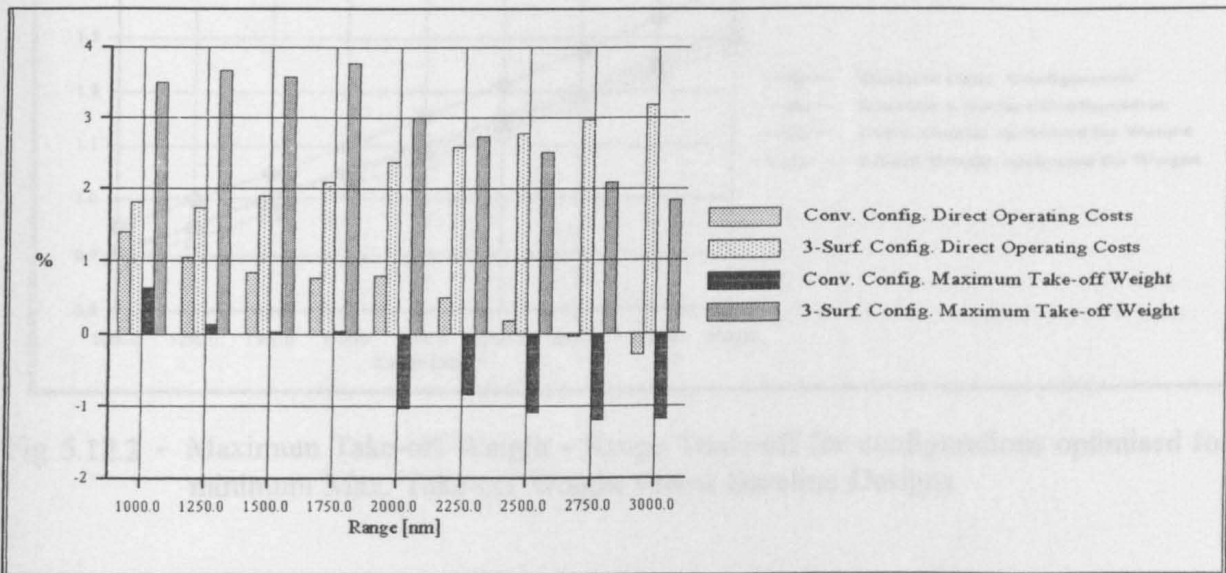


Fig 5.11.4 - Benefits of Configurations optimised for minimum D.O.C. with regard to the Three-Surface Baseline Design

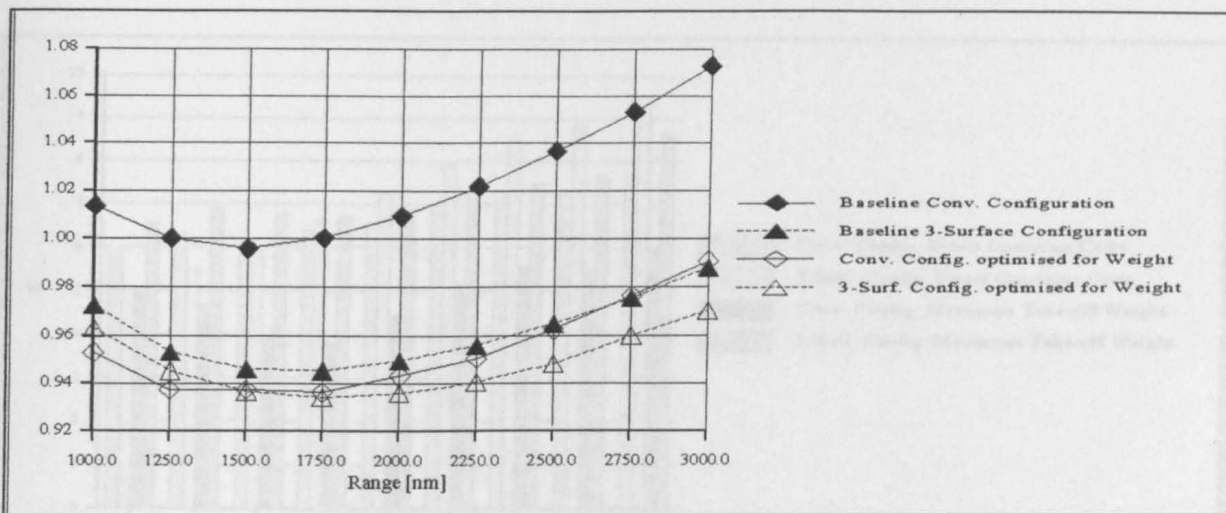


Fig 5.12.1 - Direct Operating Costs - Range Trade-off for configurations optimised for minimum Max. Take-off Weight versus Baseline Designs

Fig 5.12.3 - Benefits of Configurations optimised for minimum Max. Take-off Weight with regard to the Conventional Baseline Design

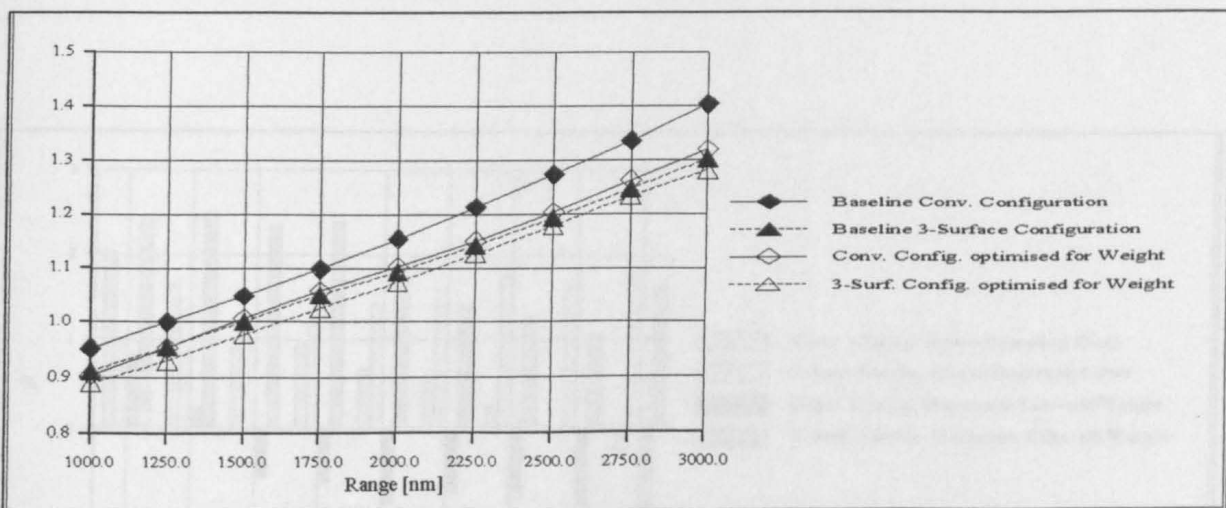


Fig 5.12.2 - Maximum Take-off Weight - Range Trade-off for configurations optimised for minimum Max. Take-off Weight versus Baseline Designs

Fig 5.12.4 - Benefits of Configurations optimised for minimum Max. Take-off Weight with regard to the Three-Surface Baseline Design

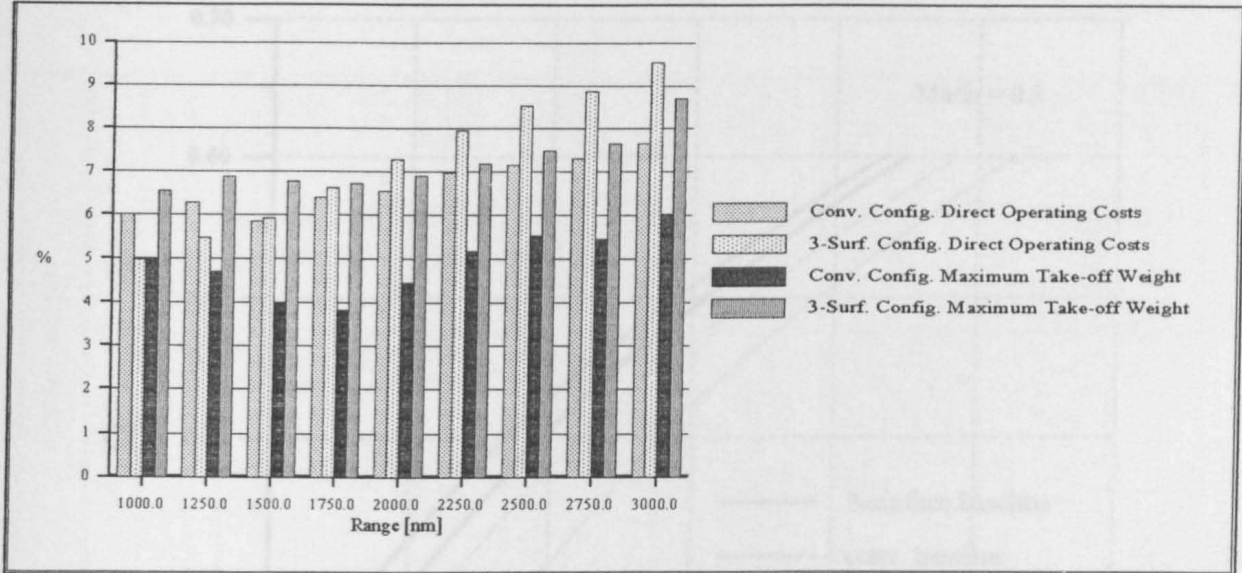


Fig 5.12.3 - Benefits of Configurations optimised for minimum Max. Take-off Weight with regard to the Conventional Baseline Design

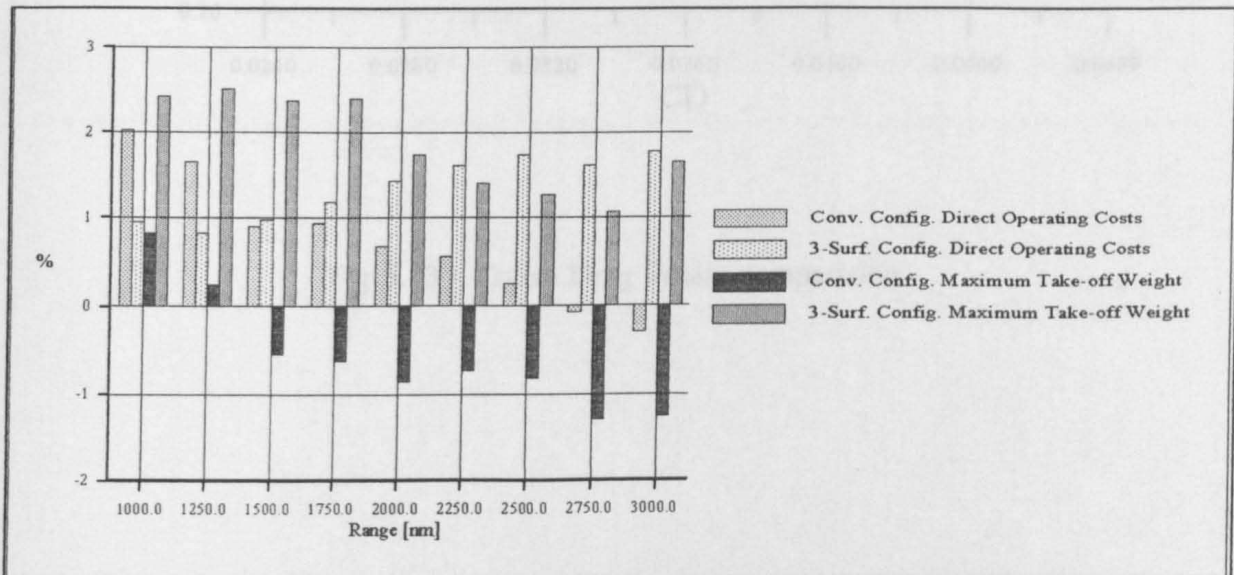


Fig 5.12.4 - Benefits of Configurations optimised for minimum Max. Take-off Weight with regard to the Three-Surface Baseline Design

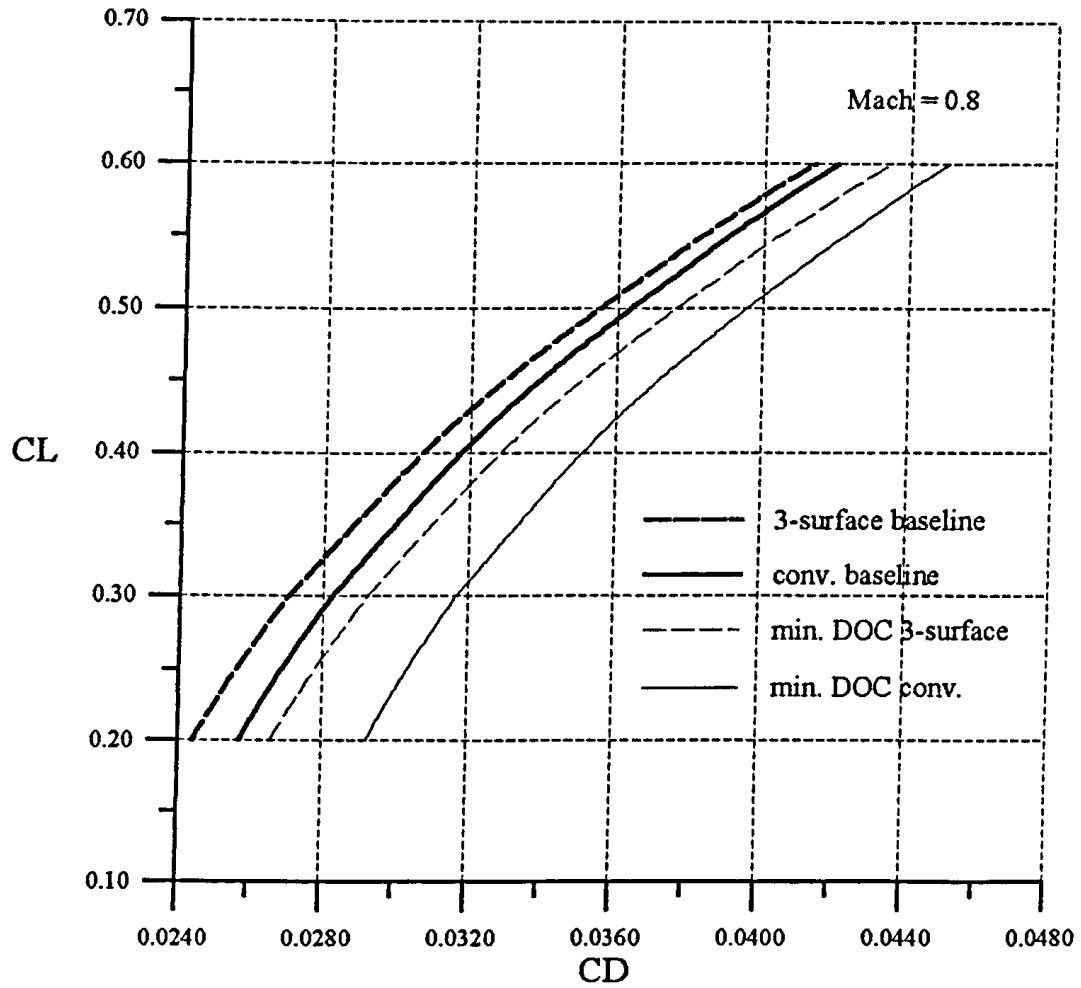


Fig 5.13 - Cruise Drag Polars comparison

	PreSiz	GASP			RQPMIN+GASP					
		Baselines			Min. D.O.C.			Min. M.T.O.W.		
		Conv.	3-Surf.		Conv.	3-Surf.		Conv.	3-Surf.	
M.T.O.W.	44076	47873	45726	45707	44050	45639	44576			
E.W.	24698	27385	25899	25554	24612	25540	25170			
Fuel Weight	8558	9389	8747	9074	8372	9020	8340			
Engine Max. St. T/O Thrust	7603	9920	9291	9756	8899	9785	8842			
T/O Wing Loading	83.75	83.00	83.00	105.00	93.00	105.00	90.80			
T/O Thrust to Weight Ratio	0.345	0.414	0.406	0.427	0.404	0.429	0.397			
Cruise Mach No.	0.80	0.79	0.81	0.83	0.80	0.84	0.79			
Cruise Height	35000	35000	35000	35000	35000	35000	35000			
Cruise L/D	11.00	11.98	12.24	11.72	12.26	11.68	12.50			
T/O CLmax	2.450	2.466	2.156	2.503	2.136	2.432	2.119			
Landing CLmax	3.250	3.264	2.845	3.296	2.811	3.187	2.783			
FAR 25 T/O Field Length	6000.0	4638.0	5360.5	5475.7	5994.8	5598.1	6004.9			
FAR 25 Land. Field Length	5000.0	4016.8	4496.0	4807.5	4965.6	4940.5	4911.8			
Wing Area	526.29	576.78	481.05	435.30	409.06	434.67	419.08			
Wing Aspect Ratio	8.30	8.30	8.30	8.88	8.40	8.72	8.84			
Wing 1/4 Chord Sweep		14.50	14.50	14.88	14.51	18.57	16.12			
Canard Area			69.75		64.77		71.91			
Canard Aspect Ratio			5.50		6.10		6.01			
Canard 1/4 Chord Sweep			15.00		20.55		18.24			
Canard to Wing Area Ratio			0.1450		0.1583		0.1716			
Mission Range	1250.00	1250.14	1250.43	1262.25	1239.81	1249.73	1238.91			
Aircraft Price		18.2E+06	17.6E+06	17.5E+06	17.0E+06	17.6E+06	17.2E+06			
D.O.C./N Mile		2.79	2.66	2.62	2.61	2.62	2.64			

Table 5.1 - Summary of Main Results

Range Case	NM	1000	1250	1500	1750	2000	2250	2500	2750	3000
Fuselage Length	FT	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25
Wing Area	SQFT	549.29	576.78	604.39	633.91	665.74	699.58	734.44	770.16	809.30
Wing Aspect Ratio		8.30	8.30	8.30	8.30	8.30	8.30	8.30	8.30	8.30
Wing 1/4 Chord Sweep	DEG	14.50	14.50	14.50	14.50	14.50	14.50	14.50	14.50	14.50
Engine Max. St. T/O Thrust	LB	9709	9920	10134	10363	10612	10878	11153	11436	11748
M.T.O.W.	LB	45591	47873	50164	52614	55257	58065	60959	63923	67172
O.E.W.	LB	27740	28484	29197	29980	30878	31831	32812	33815	34914
E.W.	LB	26647	27385	28092	28869	29760	30707	31681	32677	33769
Fuel Weight	LB	7851	9389	10967	12634	14379	16234	18147	20108	22257
T/O Wing Loading	PSF	83.0	83.0	83.0	83.0	83.0	83.0	83.0	83.0	83.0
T/O Thrust to Weight Ratio		0.426	0.414	0.404	0.394	0.384	0.375	0.366	0.358	0.350
Cruise Mach No.		0.80	0.79	0.79	0.78	0.78	0.77	0.76	0.76	0.75
Cruise Speed (TAS)	KT	462.4	458.8	455.5	451.1	447.6	444.1	440.7	437.5	434.1
Cruise Height	FT	35000	35000	35000	35000	35000	35000	35000	35000	35000
Cruise L/D		11.67	11.98	12.27	12.57	12.87	13.17	13.46	13.75	14.03
Approach Speed (EAS)	KT	109.3	109.1	109.0	108.9	108.8	108.8	108.8	108.7	108.7
Approach Speed (TAS)	KT	121.9	121.8	121.6	121.5	121.4	121.4	121.4	121.3	121.3
T/O Stall Speed (TAS)	KT	107.5	107.5	107.5	107.5	107.5	107.5	107.4	107.4	107.4
Landing Stall Speed (TAS)	KT	93.6	93.4	93.3	93.2	93.2	93.1	93.1	93.1	93.1
T/O Flap (angle/CLmax)	DEG/	15./2.466	15./2.466	15./2.467	15./2.467	15./2.468	15./2.468	15./2.469	15./2.469	15./2.47
Landing Flap (angle/CLmax)	DEG/	40./3.257	40./3.264	40./3.271	40./3.279	40./3.283	40./3.285	40./3.286	40./3.287	40./3.289
FAR 25 T/O Field Length	FT	4539.4	4638.0	4707.3	4798.6	4901.5	4972.5	5070.9	5140.9	5239.4
FAR 25 Land. Field Length	FT	4028.3	4016.8	4005.9	3994.9	3987.0	3982.4	3978.2	3974.9	3970.1
Mission Range	NM	999.64	1250.14	1499.38	1749.46	1998.84	2251.78	2499.16	2740.01	2991.25
Block Fuel	LB	6023	7515	9046	10675	12378	14203	16069	17966	20075
Block Time	HR	2.478	3.044	3.613	4.201	4.790	5.395	5.997	6.593	7.221
Aircraft Price	US\$	17.9E+06	18.2E+06	18.5E+06	18.8E+06	19.1E+06	19.5E+06	19.9E+06	20.3E+06	20.7E+06
D.O.C./Flight	US\$/Flight	2827.95	3488.65	4166.35	4883.72	5630.33	6421.80	7231.04	8054.38	8954.73
D.O.C./N Mile	US\$/NM	2.83	2.79	2.78	2.79	2.82	2.85	2.89	2.94	2.99

Table 5.2 - Conventional Baseline Configuration Range Trade-off (Datum aircraft - Range=1250 N Mile)

Range Case	NM	1000	1250	1500	1750	2000	2250	2500	2750	3000
Fuselage Length	FT	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25
Wing Area	SQFT	459.48	481.05	503.88	529.03	551.01	575.44	601.11	627.65	656.26
Wing Aspect Ratio		8.30	8.30	8.30	8.30	8.30	8.30	8.30	8.30	8.30
Wing 1/4 Chord Sweep	DEG	14.50	14.50	14.50	14.50	14.50	14.50	14.50	14.50	14.50
Canard Area	SQFT	66.63	69.75	73.06	76.71	79.90	83.44	87.16	91.01	95.16
Canard Aspect Ratio		5.50	5.50	5.50	5.50	5.50	5.50	5.50	5.50	5.50
Canard 1/4 Chord Sweep	DEG	15.00	15.00	15.00	15.00	15.00	15.00	15.00	15.00	15.00
Canard to Wing Area Ratio		0.1450	0.1450	0.1450	0.1450	0.1450	0.1450	0.1450	0.1450	0.1450
Engine Max. St. T/O Thrust	LB	9041	9291	9557	9852	9923	10140	10370	10609	10860
M.T.O.W.	LB	43669	45726	47897	50282	52351	54666	57120	59662	62349
O.E.W.	LB	26348	26979	27677	28451	29020	29742	30510	31308	32157
E.W.	LB	25274	25899	26591	27359	27924	28641	29403	30196	31038
Fuel Weight	LB	7321	8747	10220	11831	13331	14923	16609	18354	20192
T/O Wing Loading	PSF	83.0	83.0	83.0	83.0	83.0	83.0	83.0	83.0	83.0
T/O Canard Loading	PSF	83.0	83.0	83.0	83.0	83.0	83.0	83.0	83.0	83.0
T/O Thrust to Weight Ratio		0.414	0.406	0.399	0.392	0.379	0.371	0.363	0.356	0.348
Cruise Mach No.		0.81	0.81	0.81	0.81	0.80	0.79	0.79	0.79	0.78
Cruise Speed (TAS)	KT	466.4	466.7	467.2	467.0	460.6	458.5	456.4	454.4	452.3
Cruise Height	FT	35000	35000	35000	35000	35000	35000	35000	35000	35000
Cruise LD		12.02	12.24	12.47	12.72	13.09	13.37	13.64	13.92	14.19
Approach Speed (EAS)	KT	117.0	116.9	116.8	116.6	116.5	116.4	116.4	116.4	116.3
Approach Speed (TAS)	KT	130.6	130.5	130.3	130.2	130.0	129.9	129.9	129.9	129.8
T/O Stall Speed (TAS)	KT	116.5	117.4	118.2	118.9	119.7	120.2	120.6	121.0	121.2
Landing Stall Speed (TAS)	KT	101.5	102.2	102.9	103.3	103.9	104.3	104.7	105.0	105.2
T/O Flap (angle/CLmax)	DEG/	15/2.155	15/2.158	15/2.158	15/2.157	15/2.158	15/2.158	15/2.159	15/2.16	15/2.16
Landing Flap (angle/CLmax)	DEG/	40/2.839	40/2.845	40/2.851	40/2.858	40/2.863	40/2.868	40/2.869	40/2.87	40/2.872
FAR 25 T/O Field Length	FT	5280.8	5360.5	5441.1	5505.5	5658.3	5747.6	5855.4	5954.3	6062.9
FAR 25 Land. Field Length	FT	4506.2	4496.0	4485.3	4474.3	4460.2	4450.9	4447.4	4444.4	4438.3
Mission Range	NM	1000.20	1250.43	1494.02	1751.02	2008.36	2252.37	2501.73	2747.19	2995.65
Block Fuel	LB	5592	6965	8390	9960	11440	12994	14648	16342	18135
Block Time	HR	2.467	3.004	3.525	4.078	4.691	5.245	5.816	6.382	6.961
Aircraft Price	US\$	17.3E+06	17.0E+06	17.9E+06	18.3E+06	18.4E+06	18.7E+06	19.0E+06	19.4E+06	19.7E+06
O.O.C./Flight	US\$/Flight	2714.28	3226.02	3943.71	4619.85	5321.85	6009.79	6737.13	7479.25	8259.99
O.O.C./N Mile	US\$/NM	2.71	2.66	2.64	2.64	2.65	2.67	2.69	2.72	2.76

Table 5.3 - Three-Surface Baseline Configuration Range Trade-off (Datum Aircraft - Range=1250 N Mile)

Range Case	NM	1000	1250	1500	1750	2000	2250	2500	2750	3000
Fuselage Length	FT	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25
Wing Area	SQFT	413.31	435.30	456.00	478.68	503.65	524.96	549.90	574.98	600.79
Wing Aspect Ratio		8.88	8.88	8.88	8.88	8.88	8.88	8.88	8.88	8.88
Wing 1/4 Chord Sweep	DEG	14.88	14.88	14.88	14.88	14.88	14.88	14.88	14.88	14.88
Engine Max. St. T/O Thrust	LB	9457	9756	10029	10332	10664	10700	10937	11176	11424
M.T.O.W.	LB	43397	45707	47880	50261	52883	55120	57740	60373	63083
O.E.W.	LB	25856	26632	27344	28125	28968	29691	30543	31362	32200
E.W.	LB	24783	25554	26260	27034	27870	28590	29436	30250	31081
Fuel Weight	LB	7541	9074	10536	12136	13916	15429	17197	19010	20883
T/O Wing Loading	PSF	105.0	105.0	105.0	105.0	105.0	105.0	105.0	105.0	105.0
T/O Thrust to Weight Ratio		0.436	0.427	0.419	0.411	0.403	0.398	0.379	0.370	0.362
Cruise Mach No.		0.83	0.83	0.83	0.83	0.83	0.81	0.81	0.80	0.79
Cruise Speed (TAS)	KT	477.3	479.3	476.7	476.6	477.0	469.1	465.1	461.5	457.4
Cruise Height	FT	35000	35000	35000	35000	35000	35000	35000	35000	35000
Cruise L/D		11.47	11.72	11.92	12.15	12.39	12.83	13.12	13.41	13.68
Approach Speed (EAS)	KT	122.3	122.2	122.0	121.9	121.7	121.6	121.5	121.4	121.4
Approach Speed (TAS)	KT	136.5	136.3	136.2	136.0	135.8	135.7	135.6	135.5	135.5
T/O Stall Speed (TAS)	KT	120.0	120.0	120.0	120.0	119.9	119.9	119.9	119.9	119.9
Landing Stall Speed (TAS)	KT	104.7	104.7	104.5	104.3	104.2	104.1	104.0	104.0	103.9
T/O Flap [angle/CLmax]	DEG/	15./2.501	15./2.503	15./2.504	15./2.505	15./2.505	15./2.506	15./2.507	15./2.507	15./2.508
Landing Flap [angle/CLmax]	DEG/	40./3.288	40./3.296	40./3.303	40./3.31	40./3.318	40./3.325	40./3.333	40./3.336	40./3.337
FAR 25 T/O Field Length	FT	5383.8	5475.7	5543.9	5612.4	5706.5	5867.2	5974.4	6076.5	6188.1
FAR 25 Land. Field Length	FT	4819.9	4807.5	4795.9	4784.1	4771.9	4757.0	4744.1	4737.1	4732.2
Mission Range	NM	999.91	1262.25	1490.90	1737.17	1997.76	2248.64	2497.06	2748.95	2994.48
Block Fuel	LB	5717	7186	8601	10156	11873	13378	15090	16879	18711
Block Time	HR	2.408	2.950	3.445	3.964	4.510	5.118	5.694	6.284	6.874
Aircraft Price	US\$	17.2E+06	17.5E+06	17.8E+06	18.2E+06	18.6E+06	18.8E+06	19.2E+06	19.5E+06	19.8E+06
D.O.C./Flight	US\$/Flight	2675.84	3307.73	3902.71	4548.69	5251.71	5969.32	6713.30	7487.52	8279.82
D.O.C./N Mile	US\$/N Mile	2.68	2.62	2.62	2.62	2.63	2.66	2.69	2.72	2.77

Table 5.4 - Minimum D.O.C. Conventional Configuration Range Trade-off (Datum aircraft - Range=1250 N Mile)

Range Case	NM	1000	1250	1500	1750	2000	2250	2500	2750	3000
Fuselage Length	FT	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25
Wing Area	SQFT	391.21	409.06	428.72	449.25	471.60	493.79	517.05	542.30	568.11
Wing Aspect Ratio		8.40	8.40	8.40	8.40	8.40	8.40	8.40	8.40	8.40
Wing 1/4 Chord Sweep	DEG	14.51	14.51	14.51	14.51	14.51	14.51	14.51	14.51	14.51
Canard Area	SQFT	61.93	64.77	67.87	71.12	74.65	78.17	81.85	85.85	89.93
Canard Aspect Ratio		6.10	6.10	6.10	6.10	6.10	6.10	6.10	6.10	6.10
Canard 1/4 Chord Sweep	DEG	20.55	20.55	20.55	20.55	20.55	20.55	20.55	20.55	20.55
Canard to Wing Area Ratio		0.1583	0.1583	0.1583	0.1583	0.1583	0.1583	0.1583	0.1583	0.1583
Engine Max. St. T/O Thrust	LB	8656	8899	9171	9451	9754	10057	10375	10718	11069
M.T.O.W.	LB	42141	44050	46186	48385	50779	53170	55685	58414	61204
O.E.W.	LB	25080	25678	26346	27038	27796	28551	30510	30216	31106
E.W.	LB	24020	24612	25275	25961	26712	27461	29403	29113	29995
Fuel Weight	LB	7060	8372	9840	11347	12983	14618	16609	18198	20098
T/O Wing Loading	PSF	93.0	93.0	93.0	93.0	93.0	93.0	93.0	93.0	93.0
T/O Canard Loading	PSF	93.0	93.0	93.0	93.0	93.0	93.0	93.0	93.0	93.0
T/O Thrust to Weight Ratio		0.411	0.404	0.397	0.391	0.384	0.378	0.373	0.367	0.362
Cruise Mach No.		0.79	0.80	0.80	0.80	0.80	0.80	0.81	0.81	0.81
Cruise Speed (TAS)	KT	458.1	459.3	459.8	461.1	462.6	464.0	465.4	466.9	468.4
Cruise Height	FT	35000	35000	35000	35000	35000	35000	35000	35000	35000
Cruise L/D		12.06	12.26	12.50	12.71	12.94	13.15	13.35	13.57	13.77
Approach Speed (EAS)	KT	124.6	124.5	124.3	124.2	124.0	123.9	123.8	123.7	123.7
Approach Speed (TAS)	KT	139.0	138.9	138.7	138.6	138.4	138.2	138.1	138.1	138.1
T/O Stall Speed (TAS)	KT	128.1	128.9	129.7	130.4	131.0	131.4	131.8	132.2	132.4
Landing Stall Speed (TAS)	KT	111.8	112.3	113.0	113.4	113.8	114.1	114.4	114.6	114.9
T/O Flap (angle/CLmax)	DEG/	15./2.136	15./2.136	15./2.137	15./2.138	15./2.139	15./2.139	15./2.14	15./2.141	15./2.141
Landing Flap (angle/CLmax)	DEG/	40./2.806	40./2.811	40./2.818	40./2.824	40./2.831	40./2.838	40./2.843	40./2.844	40./2.846
FAR 25 T/O Field Length	FT	5335.4	5994.8	6075.0	6155.0	6232.7	6320.9	6386.2	6458.5	6548.6
FAR 25 Land. Field Length	FT	4977.3	4965.6	4955.3	4942.9	4929.9	4918.7	4910.5	4907.3	4904.4
Mission Range	NM	1000.25	1239.81	1495.17	1741.10	1998.94	2247.47	2492.61	2746.16	2991.22
Block Fuel	LB	5401	6675	8104	9534	11111	12696	14353	16144	17974
Block Time	HR	2.500	3.018	3.572	4.039	4.647	5.173	5.688	6.216	6.723
Aircraft Price	US\$	16.7E+06	17.0E+06	17.3E+06	17.6E+06	18.0E+06	18.3E+06	18.7E+06	19.1E+06	19.7E+06
D.O.C./Flight	US\$/Flight	2665.74	3239.85	3873.02	4497.98	5171.95	5841.37	6524.81	7253.99	7985.00
D.O.C./N Mile	US\$/NM	2.67	2.61	2.59	2.58	2.59	2.60	2.62	2.64	2.67

Table 5.5 - Minimum D.O.C. Three-Surface Configuration Range Trade-off (Datum aircraft - Range=1250 N Mile)

Range Case	NM	1000	1250	1500	1750	2000	2250	2500	2750	3000
Fuselage Length	FT	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25
Wing Area	SQFT	412.49	434.67	458.64	481.85	502.87	524.43	548.47	575.61	601.25
Wing Aspect Ratio		8.72	8.72	8.72	8.72	8.72	8.72	8.72	8.72	8.72
Wing 1/4 Chord Sweep	DEG	18.57	18.57	18.57	18.57	18.57	18.57	18.57	18.57	18.57
Engine Max. St. T/O Thrust	LB	9482	9785	10107	10419	10514	10720	10951	11213	11462
M.T.O.W.	LB	43309	45639	48155	50592	52799	55063	57587	60437	63128
D.E.W.	LB	25739	26619	27520	28297	28947	29661	30497	31383	32212
E.W.	LB	24667	25540	26434	27205	27851	28560	29390	30269	31093
Fuel Weight	LB	7570	9020	10635	12294	13852	15402	17090	19054	20916
T/O Wing Loading	PSF	105.0	105.0	105.0	105.0	105.0	105.0	105.0	105.0	105.0
T/O Thrust to Weight Ratio		0.438	0.429	0.42	0.412	0.398	0.389	0.38	0.371	0.363
Cruise Mach No.		0.83	0.84	0.83	0.83	0.82	0.81	0.81	0.80	0.79
Cruise Speed (TAS)	KT	480.8	482.4	480.1	480.6	473.2	469.6	465.7	461.8	457.9
Cruise Height	FT	35000	35000	35000	35000	35000	35000	35000	35000	35000
Cruise L/D		11.43	11.68	11.92	12.15	12.53	12.80	13.08	13.38	13.65
Approach Speed (EAS)	KT	124.4	124.2	124.1	123.9	123.8	123.7	123.7	123.7	123.6
Approach Speed (TAS)	KT	138.8	138.6	138.4	138.3	138.1	138.0	138.0	138.0	138.0
T/O Stall Speed (TAS)	KT	121.8	121.7	121.7	121.7	121.7	121.7	121.7	121.6	121.6
Landing Stall Speed (TAS)	KT	106.5	106.3	106.2	106.1	105.9	105.9	105.9	105.9	105.8
T/O Flap (angle/CLmax)	DEG/	15./2.431	15./2.432	15./2.433	15./2.433	15./2.434	15./2.434	15./2.435	15./2.436	15./2.436
Landing Flap (angle/CLmax)	DEG/	40./3.179	40./3.187	40./3.195	40./3.203	40./3.21	40./3.213	40./3.214	40./3.216	40./3.217
FAR 25 T/O Field Length	FT	5521.2	5598.1	5678.1	5753.1	5900.5	6012.1	6111.9	6236.3	6357.2
FAR 25 Land. Field Length	FT	4953.7	4940.5	4926.4	4914.1	4899.1	4891.4	4886.0	4880.3	4875.5
Mission Range	NM	1005.04	1249.73	1498.98	1753.78	2007.15	2239.11	2481.40	2748.56	2993.71
Block Fuel	LB	5735	7137	8680	10278	11835	13330	14994	16902	18736
Block Time	HR	2.404	2.907	3.441	3.971	4.563	5.092	5.653	6.279	6.865
Aircraft Price	US\$	17.1E+06	17.6E+06	18.0E+06	18.3E+06	18.5E+06	18.8E+06	19.1E+06	19.5E+06	19.8E+06
D.O.C./Flight	US\$/Flight	2672.41	3269.62	3920.66	4582.31	5282.69	5941.08	6665.42	7488.66	8278.03
D.O.C./N Mile	US\$/NM	2.66	2.62	2.62	2.61	2.63	2.65	2.69	2.73	2.77

Table 5.6 - Minimum Max. Take-off Weight Conventional Configuration Range Trade-off (Datum aircraft - Range=1250 N Mile)

Range Case	NM	1000	1250	1500	1750	2000	2250	2500	2750	3000
Fuselage Length	FT	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25	79.25
Wing Area	SQFT	400.71	419.08	439.70	461.48	483.68	506.55	530.01	555.00	576.41
Wing Aspect Ratio		8.84	8.84	8.84	8.84	8.84	8.84	8.84	8.84	8.84
Wing 1/4 Chord Sweep	DEG	16.12	16.12	16.12	16.12	16.12	16.12	16.12	16.12	16.12
Canard Area	SQFT	68.76	71.91	75.45	79.19	83.00	86.92	90.95	95.24	98.91
Canard Aspect Ratio		6.01	6.01	6.01	6.01	6.01	6.01	6.01	6.01	6.01
Canard 1/4 Chord Sweep	DEG	18.24	18.24	18.24	18.24	18.24	18.24	18.24	18.24	18.24
Canard to Wing Area Ratio		0.1716	0.1716	0.1716	0.1716	0.1716	0.1716	0.1716	0.1716	0.1716
Engine Max. St. T/O Thrust	LB	8598	8842	9113	9400	9693	9997	10307	10459	10687
M.T.O.W.	LB	42608	44576	46769	49074	51438	53895	56399	59022	61318
O.E.W.	LB	26597	26236	26950	27709	28488	29296	30124	30900	31622
E.W.	LB	24536	25170	25878	26631	27403	28205	29027	29798	30515
Fuel Weight	LB	7011	8340	9809	11365	12951	14599	16275	18122	19696
T/O Wing Loading	PSF	90.8	90.8	90.8	90.8	90.8	90.8	90.8	90.8	90.8
T/O Canard Loading	PSF	90.8	90.8	90.8	90.8	90.8	90.8	90.8	90.8	90.8
T/O Thrust to Weight Ratio		0.404	0.397	0.390	0.383	0.377	0.371	0.365	0.354	0.348
Cruise Mach No.		0.79	0.79	0.79	0.80	0.80	0.80	0.80	0.79	0.79
Cruise Speed (TAS)	KT	456.1	457.2	458.4	459.8	461.2	462.7	463.2	458.0	456.1
Cruise Height	FT	35000	35000	35000	35000	35000	35000	35000	35000	35000
Cruise LD		12.28	12.50	12.72	12.95	13.16	13.38	13.60	13.97	14.22
Approach Speed (EAS)	KT	123.7	123.6	123.5	123.3	123.2	123.1	122.9	122.9	122.9
Approach Speed (TAS)	KT	138.0	137.9	137.7	137.6	137.4	137.3	137.2	137.1	137.1
T/O Stall Speed (TAS)	KT	124.1	124.7	125.2	125.6	125.9	126.2	126.4	126.8	126.9
Landing Stall Speed (TAS)	KT	108.4	108.8	109.2	109.4	109.6	109.7	109.7	110.1	110.2
T/O Flap (angle/CLmax)	DEG/	15/2.118	15/2.119	15/2.12	15/2.121	15/2.121	15/2.122	15/2.123	15/2.123	15/2.124
Landing Flap (angle/CLmax)	DEG/	40/2.777	40/2.783	40/2.79	40/2.796	40/2.802	40/2.808	40/2.815	40/2.817	40/2.818
FAR 25 T/O Field Length	FT	5917.7	6004.9	6082.8	6156.1	6235.3	6324.3	6392.0	6567.6	6660.8
FAR 25 Land. Field Length	FT	4921.3	4911.8	4899.5	4888.1	4877.2	4868.0	4857.7	4848.1	4845.2
Mission Range	NM	997.59	1238.91	1493.03	1749.03	1997.71	2244.05	2485.24	2770.17	2990.79
Block Fuel	LB	5379	6658	8085	9575	11102	12690	14308	16142	17682
Block Time	HR	2.505	3.032	3.580	4.131	4.661	5.183	5.700	6.384	6.895
Aircraft Price	US\$	16.9E+06	17.2E+06	17.5E+06	17.8E+06	18.2E+06	18.6E+06	18.9E+06	19.2E+06	19.5E+06
D.O.C./Flight	US\$/Flight	2681.99	3267.41	3902.10	4559.29	5218.33	5890.85	6576.83	7422.18	8099.91
D.O.C./N Mile	US\$/N Mile	2.69	2.64	2.61	2.61	2.61	2.63	2.65	2.68	2.71

Table 5.7 - Minimum Max. Take-off Weight Three-Surface Configuration Range Trade-off (Datum aircraft - Range=1250 N Mile)

6 Discussion and Recommendations

6.1 Aircraft Conceptual Design Tools and Optimisation

In order to support the establishment of a strategy for carrying out the present investigation, a survey of past work on computerized aircraft design synthesis methods was initially done, as shown in section 2.1. A design synthesis tool was needed where many attributes learned from past systems such as flexibility, modularity, adaptability, open-ended structure and well commented coding should be considered. The tool should provide a fast and credible means for systematically assessing new designs of the transport class which in turn should provide consistent results for conventional and equivalent three-surface configurations in order to meet the same initial mission specification, and amenable to comparison. Additionally, the system should be coupled to an available numerical minimization technique, the RAE RQPMIN code, capable of driving the design synthesis in order to find the particular design solution which, while meeting the mission specification and satisfying the airworthiness requirements and performance constraints, should offer the lowest value of the cost function. In this case, either DOC or MTOW for both the envisioned aircraft concepts.

Development of an initial design synthesis tool was planned to incorporate existing CoA disciplinary analysis programs. An overall assessment of the suitability of these tools for the present investigation was made, indicating that considerable development work should be pursued in order to complete the system. This would involve compatibilization among the several codes, development of additional programs to account for features and design needs not accounted for in the existing codes, their adaptation, streamlining, integration, and appropriate modification to allow for the design of the three-surface configuration. These requirements were partially complied with the development of a preliminary parametric analysis module called PREliminary SIZing (PRESIZ), a MASS estimation program for narrow body jet transport aircraft and the correction of the MITCHELL code for the evaluation of the stability and control characteristics of rigid aeroplanes. However, this work was abandoned as the opportunity for using the NASA GASP synthesis program came along. This comprehensive, and already considerably detailed code, proved to be adequate for the present research, for which appropriate modifications were carried out to extend its capability to the conceptual design of three-surface aircraft configurations. These consisted mainly in the development of appropriate routines for the sizing of the three lifting surfaces taking into account aircraft weight and balance, and longitudinal static stability and control considerations. A complete revision of the program, including its several disciplinary modules, was performed as needed to ensure consistency in the calculations and achieve full integration with RQPMIN.

As described in Chapter 3, this program represents the mathematical model of a real system, in particular an aircraft system placed in its real environment. Thus, it represents a very complex situation. In analysing any real system, the engineer has to make many concessions to reality by means of an approximate, although meaningful, abstract representation. Since, what is actually analysed is not the real system, but only an abstraction of it, caution must be exercised on the results obtained against the limitations of the model

approach. These limitations and the model accuracy were broadly described in section 3.6, however some particular aspects deserve further comment.

6.2 The Three-surface Transport Model and Design Philosophy

In section 3.6, the Aerodynamics, Weights, and Economics modules were identified as representing critical disciplinary areas likely to produce inaccuracies in the design solutions. The methods used with appropriate empirical calibration factors were shown to give reasonable results when applied to conventional configurations (the conventional design aerodynamic predictions reinforced by the satisfactory dynamic stability and control characteristics analysed with Mitchell code, and shown in Appendix G, illustrate this view). However, the same GASP methods were extended to include the design and evaluation of three-surface configurations. Canard profile and induced drag estimates were included, however the tailplane induced drag and lifting surfaces mutual interference effects were excluded. A wing efficiency term, $\eta_w = q_w / q_\infty$, could be included to reflect some loss of the air flow dynamic pressure likely to occur on the wing due to flow interactions with both the fuselage boundary layer and the canard wake. However, for a long-coupled canard (stagger $\approx 400\%$ mac), and relatively small canard to wing span ratios ($b_c / b_w \approx 0.31 \sim 0.34$), helped by a convenient canard anhedral (not considered in the computations) to increase their relative gap, it was assumed reasonable to consider this effect negligible, i.e., $\eta_w = 1$, since only a relatively small inward portion of the wing span would be affected. Fuselage interference effects were included in the evaluation of the overall aircraft profile drag in the form of an arbitrarily assumed overall drag increment of 15 drag counts (this is listed in GASP input data, Chapter 5); this increment is also used in the evaluation of the canard and wing Oswald span efficiency factors, thus reflecting an additional influence on the lifting surfaces spanwise lift distributions. This same interference drag increment was also applied in the evaluation of the conventional designs.

In their approach to evaluate the aerodynamics of their canard configured transport, Arbuckle and Sliwa¹ included the Prandtl-Munk induced drag interference terms, but reduced the computed induced drag by 10% in face of empirical evidence provided by Feistal² and theoretically demonstrated by Butler³ and Kroo⁴. However, the Prandtl-Munk theory, as indicated by previous studies and reported in section 2.2, see Rokhsaz and Selberg⁵ for example, underestimates induced drag on three-surface arrangements. Besides, the theory assumes elliptically loaded lifting surfaces and no fuselage. The more comprehensive studies conducted by Middel⁶ showed the complexity of the problem when practical issues are accounted for in designing real aircraft. He stressed the important influence the fuselage has on the overall lift distribution with implications on the actual lifting surfaces lift fractions, producing uncertainties in the estimation of the proper location of the neutral point, as computed when using, for example, the present approach in the absence of adequate empirical correction factors. It is then necessary to employ more sophisticated techniques such as aerodynamic panel methods as utilised by Middel, or to run wind tunnel tests using models of the configurations just synthesized to check, modify or, and validate the aerodynamic predictions obtained by the modified GASP aerodynamic methods for three-surface concepts. Unless proper validation is done to the methodology employed in GASP, three-surface aircraft aerodynamic predictions will remain suspect.

However, for long canard-wing staggers of about 400% mac which is the case in the current research, the "roll-up" effect of the foreplane flow onto the wing does not influence interference drag by more than a few percent¹, but fuselage interference effects on both canard and wing lift distributions (both longitudinal and spanwise), and resulting induced drag are deemed to be important and should be determined more accurately to refine and check the present results. Probably for the three-surface configuration, GASP aerodynamic predictions may represent the most significant weakness of the model, since a poor representation of these characteristics might compromise the designs obtained by posing doubts on the predicted performance and, consequently, on the estimated direct operating costs. As well known, these are very sensitive to airlines.

For the moment, it shall be assumed that, by appropriate wing twist and lifting surfaces-fuselage intersection fairings, both lift and drag characteristics as computed are actually achievable and acceptable as a first guess.

Low speed high lift conditions impose a relatively high canard maximum lift coefficient (maximum canard lift coefficient for the three-surface designs range from $CL_{max} = 2.8 \sim 2.85$ as shown in Appendix D and E, figs D2, D4.1, E8, E15, and E17.1). This certainly will add in cost, weight and drag penalties. Canard structural weight and drag are computed accounting only for the lift fraction carried by the foreplane. At least a double slotted Fowler flap as employed in the main wing is needed on the canard to achieve this level of high lift. Additionally, this flap has to provide adequate pitch control in assisting the tail elevator for trim. Thus a complex and costly canard flap system is anticipated, where the corresponding RDE&T costs will play a significant part. For a first evaluation, the canard high lift and control actuation systems were not considered in the component weight predictions nor the associated development, manufacturing and maintenance costs estimated by the Economics module. Both these contributions should be quantified in the future on more detailed studies.

The three-surface configuration design philosophy, lies on the assumption that longitudinal equilibrium is achieved by two equal trimming pitching moment contributions each one provided by the canard and the tail, where the canard will also produce additional lift to assist the wing. So, the horizontal tail will only contribute in part to pitching moment equilibrium, whilst the canard will additionally share with the wing the lift required to balance the aircraft weight. This criteria is only a simplification of the actual trim problem because such aeroplanes are redundant in terms of ways of generating moments and forces to satisfy trim conditions. What happens is that, within aerodynamic limits, three independent lift forces may be generated. To maintain level trimmed flight, two conditions must be satisfied which are the equilibrium of forces ($L=W$), and the overall pitching moment must equal zero ($C_m=0$). Since the number of unknowns exceeds the number of equilibrium equations, an unlimited combination of longitudinal load distributions is possible to satisfy the trim condition which makes the system statically indeterminate. This situation offers the designer flexibility, not present in conventional nor in pure canard designs, to select the longitudinal lift distribution which minimizes (or maximizes) a given performance index. In cruise conditions a performance index to minimize could be trim drag.

One of the lessons learned from past studies, Kendall⁷ and Middel⁶, was the potential offered by the three-surface configuration in yielding minimum trim drag at all centre of gravity locations. This is attractive for general aviation and transport aeroplanes but some

type of longitudinal lift distribution optimisation is required. So, an appropriate automatic flight control system should be designed to control the incidence of both the canard and horizontal tail, or the deflections of their trailing edge control surfaces, or both in combination, in a way to minimize trim drag at arbitrary cg locations, during cruise and at any high lift mode. Costs associated with this particular flight control system should also be considered in future more detailed studies.

Regarding the present work and the figures of merit used, optimisation of the longitudinal load distribution for minimum drag could be indirectly achieved by relieving the arbitrary imposition of 0 degree setting angle of the horizontal tail, i.e., assuming this parameter is an additional design variable and allowing RQPMIN to find the incidences of the three lifting surfaces (canard, wing, and horizontal tail) while searching for the "best" aircraft. However, this would entail some changes in the synthesis aerodynamic model, at least in making allowances for induced drag on the tailplane, since the probably reasonable assumption made of neglecting this contribution may not hold. This approach would probably give better results than those obtained, although no other empirical calibration would be possible. Problems with the operation of the nonlinear programming package, and reported in Chapter 5, suggested the use of a reduced number of design variables as well as of constraint functions as possible and, at the same time, consistent with the desire of not excessively compromising the answers of the present investigation. Increasing the number of design variables would add in the multi-dimensionality of the design space, thus increasing its complexity. Constraining it further would make the numerical technique to find a feasible optimum solution more difficult. Thus, in face of problems encountered in driving the designs with the current design variables and constraint functions, it was decided to limit any potential problems to the present level and not running into difficulties of losing convergence, or of longer computer run times with their associated increased costs.

The specification of constant cruise altitude in the Performance module is somewhat restrictive, since it might play a significant part in the optimisation of any real aircraft, most importantly when the consideration of long design ranges is involved. However, this simplification was felt justified at this stage.

6.3 Multidisciplinary Synergism and Results

The Design Study

As noted above, the three-surface designs in the present work, assume both the canard and wing will produce the lift required to balance the aircraft weight. Thus, it differs from Kendall's⁷ analysis where the canard and tail only trim the aircraft for different centre of gravity locations to achieve minimum induced trim drag conditions. This author, as well as Rokhsaz and Selberg⁵, assume that all their three configurations (i.e, conventional, canard and three-surface) use the same wing, all aircraft have the same weight and do not account for any configuration synergism in the sense of taking advantage of the canard lifting capability other than that required to satisfy trim. By doing so, a smaller wing could be selected while maintaining the same wing loading even for the same aircraft weight. This was accomplished in the present approach. The equivalent three-surface baseline aircraft was derived while keeping constant the same lifting surfaces aerodynamic loading as selected for the

conventional baseline, excluding that of the horizontal tail. It is worth noting that it is possible to have a c.g. location for which the trim surface load becomes zero and the lift/weight couple is enough to balance the zero-lift moment. Since this is negative for most practical configurations, the centre of gravity for this particular condition shall lie behind the wing-body aerodynamic centre⁷. Within the assumptions made, the tail may only take a limited amount of negative load to generate its share in pitching moment to offset any changes in trim. This results in a smaller size tailplane, due to the useful positive canard trim load, and in a smaller wing which is complemented by the canard lift potential. Moreover, when comparing with equivalent conventional designs at high lift conditions, requiring the same maximum lift coefficient to satisfy field performance constraints, and with similar inherently stable static stability margins, the wing and canard together no longer need to supply the required increased maximum lift to balance the higher tail trimming download, potentially yielding a lower induced drag. This will further results in reduction of the required wing size.

Previous research^{8,9} indicated that three-surface designs can have improved high lift performance, however to also achieve efficient performance in cruise, a compromise should be worked out. An approach to this compromise was to adopt the criterion of equal canard and tail control powers for sizing purposes. For practical designs, this condition poses limits on the feasibility of the canard to wing area ratio. In the present case, where a fuselage length related to a typical 50 passenger transport with the same specified interior layout is considered, this area ratio will be bound between 0.145 and 0.175. The design strategy presented, then allows for the sizing of the canard and tail to provide the required stability and control characteristics and for possible reduction (optimisation) of the relative sizes of both the wing and horizontal tail when compared with an equivalent conventional configuration. It implies, however, the addition of a relatively small foreplane. Since all the horizontal lifting surfaces will be of a smaller size, scope for structurally lighter and more efficient components exists, thus decreasing the aircraft empty weight. For a given mission and design range, a lower empty weight combined with a good aerodynamic design may result in drag savings leading to the selection of less powerful, smaller and probably more economic engines. These will further contribute for lower drag levels and decrease of the design fuel weight. Small engines will also improve engine-out conditions. This may result in smaller fin and rudder, with the associated drag and weight savings, in favour of a better lift to drag ratio. Block fuel may even decrease for the same level of engine fuel specific consumption. It seems that the use of a canard provides a reasonable mean to achieve an improved overall aerodynamic load distribution over the aircraft configuration yielding a structurally more efficient solution. Owing to a more uniform distributed load, structural weight relief may also be encouraged in the fuselage, especially for aft engine mounted configuration types with high fuselage fineness ratios, such as exemplified by the McDonnell Douglas MD 90¹⁰. This weight relief effect can also be considered in further detailed studies. However, increases in the field length of the three-surface designs are identified. These are mainly due to wing geometric constraints which affect flap size, thus decreasing the available maximum lift coefficient. For the same flap type and the same flap to wing span ratio, as used for the equivalent conventional designs, reduction in wing size entails a smaller wing high lift device being applied. All these effects influence the overall design towards a reduced MTOW, better cruise performance, although compromised by field length requirements, and operational profitability to the airliner through reduced direct operating costs.

While keeping the aircraft wing loading constant, replacement of the conventional baseline by an equivalent three-surface configuration is viewed as a powerful way to improve it, through multidisciplinary synergism as just described. The improvement approximates that obtained by optimising the baseline designs (figs 5.11 and 5.12). It is seen that all three-surface designs show higher cruise lift to drag ratios, thus offering better aerodynamic efficiency, than their equivalent conventional counterparts (table 5.1). Range trade-off studies indicated that all designs benefited from better cruise lift to drag ratios for increased design ranges as well as from longer cruise stage legs. However, three-surface designs are slightly better with the advantage of being less cost sensitive at longer ranges than the equivalent classical designs (figs 5.11, 5.12; tables 5.2 through 5.7). Within the economic assumptions made, a DOC benefit of about 4.7% for the three-surface baseline datum design (Range=1250 NM) was found, which increases linearly up to 7.9% at a design range of 3000 NM. On the other hand, when the designs were optimised for minimum DOC, the tail-aft and the three-surface concepts offered respectively a 6.1% and 6.4% DOC advantage at 1250 NM design range, and 7.6% and 10.9% at 3000 NM range. Additionally, the three-surface designs showed weight savings with regard to all the conventional designs, including the optimised ones, at design ranges above 1250 NM (figs 5.11 and 5.12). For all design ranges considered, an average weight saving of 3.45% was identified for the three-surface designs with respect to their equivalent conventional designs, where all the configurations were optimised for DOC. Similar trends were found for minimum MTOW optimisation cases. Whichever the performance index used, DOC or MTOW, no significant differences were found on the optimum designs generated. This may be due to the prevailing cost scenario as assumed. Should the economic environment change, probably the optimum designs would be different^{11,12}.

All designs driven by the mathematical constrained minimization technique experienced an increase in wing loading. This suggests a reduction in the wetted area of the lifting surfaces leading to lower aircraft total drag (fig 6.1) and weight levels, as well as improvement of the ride quality characteristics, hence in passenger comfort standards. Minimum DOC designs (for Range=1250 NM) experienced drag reductions of about 16.6% for the conventional design, and 7.9% for the three-surface respectively with regard to the corresponding baseline configurations. With respect to the conventional baseline, the three-surface baseline overall drag reduced in 7.7%, while that of the optimised one was 15% lower. However, the resulting engine thrust levels on the optimised conventional designs didn't decrease so much as it happened on the optimised three-surface configurations. In fact, the optimised tail-aft designs show higher take-off sea level static thrust to weight ratios than their related baseline design (3.1% more was found on the minimum DOC conventional datum design), whilst the reverse is true for the optimised three-surface designs which show a relative decrease in this ratio (table 5.1 and fig 6.2). This is due to the reduction in cruise lift to drag ratios experienced by the conventional optimised designs, while the three-surface optimised configurations offer an improved aerodynamic efficiency (table 5.1).

Figures 7.3 through 7.5 show the impact of the design range on the aircraft Operating Empty to Maximum Take off Weight (OEW/MTOW) ratios. This ratio decreases with increased range in virtue of the increased amount of fuel required to satisfy it, but also gives an indication on how efficient the design is to accomplish its mission. For small ranges its sensitivity also increases with trip length variations which reflects the difficulty associated with the design of successful short-haul aircraft¹³. Fig 6.3 shows the reductions in this ratio

when the three-surface concept is adopted instead of the conventional one (baselines). Further decrease on the optimised designs OEW/MTOW ratio is also experienced for all ranges. However, a slight improvement is observed on the DOC optimised three-surface ratios, which increases with range, when compared with their equivalent optimised conventional designs. Fig 6.5 shows the OEW/MTOW ratios pertaining to the optimised design studies. The curves of both conventional design optimisations, (DOC and MTOW), match. This reinforces the feeling that both DOC and MTOW optimisations virtually give identical answers for the present case. However, the minimum MTOW three-surface configuration designs show higher values for the OEW/MTOW ratios which are close to the corresponding values of their baselines (fig 6.4). This illustrates the local nature of the optimum results, as obtained by RQPMIN, rather than the desired global optimum. This particularity represents a limitation of the gradient-based minimization techniques. It is recalled that the minimum weight for this configuration, which was the best achieved from all the weight optimisations performed, came up slightly higher than that obtained from the minimum DOC optimisation (section 5.4).

The above differences, attributes, and trends may also suggest the three-surface transport aircraft offers a greater stretch potential.

As seen, there is an intimate coupling among every engineering discipline, and their interrelating influences shall be adequately modelled for any comprehensive and useful assessment. Methods and techniques used for the conceptual designs were considered adequate for the purposes of the present work, however validation is required to ascertain the limitations of the aerodynamic model applied on three-surface configurations. The use of optimisation techniques in the initial project design work which guide the configuration towards the optimum was seen to be highly beneficial. The results of the present study are regarded more conclusive in nature than those obtained by others on this type of aircraft (three-surface transports), as surveyed in section 2.2. The results are based on a comprehensive model where many real life considerations, operational and practical constraints are incorporated. Because of the strong influence these considerations have on any realistic design project, they cannot be excluded if a practical and satisfactory solution is sought. As in any preliminary study, there are however limitations which are inherent to the model used, as described above. These will only be minimized by more detailed studies. Nevertheless, owing to the considerable completeness employed in the approach, practical potential merits of a three-surface transport were quantified and were clearly shown when it was compared with an equivalent mission conventional turbofan powered airliner.

Other Advantages of the Concept of Three-surface Aircraft

Another advantage offered by the three-surface against the pure canard configuration relates the main landing gear location which, for this case, works out in a favourable manner similar to that in conventional designs. Additionally, nose gear collapse may be minimized in the case of canard stall after landing touch down by preserving the remaining elevator pitch control authority. Manoeuvrability at stall might be enhanced when compared to canard and conventional aircraft. Assuming the canard stalls first, which should be ensured by careful design, both the tailplane elevator and the ailerons provide control at stall conditions. On pure canard arrangements a complete loss of pitch control will occur, whilst on conventional designs elevator control is still preserved but loss of lateral control can be experienced although it may be limited, provided an appropriate inboard spanwise location of the stall

initiation is ensured.

All these advantages, combined with the prospects of maintaining minimum trimmed drag at all centre of gravity locations with an appropriate flight control system, better cruise lift to drag ratios and the potential for synergetically achieving savings in weight, contributing to reduced direct operating costs as quantified and shown in Chapter 5, make the three-surface concept an attractive choice to the airline transport industry. Although these cost benefits seem apparently very small, they may turn to be meaningful for an airline in the long run. It appears there is a justifiable and well founded interest on the application of the three-surface concept to transport aircraft.

RQPMIN - Constrained Optimisation Numerical Technique

Problems with the operation of the optimisation technique (RQPMIN) were identified and commented in section 5.4. These suggest some improvement can be made in the future. It is worth mention that some results uncovered an ill-conditioning condition affecting the method coverage criteria. Thus, a revision of the related coding is suggested. The implementation of a user-friendly interactivity through graphical displays, to adequately monitoring the convergence process, as referred to in the same section, would improve design visibility. This enhancement would help the users in understanding which parameters drive the design, refining the problem formulation and accelerating the optimum design process. It would also enable one to easily identify any potential problems in the mathematical programming algorithm, if it is the case.

New Technologies

The designs were based on the assumption of employing available and proven technology. Concerning the applicability of new technological advances a word of caution must be said. Its criterious use, with emphasis on reliable, safe and affordable technologies, would probably produce benefits. However it is restricted by adequate balance between increases in acquisition costs and decreases in direct operating costs, these in turn are highly dependent on the prevailing operating economic conditions^{11,12}.

Additional Work Done

Validation of the GASP design synthesis program was demonstrated for two actual conventional aircraft, the Canadair Regional Jet 100 and the Learjet 35A. The calculated MTOWs are within 7% of those of the real aircraft, using similar requirements, geometric parameters and wing loadings. Results are shown in Appendix I, and confirm its adequacy for the initial conceptual design work.

The above discussion on the GASP model for the design synthesis of three-surface transport aircraft highlighted an eventual defficiency in the aerodynamic modelling of the fuselage/canard interference due to the absence of actual empirical evidence which shall be assessed in future more detailed studies. On the other hand, interdisciplinary synergism suggests that potential structural weight savings are likely to be encouraged in the fuselage. It is also recognised that the fuselage weight estimating relationship employed, although quite elaborated, since it also depends on its weight including the contents, empennage and engine

weights and their variations during the design synthesis, probably will not predict, with the desired accuracy, the fuselage weight of unusual aircraft as it does for a conventional one. The reason being that it was developed based on a statistically derived correlation of actual conventional aircraft. Three-surface aircraft fuselage weights as computed are thought to be conservative. In trying to control these uncertainties, an inexpensive way will be by performing a sensitivity analysis on the minimum DOC conventional aircraft to incremental changes, say $\pm 10\%$ of fuselage weight and drag. Appendix J presents the results of such a study. It was shown that benefits arise from reducing both fuselage structural mass and drag. This is especially important of fuselage mass due to the large impact its changes have on range performance. Fuselage mass decrease also improves the aircraft economic worth by additionally increasing its cargo payload potential. The results indicate a very low sensitivity to drag variations. It may be reasonable to assume that a similar fuselage weight and drag sensitivity hold for the three-surface configuration transport. This fact will increase the confidence on the GASP performance and economics by minimising the impact of drag uncertainties in the final design. Because fuselage mass, as predicted for the unusual configuration, may be on the conservative side, the benefits indicated may improve with regard to the results obtained. As already suggested above, this should be confirmed in future work.

The GASP drag, mass and cost equations were reviewed to identify any discontinuities which might cause the difficulties experienced during the optimisation process. It was observed that these discontinuities were unlikely for the aircraft sizes studied, thus they would not explain the optimisation "jumps". Additionally a more detailed analysis of the convergence history diagrams of figure F1, in Appendix F, was performed. The analysis suggested that the large divergent excursions encountered during the process of minimisation may be produced by the numerical technique itself. This happens after RQPMIN experiences difficulty in improving the objective function, probably because of the particular nature of the design surface, in combination with the difficulty in satisfying the method convergence criteria. The latter one may be related with very small tolerances imposed on the problem functions. Instead of stopping, the process suddenly diverges, possibly to re-initiate a new minimisation. This work is described in Appendix K.

6.4 Suggestions for Future Work

From the foregoing, the following suggestions are made for further research work:

- Perform aerodynamic analytical studies, employing more sophisticated analytical tools, and, or wind tunnel experiments, using geometric models based on the three-surface aircraft configurations as obtained in the present study. Results should be utilised to provide empirical evidence for confirming, or calibrating the GASP aerodynamic model in order to produce more credible predictions for this concept.

- Design of a special flap control system suitable for the three-surface aircraft, and estimation of aerodynamic, weight and costs information to feedback in the iterative synthesis evaluation process. The respective actuation system weight and associated costs should be predicted as well. This is useful for checking the error incurred in the current design evaluation.
- Evaluate the costs associated with a special purpose longitudinal lift distribution optimisation flight control system and analyse its impact on the present results.
- Evaluate the potential for fuselage weight savings in case of canard application on high fineness ratio fuselages of transport aircraft.
- Modify the MITCHELL Stability and Control program to perform handling quality evaluations on three-surface aircraft.
- Revise the RQPMIN numerical technique in the light of suggestions made in the previous section, and enhance it with the addition of a flexible interactive capability.
- After adequate empirical calibration of GASP aerodynamic model, and appropriate improvement of RQPMIN have been made, optimisation of the baseline designs should be performed with the canard, wing and tail incidence setting angles as additional design variables to allow for the longitudinal load distribution optimisation. Other design variables could be employed as, for example, the longitudinal stability static margin to assess its impact on the overall optimum designs. Results should be compared with the present ones.
- Overall improvement of the design synthesis program with the incorporation of more accurate and updated analysis methods, with provision for increased design options and flexibility. The integration of a dynamic stability and control analysis module would be useful for future research. The implementation of an interactive operating mode would be desirable.

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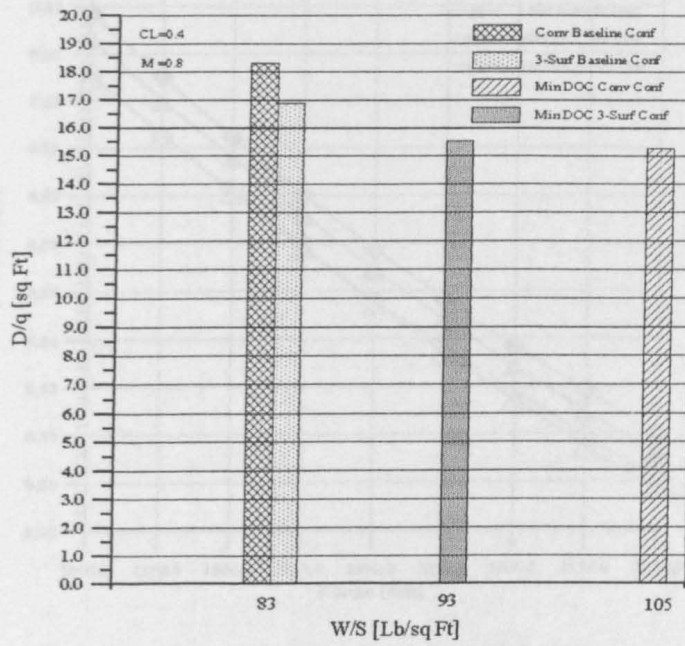


Fig 6.1 - Baseline and Min DOC Datum Designs Drag Levels

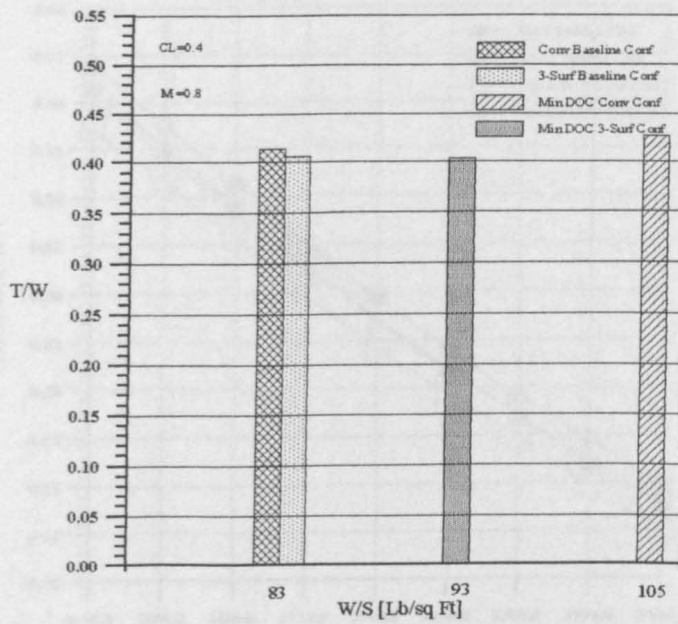


Fig 6.2 - Baseline and Min DOC Datum Designs Thrust to Weight Ratios

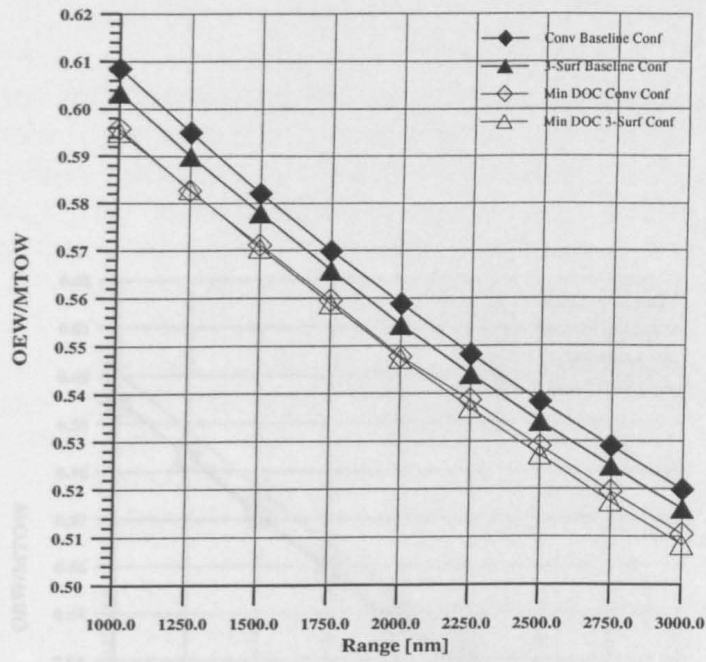


Fig 6.3 - OEW/MTOW Ratios - Range Trade-off for Min DOC Configurations versus Baseline Designs

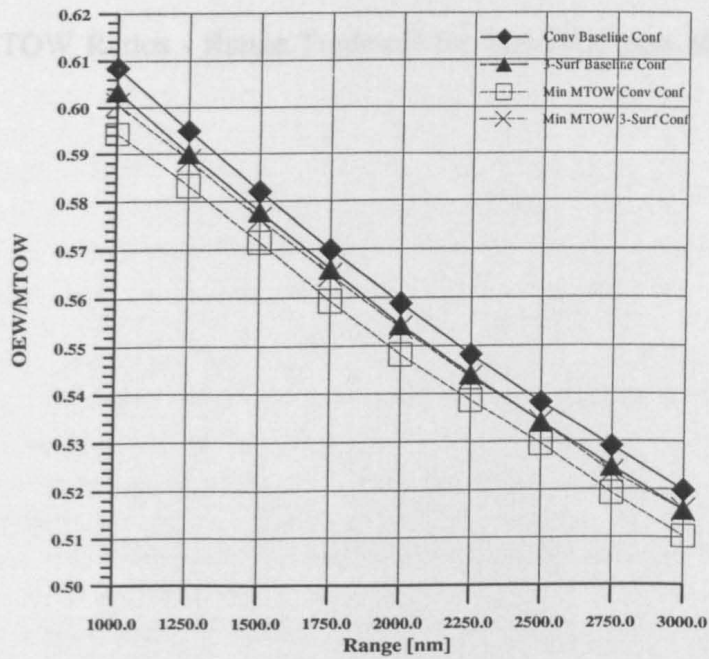


Fig 6.4 - OEW/MTOW Ratios - Range Trade-off for Min MTOW Configurations versus Baseline Designs

7. Conclusions

In this research project, advantage was taken from aerodynamic and structural aspects to design and optimise conventional and three-surface configurations transport aircraft to satisfy the same mission requirements. An integrated aerodynamic design optimisation approach was employed where typical aerodynamic disciplines, as well as their complex interactions, were taken into account. All these evaluations, whether on the level of airframe and field

performance, and stability, were conducted for both configurations of both aircraft. The results show that the three-surface aircraft configurations of both aircraft, for the same MTOWs, lifting surface area and cruise speed, were able to achieve lower OEW/MTOW ratios than the conventional designs were performed. The results also show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range. The results also show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range.

Using the same aircraft configuration, the results show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range. The results also show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range.

By keeping the aircraft configuration the same, the results show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range. The results also show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range.

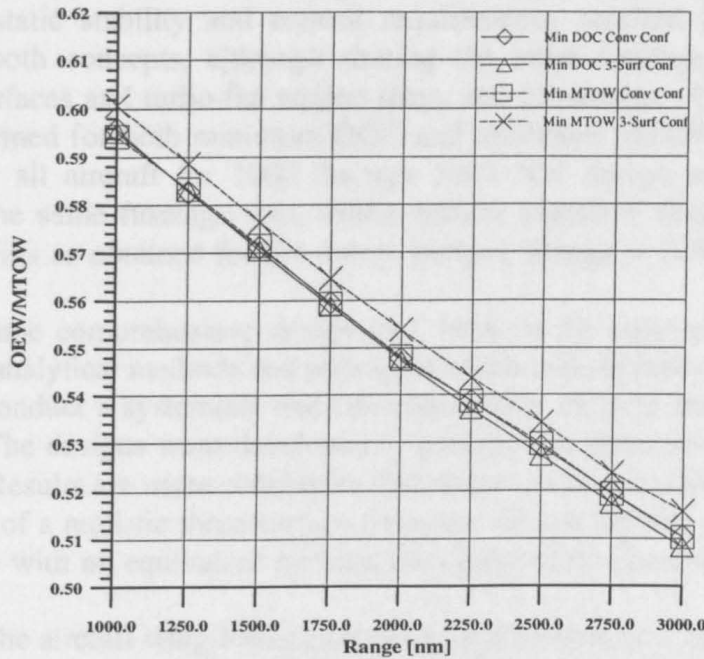


Fig 6.5 - OEW/MTOW Ratios - Range Trade-off for Min DOC and Min MTOW Designs

their equivalent conventional designs. The results show that the three-surface aircraft benefited from better cruise lift to drag ratios, as well as from longer cruise stage legs. Therefore, the three-surface aircraft have the advantage of being less cost sensitive to cruise speed changes. Within the economic assumptions used, a 10% increase in cruise speed became

datum design (Range = 1250 nm) and a 10% increase in cruise speed found, which increased linearly up to 1000 nm. The results show that the three-surface aircraft achieved minimum DOC, the value of which was 1.1% lower than the conventional aircraft. Additionally, the three-surface aircraft achieved a 1.1% lower OEW/MTOW ratio.

conventional designs, which were 1.1% higher than the three-surface aircraft for all design ranges, an average of 1.1% higher. The results show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range. The results also show that the three-surface aircraft were able to achieve lower OEW/MTOW ratios than the conventional aircraft on all parameters, including the maximum range.

7 Conclusions

In this research project, advantage was taken from aerodynamic and structural aspects to design and optimise conventional and three-surface configuration transport aircraft to satisfy the same mission requirement. An integrated conceptual design synthesis approach was employed where typical aeronautical disciplines, as well their complex interrelations, were taken into account. All these considerations, together with both cruise and field performance, and static stability and control requirements, resulted in different baseline configurations of both concepts, although sharing the same fuselage, but with different MTOWs, lifting surfaces and turbo-fan engine sizes, and economics. Optimisation of these designs were performed for both minimum DOC and minimum MTOW. Trade-off studies were conducted on all aircraft for 1000 through 3000 NM design mission ranges while keeping invariant the same fuselage size, lifting surface planform shapes and longitudinal static stability margins as obtained for the datum designs (Range = 1250 NM).

Using the same comprehensive design tool, built on the same primary assumptions, and using the same analytical methods and principles which include many real life constraints, it was possible to conduct a systematic and consistent study on both design concepts (same technology level). The designs were developed to perform the same mission, and compared on an equal basis. Results are more conclusive than those previously obtained by others, and the potential merits of a realistic three-surface transport aircraft are clearly established when comparison is made with an equivalent mission conventional jet transport.

By keeping the aircraft wing loading constant, replacement of a conventional baseline aircraft by an equivalent three-surface configuration was demonstrated to be a powerful design strategy to improve it, through multidisciplinary synergism. The improvement obtained almost mixes up with that obtained by optimising the baseline designs. All three-surface designs exhibited higher cruise lift to drag ratios, thus offering better aerodynamic efficiency than their equivalent conventional designs. Range trade-off studies indicated that all designs benefited from better cruise lift to drag ratios for increased design ranges as well as from longer cruise stage legs. However, three-surface designs are slightly better with the advantage of being less cost sensitive at longer ranges than the equivalent classical designs. Within the economic assumptions made, a DOC benefit of about 4.7% for the three-surface baseline datum design (Range=1250 NM) with respect to the conventional one was found, which increased linearly up to nearly 8% at a design range of 3000 NM. When optimised for minimum DOC, the conventional and the three-surface concepts offered a 6.1% and 6.4% DOC advantage at a 1250 NM range, respectively, and 7.6% and 10.9% at 3000 NM range. Additionally, the three-surface designs revealed weight savings with regard to all the conventional designs, including the optimised ones at design ranges above 1250 NM. For all design ranges, an average saving in weight of 3.45% was identified for the unusual designs with respect to their equivalent conventional designs, where all the configurations were optimised for DOC. Similar trends were found for minimum MTOW optimisation cases. For the figures of merit used in the optimisations, DOC or MTOW, no significant differences were found on the optimum designs generated. This may be attributed to the prevailing particular economic conditions.

All designs driven by the minimization numerical technique experienced an increase in wing loading. This produced a reduction in the wetted area of the lifting surfaces yielding both lower aircraft drag and weight. This would result in better ride quality characteristics, and comfort. However, the resulting engine thrust of the optimised conventional designs didn't experience as much a reduction as in the optimised three-surface configurations. Effectively, the optimised classical designs showed higher thrust to weight ratios than the respective baseline design, whilst the reverse was found for the optimised three-surface designs. These presented lower thrust to weight ratios than its baseline. The relatively high engine thrust of the optimised conventional designs is related to the degradation in cruise lift to drag ratios these aircraft experience, while the three-surface optimised configurations offered an improved aerodynamic efficiency. These attributes may also suggest that three-surface transports offer a greater stretch potential than the equivalent conventional aircraft.

It appears that the concept of a three-surface transport can effectively improve in terms of performance and costs when compared to conventional and canard configured aircraft designed for the same operational environment and mission profiles whose benefits tend to increase with increased design range by wisely exploiting and compromising the particular advantages offered by these two configurations. However, an overall criticism is that very little test data exists to confirm the potential drag savings predicted for the three-surface concept. Thus, more detailed studies, both analytical and experimental, on the three-surface should be done in the future as suggested in Chapter 6, for checking and validation purposes.

The importance of optimisation techniques coupled with a multidisciplinary approach for the design of real systems has again been demonstrated with the present design study. It is in complete agreement with Sobieski and Chopra¹ in their introductory note to the "Journal of Aircraft" special section on "Multidisciplinary Optimisation of Aeronautical Systems", where they anticipated that optimisation will be the primary tool to employ when designers face the question: *"How to decide what to change, and to what extent to change it, when everything influences everything else."*

References for Chapter 7:

1. Sobieszczanski-Sobieski, J.; Chopra, I.
Multidisciplinary Optimisation of Aeronautical Systems
Journal of Aircraft, Vol 27, No.12, Dec 1990

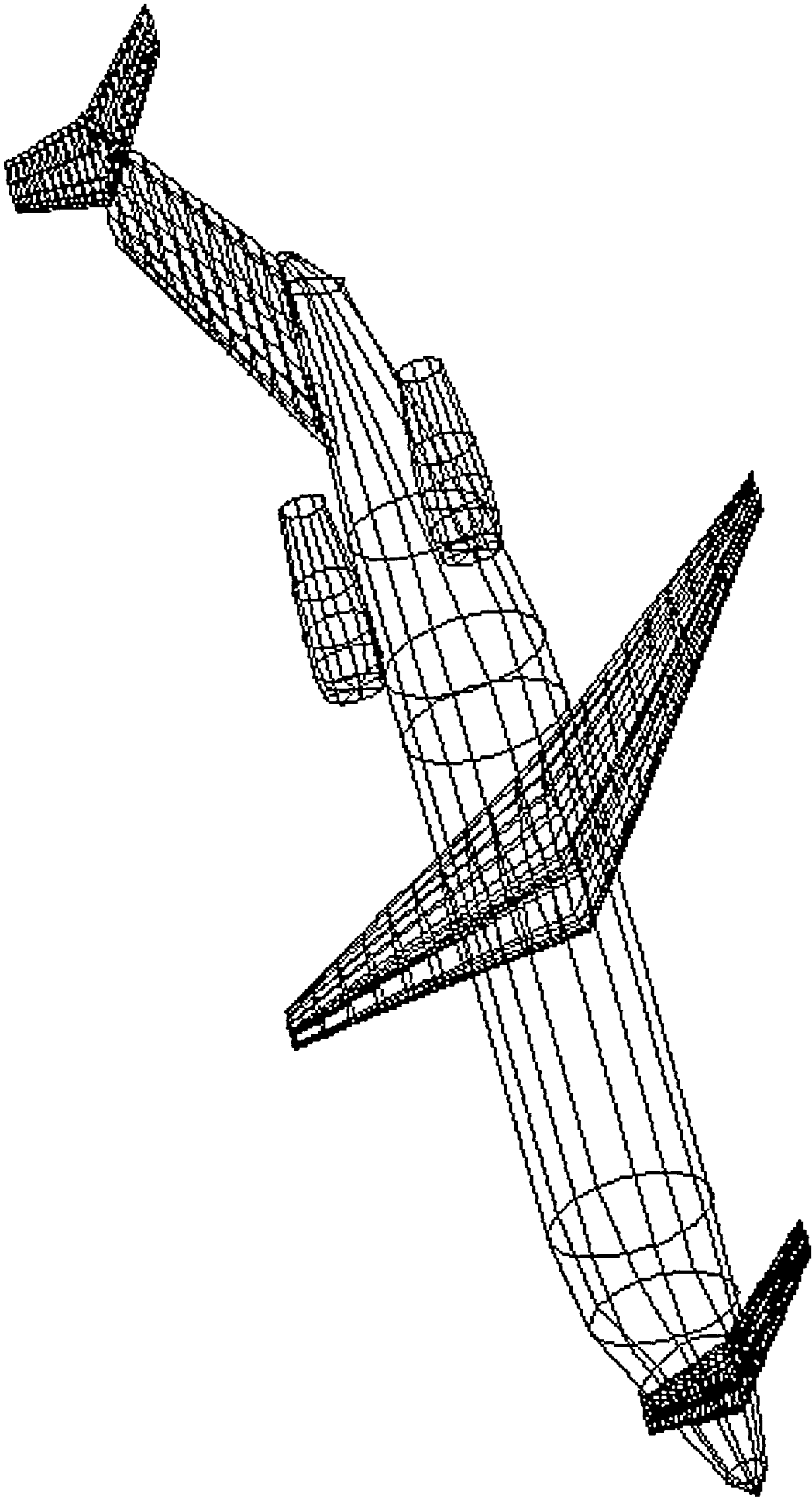


Fig 7.2 - Min DOC Three-lifting Surface Turbo-fan Transport

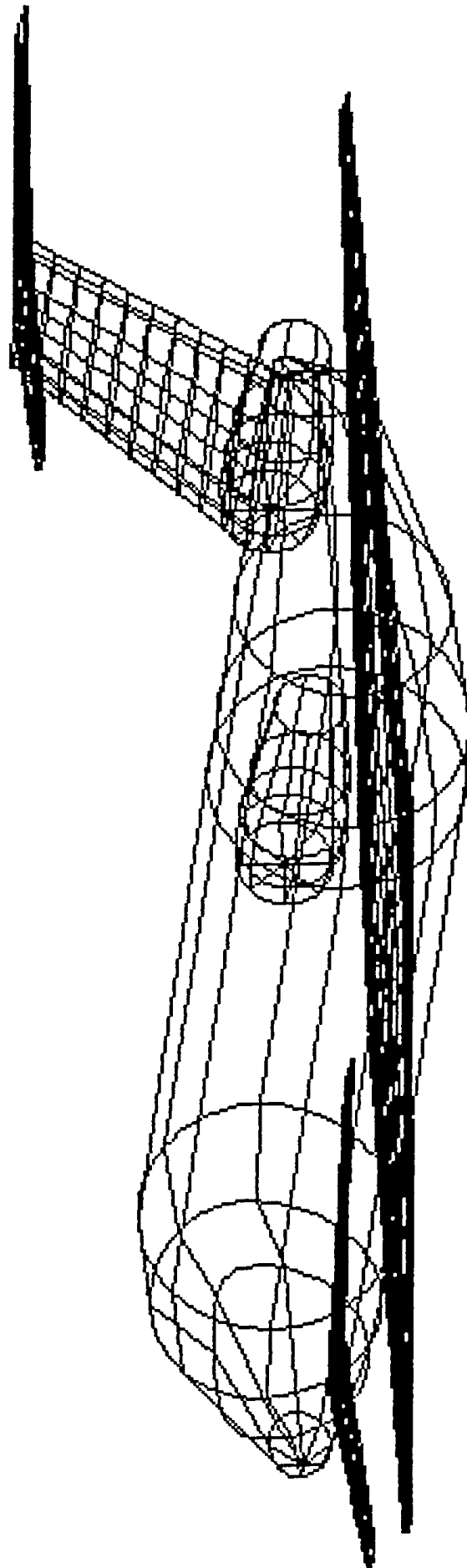


Fig 7.1 - Min DOC Three-lifting Surface Turbo-fan Transport

APPENDIX A

Longitudinal Stability and Control Considerations (stick-fixed) Applied to the Three-Lifting Surface Concept

Introduction

In this Appendix, the longitudinal static stability and control (stick fixed) equations for the three-surface concept are theoretically derived from basic principles. These equations form the basis of the procedure implemented in subroutine TAIL to size the horizontal tailplane and the canard, as shown in section 3.5.2.2 under "Aircraft Balance".

Longitudinal Stability and Control Considerations (stick-fixed) Applied to the Three-Lifting Surface Concept

A.1 Static Longitudinal Stability

Static longitudinal equilibrium of an aircraft may be studied by referring to the equation of moments about the YY axis passing through the centre of gravity. These moments and their variations with respect to the aircraft lift coefficient are considered.

The simplified case of a gliding (power-off), controls locked, flight condition is first analysed.

A.1.1 Pitching Moment Equilibrium and Static Stability Equations

From figure A.1, the equation of moment equilibrium may be written as:

$$M_{cg} = N(x_{cg} - x_{ac}) + CZ_a + M_{ac} + M_{fus} + M_{nac} + N_c(x_{cg} - x_c) + C_c Z_c + M_{ac_c} + N_t(x_{cg} - x_t) + C_t Z_t + M_{ac_t}$$

(A1)

The angle of attack, α , usually is very small and so are the wing drag related contribution at low lift coefficients and the canard and tail pitching moment and drag contributions to the overall pitching moment. This allows writing equation (A1) in a more familiar and simplified form by neglecting these influences:

$$M_{cg} = L(x_{cg} - x_{ac}) + M_{ac} + M_{fus} + M_{nac} + L_c(x_{cg} - x_c) + L_t(x_{cg} - x_t)$$

(A2)

Dividing through by $qS_w\bar{c}$, the coefficient form of equation (A2) may be written:

$$C_{m_{cg}} = C_L(\bar{x}_{cg} - \bar{x}_{ac})\eta_w + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{L_c}\bar{V}_c\eta_c + C_{L_t}\bar{V}_t\eta_t$$

(A3)

where

q is the undisturbed flow dynamic pressure,

S_w is the wing reference area,

\bar{c} is the wing mean aerodynamic chord,

$\bar{x} = \frac{x}{\bar{c}}$ are the distances as fractions of the wing mean aerodynamic chord,

$\eta_w = \frac{q_w}{q}$ is the dynamic pressure ratio at the wing to that of the undisturbed free air stream,

$\eta_c = \frac{q_c}{q}$ is the dynamic pressure ratio at the canard to that of the undisturbed free air stream,

$\eta_t = \frac{q_t}{q}$ is the dynamic pressure ratio at the tail to that of the undisturbed free air stream,

$\bar{V}_c = (\bar{x}_{cg} - \bar{x}_c) \frac{S_c}{S_w}$ is the canard volume coefficient,

$\bar{V}_t = (\bar{x}_{cg} - \bar{x}_t) \frac{S_t}{S_w}$ is the tail volume coefficient,

Since the canard is placed near the fuselage nose, it is assumed that no energy losses due to fuselage boundary layer interactions will be incurred by the air surrounding this lifting surface.

Thereby, it may be assumed that $\eta_c = 1$. However, the same can not be said for the wing due to those flow interactions with the fuselage boundary layer and with the canard induced wake. Nevertheless, it will be assumed that the canard has a small span when compared with that of the wing and, in this way, affecting only a relatively small inner portion of the wing span. Therefore, it may be reasonable to consider the wing efficiency as unity, $\eta_w = 1$. Another simplification concerns the canard downwash/upwash effects on the wing which will be assumed to be minimized through an appropriate wing twist, and for this reason will not be considered in the analysis.

Remembering that:

$$C_{L_c} = (dC_{L_c}/d\alpha_c) (\alpha_c - \alpha_{0c}) = a_c (\alpha_c - \alpha_{0c}) \quad \text{for a cambered canard,}$$

where α_{0c} is the canard zero-lift angle of attack,

$$C_{L_t} = (dC_{L_t}/d\alpha_t) \alpha_t = a_t \alpha_t \quad \text{using a symmetric aerofoil in the horizontal tail, and that}$$

$$(dC_L/d\alpha) = a_w$$

for a long coupled canard configuration, which is the case under consideration, the influence of the wing upwash on the canard may be assumed negligible, i.e., $\varepsilon_u=0$, then,

$$\alpha_c = (\alpha_w - i_w + i_c) = (\alpha_0 + \frac{1}{a_w} C_L - i_w + i_c)$$

$$\alpha_t = (\alpha_w - \varepsilon - i_w + i_t) = [\alpha_0 + \frac{1}{a_w} C_L (1 - \frac{d\varepsilon}{d\alpha}) - i_w + i_t]$$

where

α_w and i_w are the wing angles of attack and incidence, respectively,

α_0 is the wing zero-lift angle of attack,

a_w , a_c and a_t are the wing, canard and tail lift curve slopes,

i_c and i_t are the canard and tail incidence setting angles and

ε is the wing downwash angle at the tail.

Equation (A3) may now read:

$$C_{m_{cg}} = C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + a_c (\alpha_c - \alpha_{0c}) \bar{V}_c + a_t \alpha_t \bar{V}_t \eta_t$$

(A4)

or

$$C_{m_{cg}} = C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + \frac{a_c}{a_w} C_L \bar{V}_c + a_c (\alpha_0 - \alpha_{0c} - i_w + i_c) \bar{V}_c + \frac{a_t}{a_w} C_L \bar{V}_t \eta_t (1 - \frac{d\varepsilon}{d\alpha}) + a_t (\alpha_0 - i_w + i_t) \bar{V}_t \eta_t$$

(A5)

Equations (A1) through (A5) are the equilibrium equations in pitch for gliding flight, power-off, stick fixed, which must sum up to

$$C_{m_{cg}} = 0 \text{ for equilibrium.}$$

The pitching moment coefficient is a function of the lift coefficient and for longitudinal static stability to be achieved the derivative dC_m/dC_L should be negative.

Differentiating equation (A5) with respect to C_L , the stability equation for this flight condition is obtained:

$$\frac{dC_m}{dC_L} = (\bar{x}_{cg} - \bar{x}_{ac}) + \left(\frac{dC_m}{dC_L}\right)_{fus} + \left(\frac{dC_m}{dC_L}\right)_{nac} + \frac{a_c}{a_w} \bar{V}_c + \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha}\right) \quad (A6)$$

where $\frac{dC_{mac}}{dC_L} = 0$ by definition of the aerodynamic centre.

A.1.2 Neutral Point (stick-fixed)

The stick-fixed neutral point, x_{np} , is the c.g. position for which the aircraft becomes neutrally stable, i.e., $dC_m/dC_L = 0$. The neutral point establishes an absolute rear limit on the permissible c.g. travel if a stable aircraft with irreversible controls is desired.

Equating equation (A6) to zero, the aircraft neutral point may be determined:

$$\bar{x}_{np} = \bar{x}_{cg_{dC_m/dC_L=0}} = \bar{x}_{ac} - \left(\frac{dC_m}{dC_L}\right)_{fus} - \left(\frac{dC_m}{dC_L}\right)_{nac} - \frac{a_c}{a_w} \bar{V}_c - \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha}\right) \quad (A7)$$

Once the neutral point is known, the stability at any other c.g. position may be evaluated from:

$$\frac{dC_m}{dC_L} = \bar{x}_{cg} - \bar{x}_{np} \quad (A8)$$

A.1.3 Thrust Effects on Stability

For jet-powered aircraft three major contributions to equilibrium and longitudinal static stability are due to the powerplant installation:

- . the direct thrust,
- . the normal forces at the diffuser inlet, if any, and
- . the jet-induced downwash at the horizontal tail.

In most cases the thrust, T , is nearly independent of speed and may be assumed constant. For unaccelerate flight, its contribution

is:

$$\left(\frac{dC_m}{dC_L}\right)_{th} = \frac{T}{W} \frac{z_{th}}{\bar{c}}$$

(A9)

where T is the total thrust,
 W is the aircraft weight,
 z_{th} is the distance above or below the c.g. (positive if thrust line below c.g.).

The contribution from the direct normal force on the intake inlets can be evaluated from intake airflow momentum considerations:

$$\left(\frac{dC_m}{dC_L}\right)_{F_N} = \frac{W_a}{g} \frac{1 - \frac{d\epsilon}{d\alpha}}{a_w} \frac{x_{cg} - x_n}{\bar{c}} \frac{0.05}{\rho S_w v}$$

(A10)

where W_a is the weight of the air taken by the engines,
 ϵ is the downwash angle at the inlets for engines installed on the rear fuselage (which is the case),
 x_n is the distance from nose to the inlet locations,
 v is the air velocity at the inlets.

The contribution from the jet-induced downwash at the horizontal tail need be considered for those installations where the jet stream passes under or over the horizontal tail surface. The change in pitching moment coefficient due to the change in flow inclination at the horizontal tail is given by:

$$\Delta C_m = a_t \bar{V}_t \eta_t \Delta \alpha_t$$

(A11)

The change in angle of attack of the tail due to the downwash must be determined at each value of the lift coefficient and plotted against C_L . It may be predicted using the methods presented in NACA WR-L-213, in e.g. Perkins and Hage^{A1}. Finally, a plot of C_m vs C_L may be constructed.

For the purposes of this study and having in mind that the engines are located aft on the fuselage at about the same vertical location as the aircraft cg, for every configurations analysed, it will be assumed the overall effect from the power units will be destabilizing and approximately $(dC_m/dC_L)_{th} \approx 0.03$, the main contribution being due to the flow inclination at the tail. Flight test data may substantiate this assumption (see Perkins and Hage^{A1}, for example).

A.1.4 Centre of Gravity Rear Location

In order that the aircraft possess stick-fixed longitudinal stability, the most rear location for the c.g. may be determined by using equations (A7) and (A8) for a given static stability margin including the contribution from the power effects. Since these represent a destabilising term, as explained above, the power-off neutral point will shift forward roughly 3 percent of the mean aerodynamic chord as experience suggests.

A.2 Control Theory

Control moments on three-surface aircraft may be produced by changing the lift on the horizontal tail and canard. This can be accomplished by deflecting the elevator and the canardvator or changing the incidence of the tail and canard if all-moving surfaces are used.

A.2.1 Longitudinal Control Power

The magnitudes of the moment coefficients obtained per degree deflection of the elevator and the canardvator are called the control powers, and both may be evaluated analytically from equation (A4) by differentiating $C_{m_{cg}}$ with respect to

elevator deflection, δ_e and to canardvator deflection, δ_c .

It shall be assumed that the control deflections are positive downward.

The elevator power is:

$$C_{m_{\delta_e}} = \frac{dC_m}{d\delta_e} = a_t \bar{V}_t \eta_t \frac{d\alpha_t}{d\delta_e} = a_t \bar{V}_t \eta_t \tau_e$$

(A12)

and, similarly, the canardvator power is:

$$C_{m_{\delta_c}} = \frac{dC_m}{d\delta_c} = a_c \bar{V}_c \frac{d\alpha_c}{d\delta_c} = a_c \bar{V}_c \tau_c$$

(A13)

where the control effectivenesses τ_e and τ_c are functions of the ratio of the elevator or canardvator area to the whole horizontal tail or canard area, respectively. An empirically determined curve for the control effectiveness versus the area ratio is given in figure 5.33 of Perkins and Hage^{A1}.

A.2.2 Control Surface Deflections versus Equilibrium Lift Coefficient

The elevator and canardvator deflections required for equilibrium may be determined analytically from a knowledge of the pitching moment curve slope, dC_m/dC_L and the control powers,

$$C_{m_{\delta_e}}, \text{ and } C_{m_{\delta_c}}.$$

Including now the influence of the control deflections, equation (A4) may be written:

$$C_{m_{cg}} = C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + a_c (\alpha_c - \alpha_{0c} + \tau_c \delta_c) \bar{V}_c + a_t (\alpha_t + \tau_e \delta_e) \bar{V}_t \eta_t \quad (A14)$$

Note that the control of the equilibrium lift coefficient is effected solely through the influence of the terms $\tau_e \delta_e$ and $\tau_c \delta_c$.

The control angles required for equilibrium lift coefficient may be expressed by:

$$\delta_e = \delta_{e0} + \frac{d\delta_e}{dC_L} C_L \quad (A15)$$

and

$$\delta_c = \delta_{c0} + \frac{d\delta_c}{dC_L} C_L \quad (A16)$$

where δ_{e0} and δ_{c0} are the elevator and the canardvator angles at the overall zero lift.

Assuming that both contributions to the pitching moment coefficient are identical in magnitude it may be convenient to write:

$$a_c (\alpha_c - \alpha_{0c} + \tau_c \delta_c) \bar{V}_c = a_t (\alpha_t + \tau_e \delta_e) \bar{V}_t \eta_t$$

(A17)

and resolving for δ_c :

$$\delta_c = \frac{a_t}{a_c} \frac{\bar{V}_t}{V_c} \frac{\eta_t}{\tau_c} (\alpha_t + \tau_e \delta_e) - \frac{(\alpha_c - \alpha_{0c})}{\tau_c}$$

(A18)

which replaced in equation (A14) and equating it to zero, for moment equilibrium, the corresponding elevator deflection may be expressed as:

$$\delta_e = -\frac{1}{2C_{m_{\delta_e}}} [C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + 2a_t \alpha_t \bar{V}_t \eta_t]$$

(A19)

or

$$\delta_e = -\frac{1}{2C_{m_{\delta_e}}} [C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}}] - \frac{C_L}{a_w \tau_e} (1 - \frac{d\epsilon}{d\alpha}) - \frac{\alpha_0 - i_w + i_t}{\tau_e}$$

(A20)

Differentiating equation (A19) with respect to C_L , the rate of change of elevator angle with equilibrium lift coefficient may be obtained:

$$\frac{d\delta_e}{dC_L} = -\frac{1}{2C_{m_{\delta_e}}} [(\bar{x}_{cg} - \bar{x}_{ac}) + (\frac{dC_m}{dC_L})_{fus} + (\frac{dC_m}{dC_L})_{nac} + 2\frac{a_t}{a_w} \bar{V}_t \eta_t (1 - \frac{d\epsilon}{d\alpha})]$$

(A21)

or

$$\frac{d\delta_e}{dC_L} = -\frac{1}{2C_{m_{\delta_e}}} [(\bar{x}_{cg} - \bar{x}_{ac}) + (\frac{dC_m}{dC_L})_{fus} + (\frac{dC_m}{dC_L})_{nac}] - \frac{1}{a_w \tau_e} (1 - \frac{d\epsilon}{d\alpha})$$

(A22)

where the elevator power, $C_{m_{\delta_e}}$ was defined in equation (A12).

Equation (A15) may now take the form:

$$\delta_e = \delta_{e0} - \frac{C_L}{2C_{m_{\delta_e}}} \left[(\bar{x}_{cg} - \bar{x}_{ac}) + \left(\frac{dC_m}{dC_L} \right)_{fus} + \left(\frac{dC_m}{dC_L} \right)_{nac} + 2 \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\epsilon}{d\alpha} \right) \right] \quad (A23)$$

δ_{e0} may be evaluated from equation (A19) or (A20) for $C_L=0$, as follows, and assuming that at zero-lift the contribution from the fuselage and nacelles are negligible:

$$\delta_{e0} = - \frac{C_{m_{ac}}}{2C_{m_{\delta_e}}} - \frac{\alpha_0 - i_w + i_t}{\tau_e} \quad (A24)$$

the elevator angle required to vary the equilibrium lift coefficient therefore varies inversely with the elevator power $C_{m_{\delta_e}}$.

A similar treatment for the canardvator deflection will follow.

So, replacing in equation (A18) δ_e , from equation (A19), it may be written as:

$$\delta_c = - \frac{1}{2C_{m_{\delta_c}}} \left[C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + 2a_c (\alpha_c - \alpha_{0c}) \bar{V}_c \right] \quad (A25)$$

or

$$\delta_c = - \frac{1}{2C_{m_{\delta_c}}} \left[C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} \right] - \frac{C_L}{a_w \tau_c} - \frac{\alpha_0 - \alpha_{0c} - i_w + i_c}{\tau_c} \quad (A26)$$

Differentiating equation (A25) with respect to C_L , it may be written:

$$\frac{d\delta_c}{dC_L} = - \frac{1}{2C_{m_{\delta_c}}} \left[(\bar{x}_{cg} - \bar{x}_{ac}) + \left(\frac{dC_m}{dC_L} \right)_{fus} + \left(\frac{dC_m}{dC_L} \right)_{nac} + 2 \frac{a_c}{a_w} \bar{V}_c \right] \quad (A27)$$

or

$$\frac{d\delta_c}{dC_L} = -\frac{1}{2C_{m\delta_c}} [(\bar{x}_{cg} - \bar{x}_{ac}) + (\frac{dC_m}{dC_L})_{fus} + (\frac{dC_m}{dC_L})_{nac}] - \frac{1}{a_w \tau_c}$$

(A28)

and equation (A16) may take the form:

$$\delta_c = \delta_{c0} - \frac{C_L}{2C_{m\delta_c}} [(\bar{x}_{cg} - \bar{x}_{ac}) + (\frac{dC_m}{dC_L})_{fus} + (\frac{dC_m}{dC_L})_{nac} + 2\frac{a_c \bar{V}_c}{a_w}]$$

(A29)

where δ_{c0} can be evaluated from equation (A25) or (A26) for $C_L=0$, with the assumption that $C_{m_{fus}} = C_{m_{nac}} = 0$:

$$\delta_{c0} = -\frac{C_{m_{ac}}}{2C_{m\delta_c}} - \frac{\alpha_0 - \alpha_{0c} - i_w + i_c}{\tau_c}$$

(A30)

A.3 Centre of Gravity Forward Location

Evaluation of the most forward c.g. available results from the requirement that the elevator and the canardvator possess enough control authority in all flight conditions within the flight envelope, in order to bring the aircraft into equilibrium at the maximum lift coefficient, to rotate it during take-off, flaring-out on landing and yet preserve a safe margin for manoeuvring. An analysis will be carried out for free flight out of ground effect and for flight in ground effect such as during landing flare and take-off.

A.3.1 Free Flight

The maximum permissible forward c.g. for this condition will be that for which maximum up elevator and maximum down canardvator will just balance out the maximum lift coefficient.

Equations (A23) and (A29) may be used to obtain δ_e and δ_c as functions of (dC_m/dC_L) in order to find the $(dC_m/dC_L)_{Limit}$.

Then, from equation (A23), it can be written:

$$\delta_e = \delta_{e0} - \frac{C_L}{2C_{m\delta_e}} \left[\left(\frac{dC_m}{dC_L} \right) - \frac{a_c}{a_w} \bar{V}_c + \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right) \right]$$

(A31)

and from equation (A29),

$$\delta_c = \delta_{c0} - \frac{C_L}{2C_{m\delta_c}} \left[\left(\frac{dC_m}{dC_L} \right) + \frac{a_c}{a_w} \bar{V}_c - \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right) \right]$$

(A32)

Expressions for the limiting stability may be found analytically by substituting $C_{L_{max}}$, $\delta_{e_{max}}$ and $\delta_{c_{max}}$, respectively in equations (A31) and (A32), and solving for $(dC_m/dC_L)_{max}$.

Then,

$$\left(\frac{dC_m}{dC_L} \right)_{max} = \frac{2C_{m\delta_e}}{C_{L_{max}}} (\delta_{e0} - \delta_{e_{max}}) + \frac{a_c}{a_w} \bar{V}_c - \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right)$$

(A33)

and

$$\left(\frac{dC_m}{dC_L} \right)_{max} = \frac{2C_{m\delta_c}}{C_{L_{max}}} (\delta_{c0} - \delta_{c_{max}}) - \frac{a_c}{a_w} \bar{V}_c + \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right)$$

(A34)

From these two relations an expression may be obtained relating the maximum canardvator deflection to the maximum elevator deflection in order to balance the maximum lift coefficient:

$$\delta_{c_{max}} = \delta_{c0} - \frac{C_{L_{max}}}{C_{m\delta_c}} \left[\frac{C_{m\delta_e}}{C_{L_{max}}} (\delta_{e0} - \delta_{e_{max}}) + \frac{a_c}{a_w} \bar{V}_c - \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right) \right]$$

(A35)

and for any equilibrium lift coefficient the following expression may be useful:

$$\delta_c = \delta_{c0} - \frac{C_L}{C_{m\delta_c}} \left[\frac{C_{m\delta_e}}{C_L} (\delta_{e0} - \delta_e) + \frac{a_c}{a_w} \bar{V}_c - \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha} \right) \right]$$

(A36)

another relation but in terms of (dC_m/dC_L) may be obtained by combining equations (A23) and (A29):

$$\delta_c = \delta_{c0} - \frac{C_{m_{\delta_e}}}{C_{m_{\delta_c}}} (\delta_{e0} - \delta_e) \frac{\left(\frac{dC_m}{dC_L}\right) + \frac{a_c}{a_w} \bar{V}_c - \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha}\right)}{\left(\frac{dC_m}{dC_L}\right) - \frac{a_c}{a_w} \bar{V}_c + \frac{a_t}{a_w} \bar{V}_t \eta_t \left(1 - \frac{d\varepsilon}{d\alpha}\right)}$$

(A37)

Aircraft are usually more stable with power-off than they are with high power. So the critical forward location of the c.g. will be for power-off and equations (A33) and (A34) will indicate how far forward the c.g. may be moved from the power-off neutral point. The maximum allowable stability, i.e., the most forward permissible c.g. location, varies directly with the elevator

power, $C_{m_{\delta_e}}$, and with the canardvator power, $C_{m_{\delta_c}}$ and

inversely with the aircraft maximum lift coefficient. If a large c.g. range is needed according to the loading schedules, the aircraft must present large horizontal tail and canard, both of high aspect ratio and long arms to the c.g.. So, the horizontal tail and canard sizes are greatly determined by the extent of the aircraft c.g. range.

A.3.2 Landing Flare

The proximity of the ground changes the lifting surfaces induced flow field in terms of downwash reduction. This reduction in downwash entails an increase of the tail angle of attack which means that to trim out the same aircraft lift coefficient, the elevator and the canardvator will require greater deflections than those that would be required when out of the ground influence. On the other hand, the downwash reduction increases the slope of the lifting surfaces lift curves. These effects mean that the most forward location, as determined from equations (A33) or (A34), will shift rearward and to relocate it to the same point, in other words, to trim out the maximum lift coefficient, in the presence of the ground, the control deflection increases shall be determined. If not practical, the c.g. forward location should be moved rearwards becoming a more critical situation, and a compromise should be achieved.

Aircraft stability is also affected by the ground effect the main contribution coming from the reduction in wing downwash at the tail. Since ε is reduced for a given C_L , $d\varepsilon/d\alpha$ will be reduced as well increasing in this way the tail contribution to stability, i.e., moving the neutral point rearwards. As this effect is stabilising it will pose no problem.

The most forward c.g. for trimming out $C_{L_{max}}$ in the ground effect may be obtained from the equilibrium equation and including the pitching moment contribution from the engines idle thrust:

Equation (A19) may be written as:

$$\delta_e = -\frac{1}{2C_{m_{\delta_e}}} [C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}} + 2a_t (\alpha_w - \varepsilon - i_w + i_t) \bar{V}_t \eta_t] \quad (A38)$$

Rearranging this equation and replacing δ_e and C_L for $\delta_{e_{max}}$ and $C_{L_{max}}$, respectively, assuming all other variables corresponding to those at $C_{L_{max}}$ (landing configuration) and in the ground effect, the $\bar{x}_{cg_{fwd}}$ will become:

$$\bar{x}_{cg_{fwd}} = \bar{x}_{ac} - \frac{2C_{m_{\delta_e}}}{C_{L_{max}}} \left[\delta_{e_{max}} + \frac{\alpha_w - \varepsilon - i_w + i_t}{\tau_e} + \frac{C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}}}{2C_{m_{\delta_e}}} \right] \quad (A39)$$

or

$$\bar{x}_{cg_{fwd}} = \bar{x}_{ac} - \frac{2C_{m_{\delta_e}}}{C_{L_{max}}} \left[\delta_{e_{max}} + \frac{C_{L_{max}}}{a_w \tau_e} \left(1 - \frac{d\varepsilon}{d\alpha} \right) + \frac{\alpha_0 - i_w + i_t}{\tau_e} + \frac{C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}}}{2C_{m_{\delta_e}}} \right] \quad (A40)$$

similarly, from equation (A25):

$$\delta_c = -\frac{1}{2C_{m_{\delta_c}}} [C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}} + 2a_c (\alpha_w - \alpha_{0c} - i_w + i_c) \bar{V}_c] \quad (A41)$$

and rearranging:

$$\bar{x}_{cg_{fwd}} = \bar{x}_{ac} - \frac{2C_{m_{\delta_c}}}{C_{L_{max}}} \left[\delta_{c_{max}} + \frac{\alpha_w - \alpha_{0c} - i_w + i_c}{\tau_c} + \frac{C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}}}{2C_{m_{\delta_c}}} \right] \quad (A42)$$

or

$$\bar{X}_{cg\,fwd} = \bar{X}_{ac} - \frac{2C_{m\delta_c}}{C_{L_{max}}} \left[\delta_{c_{max}} + \frac{C_{L_{max}}}{a_w \tau_c} + \frac{\alpha_0 - \alpha_{0c} - i_w + i_c}{\tau_c} + \frac{C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}}}{2C_{m\delta_c}} \right]$$

(A43)

combining equations (A39) and (A42), a simple relation for $\delta_{c_{max}}$ may be found:

$$\delta_{c_{max}} = \frac{C_{m\delta_e}}{C_{m\delta_c}} \left(\delta_{e_{max}} + \frac{\alpha_t}{\tau_e} \right) - \frac{(\alpha_c - \alpha_{0c})}{\tau_c}$$

(A44)

Equation (A44) may be derived directly from the design criterium represented by equation (A17).

the following may also be useful:

$$\delta_c = \frac{C_{m\delta_e}}{C_{m\delta_c}} \left(\delta_e + \frac{\alpha_t}{\tau_e} \right) - \frac{(\alpha_c - \alpha_{0c})}{\tau_c}$$

(A45)

Both equations (A39) and (A42) will give the limiting forward c.g. location for any condition of flight, including flight in ground effect. Information on the change of the variables in (A39), (A40), (A42) through (A45) due to this effect may be found with the methods suggested by Perkins and Hage^{A1}, for example.

A.3.3 Take-off Rotation

For a tricycle-gear aircraft the longitudinal controls must be powerful enough to rotate the nose at 80 to 85% of the take-off speed with the most forward c.g..

Again, for rotation analysis, the equilibrium equation will be used, including, as it was the case for the landing flare, the pitching moment contribution from thrust (here, maximum thrust) in ground effect, but adding the contributions from the landing gear and from the control pitching moment in order to overcome the aircraft inertial resistance to pitch. From this description it appears that a more severe situation than that for the landing is found with regard to the design of the canard and the elevator. This explains why sometimes the elevator is sized by take-off rotation requirements.

Then, equation (A19) may be written as

$$\delta_e = -\frac{1}{2C_{m_{\delta_e}}} [C_L (\bar{x}_{cg} - \bar{x}_{ac}) + C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}} + C_{m_{1g}} - C_{m_{IYY}} + 2a_t (\alpha_w - \epsilon - i_w + i_t) \bar{v}_t \eta_t]$$

(A46)

rearranging and assuming that all other variables correspond to those at the lift-off rotation (take-off configuration),

then $\bar{x}_{cg_{fwd}}$ becomes:

$$\bar{x}_{cg_{fwd}} = \bar{x}_{ac} - \frac{2C_{m_{\delta_e}}}{C_{L_r}} \left[\delta_{e_r} + \frac{\alpha_w - \epsilon - i_w + i_t}{\tau_e} + \frac{C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}} + C_{m_{1g}} - C_{m_{IYY}}}{2C_{m_{\delta_e}}} \right]$$

(A47)

and similarly with regard to the canard:

$$\bar{x}_{cg_{fwd}} = \bar{x}_{ac} - \frac{2C_{m_{\delta_c}}}{C_{L_r}} \left[\delta_{c_r} + \frac{\alpha_w - \alpha_{0c} - i_w + i_c}{\tau_c} + \frac{C_{m_{ac}} + C_{m_{fus}} + C_{m_{nac}} + C_{m_{th}} + C_{m_{1g}} - C_{m_{IYY}}}{2C_{m_{\delta_c}}} \right]$$

(A48)

A.3.3.1 Pitching Moment Contribution Due to Landing Gear

It is assumed that the nose gear is resting without carrying any weight and that the main gear supports the difference between the maximum take-off weight and the lift generated at the rotation initiation. This contribution is compounded by a normal force term and a rolling friction term as follows:

$$C_{m_{1g}} = C_{m_{1gFN}} + C_{m_{1gF}}$$

(A49)

$$C_{m_{1g}} = \frac{W-L}{qS_w} \left[(\bar{x}_{cg} - \bar{x}_{1g}) - \mu \frac{z_{1g}}{c} \right]$$

(A50)

where W is the maximum aircraft take-off weight,
 L is the total lift at the start of rotation,
 \bar{x}_{lg} is the distance of the main landing gear from the nose
as a fraction of the mean aerodynamic chord,
 z_{lg} is the c.g. height above the ground,
 μ is the rolling friction coefficient (usually taken
as =0.03).

A.3.3.2 Control Pitching Moment Contribution to Induce the Overall Aircraft Pitching Acceleration.

The pitching moment coefficient due to the aircraft inertial resistance to rotation is given as follows:

$$C_{m_{IYY}} = \frac{I_{YY}\dot{\theta}}{qS_w\bar{c}}$$

(A51)

where I_{YY} is the aircraft moment of inertia about the YY axis,
 $\dot{\theta}$ is the aircraft angular pitch acceleration.

Assuming that the rotation follows a circular arc path of radius r at constant pitch rate, $\dot{\theta} = \text{const}$, the pitch acceleration

$\dot{\theta}$ may be expressed as:

$$\dot{\theta} = \frac{V_{trans}^2}{r}$$

(A52)

with V_{trans} as the transition speed.

From

$$L = W \frac{V_{trans}^2}{V_{St0}^2} \frac{C_{L_{trans}}}{C_{L_{max}}} = W + \frac{W}{g} \frac{V_{trans}^2}{r}$$

(A53)

where $\frac{W}{g} \frac{V_{trans}^2}{r}$ is the centrifugal force, it comes

$$\frac{V_{trans}^2}{r} = \left(\frac{V_{trans}^2}{V_{St0}^2} \frac{C_{L_{trans}}}{C_{L_{max}}} - 1 \right) g$$

(A54)

now equation (A51) may read:

$$C_{m_{IYY}} = \frac{I_{YY}}{qS_w \bar{c}} \frac{V_{trans}^2}{r} = \frac{I_{YY}}{qS_w \bar{c}} \left(\frac{V_{trans}^2}{V_{St0}^2} \frac{C_{L_{trans}}}{C_{L_{max}}} - 1 \right) g$$

(A55)

where

$$\frac{C_{L_{trans}}}{C_{L_{max}}} \approx 0.8 \sim 0.9$$

and

$$V_{trans} \approx 0.85 V_{t0} = 0.85 * 1.2 V_{St0}$$

To overcome this inertial moment coefficient the control contribution to the overall pitching moment coefficient will be equal to $-C_{m_{IYY}}$.

References

- A1. Perkins, C.D.; Hage, R.E.
Airplane Performance Stability and Control
ed. John Wiley & Sons, Inc., 1949

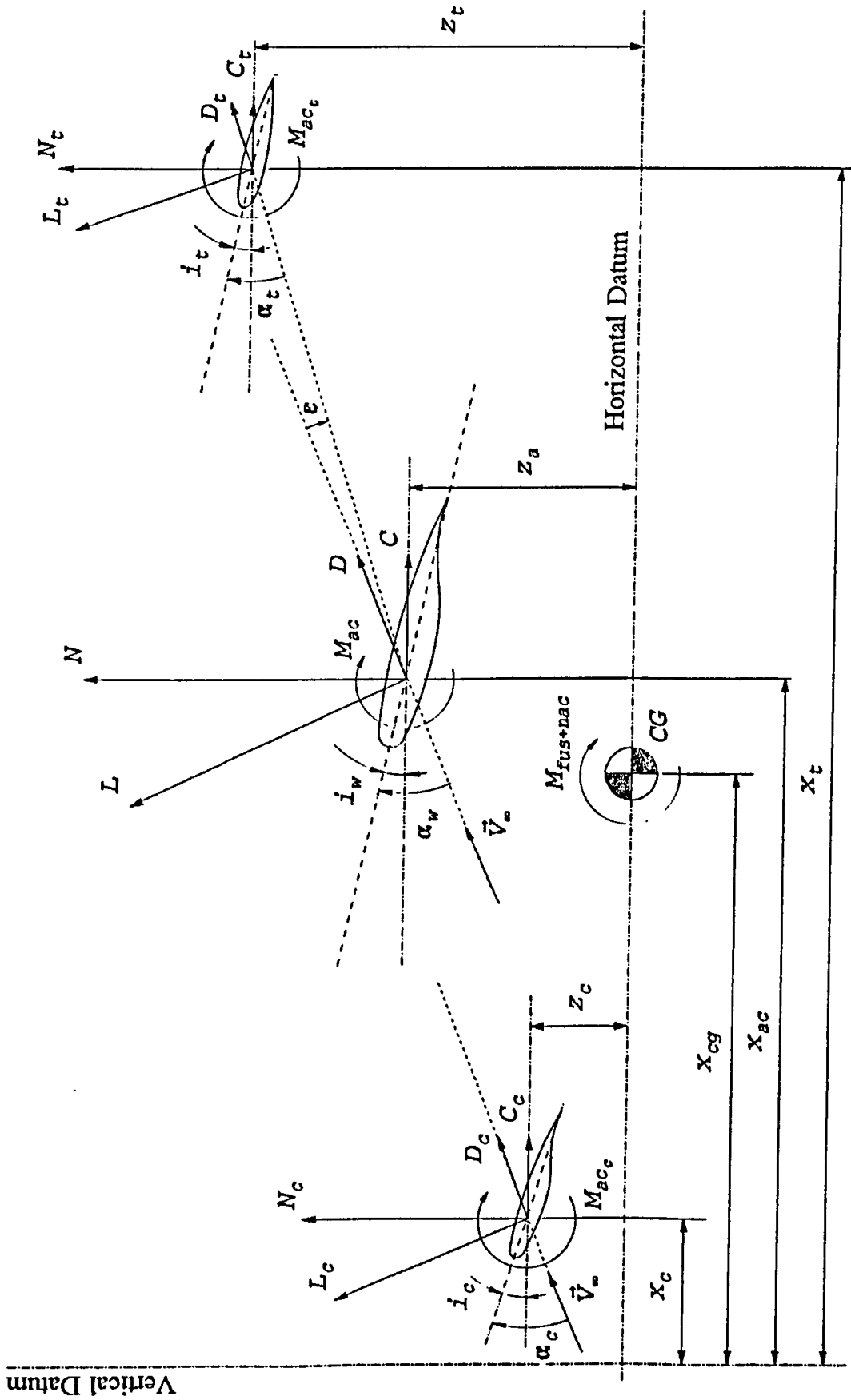


Fig A1 - Forces and Moments Scheme

APPENDIX B

**Equations Implemented in GASP-3S
(Three-lifting Surface Concept)**

Introduction

GASP code was modified and extended to include the design synthesis of three-surface aircraft. The procedure was described in Chapter 3, and the required equations presented. However, additional formulae was included to ensure computational consistency. This is listed in the present Appendix.

Note to figure B1: To initialise the synthesis, the GEOMETRY module assumes that the horizontal tail apex is coincident with the vertical tail leading edge. This is consistent with the relationship provided in the present Appendix. Subsequent refinement of the surface sizes assumes the root chord of the tailplane trailing edge lying on the fin trailing edge.

Equations Implemented in GASP-3S

B.1 Geometry

Wing

$$\text{Wing area, } S_w = \frac{W_0}{\left(\frac{W}{S}\right)} \frac{1}{\left(1 + \left(\frac{S_c}{S_w}\right)\right)}$$

where $\frac{W}{S} = \frac{W_0}{(S_c + S_w)} = \frac{W_{0c}}{S_c} = \frac{W_{0w}}{S_w}$ is the wing or canard loading.

Canard

$$\text{canard area, } S_c = S_w \left(\frac{S_c}{S_w}\right)$$

$$\text{canard span, } b_c = (A_c S_c)^{\frac{1}{2}}$$

$$\text{canard chord at fuselage centreline, } c_{c_r} = 2 \frac{S_c}{b_c (1 + \lambda_c)}$$

$$\text{canard mean aerodynamic chord, } \bar{c}_c = \frac{2}{3} c_{c_r} \left(1 + \frac{\lambda_c^2}{1 + \lambda_c}\right)$$

$$\text{canard leading edge sweep angle, } \Lambda_{c_{l_e}} = \arctan\left(\frac{1 - \lambda_c}{A_c (1 + \lambda_c)} + \tan \Lambda_{c_{c/4}}\right)$$

$$\text{canard trailing edge sweep angle, } \Lambda_{c_{t_e}} = \arctan\left(\frac{3(\lambda_c - 1)}{A_c (1 + \lambda_c)} + \tan \Lambda_{c_{c/4}}\right)$$

distance of the horizontal tail mean aerodynamic quarter chord point from the fuselage nose apex, see figure B1:

$$l_{\bar{c}_{htc/4}} = l_{fus} - c_{vt_r} + (b_{vt} h_{loc} \tan \Lambda_{vt_{l_e}}) + \bar{X}_{ht_{\bar{c}}} + 0.25 \bar{c}_{ht}$$

distance of the canard mean aerodynamic quarter chord point from fuselage nose apex. It is assumed the canard main spar located at 30% chord attached to the front fuselage pressure bulkhead main frame and passing through a centreline point at a distance from nose apex defined as the product of the maximum nose depth by the nose fineness ratio, see figure B1:

$$l_{\bar{c}_{c/4}} = (r_n h_n) - 0.3 c_{c_r} + \bar{X}_{c_{\bar{c}}} + 0.25 \bar{c}_c$$

with $\bar{X}_{c_{\bar{c}}} = \frac{b_c}{2} \tan \Lambda_{c_{1\sigma}} \frac{1+2\lambda_c}{3(1+\lambda_c)}$

canard moment arm,

$$l_{c_{\bar{c}/4}} = l_{\bar{c}_{htc/4}} - l_{\bar{c}_{cc/4}} - l_{ht\bar{c}/4}$$

where $l_{ht\bar{c}/4}$ and $l_{c_{\bar{c}/4}}$ are respectively the tailplane and canard moment arms referred to the wing mean aerodynamic quarter chord point rather than to the aircraft aft centre of gravity point as later considered on the stability evaluations and subsequent refinements.

canard volume coefficient, $\bar{V}_c = \frac{l_{c_{\bar{c}/4}}}{c_w} \frac{S_c}{S_w}$

Tailplane

horizontal tail volume coefficient, $\bar{V}_{ht} = \frac{l_{ht\bar{c}/4}}{c_w} \frac{S_{ht}}{S_w}$

B.2 Aerodynamics

Canard aerodynamic form factor, $K_c = 1.03 [2 + 4 (\frac{t}{c})_c + 240 (\frac{t}{c})_c^4]$

Canard Reynolds number, $Re_c = Re_1 \bar{c}_c$

where $Re_1 = (\frac{V}{v})_{cr}$ is the Reynolds number per foot at cruise conditions

Canard Reynolds number correction factor, $F_{Re_c} = (\frac{\log Re_c}{7})^{-2.6}$

Canard parasite drag coefficient, $C_{D_{pc}} = K_c C_{f_{Re=10^7}} F_{Re_c} C_{D_f} \frac{S_c}{S_w} \frac{1}{1+S_c/S_w}$

Canard wetted area, $S_{wet_c} = 2S_c - 3\bar{c}_c w_{f_{oc}} \frac{1+\lambda_c}{\lambda_c^2 + \lambda_c + 1} \left[1 + \frac{w_{f_{oc}}}{2b_c} (\lambda_c - 1) \right]$

where $w_{f_{oc}}$ is the fuselage width at the canard intersection.

In low speed flight conditions, the aircraft aerodynamic drag coefficient is represented by:

$$C_D = \sum_i C_{D_{pi}} + C_{D_{pw}} + C_{D_{pc}} + C_{D_{iw}} + C_{D_{ic}} + \Delta C_{D_f}$$

The first term may include now the landing gear parasite drag coefficient when appropriate and,

where, ΔC_{D_f} is the parasite drag increment due to trailing edge flaps,

$C_{D_{iw}} = \frac{(C_L - \sigma \Delta C_L)^2}{\pi e_w A_w s_f} \frac{1}{1+S_c/S_w}$ is the wing induced drag coefficient,

$C_{D_{ic}} = \frac{(C_L - \sigma \Delta C_L)^2}{\pi e_c A_c s_f} \frac{S_c}{S_w} \frac{1}{1+S_c/S_w}$ is the canard induced drag coefficient,

ΔC_L is the lift increment due to flaps,

σ is an empirical flap efficiency factor obtained as a function of flap deflection,

s_f is a wing or canard efficiency correction factor due to change in spanwise lift caused by flap deflection.

Canard lift curve slope:

$$a_c = \frac{\pi A_c}{1 + \sqrt{1 + C_1 C_2}}$$

where, $C_1 = \left(\frac{A_c}{2 \cos \Lambda_{c/4}} \right)^2$

and $C_2 = 1 - (M \cdot \cos \Lambda_{c/4})^2$

B.3 Weight and Balance

Canard Weight:

$$W_C = S_{K_{CW}} S_{K_{NO}} S_{K_{EPOS_C}} S_{K_{GEAR_C}} F_{OO_C} \frac{b_c^{1.049} (1 + \lambda_c)^{0.4}}{\left(\frac{t}{c}\right)_{c_r}^{0.4} \cos^{1.535} \Lambda_{c/2}} * 10^{-5}$$

where

$S_{K_{CW}} = 133.4$ is the canard weight trend factor (it takes the same value as the wing weight trend factor, $S_{K_{W}}$)

$S_{K_{NO}} = 1 + \frac{2.5}{\sqrt{\frac{b_c}{\cos \Lambda_{c/2}}}}$ is the correction factor for the non-optimum material,

$S_{K_{EPOS_C}} = 1.05$ is the correction factor for high-subsonic jet aircraft with no canard mounted engines,

$S_{K_{GEAR_C}} = 0.95$ is the correction factor for landing gear not mounted on canard,

$F_{OO_C} = [S_{K_{STR}} U_{LF} [S_c (\frac{W_0}{S_c + S_w}) - 0.8 W_{c_1}]]^{0.757}$ is the canard loading parameter,

$S_{K_{STR}} = 1$ is the reduction in bending moment factor for braced canard,

U_{LF} is the ultimate design load factor determined in subroutine DLOAD,

W_0 is the design maximum take-off weight,

W_{c_1} is the canard weight,

b_c is the canard span,

λ_c is the canard taper ratio,

$(t/c)_{c_r}$ is the canard root thickness ratio,

$\Lambda_{c/2} = \arctan\left(\tan\Lambda_{c/4} - \frac{1-\lambda_c}{A_c(1+\lambda_c)}\right)$ is the canard half chord sweep angle.

Assuming the canard centre of gravity is located 8% aft of the canard mean aerodynamic quarter chord point, its distance from the fuselage nose apex may be expressed by:

$$l_{c_{cgc}} = l_{w_{c/4}} - 0.25c_{w_r} + \bar{X}_{w_c} + 0.25\bar{c}_w - l_{c_{c/4}} + 0.08\bar{c}_c$$

Spanwise distance of canard mean aerodynamic chord from fuselage centreline:

$$\bar{Y}_{c_c} = \frac{b_c(1+2\lambda_c)}{6(1+\lambda_c)}$$

Distance of canard centreline quarter chord point from fuselage nose apex:

$$l_{c_{r/4}} = (r_n h_n) - 0.05c_{c_r}$$

canard tip chord:

$$c_{c_t} = \lambda_c c_{c_r}$$

Propulsion Installation pitching moment coefficients due to jet inclination at the tail:

- at landing conditions

$$C_{m_{thjinc_L}} = \left(\frac{dC_m}{dC_L}\right)_{thjinc} C_{L_{max_L}}$$

- at take-off rotation conditions

$$C_{m_{thjinc_r}} = \left(\frac{dC_m}{dC_L}\right)_{thjinc} C_{L_r}$$

where $\left(\frac{dC_m}{dC_L}\right)_{thjinc} = 0.03$, as assumed in Appendix A, is the jet-flow inclination contribution to the aircraft longitudinal static stability.

Aircraft moment of inertia about the YY axis:

$$I_{YY} = \frac{W_0}{g} (K_y)^2$$

where, K_y is the aircraft pitch radius of gyration as obtained through the empirical linear regression of figure V.1.11¹⁹, and g is the acceleration due to gravity.

Lift force at nose wheel liftoff rotation:

$$L = C_{L_r} q S_w \left(1 + \frac{S_c}{S_w}\right)$$

where, $C_{L_r} = \frac{1}{2} \rho_r (0.85 V_s)^2$ is the lift coefficient at nose wheel liftoff conditions,

ρ_r is the air density at the field height,

V_s is the aircraft stall speed at the take-off configuration.

B.4 Performance

Stall speed at sea level International Standard Atmospheric (ISA) conditions:

$$V_{s_{sl}} = \sqrt{\frac{2W_0}{\rho_0 C_{L_{max}} S_w \left(1 + \frac{S_c}{S_w}\right)}}$$

Take-off speed:

$$V_t = r_{v_t} V_{s_{sl}} \frac{1}{\sqrt{\sigma}}$$

where $r_{v_t} = \frac{V_t}{V_{s_{sl}}}$ is the ratio of the take-off speed to the stall speed at sea level ISA conditions,

$\sigma = \frac{\rho}{\rho_0}$ the ratio of the actual air density at the runway altitude to that at sea level ISA conditions.

Take-off lift coefficient:

$$C_{L_t} = \frac{2W_0}{\rho V_t^2 S_w \left(1 + \frac{S_c}{S_w}\right)}$$

Take-off thrust required:

$$T_{RQ} = q S_w \left(1 + \frac{S_c}{S_w}\right) C_D V_t$$

Take-off horizontal acceleration:

$$\left(\frac{dV}{dt}\right)_t = \frac{g}{W} \left[T_a \cos \alpha_t - q S_w \left(1 + \frac{S_c}{S_w}\right) C_D - \mu \left(W - q S_w \left(1 + \frac{S_c}{S_w}\right) C_L - T_a \sin \alpha_t\right) - W \sin \gamma \right]$$

where T_a is the available Thrust,

μ is the ground rolling coefficient of friction,

γ is the flight path angle.

Horizontal flight acceleration:

$$\left(\frac{dV}{dt}\right) = \frac{g}{W} \left[T - 0.7 P M^2 S_w \left(1 + \frac{S_c}{S_w}\right) C_D \right]$$

where P is the absolute air pressure at flight altitude,

M is the momentary flight Mach number.

Minimum climb speed:

$$V_{cl} = 1.1 \sqrt{\frac{2W}{S_w \left(1 + \frac{S_c}{S_w}\right) \rho C_{L_{max}}}}$$

Where 1.1 represents a margin above the stall speed.

Climb lift coefficient:

$$C_L = \frac{W \cos \gamma}{q S_w \left(1 + \frac{S_c}{S_w}\right)}$$

Rate of climb:

$$RC = \frac{V \left[T_a - q S_w \left(1 + \frac{S_c}{S_w}\right) C_D \right]}{W}$$

Wing loading:

$$\frac{W}{S} = \frac{W}{S_w \left(1 + \frac{S_c}{S_w}\right)}$$

Sink rate:

$$RS = \frac{V_{app} \left[q S_w \left(1 + \frac{S_c}{S_w}\right) C_D - T_{idle} \right]}{W}$$

where $V_{app} = 1.3 V_{s_l}$ is the approach speed,

V_{s_l} is the landing stall speed,

T_{idle} is the idle thrust.

Normal load factor increment due to lift and thrust:

$$X_{LF} = \frac{\left[q S_w \left(1 + \frac{S_c}{S_w}\right) C_L + T_a \sin \alpha \right]}{W \cos \gamma}$$

Variations of the above equations are used throughout the Mission Performance module, where necessary, for the computation of some of the as shown implicit parameters and thus they are not reproduced.

B.5 Economics

Canard production cost:

$$C_c = 1730 W_c^{0.766} (Q_p)^{-0.218} CEF$$

where W_c is the canard weight as determined above,

Q_p is the estimated aircraft production quantity,

$CEF = (1 + IR)^{(\text{year} - 1975)}$ is the cost escalation factor,

IR is the annual average inflation rate,

year is the actual year of the calculation.

This cost estimating relationship is the same as used for the wing and includes both production cost and an assumed aircraft manufacturer's profit of 10%.

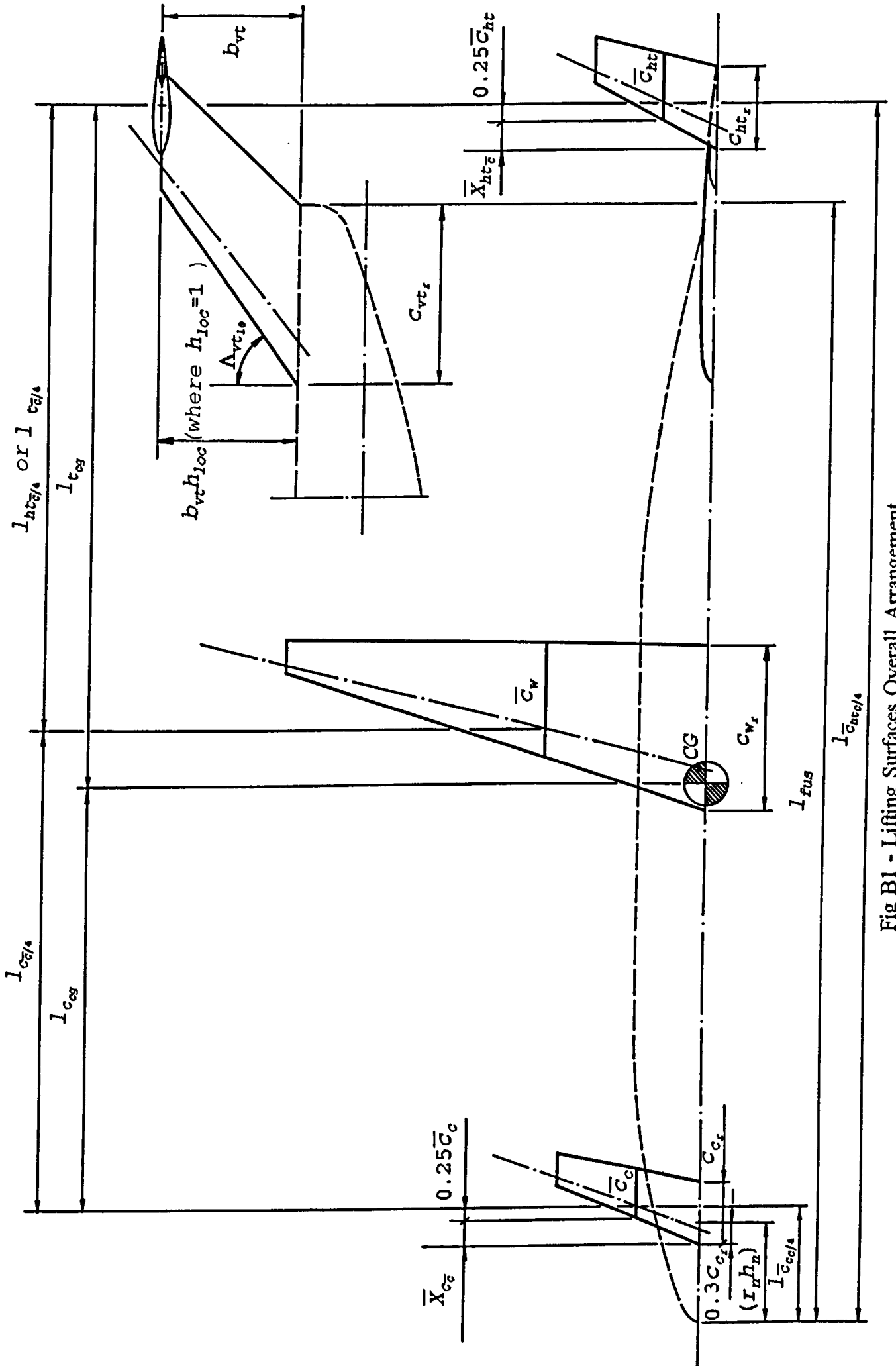


Fig B1 - Lifting Surfaces Overall Arrangement

APPENDIX C

Parametric Analysis - Aircraft Initial Sizing

Introduction

Following the preliminary sizing method presented by Roskam^{5.1}, a Parametric Analysis module named "PRESIZ" was developed. This module relies on historical data and allows for the estimation of aircraft take-off, empty and fuel weights. Results allow for establishing a take-off Thrust to Weight versus Wing Loading plot. This diagram represents a constrained solution space where all the mission, performance and airworthiness requirements are satisfied. Take-off gross weight sensitivity studies with respect to mission, aerodynamic and propulsion parameters are also evaluated. A mission specification, together with some assumptions on empirical and technology related parameters, are all required as input to run the program.

This Appendix encloses the PRESIZ input file (fig C2), and the output listing (fig C3) required to create the design diagram shown in fig 5.1. This Thrust to Weight vs Wing Loading plot was used to select the starting design point for the more elaborate GASP evaluations that followed. A key is also provided in fig C1 to describe what the data in the input file is.

Note: ref 5.1 refers to ref 1 of Chapter 5, Vol Part I.

PreSiz Input File Data (description)

Passenger no.;passenger weight[lb];baggage weight[lb];
 flight crew no.;cabin crew no.;crew weight [lb];crew baggage weight[lb];
 range[NM];loiter time[hr];distance to alternate[NM];
 cruise Mach no.;cruise altitude[ft];
 FAR 25 take-off field length[ft];field altitude[ft];day temperature[degree F];
 FAR 25 landing field length[ft];
 Landing weight to maximum take-off weight ratio;

- mission weight fuel fractions:
 engine start & warm-up;taxi;take-off;climb;descent;landing,taxi and shut down;

cruise lift to drag ratio;engine cruise specific fuel consumption[lb/lb/hr];loiter lift to drag
 ratio;engine loiter specific fuel consumption[lb/lb/hr];
 average climb speed[kt];average climb rate[ft/min];cruise altitude sonic speed[kt];trapped fuel
 and oil weight as a fraction of the maximum take-off weight;reserve fuel to used fuel weight
 ratio(usually representing 45 min of flight at cruise conditions);A and B regression line
 constants of equation 2.16 which relates the aircraft empty weight to the maximum take-off
 weight, taken from table 2.15 for the appropriate aircraft category (in ref. 5.1);

CLmax array dimension (N) at take-off configuration;wing loading array dimension (M) at
 take-off configuration;
 air pressure ratio at take-off field altitude;
 CLmax array at take-off configuration (N values);
 wing loading array at take-off configuration (M values)[lb/sqft];

CLmax array dimension (K) at landing configuration;
 air density at sea level standard conditions [slugs/cuft];
 CLmax array at landing configuration (K values);

a and b regression line coefficients for equation 3.21 which relates the equivalent parasite area
 to the aircraft wetted area and assuming an equivalent skin friction coefficient of $cf=0.003$.
 These coefficients are taken from table 3.4 of ref.(5.1);c and d regression line coefficients for
 equation 3.22 which relates the wetted area to the aircraft maximum take-off weight. The
 coefficients are taken from table 3.5 of ref.(5.1) for the category of aircraft into consideration;

lowest wing aspect ratio to consider;clean configuration Oswald efficiency factor;
 additional zero-lift drag coefficient due to take-off flaps; take-off configuration Oswald
 efficiency factor;
 additional zero-lift drag coefficient due to landing flaps; landing configuration Oswald
 efficiency factor;
 additional zero-lift drag coefficient due to landing gear;
 number of engines;

clean configuration CLmax;take-off CLmax;landing CLmax;
 Mach drag divergency compressibility drag increment;air density at cruise altitude
 [slugs/cuft];rate of climb capability at cruise altitude [ft/min];
 Initial guess for the maximum take-off weight [lb]

Fig C1 - PreSiz Input Data List

```

50      175.    25.
 2      1      175.    25.
1250.   .0      .0
.8 35000.
6000.   5000.    95.
5000.
.94
8000.
.9983   .9983   .9983   .9742   .9806  1.
11.     .5     12.7    .4
315.    2220.   576.3    .005   .27    .0833  1.0383

 5      5
.8320
1.2     1.6     2.0     2.4     2.8
40.     60.     80.     100.    120.

 7
23.78E-04
1.6     1.9     2.2     2.5     2.8     3.1     3.4

-2.5229  1.     .0199   .7531
.6.     .85
.015    .80
.065    .75
.020

 2
1.3     2.45    3.25

.0007   7.365E-04   500.

50000.

```

Fig C2 - PreSiz Input.dat File

TRANSPORT AIRCRAFT MISSION SPECIFICATION

PAYLOAD: NUMBER OF PASSENGERS = 50
 PASSENGER WEIGHT = 175.0 LBS
 HAND BAGGAGE WEIGHT = 25.0 LBS

CREW: FLIGHT DECK = 2
 CABIN = 1
 CREW WEIGHT = 175.0 LBS
 HAND BAGGAGE WEIGHT = 25.0 LBS

RANGE: DISTANCE TO DESTINATION = 1250.0 NM
 HOLDING TIME = .0 HOURS
 DISTANCE TO ALTERNATE = .0 NM

CRUISE ALTITUDE = 35000.0 FT

CRUISE MACH NO. @ 35000.0 FT = .80

CLIMB: DIRECT TO 35000.0 FT @ MAX TAKE-OFF WEIGHT

FIELD LENGTH: TAKE-OFF = 6000.0 FT
 LANDING = 5000.0 FT
 FIELD ALTITUDE = 5000.0 FT
 FIELD TEMPERATURE = 95.0 F

POWER-PLANTS: 2 TURBO-FANS

CERTIFICATION BASE: FAR 25

I. TAKE-OFF GROSS WEIGHT, EMPTY WEIGHT AND FUEL WEIGHT

TAKE-OFF GROSS WEIGHT, WTO	=	44076.48	LBS
EMPTY WEIGHT, WE	=	24698.35	LBS
FUEL WEIGHT, WF	=	8557.75	LBS

II. SENSITIVITIES OF AEROPLANE TAKE-OFF GROSS WEIGHT

GROWTH FACTOR DUE TO PAYLOAD	=	3.8291	LBS/LB
GROWTH FACTOR DUE TO EMPTY WEIGHT	=	1.8529	LBS/LB
GROWTH FACTOR DUE TO RANGE	=	17.9014	LBS/NM
GROWTH FACTOR DUE TO ENDURANCE	=	5718.7880	LBS/HR
GROWTH FACTOR DUE TO SPEED	=	-48.5353	LBS/KT

***** RANGE CASE *****

GROWTH FACTOR DUE TO SPECIFIC FUEL CONSUMPTION	=	44753.4400	LBS/(LBS/HR LB)
GROWTH FACTOR DUE TO LIFT-TO-DRAG RATIO	=	-2034.2470	LBS

III. SIZING TO PERFORMANCE

1. ESTIMATING DRAG POLARS AT LOW SPEED

WTO [LBS]	W/S(TO) [PSF]	S [FT2]	SWET [FT2]	F [FT2]	CDO
44076.480	80.000	550.956	3291.942	9.875	.0179

ASPECT RATIO (ASSUMED), AR = 8.00

LOW SPEED, CLEAN : CD = .0179 + .0468 CL²

TAKE-OFF, GEAR UP : CD = .0329 + .0497 CL²

TAKE-OFF, GEAR DOWN: CD = .0529 + .0497 CL²

LANDING, GEAR UP : CD = .0829 + .0531 CL²

LANDING, GEAR DOWN : CD = .1029 + .0531 CL²

ASPECT RATIO (ASSUMED), AR = 9.00

LOW SPEED, CLEAN : CD = .0179 + .0416 CL²

TAKE-OFF, GEAR UP : CD = .0329 + .0442 CL²

TAKE-OFF, GEAR DOWN: CD = .0529 + .0442 CL²

LANDING, GEAR UP : CD = .0829 + .0472 CL²

LANDING, GEAR DOWN : CD = .1029 + .0472 CL²

Fig C3 - PreSiz Output.dat File (continued)

WTO [LBS]	W/S(TO) [PSF]	S [FT2]	SWET [FT2]	F [FT2]	CDO
44076.480	100.000	440.765	3291.942	9.875	.0224

ASPECT RATIO (ASSUMED), AR = 8.00

LOW SPEED, CLEAN : CD = .0224 + .0468 CL²

TAKE-OFF, GEAR UP : CD = .0374 + .0497 CL²

TAKE-OFF, GEAR DOWN: CD = .0574 + .0497 CL²

LANDING, GEAR UP : CD = .0874 + .0531 CL²

LANDING, GEAR DOWN : CD = .1074 + .0531 CL²

ASPECT RATIO (ASSUMED), AR = 9.00

LOW SPEED, CLEAN : CD = .0224 + .0416 CL²

TAKE-OFF, GEAR UP : CD = .0374 + .0442 CL²

TAKE-OFF, GEAR DOWN: CD = .0574 + .0442 CL²

LANDING, GEAR UP : CD = .0874 + .0472 CL²

LANDING, GEAR DOWN : CD = .1074 + .0472 CL²

Fig C3 - PreSiz Output.dat File (continued)

3. SIZING TO TAKE-OFF DISTANCE REQUIREMENTS

*** SUMMARY OF MINIMUM VALUES FOR T/W(TO) ***

CLMAX (TO) =	1.200	1.600	2.000	2.400	2.800
W/S(TO) [PSF]					
40.00	.337	.252	.202	.168	.144
60.00	.505	.379	.303	.252	.216
80.00	.673	.505	.404	.337	.288
100.00	.841	.631	.505	.421	.361
120.00	1.010	.757	.606	.505	.433

4. SIZING TO LANDING DISTANCE REQUIREMENTS

CLMAX(L)	W/S(TO) [PSF]
1.600	41.186
1.900	48.908
2.200	56.630
2.500	64.353
2.800	72.075
3.100	79.797
3.400	87.520

Fig C3 - PreSiz Output.dat File (continued)

5. SIZING TO CLIMB REQUIREMENTS (FAA)

NUMBER OF ENGINES, NENG = 2

CL MAX (CLEAN) (ASSUMED), CLMAX = 1.300

CL MAX (TO) (ASSUMED), CLMAXTO = 2.450

CL MAX (L) (ASSUMED), CLMAXL = 3.250

LANDING CLIMB REQ. TAKE-OFF CLIMB REQ. (OEI)
 - FAR 25.121 (OEI) - FAR 25.121 - 2ND SEGMENT

ASPECT RATIO = 8.0

W/S (TO) [PSF]	T/W(TO)	W/S (TO) [PSF]	T/W(TO)
40.000	.335	40.000	.307
60.000	.344	60.000	.313
80.000	.352	80.000	.320
100.000	.360	100.000	.327
120.000	.368	120.000	.333

ASPECT RATIO = 9.0

W/S (TO) [PSF]	T/W(TO)	W/S (TO) [PSF]	T/W(TO)
40.000	.318	40.000	.283
60.000	.326	60.000	.290
80.000	.334	80.000	.296
100.000	.343	100.000	.303
120.000	.351	120.000	.310

Fig C3 - PreSiz Output.dat File (continued)

6. SIZING TO CRUISE SPEED REQUIREMENTS

*** SUMMARY OF MINIMUM VALUES FOR T/W(TO) ***

COMPRESSIBILITY DRAG INCREMENT (ASSUMED) = 7.00 DRAG COUNTS

ASPECT RATIO =	6.0	7.0	8.0	9.0	10.0	11.0	12.0
W/S(TO) [PSF]							
40.00	.283	.276	.271	.267	.263	.261	.259
60.00	.302	.291	.283	.277	.272	.268	.265
80.00	.323	.309	.299	.291	.284	.279	.274
100.00	.346	.328	.315	.305	.297	.290	.285
120.00	.369	.348	.332	.320	.311	.303	.296

7. SIZING TO DIRECT CLIMB REQUIREMENTS

*** SUMMARY OF MINIMUM VALUES FOR T/W(TO) ***

CLIMB RATE AT 35000 FT SERVICE CEILING (ASSUMED) = 500.00 FPM

ASPECT RATIO =	6.0	7.0	8.0	9.0	10.0	11.0	12.0
W/S(TO) [PSF]							
40.00	.329	.323	.317	.313	.310	.307	.305
60.00	.348	.338	.330	.324	.319	.315	.312
80.00	.370	.356	.345	.337	.331	.325	.321
100.00	.392	.375	.362	.352	.344	.337	.331
120.00	.415	.395	.379	.367	.357	.349	.342

Fig C3 - PreSiz Output.dat File (concluded)

APPENDIX D

The Baseline Designs

Introduction

This Appendix encloses the GASP output listings containing the detailed results for the conventional and the three-surface baseline designs. The parameters composing the GASP input files, organised by their respective disciplinary groups, were repeated on the first page of the output print-outs. These are listed in section 5.3 with the proposed values for the initial trial configurations, both conventional and unconventional. A complete list of GASP input variable names is given in Appendix H. The low speed and cruise drag polars related to the conventional and the three-surface baseline designs are illustrated respectively in figs. D.3 and D.4. Table 5.1, included in the main text, summarizes the main results obtained. Figures 5.2 and 5.3 show the three view sketches of the classical and the three-surface baseline airliners which are based on the present results.

Note: The research was conducted on the CoA SUN Spark stations, where Range Trade-off studies were done up to a maximum design range of 2000 NM. However, it was thought useful to extend the investigation to higher ranges. This was later accomplished using a Hewlett Packard 9000 platform, at IST. Because the numerical results for the same run cases were found slightly different, due to differences in the FORTRAN compilers employed, a new set of results were obtained by repeating all the design synthesis and design optimisation computer work. So, numerical consistency is preserved in the results. All output listings herein, as well as those included in Appendix E, were obtained on a HP workstation.

50 FAX TURBOPAN AIRLINER USING SCALED GE CP-34 - CONVENTIONAL CONFIG.

ENGINE CYCLE IS G. E. CP-34

INPUT DATA FOLLOW

*****GEOMETRY*****

0	0 CONFIG	WG = 44050.	KWRITE = 2	FUSEL SAB = 4.	ELODN = 1.000
		WGS = 83.000	IGEAR = 0	WS = 20.000	ELODT = 3.200
		BAX = 50.	KCONFG = 0	AS = 1.	BMLOD = 14.500
		EMCRU = .800	KTIPI = 0	WAS = 19.000	NACELLE KNAC = 1
		HNCRU = 35000.	ENP = 2.	FS = 31.0	ELN = .000
		Canard = 0	NTYE = 7	ELPC = 11.220	DBARN = .000
			KPLOT = 1	HCK = 2.470	ELRW = 10.000
0	WING	TCT = .100	HORIZ VBARHX = .0000	VERT VBARVX = .0000	Canard TCoen = .100
		TCR = .130	TAIL TCNT = .100	TAIL TCVT = .120	ARcan = 3.500
		AR = 8.300	ARHT = 4.000	ARVT = 1.000	SLMcan = .500
		SLM = .200	SLMH = .550	SLMV = .700	DwpqCa = 15.000
		DLMC4 = 14.500	DWPOCH = 27.500	DWPCCV = 50.500	EYEcan = 2.000
		EYEW = 2.000	COELTH = .000	BOELTV = .000	SWCOSW = .150
			SAH = 1.000		

*****AERODYNAMICS*****

0	0	CRW = -1.000	CKRT = -1.000	GRPE = .000	DCDSE = -1.0000								
		CKP = -1.000	CKTP = -1.000	SCFAC = .750	CKWc = -1.000								
		CRN = -1.000	DELCD = .00150	DESWW = .000	cmacw = -.060								
		CKVT = -1.000	DELPE = .200	ALPHLO = -1.600	alvrc = -1.000								
0		KWCD = 12											
		ACLS = -1.000	-.600	-.400	-.200	.000	.100	.200	.400	.600	.800	1.000	1.200
		ACDCDR = 2.400	1.466	1.221	1.066	1.005	1.000	1.005	1.046	1.138	1.333	1.743	2.718

HIGH LIFT DEVICES

0	0	RCLMAX = 1.200	FLAPS JFLTYP = 7	LED CLEOC = .000
		ALTFLP = 5000.	DPLPTO = 15.000	DELLED = .000
		FLAPN = 1.	DPLPLD = 40.000	DCLMLE = .930
		MCPFLAP = -1.000	CFOC = .300	DELLEO = 45.000
		BENGOB = .000	BTEOB = .750	
			DCLMTE = .000	
			DCDOTE = .000	
			DELTEO = .000	

*****PROPULSION*****

0	0	JENGSZ = 2	HPORT = 5000.	RCCRU = 50.000	RWCRTX = .970
		IPART = 1	TDELTO = 36.	ITORQ = 99999.	HSCREQ = 0.
		KODETO = 5	KODECL = 7	SMID = .500	THIN = 0.
		KODETR = 5	KODEAC = 5	HBTP = .437	PR = 1.000

*****WEIGHTS*****

0	0	SKPEI = .1350	SKY = .1800	SKB = 107.000	SKFS = .0200
		SKLG = .0380	SKZ = .2200	SKCC = 20.000	SKWF = .4300
		SKMG = .8000	SKTL = 1.0000	SKFW = .4300	SKFT = .9790
		SKPES = .3380	SKW = 133.400	SKSAS = .000	SKWTP = 1.8900
		WPLX = .0	YMG = .2500	EGMRGN = .0000	LCWING = 2
		WPEX = .0	RELX = .7500	CPMRGN = .2000	
		WFUL = .0	RELZ = .4500	STMRGN = .0000	LDCRMX = 8.000
		UWEAX = 200.0	CATD = 3.	DELP = 8.200	ATMIOC = 3.160
		STRUT = .0000	VMLPSL = 685.0	YP = .0000	DELWST = .0
		DELWFC = .0			
0	ENGINE	WENG = .0	WNAC = .0	WBYLON = .0	
		SWSLS = .160	UWNAC = 2.287	FPYL = .700	ELQDE = 3.000

STABILITY AND CONTROL

0	0	KSPind = 1	STATIC = .100	ZCG = 999.000	CNPAC = .0020
		CMPLPL = 999.000	CHALF = 999.000	TP = .0	ARVTE = -1.000
		CMPLPT = 999.000	CHDEL = 999.000	CEA = .520	RV = .300
		CMPLD = .000	RH = .350	DCMCLP = 9999.000	TAUV = 999.000
			DEMAX = -25.0	HWING = 0.	RVWCS = .990
			EYET = .0	dcmcpi = .030	DRMAX = 25.0
			TAUH = 999.000	rc = .350	

PERFORMANCE

0	0	TAXI DELTT = .167	XLPMAX = 1.100	DVR = 5.000	TDELTX = 36.000
		TO IFLY = 1	DELTVR = 3.500	UM = .020	HIMAX = 500.000
		THEMAX = 15.000	DVI = 5.000	MUB = .400	NFAIL = 0
		HOO = 5000.	VRAT = 1.10	WTMISM = 0.	
0	CLIMB	ICLM = 1	CRUISE CRMACH = .000	FRESF = 1.000	FACW1 = .800
		DELH = 1000.	CRALT = 0.	RCRRQ = 1250.0	ISWING = 0
		VCLMB = .0	ICRUS = 1	OPALT = 25000.	OFEM = .500
0	LAND	IWLD = 2	ILDGRQ = 99999.	VRATT = 1.300	HAPP = 50.
		TDELLD = 36.0	ALTEND = 5000.	RSMX = 1000.	SINKTD = 3.0
		TDELAY = 1.0	WLPCT = .9400	TROTID = .000	XLFMX = 1.200
		HTG = 5.5	TIDLE = .0	VTDROT = 1.1	

*****COST*****

0	0	NCADE = 1	HIR = .005	RI = .300	CMV = .800
		CLIB = 1993.0	TR = 2.000	OHR = 500.000	CCRW = 0.
		HRI = 4000000.	ERV = .100	CRWON = 23.000	UCSENG = .000
		CMF = .2	DYR = 15.0	CINP = 0.	UCSPF = .000
		TBO = 3200.0	SRPM = .0	CP = 0.	ALR = 3.400
		FCSP = .850			

1
0***** H.TAIL C.L. CHORD MUST = 8.502 TO BE LOCATED AT SPECIFIED POSITION ON VERTICAL*****
***** H.TAIL TAPER CHANGED TO .8214

Fig. D1 - Conventional Baseline Configuration GASP output file

```

.....
ITERATION TO BALANCE RANGE
RANGE ERROR, RANGE ERROR MINUS 1 .0223 .5848
GROSS WGT, GROSS WGT MINUS1 47873.0 48147.5

0 .....
0 FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
CLMAX VSTALL,KTS FLAP ANGLE LE ANGLE DELTA CL DELTA CT
FLAPS UP 1.2932 148.7 .0 .0 .0000 .0000
T.O. CONFIG 2.4660 107.5 15.0 .0 1.1629 .0432
LDG. CONFIG 3.2639 93.4 40.0 .0 1.9705 .1924

0 DOUBLE SLOTTED FOWLER FLAPS
OPT ANGLE DELCL AT OPT DELCD AT OPT AREA(FT2) WEIGHT(LB)
FLAPS 30.0 2.2500 .1500 120.6 697.3
0 .....
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK(DEGREES)= 1.476 LIPT= 46436.8 L/D= 13.055 ALTITUDE= 35000.0 MACH= .8000

1 ENGINE SIZING DATA FOLLOW
.....
OVSTLKT= 99.6 KTS EAS VRAT= 1.100 CLTO= 2.0380
VEND = 237.6 KNOTS EAS
0
ROTATION (TIME= 23.1 AND TAS= 122.2 EAS= 109.6)
LIPTOFF (TIME= 25.0 DIST= 2951.1 TAS= 129.8 EAS= 116.4)
DISTANCE TO 35 FT.= 4176.5 TAS= 144.9 EAS= 129.9 V35/V5= 1.3035
GEAR RETRACTION STARTED AT 31.2 SEC, COMPLETE AT 38.2 SEC
FLAP RETRACTION STARTED AT 41.3 SEC, COMPLETE AT 45.8 SEC
OVSTLKT= 99.6 KTS EAS VRAT= 1.100 CLTO= 2.0380
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 205.2 KNOTS EAS
ENGINE FAILURE (TIME= 21.8 AND TAS= 116.6 EAS= 104.6)
0
ROTATION (TIME= 25.0 AND TAS= 122.2 EAS= 109.6)
LIPTOFF (TIME= 27.8 DIST= 3518.5 TAS= 125.8 EAS= 112.8)
DISTANCE TO 35 FT.= 4913.6 TAS= 127.7 EAS= 114.5 V35/V5= 1.1489

ACCELERATE - STOP DISTANCE = 5192.0 FEET.
0 ENGINE OUT DISTANCE TO 35 FT.= 4913.6 FEET
OALL ENGINE DISTANCE TO 35 FT. (L) = 4176.5 FEET
FAR 25 T.O. DISTANCE (1.15XL) = 4803.0 FEET
ALL ENGINE DISTANCE TO 50 FT. = 4397.4 FEET
0 AT END OF TAKEOFF PHASE
TIME= .012 HRS FUEL USED= 73. LBS WEIGHT= 47800. LBS ALT.= 5500. FT.
0TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION ALT (FT) VS KEAS V/V5 V KTAS GRAD (PCT) R/C (PPM) REQ.R/C (PPM) CL L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT 5000. 99.8 1.1403 126.8 2.517 323.01 1.00 1.904 8.721
2ND SEG: T.O. FLAPS - ONE ENGINE OUT 5250. 99.8 1.2000 134.0 4.244 575.44 325.40 1.719 10.524
FINAL T.O. CRUISE CONFIG - ONE ENG OUT 6500. 137.2 1.2500 195.7 5.256 1041.15 237.69 .838 14.118
APPROACH FLAPS -ONE ENG OUT 5000. 95.3 1.4116 150.0 4.813 730.41 318.72 1.362 11.498
LANDING FLAPS - ALL ENGINES 5000. 86.7 1.3000 125.7 14.150 1799.64 406.99 1.939 7.204

APPROACH FLAP SETTING = 19.8 DEG.

+++ ENGINE-OUT SERVICE CEILING = 24584.5 FT.
BEST RATE OF CLIMB SPEED = 271.1 KTAS
ENGINE-OUT RATE OF CLIMB = 49.6 FPM
WEIGHT AT ALTITUDE = 45958.1 LBS

0 *****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES*****

0PROPULSION SYSTEM WEIGHTS
ENGINE WEIGHT/ENGINE 1522.4
NACELLE WEIGHT/ENGINE 342.4
PYLON WEIGHT/ENGINE 178.8
PROP OR QPAN .0
GEARBOX .0
SHROUD .0

0ENGINE POD DIMENSIONS
ENGINE FACE DIAMETER(PT) 3.99
NACELLE LENGTH(PT) 11.96

OVSTLKT= 99.6 KTS EAS VRAT= 1.100 CLTO= 2.0380
VEND = 237.1 KNOTS EAS
0
ROTATION (TIME= 22.1 AND TAS= 122.2 EAS= 109.6)
LIPTOFF (TIME= 24.0 DIST= 2844.6 TAS= 130.4 EAS= 117.0)
DISTANCE TO 35 FT.= 4042.7 TAS= 146.0 EAS= 130.9 V35/V5= 1.3137
GEAR RETRACTION STARTED AT 30.0 SEC, COMPLETE AT 37.0 SEC
FLAP RETRACTION STARTED AT 40.1 SEC, COMPLETE AT 44.6 SEC
OVSTLKT= 99.6 KTS EAS VRAT= 1.100 CLTO= 2.0380
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 197.2 KNOTS EAS
ENGINE FAILURE (TIME= 20.8 AND TAS= 116.6 EAS= 104.6)
0
ROTATION (TIME= 23.8 AND TAS= 122.2 EAS= 109.6)
LIPTOFF (TIME= 26.4 DIST= 3328.7 TAS= 125.9 EAS= 113.0)
DISTANCE TO 35 FT.= 4670.0 TAS= 128.4 EAS= 115.1 V35/V5= 1.1555

```

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

ACCELERATE - STOP DISTANCE = 5094.3 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 4670.0 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4042.7 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 4649.1 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 4266.5 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .012 HRS FUEL USED= 74. LBS WEIGHT= 47799. LBS ALT.= 5500. FT.
 0 TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	V5 KEAS	V/V5	V KTAS	GRAD (PCT)	R/C (FPM)	REQ.R/C (FPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	99.8	1.1403	126.8	2.864	367.58	1.00	1.904	8.536
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	99.8	1.2000	134.0	4.576	620.48	325.40	1.719	10.251
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	137.2	1.2500	195.7	5.398	1069.14	237.69	.838	13.392
APPROACH FLAPS -ONE ENG OUT	5000.	95.3	1.4116	150.0	5.109	775.33	318.72	1.362	11.140
LANDING FLAPS - ALL ENGINES	5000.	86.7	1.3000	125.7	15.280	1943.37	406.99	1.939	7.171

APPROACH FLAP SETTING = 19.8 DEG.

+++ ENGINE-OUT SERVICE CEILING = 25133.1 FT.
 BEST RATE OF CLIMB SPEED = 269.8 KTAS
 ENGINE-OUT RATE OF CLIMB = 49.8 FPM
 WEIGHT AT ALTITUDE = 45958.1 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 389.02

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R;ALT= 5000.) SLS AIRFLOW= 389.02

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 9920.1 LBS

OPROPULSION SYSTEM WEIGHTS

ENGINE WEIGHT/ENGINE	1587.2
NACELLE WEIGHT/ENGINE	342.4
PYLON WEIGHT/ENGINE	183.3
PROP OR QFAN	.0
GEARBOX	.0
SHROUD	.0

ENGINE POD DIMENSIONS

ENGINE FACE DIAMETER(FT)	3.99
NACELLE LENGTH(FT)	11.96

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

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*****
---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---
      MOST FWD LOAD      MOST AFT LOAD      DESIGN LOAD
      WT      CG      WT      CG      WT      CG
A/C OWE  28484.05  44.05  28484.05  44.05  28484.05  44.05
PAX      6120.00
BAGGAGE  .00      56.36  1500.00  56.36  1500.00  56.36
WING FUEL 1877.79  44.22  1877.79  44.22  9388.94  44.22
TIP FUEL .00      .00
FUS FUEL .00      44.22  .00      44.22  .00      44.22
TOTAL    36481.84  41.71  33901.84  44.85  47872.99  43.15
0
---TAIL SIZING SUMMARY---
      Static Longitudinal Stability, Stick-fixed, considered
0
      CONDITION ALPHA  WING CL  WING CLA  CANARD CMac  CANARD ALPHA  CANARD CLA  TAIL CLA  TAIL EFF.  DOWN WASH  FLAP CM
      CRUISE  1.5712  .3710  .1170  -.0600  .0000  .0000  .0762  1.0000
      LIFTOFF 2.0000  1.4720  .0618  -.0600  .0000  .0000  .0635  1.0000  .3767  -.1031
      LANDING 13.7607  3.2639  .0842  -.0600  .0000  .0000  .0635  1.0000  2.5920  -.2000
0
      --FUSELAGE-- --NACELLE-- -----POWER----- L.GEAR ROT.POWER
      CONDITION DCM  CM  DCM  CM  DCMdth  DCMfinc  CMdth  CMfinc  CT  CM  CM
      CRUISE  .3054  .1052  .0000  .0300  .0000  .0442  .0000  -.3641  4.6176
      LIFTOFF .5781  .1052  .0000  .0000  .0000  .0979
      LANDING .4244  .4202  .1052  .1041  .0000  .0979
0
      ELEVATOR PARAMETERS
      CMDELTA(CONTROL POWER) = -.06308  WING DE/DALPHA = .37673
      TAUH(EFFECTIVENESS) = .48250
      DEMA(X(MAX.ELEVATOR DEFLEC.) = -25.00000
0
      FRACTION STATION HORIZONTAL TAIL SIZES
      MAC (DATUM NOSE)
      NEUTRAL POINT .6452  46.270  STATIC STABILITY AND LANDING TRIM 215.1616
      STATIC MARGIN .1000  STATIC STABILITY AND LIFTOFF ROT. 270.2973
      AFT CG LIMIT(STABILITY) .5452  45.313
      CG RANGE(LOADING) .3280  REQUIRED TAIL SIZE 270.2973
      FWD CG LIMIT(CONTROL) .2172  42.243  TAIL ARM(ELTH) 44.8583
0
      VERTICAL TAIL AREA = 117.2811 FOR DIRECTIONAL STABILITY OF .00200
      RUDDER POWER AT MAX.DEFL.= .0178 PER DEG. RUDDER CL AT MAX.DEFL.= .4461
      VERTICAL TAIL AREA= 121.9062 FOR MINIMUM CONTROL SPEED = 98.62 KTS
      REQUIRED VERTICAL TAIL AREA = 121.9062 TAIL ARM(ELTV) = 33.5393
*****
0
      SUMMARY OF CRUISE LIPT-WEIGHT BALANCE
      ANGLE OF ATTACK(DEGREES)= 1.476  LIPT= 46436.8  L/D= 11.906  ALTITUDE= 35000.0  MACH= .8000
0
      WING LOCATION INFO.
      FUSELAGE LENGTH = 79.25  H-TAIL VOL. ARM = 44.86  C.G.LOCATION OF PROPULSION= 59.43
      WING 1/4C LOC.ON C.L.= 38.79  H-TAIL C.G.LOCATION = 87.79  C.G.OF REMAINING WEIGHT = 35.66
      MAC 1/4C LOCATION = 42.27  H-TAIL MAC FROM C.L. = 7.95
      MAC DIST.FROM C.L. = 13.45  H-TAIL LOCAT ON VERT.= 1.00
      WING C.G.LOCATION = 44.18  V-TAIL VOL. ARM = 33.54
      TIP TANKS C.G.LOCATE = .00  V-TAIL C.G.LOCATION = 76.70  DIST.L.E.VERT.TO L.E.HORZ.= .07
0
      WING H-TAIL V-TAIL
      AREA 576.783 270.297 121.906
      SPAN 69.190 32.881 11.041
      ASPECT RATIO 8.300 4.000 1.000
      TAPER RATIO .200 .821 .700
      1/4C. SWEEP 14.500 27.500 50.500
      L.E. SWEEP 18.723 28.593 52.459
      C.L. CHORD 13.894 9.026 12.990
      MEAN CHORD 9.571 8.247 11.156
      TIP CHORD 2.779 7.414 9.093

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Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

MISSION PERFORMANCE DATA FOLLOWS

TAXI AT IDLE THRUST

Table with columns: TIME (MRS), RANGE (NM), FUEL USED (LBS), WEIGHT (LBS), ALT. (FT), FUEL FLOW (LB/HR). Includes data for 0.000, .167, and 0VSTLKT= 99.5 KTS EAS VRAT= 1.100 CLTO= 2.0380.

Main performance table with columns: TIME (SEC), DIST. (FEET), FUEL USED (LBS), WEIGHT (LBS), ALT. (FT), TAS (KTS), EAS (KTS), MACH NO., ACCEL (FPS2), CL, CD, ALPHA (DEG), GAMMA (DEG), ROC (FPM), LOAD FACT, THRUST (LBS), FUEL FLOW (LB/HR), FUS. ANGLE (DEG).

Table containing ROTATION (TIME= 22.0 AND TAS= 122.0 EAS= 109.5), LIFTOFF (TIME= 23.8 DIST= 2808.2 TAS= 129.8 EAS= 116.5), GEAR RETRACTION STARTED AT 29.9 SEC, COMPLETE AT 36.9 SEC, and FLAP RETRACTION STARTED AT 40.0 SEC, COMPLETE AT 44.5 SEC.

0VSTLKT= 99.5 KTS EAS VRAT= 1.100 CLTO= 2.0380
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 199.7 KNOTS EAS
(TEMP. = 537. DEG: STD. +36.)
0 TAKEOFF (ELEVATION= 5000. FT)

Main performance table (continued) with columns: TIME (SEC), DIST. (FEET), FUEL USED (LBS), WEIGHT (LBS), ALT. (FT), TAS (KTS), EAS (KTS), MACH NO., ACCEL (FPS2), CL, CD, ALPHA (DEG), GAMMA (DEG), ROC (FPM), LOAD FACT, THRUST (LBS), FUEL FLOW (LB/HR), FUS. ANGLE (DEG). Includes data for 0.0 to 24.0 and ENGINE FAILURE (TIME= 20.7 AND TAS= 116.5 EAS= 104.5).

Table containing ROTATION (TIME= 23.9 AND TAS= 122.0 EAS= 109.5) and 25.0 3036.8 191.0 47682. 5000.0 123.6 110.9 .183 2.38 1.6112 .1379 3.68 .00 .0 .81 7017. 3164. 1.68

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

LIFTOFF (TIME=	26.6	DIST=	3373.7	TAS=	125.7	EAS=	112.7)											
27.0	3458.8	192.8	47680.	5000.0	126.1	113.2	.187	1.88	1.9234	.1654	7.74	.03	6.0	1.02	6986.	3165.	5.76	
28.0	3672.7	193.7	47679.	5000.8	127.1	114.1	.189	1.42	2.0021	.1755	8.74	.45	102.3	1.08	6973.	3166.	7.19	
29.0	3888.0	194.6	47678.	5004.0	127.8	114.6	.190	.69	2.0101	.1887	8.54	1.27	287.5	1.10	6965.	3166.	7.81	
30.0	4103.9	195.4	47678.	5010.3	128.0	114.8	.190	.01	1.9695	.2009	7.84	2.09	473.9	1.08	6962.	3166.	7.93	
31.0	4319.8	196.3	47677.	5018.9	128.0	114.8	.190	.00	1.8278	.1932	6.14	2.34	530.5	1.00	6961.	3165.	6.48	
32.0	4535.8	197.2	47676.	5027.6	128.0	114.7	.190	-.01	1.8089	.1967	5.94	2.26	510.7	.99	6960.	3164.	6.19	
DISTANCE TO 35 FT.= 4727.8 TAS= 128.0 EAS= 114.7 V35/V35= 1.1534																		
33.0	4751.7	198.1	47675.	5035.9	128.0	114.7	.190	.00	1.8075	.1999	5.94	2.14	483.4	.99	6958.	3164.	6.07	
34.0	4967.7	199.0	47674.	5043.8	128.0	114.7	.190	.00	1.8150	.2032	6.04	2.04	461.8	.99	6957.	3163.	6.08	
35.0	5183.8	199.8	47673.	5051.3	128.0	114.7	.190	-.01	1.8230	.2057	6.14	1.97	445.9	1.00	6956.	3163.	6.11	

ACCELERATE - STOP DISTANCE = 5078.4 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 4727.8 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4033.0 FEET
 0 PAR 25 T.O. DISTANCE (1.15XIL) = 4638.0 FEET
 0 ALL ENGINE DISTANCE TO 50 FT. = 4256.3 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .178 HRS FUEL USED= 225. LBS WEIGHT= 47648. LBS ALT.= 5500. FT.

ACCELERATE TO MACH NO. = .396

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.178	.00	224.7	47648.	5500.	152.	140.	.235	.708	13522.	6202.
.186	1.77	277.5	47596.	5500.	257.	237.	.396	.806	11555.	6380.

END OF ACCELERATION SEGMENT

TIME= .186 HRS FUEL USED= 277.5 LBS WEIGHT= 47596. LBS RANGE= 2. NM
 0 CLIMB TO 35000. FT. AT MAXIMUM RATE OF CLIMB

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	FUS. ANGLE (DEG)	R/C (FPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
.186	2.	277.	47596.	5500.	241.	222.	.371	.801	.4882	.0361	3.90	8.16	10.06	3468.	10244.	5613.
.189	2.	291.	47582.	6000.	242.	222.	.374	.800	.4907	.0362	3.92	7.61	9.53	3251.	10147.	5559.
.194	4.	319.	47554.	7000.	245.	221.	.379	.800	.4958	.0365	3.97	7.44	9.40	3210.	9946.	5447.
.199	5.	348.	47525.	8000.	247.	219.	.383	.799	.5038	.0369	4.05	7.34	9.39	3191.	9756.	5334.
.204	6.	376.	47497.	9000.	248.	217.	.387	.798	.5121	.0373	4.14	7.13	9.27	3125.	9566.	5221.
.210	7.	403.	47470.	10000.	258.	222.	.404	.801	.4895	.0361	3.85	5.67	7.52	2587.	9249.	5117.
.216	9.	436.	47437.	11000.	261.	221.	.410	.800	.4939	.0364	3.89	6.76	8.65	3113.	9059.	5002.
.221	10.	463.	47410.	12000.	264.	220.	.416	.799	.4998	.0367	3.95	6.17	8.11	2869.	8870.	4889.
.227	12.	492.	47381.	13000.	266.	218.	.421	.799	.5059	.0370	4.00	5.98	7.98	2810.	8694.	4780.
.233	14.	520.	47353.	14000.	269.	217.	.427	.798	.5122	.0373	4.06	5.78	7.84	2742.	8498.	4673.
.239	15.	548.	47325.	15000.	272.	216.	.435	.798	.5145	.0374	4.07	5.41	7.48	2605.	8302.	4569.
.246	17.	578.	47295.	16000.	277.	217.	.444	.798	.5138	.0374	4.04	5.06	7.10	2477.	8078.	4457.
.252	19.	608.	47265.	17000.	280.	215.	.450	.797	.5205	.0378	4.10	5.08	7.18	2511.	7878.	4343.
.259	21.	636.	47237.	18000.	283.	214.	.456	.796	.5276	.0382	4.17	4.86	7.03	2427.	7681.	4232.
.266	23.	665.	47208.	19000.	285.	212.	.462	.795	.5348	.0385	4.23	4.65	6.88	2344.	7487.	4123.
.273	25.	695.	47178.	20000.	288.	211.	.469	.794	.5421	.0389	4.29	4.44	6.73	2261.	7296.	4016.
.280	27.	724.	47149.	21000.	291.	209.	.475	.793	.5495	.0394	4.36	4.23	6.59	2177.	7109.	3912.
.288	29.	754.	47119.	22000.	294.	208.	.482	.792	.5569	.0398	4.42	4.03	6.45	2094.	6924.	3809.
.296	31.	785.	47088.	23000.	298.	207.	.490	.792	.5625	.0401	4.46	3.77	6.23	1984.	6739.	3710.
.304	34.	816.	47057.	24000.	304.	207.	.502	.792	.5590	.0399	4.39	3.32	5.71	1782.	6527.	3623.
.314	37.	850.	47023.	25000.	306.	206.	.508	.791	.5683	.0404	4.47	3.41	5.88	1845.	6338.	3533.
.323	39.	882.	46991.	26000.	309.	204.	.515	.790	.5780	.0410	4.56	3.20	5.76	1751.	6153.	3443.
.332	42.	914.	46959.	27000.	312.	202.	.523	.789	.5860	.0415	4.62	2.96	5.58	1636.	5968.	3356.
.343	45.	949.	46924.	28000.	316.	201.	.532	.788	.5920	.0418	4.65	2.72	5.38	1522.	5786.	3271.
.353	49.	984.	46889.	29000.	320.	200.	.540	.787	.5991	.0423	4.70	2.55	5.25	1441.	5608.	3187.
.365	53.	1021.	46852.	30000.	325.	199.	.551	.787	.6029	.0425	4.71	2.29	5.00	1317.	5431.	3106.
.378	57.	1061.	46812.	31000.	328.	198.	.559	.786	.6120	.0431	4.77	2.13	4.92	1249.	5226.	3000.
.391	61.	1101.	46772.	32000.	336.	199.	.575	.786	.6061	.0427	4.66	1.71	4.37	1017.	5010.	2905.
.407	67.	1148.	46725.	33000.	354.	205.	.607	.791	.5680	.0404	4.15	1.15	3.30	720.	4776.	2829.
.431	75.	1214.	46659.	34000.	362.	206.	.625	.792	.5613	.0400	4.02	1.23	3.25	790.	4607.	2740.
.452	83.	1272.	46601.	35000.	370.	207.	.641	.792	.5578	.0398	3.92	1.08	3.00	709.	4438.	2655.

0 END OF CLIMB TO 35000. FT
 TIME= .452 HRS FUEL USED= 1272. LBS WEIGHT= 46601. LBS RANGE= 83. NM

0 ALTITUDE= 35000. FT TAS= 458.77 KTS MACH NO= .7949

ACCELERATE TO MACH NO. = .800

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.452	82.51	1271.6	46601.	35000.	370.	207.	.641	.792	4737.	3020.
.503	104.91	1436.3	46437.	35000.	461.	258.	.800	.816	4846.	3167.

END OF ACCELERATION SEGMENT

TIME= .503 HRS FUEL USED= 1436.3 LBS WEIGHT= 46437. LBS RANGE= 105. NM
 SPECIFIED MACH NUMBER CONDITION CAN NOT BE PERFORMED AT NORMAL RATED POWER CONDITION

ACCELERATE TO MACH NO. = .795

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.452	82.51	1271.6	46601.	35000.	370.	207.	.641	.792	4737.	3020.
.501	104.12	1430.9	46442.	35000.	458.	256.	.795	.815	4842.	3163.

END OF ACCELERATION SEGMENT

TIME= .501 HRS FUEL USED= 1430.9 LBS WEIGHT= 46442. LBS RANGE= 104. NM

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

ACCELERATE TO MACH NO. = .739

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.452	82.51	1271.6	46601.	35000.	370.	207.	.641	.792	4737.	3020.
.480	94.53	1363.6	46509.	35000.	426.	238.	.739	.808	4792.	3107.

END OF ACCELERATION SEGMENT
 TIME= .480 HRS FUEL USED= 1363.6 LBS WEIGHT= 46509. LBS RANGE= 95. NM

DESIGN CASE
 CRUISE PERFORMANCE SUMMARY
 FOR
 ***** MAXIMUM FUEL *****
 FUEL AVAILABLE= 10835.

	TIME	RANGE	AT SPECIFIED SPEED		AT NORMAL POWER		AT BEST SPEC. RANGE	
			START CRUISE	END CRUISE	START CRUISE	END CRUISE	START CRUISE	END CRUISE
			.000	.000	.501	3.272	.480	3.951
			0.	0.	104.	1375.	95.	1375.
			0.	0.	1431.	8193.	1364.	9094.
			0.	0.	46442.	39680.	46509.	38779.
			0.	0.	35000.	35000.	35000.	35000.
			.0	.0	458.8	458.8	426.8	426.8
			.0	.0	255.7	255.7	237.8	237.8
			.0000	.0000	.7949	.7949	.7395	.7395
			.0000	.0000	.8159	.8237	.8088	.8174
			.000	.000	1.535	.985	2.252	1.612
			.000	.000	-.465	-1.015	.252	-.388
			.0000	.0000	.3645	.3006	.4219	.3517
			.000	.000	11.980	10.622	12.754	11.597
			.0	.0	2518.4	2368.7	2321.5	2140.1
			0.	0.	8465.	7690.	8555.	7738.
			.00000	.00000	.18216	.19368	.18383	.19941

0 DESCENT FROM CRUISE AT NORMAL POWER CONDITION
 (U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MMO OR VMO)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ANGLE (DEG)	R/S (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
3.284	1381.	8215.	39658.	35000.	459.	256.	.795	.823	.3084	.0289	1.05	-1.65	-2.60	1339.	2574.	1764. R
3.297	1387.	8239.	39634.	34000.	461.	262.	.795	.825	.2941	.0285	.93	-1.60	-2.67	1306.	2727.	1871. R
3.310	1393.	8265.	39608.	33000.	463.	268.	.795	.826	.2805	.0281	.81	-1.55	-2.74	1271.	2888.	1984. R
3.324	1399.	8293.	39580.	32000.	465.	275.	.795	.828	.2677	.0277	.70	-1.51	-2.81	1241.	3054.	2100. R
3.338	1406.	8324.	39549.	31000.	467.	281.	.795	.829	.2555	.0274	.60	-1.46	-2.87	1209.	3228.	2223. R
3.352	1412.	8357.	39516.	30000.	469.	288.	.795	.831	.2440	.0271	.50	-1.42	-2.92	1180.	3406.	2350. R
3.366	1419.	8393.	39480.	29000.	471.	294.	.795	.832	.2331	.0268	.40	-1.38	-2.98	1153.	3590.	2482. R
3.381	1426.	8432.	39441.	28000.	473.	301.	.795	.833	.2227	.0266	.32	-1.35	-3.03	1127.	3781.	2619. R
3.396	1433.	8474.	39399.	27000.	475.	308.	.795	.834	.2129	.0264	.23	-1.31	-3.08	1100.	3981.	2763. R
3.412	1441.	8519.	39354.	26000.	477.	314.	.795	.836	.2035	.0262	.15	-1.28	-3.13	1077.	4200.	2918. R
3.427	1448.	8568.	39305.	25000.	479.	321.	.795	.837	.1946	.0260	.07	-1.24	-3.17	1053.	4412.	3073. R
3.443	1456.	8620.	39253.	24000.	481.	328.	.795	.838	.1862	.0258	.00	-1.21	-3.21	1032.	4631.	3234. R
3.460	1464.	8676.	39197.	23000.	483.	335.	.795	.839	.1782	.0257	-.07	-1.18	-3.25	1011.	4858.	3401. R
3.477	1472.	8734.	39139.	22000.	477.	337.	.782	.839	.1762	.0256	-.06	-1.17	-3.24	992.	4903.	3451. R
3.494	1480.	8794.	39079.	21000.	472.	339.	.770	.839	.1739	.0256	-.06	-1.16	-3.23	972.	4967.	3513. R
3.499	1482.	8798.	39075.	20000.	391.	286.	.636	.831	.2429	.0271	.81	-4.81	-6.00	3329.	1059.	762. A
3.504	1484.	8802.	39071.	19000.	387.	288.	.627	.831	.2402	.0270	.80	-4.80	-6.00	3285.	1104.	798. A
3.509	1486.	8806.	39067.	18000.	383.	289.	.617	.831	.2375	.0269	.79	-4.79	-6.00	3240.	1150.	835. A
3.514	1488.	8811.	39062.	17000.	378.	291.	.608	.832	.2349	.0269	.78	-4.78	-6.00	3196.	1199.	873. A
3.520	1490.	8816.	39057.	16000.	374.	293.	.599	.832	.2322	.0268	.76	-4.76	-6.00	3153.	1248.	913. A
3.525	1492.	8821.	39052.	15000.	370.	294.	.591	.832	.2295	.0267	.75	-4.75	-6.00	3110.	1300.	954. A
3.530	1494.	8826.	39047.	14000.	367.	296.	.583	.833	.2269	.0267	.73	-4.73	-6.00	3067.	1353.	997. A
3.536	1496.	8832.	39041.	13000.	363.	298.	.574	.833	.2242	.0266	.72	-4.72	-6.00	3025.	1408.	1041. A
3.542	1498.	8838.	39035.	12000.	359.	299.	.567	.833	.2215	.0266	.70	-4.70	-6.00	2984.	1465.	1088. A
3.547	1500.	8844.	39029.	11000.	356.	301.	.559	.834	.2189	.0265	.68	-4.68	-6.00	2944.	1523.	1135. A
3.557	1503.	8853.	39021.	10000.	291.	250.	.455	.822	.3180	.0292	1.88	-3.48	-3.60	1789.	1203.	866. S
3.566	1505.	8861.	39012.	9000.	286.	250.	.446	.822	.3180	.0292	1.89	-3.42	-3.53	1731.	1244.	898. S
3.576	1508.	8870.	39003.	8000.	282.	250.	.438	.822	.3179	.0292	1.90	-3.36	-3.46	1674.	1286.	931. S
3.586	1511.	8880.	38993.	7000.	277.	250.	.430	.822	.3179	.0292	1.91	-3.29	-3.39	1617.	1330.	965. S
3.597	1514.	8891.	38982.	6000.	273.	250.	.422	.822	.3178	.0292	1.92	-3.23	-3.31	1561.	1375.	1000. S
3.608	1517.	8903.	38971.	5000.	269.	250.	.414	.822	.3177	.0292	1.93	-3.16	-3.23	1505.	1421.	1037. S
3.620	1520.	8915.	38958.	4000.	265.	250.	.406	.822	.3176	.0292	1.94	-3.09	-3.16	1450.	1469.	1075. S
3.632	1523.	8928.	38945.	3000.	261.	250.	.399	.822	.3175	.0292	1.94	-3.02	-3.08	1396.	1518.	1115. S
3.644	1526.	8943.	38930.	2000.	257.	250.	.391	.822	.3174	.0292	1.95	-2.95	-3.00	1341.	1569.	1155. S
3.650	1528.	8950.	38923.	1500.	255.	250.	.388	.822	.3173	.0292	1.95	-2.91	-2.95	1314.	1595.	1176. S

0 END OF DESCNT TO 1500. FT
 TIME= 3.650 HRS FUEL USED= 8950. LBS WEIGHT= 38923. LBS RANGE= 1528. NM

0 RESERVE FUEL(LBS) 0. 1889. 1741.
 (45.0 MIN.)

ACCELERATE TO MACH NO. = .800

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.452	82.51	1271.6	46601.	35000.	370.	207.	.641	.792	4737.	3020.
.503	104.91	1436.3	46437.	35000.	461.	258.	.800	.816	4846.	3167.

END OF ACCELERATION SEGMENT
 TIME= .503 HRS FUEL USED= 1436.3 LBS WEIGHT= 46437. LBS RANGE= 105. NM
 SPECIFIED MACH NUMBER CONDITION CAN NOT BE PERFORMED AT NORMAL RATED POWER CONDITION

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

ACCELERATE TO MACH NO. = .795

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.452	82.51	1271.6	46601.	35000.	370.	207.	.641	.792	4737.	3020.
.501	104.12	1430.9	46442.	35000.	458.	256.	.795	.815	4842.	3163.

END OF ACCELERATION SEGMENT

TIME= .501 HRS FUEL USED= 1430.9 LBS WEIGHT= 46442. LBS RANGE= 104. NM

ACCELERATE TO MACH NO. = .739

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.452	82.51	1271.6	46601.	35000.	370.	207.	.641	.792	4737.	3020.
.480	94.53	1363.6	46509.	35000.	426.	238.	.739	.808	4792.	3107.

END OF ACCELERATION SEGMENT

TIME= .480 HRS FUEL USED= 1363.6 LBS WEIGHT= 46509. LBS RANGE= 95. NM

DESIGN CASE
CRUISE PERFORMANCE SUMMARY
FOR
***** DESIGN PAYLOAD *****
**** MAXIMUM PAYLOAD ****
FUEL AVAILABLE= 9389.

TIME (HRS)	RANGE (NM)	AT SPECIFIED SPEED		AT NORMAL POWER		AT BEST SPEC. RANGE		
		START CRUISE	END CRUISE	START CRUISE	END CRUISE	START CRUISE	END CRUISE	
		HRS.	.000	.000	.501	2.664	.480	3.280
		RANGE N.MI.	0.	0.	104.	1097.	95.	1289.
		FUEL USED LBS.	0.	0.	1431.	6746.	1364.	7648.
		WEIGHT LBS.	0.	0.	46442.	41127.	46509.	40225.
		ALTITUDE FT.	0.	0.	35000.	35000.	35000.	35000.
		TAS KTS.	0.	0.	458.8	458.8	426.8	426.8
		EAS KTS.	0.	0.	255.7	255.7	237.8	237.8
		MACH NO.	.0000	.0000	.7949	.7949	.7395	.7395
		DIV. MACH	.0000	.0000	.8159	.8223	.8088	.8158
		ANGLE ATTACK DEG.	.000	.000	1.535	1.082	2.252	1.731
		FUSE. ANGLE DEG.	.000	.000	-.465	-.918	.252	-.269
		CL	.0000	.0000	.3645	.3119	.4219	.3649
		L/D	.000	.000	11.980	10.888	12.754	11.846
		FUEL FLOW LB/HR	0.	0.	2518.4	2400.5	2321.5	2173.0
		BREG. FACTOR N.MI.	0.	0.	8465.	7865.	8555.	7905.
		SPEC. RANGE NM/LB	.00000	.00000	.18216	.19111	.18383	.19640

DESCENT FROM CRUISE AT NORMAL POWER CONDITION

(U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MMO OR VMO)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	FUS. ANGLE (DEG)	R/S (FPM)	THRUST (LBS)	FUEL FLOW (LB/HR)	
2.677	1102.	6768.	41105.	35000.	459.	256.	.795	.821	.3196	.0292	1.15	-1.65	-2.50	1339.	2578.	1766.	R
2.690	1108.	6792.	41081.	34000.	461.	262.	.795	.823	.3048	.0288	1.02	-1.60	-2.58	1306.	2730.	1872.	R
2.703	1114.	6818.	41055.	33000.	463.	268.	.795	.825	.2907	.0284	.90	-1.55	-2.65	1271.	2891.	1985.	R
2.716	1120.	6846.	41027.	32000.	465.	275.	.795	.827	.2774	.0280	.79	-1.51	-2.72	1241.	3056.	2101.	R
2.730	1127.	6877.	40996.	31000.	467.	281.	.795	.828	.2648	.0276	.68	-1.46	-2.79	1209.	3229.	2224.	R
2.744	1134.	6910.	40963.	30000.	469.	288.	.795	.830	.2529	.0273	.58	-1.42	-2.85	1180.	3407.	2350.	R
2.758	1140.	6946.	40927.	29000.	471.	294.	.795	.831	.2416	.0270	.48	-1.38	-2.91	1153.	3590.	2482.	R
2.773	1147.	6985.	40888.	28000.	473.	301.	.795	.832	.2309	.0268	.39	-1.35	-2.96	1127.	3781.	2619.	R
2.788	1155.	7027.	40847.	27000.	475.	308.	.795	.834	.2207	.0265	.30	-1.31	-3.01	1100.	3980.	2762.	R
2.804	1162.	7072.	40801.	26000.	477.	314.	.795	.835	.2110	.0263	.21	-1.28	-3.06	1077.	4198.	2918.	R
2.820	1170.	7120.	40753.	25000.	479.	321.	.795	.836	.2018	.0261	.14	-1.24	-3.11	1053.	4409.	3072.	R
2.836	1177.	7173.	40701.	24000.	481.	328.	.795	.837	.1930	.0260	.06	-1.21	-3.15	1032.	4627.	3232.	R
2.852	1185.	7229.	40645.	23000.	483.	335.	.795	.838	.1847	.0258	-.01	-1.18	-3.19	1011.	4854.	3399.	R
2.869	1193.	7287.	40586.	22000.	477.	337.	.782	.838	.1825	.0258	-.01	-1.17	-3.18	992.	4902.	3451.	R
2.886	1201.	7347.	40526.	21000.	472.	339.	.770	.838	.1802	.0257	-.01	-1.16	-3.17	972.	4966.	3513.	R
2.891	1204.	7362.	40511.	20000.	489.	357.	.795	.841	.1618	.0254	-.21	-3.79	-6.00	3277.	3686.	3022.	A
2.896	1206.	7366.	40507.	19000.	392.	292.	.635	.831	.2425	.0271	.81	-4.81	-6.00	3335.	1104.	798.	A
2.901	1208.	7370.	40503.	18000.	388.	293.	.626	.831	.2398	.0270	.80	-4.80	-6.00	3290.	1150.	835.	A
2.907	1210.	7375.	40498.	17000.	383.	295.	.616	.831	.2372	.0269	.79	-4.79	-6.00	3246.	1199.	873.	A
2.912	1212.	7380.	40493.	16000.	379.	296.	.607	.832	.2345	.0269	.78	-4.78	-6.00	3202.	1248.	913.	A
2.917	1214.	7385.	40488.	15000.	375.	298.	.599	.832	.2319	.0268	.76	-4.76	-6.00	3159.	1300.	954.	A
2.922	1216.	7390.	40483.	14000.	371.	300.	.590	.832	.2293	.0267	.75	-4.75	-6.00	3116.	1353.	997.	A
2.928	1218.	7396.	40477.	13000.	368.	301.	.582	.833	.2266	.0267	.73	-4.73	-6.00	3074.	1408.	1041.	A
2.933	1220.	7402.	40471.	12000.	364.	303.	.574	.833	.2240	.0266	.71	-4.71	-6.00	3032.	1465.	1088.	A
2.939	1222.	7408.	40465.	11000.	360.	305.	.566	.833	.2213	.0266	.70	-4.70	-6.00	2991.	1523.	1135.	A
2.948	1224.	7416.	40457.	10000.	291.	250.	.455	.820	.3298	.0296	2.01	-3.42	-3.42	1759.	1203.	866.	S
2.958	1227.	7425.	40448.	9000.	286.	250.	.446	.820	.3297	.0296	2.02	-3.36	-3.35	1703.	1244.	898.	S
2.968	1230.	7434.	40439.	8000.	282.	250.	.438	.820	.3296	.0296	2.03	-3.31	-3.28	1647.	1286.	931.	S
2.979	1233.	7444.	40429.	7000.	277.	250.	.430	.820	.3296	.0296	2.04	-3.24	-3.21	1592.	1330.	965.	S
2.990	1236.	7455.	40418.	6000.	273.	250.	.422	.820	.3295	.0296	2.05	-3.18	-3.13	1538.	1375.	1000.	S
3.001	1239.	7467.	40406.	5000.	269.	250.	.414	.820	.3294	.0296	2.06	-3.12	-3.06	1483.	1421.	1037.	S
3.012	1242.	7479.	40394.	4000.	265.	250.	.406	.820	.3293	.0296	2.07	-3.05	-2.98	1430.	1469.	1075.	S
3.025	1245.	7493.	40380.	3000.	261.	250.	.399	.820	.3292	.0296	2.07	-2.98	-2.91	1377.	1518.	1115.	S
3.037	1248.	7508.	40366.	2000.	257.	250.	.391	.820	.3291	.0296	2.08	-2.91	-2.83	1324.	1569.	1155.	S
3.044	1250.	7515.	40358.	1500.	255.	250.	.388	.820	.3290	.0296	2.08	-2.87	-2.79	1298.	1595.	1176.	S

END OF DESCENT TO 1500. FT

TIME= 3.044 HRS FUEL USED= 7515. LBS WEIGHT= 40358. LBS RANGE= 1250. NM

RESERVE FUEL(LBS) 0. 1889. 1741.
(45.0 MIN.)

RANGE = 1250. BLOCK TIME= 3.044 USED FOR DESIGN RANGE AND COST

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

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0 *****
0 TEMP.= 537. DEG:STD.+36.
  LANDING ELEVATION= 5000. FT.
  LANDING WING LOADING= 78.02 PSF.
  LANDING WEIGHT = 45001. LBS.

  LANDING DISTANCE FROM 50. FT.= 2410. FT.

  F.A.R. FACTORED FIELD LENGTH = 4017. FT.
0 APPROACH TRANSITION DELAY ROLL
0 DIST= 615. DIST= 179. DIST= 182. DIST= 1434.
  R/S= 1000. XLFMX= 1.200 TDELAY= 1.00 MUB= .4000
  VAPEAS= 109.13 SINKTD= 3.000 TIDLE= 645. TR/TIDLE= .0000
  VAPTAS= 121.77 VSTEAS= 83.95 VDTAS= 107.72 ABAR(G)= .3590
  THETA= 4.65 CLMX= 3.2639
  THRUST= 2700. HFLAR= 20.9
0 *****
0 RANGE OR ENDURANCE ITERATION SUMMARY

  GROSS RANGE (NMI) OR
  ITERATION WEIGHT (LB) ENDURANCE (HR)
  0 44050.00 816.875
  1 55062.50 1980.942
  2 48147.52 1277.911
  3 47872.99 1250.136
  REQUIRED RG. OR END. = 1250.000
0
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
  ANGLE OF ATTACK(DEGREES)= 1.476 LIFT= 46436.8 L/D= 11.906 ALTITUDE= 35000.0 MACH= .8000
0 GROSS WEIGHT = 47873. PASSENGERS = 50. PLUS CREW
0 FUSELAGE LENGTH (ELF) 79.25 FT
  WIDTH (SW) 9.25 FT
  WETTED AREA (SF) 1910. SQFT
  DELTA P (DELP) 8.20 PSI
0 WING ASPECT RATIO (AR) 8.30
  AREA (SW) 576.8 SQFT
  SPAN (B) 69.2 FT
  GEOM. MEAN CHORD (CBARW) 9.57 FT
  QUARTER CHORD SWEEP (DLMC4) 14.5 DEG
  TAPER RATIO (SLM) .200
  ROOT THICKNESS (TCR) .130
  TIP THICKNESS (TCT) .100
  WING LOADING (WGS) 83.0 PSF
  WING FUEL VOLUME (VFW) 1620.4 GAL
0 HOR. TAIL ASPECT RATIO (ARHT) 4.00
  AREA (SHT) 270.3 SQFT
  SPAN (BHT) 32.88 FT
  MEAN CHORD (CBARHT) 8.25 FT
  THICKNESS/CHORD (TCHT) .100
  MOMENT ARM (ELTH) 44.9 FT
  VOLUME COEFF. (VBARH) 2.196
0 VERT. TAIL ASPECT RATIO (ARVT) 1.00
  AREA (SVT) 121.9 SQFT
  SPAN (BVT) 11.04 FT
  MEAN CHORD (CBARVT) 11.16 FT
  THICKNESS/CHORD (TCVT) .120
  MOMENT ARM (ELTV) 33.5 FT
  VOLUME COEFF. (VBARV) .102
0 ENG. NACELLES LENGTH (ELN) 11.96 FT
  MEAN DIAMETER (DBARN) 3.99 FT
  NUMBER ENGINES (ENP) 2.0
  WETTED AREA (SN) 299.40 SQFT

  LOCATION ON FUSELAGE
0 VDIVE = 715. KTS VMD = 596. KTS MMD = .900
  ULT. LP = 5.70 MAN. LP = 2.50 GUST LP = 3.80
0 PROPULSION GROUP
  PRIMARY ENGINES (WEP) 3174.
  PRIMARY ENGINE INSTL. (WPEI) 429.
  FUEL SYSTEM (WFSS) 188.
  TOTAL PROP. GROUP WT. (WE) 3791.
0 STRUCTURES GROUP
  WING (WW) 5378.
  HOR. TAIL (WHT) 950.
  VERT. TAIL (WVT) 544.
  FUSELAGE (WF) 6038. (INCL. .0 LBS A.T.W.)
  LANDING GEAR (WLG) 1819.
  PRIMARY ENG. SECTION (WPES) 1051.
  GROUP WEIGHT INC. (DELWST) 0.
  TOTAL STRUC. GROUP WT. (WST) 15779.
0 FLIGHT CONTROLS GROUP
  COCKPIT CONTROLS (WCC) 98.
  FIXED WING CONTROLS (WCFW) 983.
  SAS (WSAS) 0.
  GROUP WEIGHT INC. (DELWPC) 0.
  TOTAL CONTROL WT. (WPC) 1081.
0 WT. OF FIXED EQUIPMENT (WFE) 6734.

  WEIGHT EMPTY (WE) 27385.
  FIXED USEFUL LOAD (WFUL) 1099. (INC. CREW )
  OPERATING WEIGHT EMPTY (OWE) 28484.
0 PAYLOAD (WPL) 10000. (PAX.VOL.= 50. DESIGN PAX= 50.)
  FUEL (WFA) 9389. (WFW= 9389.) (WFTP= 0.)
  GROSS WEIGHT (WG) 47873.

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Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

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0      FIXED EQUIP GROUP                FIXED USEFUL LOAD
0      WAFU      372.27                WCREW ( 2.)      340.00
      WINSTR      261.68                WSTU ( 1.)      130.00
      WHYD      399.15                WCBAG           110.00
      WELEC      970.00                WUF            144.10
      MAV       500.00                WOIL           131.14
      WFUR      3410.00                WSRV           116.00
      WAC       477.91                WHZO           53.00
      WAI       323.00                WEMER          40.00
      WAUXG     20.00                WCATER         35.00

      WFE       6734.01                WFUL           1099.24

0  DESIGN MACH = .800          DESIGN ALTITUDE = 35000.          DESIGN Q (PSF) =224.03
0  DESIGN RE.NUM. PER FT. = 1.922E+06  FLATPLATE CP AT RE=10EX7 IS .00274
0  AERODYNAMIC DATA

0      DRAG BREAKDOWN          FLATPLATE          CDO          WETTED
0      WING                    AREA(SQFT)         .00650        AREA(SQFT)
      FUSELAGE                 5.4592            .00946        1910.38
      VERT.TAIL                 .7493             .00130        243.81
      HOR. TAIL                 1.6685            .00289        540.59
      ENGINE MAC.              1.2061            .00209        299.40
      TIP TANKS                 .0000             .00000        .00
      INCREMENTAL              .8652             .00150        .00
0      TOTAL                   13.6964           .02375        3904.47

      MEAN SKIN FRICTION COEF.= .003508

0  AERODYNAMIC COEPP.
      A1                        .8006
      A2                       -.1227
      A3                        .0386
      A4=.75X(T/C)              .0909
      A5=CDO--                  .0152
      A6                        2.3717
      A7=1/(PI.SEE.AR)         .0481
      3-D LIPT SLOPE AT CRUISE MACH (CLALPH) 6.7033 PER RADIAN
      OSWALD FACTOR (SEE)      .7980
0  CRUISE CD = .0237 + .0481 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
0  RETRACTABLE LANDING GEAR CD INC.= .02700

0  CRUISE DRAG
0CL= .2000
      MACH    CD    L/D    CLALPH    ALPHA
      .50000  .02570  7.7818  5.3413  .5454
      .55000  .02570  7.7818  5.4739  .4934
      .60000  .02570  7.7818  5.6323  .4345
      .65000  .02570  7.7818  5.8228  .3680
      .70000  .02570  7.7818  6.0544  .2927
      .75000  .02570  7.7818  6.3408  .2072
      .80000  .02570  7.7818  6.7033  .1095
      .85000  .02577  7.7604  7.1781  -.0036
0CL= .3000
      MACH    CD    L/D    CLALPH    ALPHA
      .50000  .02824  10.6242  5.3413  1.6181
      .55000  .02824  10.6242  5.4739  1.5401
      .60000  .02824  10.6242  5.6323  1.4518
      .65000  .02824  10.6242  5.8228  1.3520
      .70000  .02824  10.6242  6.0544  1.2390
      .75000  .02824  10.6242  6.3408  1.1108
      .80000  .02824  10.6242  6.7033  .9642
      .85000  .02871  10.4502  7.1781  .7946
0CL= .4000
      MACH    CD    L/D    CLALPH    ALPHA
      .50000  .03173  12.6045  5.3413  2.6907
      .55000  .03173  12.6045  5.4739  2.5868
      .60000  .03173  12.6045  5.6323  2.4691
      .65000  .03173  12.6045  5.8228  2.3360
      .70000  .03173  12.6045  6.0544  2.1854
      .75000  .03173  12.6045  6.3408  2.0144
      .80000  .03173  12.6045  6.7033  1.8189
      .85000  .03322  12.0399  7.1781  1.5928
0CL= .5000
      MACH    CD    L/D    CLALPH    ALPHA
      .50000  .03636  13.7517  5.3413  3.7634
      .55000  .03636  13.7517  5.4739  3.6335
      .60000  .03636  13.7517  5.6323  3.4863
      .65000  .03636  13.7517  5.8228  3.3200
      .70000  .03636  13.7517  6.0544  3.1317
      .75000  .03636  13.7517  6.3408  2.9180
      .80000  .03636  13.7517  6.7033  2.6737
      .85000  .03977  12.5714  7.1781  2.3910
0CL= .6000
      MACH    CD    L/D    CLALPH    ALPHA
      .50000  .04194  14.3045  5.3413  4.8361
      .55000  .04194  14.3045  5.4739  4.6802
      .60000  .04194  14.3045  5.6323  4.5036
      .65000  .04194  14.3045  5.8228  4.3039
      .70000  .04194  14.3045  6.0544  4.0781
      .75000  .04194  14.3045  6.3408  3.8216
      .80000  .04200  14.2849  6.7033  3.5284
      .85000  .04848  12.3759  7.1781  3.1892

```

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

0 LOW SPEED LIFT/DRAG-GR.UP(IF R)O.G.E.

FLAPS UP				TAKEOFF				LANDING				
ALPHA	CL	CD	L/D	CL	CD	L/D	CL	CD	L/D	CL	CD	L/D
-2.00000	-.03398	.02390	-1.42164	1.12894	.09199	12.27200	1.93656	.25363	7.63548			
.00000	.13592	.02465	5.51486	1.29884	.10647	12.19921	2.10646	.27263	7.72653			
2.00000	.30582	.02841	10.76268	1.46874	.12512	11.73825	2.27636	.29737	7.65506			
4.00000	.47571	.03515	13.53470	1.63863	.14913	10.98798	2.44626	.32602	7.50338			
6.00000	.64561	.04496	14.35835	1.80853	.17597	10.27770	2.61615	.35792	7.30934			
8.00000	.81551	.05808	14.04126	1.97843	.20563	9.62109	2.78605	.39306	7.08805			
10.00000	.98541	.07505	13.13038	2.14833	.23813	9.02151	2.95595	.43145	6.85116			
12.00000	1.15530	.09764	11.83206	2.31822	.27346	8.47725	3.12585	.47309	6.60735			
13.62379	1.29324	.11824	10.93707	2.45616	.30423	8.07335	3.26378	.50928	6.40868			
13.62379	1.29324	.11824	10.93707	2.45616	.30423	8.07335	3.26378	.50928	6.40868			

0 DFLAP= .00 DFLAP= 15.00 DFLAP= 40.00
 0 CLMAX= 1.29324 CLMAX= 2.46601 CLMAX= 3.26389

0 LOW SPEED AERO FOR OTHER FLAP DEPLECTIONS

FLAP DEFL.	CLMAX	CL	CD	L/D
10.000	2.10997	.78264	.06760	11.57796
		.95254	.07898	12.06072
		1.12244	.09386	11.94634
		1.29233	.11339	11.39711
		1.46223	.13765	10.62254
		1.63213	.16472	9.90860
		1.80203	.19459	9.26083
		1.97192	.22726	8.67711
		2.10997	.25586	8.24644
		2.10997	.25586	8.24644
20.000	2.71356	1.38623	.11999	11.55260
		1.55613	.13640	11.40830
		1.72603	.15788	10.93243
		1.89592	.18335	10.34037
		2.06582	.21168	9.75906
		2.23572	.24287	9.20528
		2.40562	.27692	8.68689
		2.57551	.31384	8.20654
		2.71356	.34593	7.84415
		2.71356	.34593	7.84415
30.000	3.06861	1.74128	.17737	9.81722
		1.91118	.19541	9.78051
		2.08108	.21931	9.48918
		2.25098	.24640	9.13541
		2.42087	.27646	8.75671
		2.59077	.30948	8.37125
		2.76067	.34548	7.99088
		2.93057	.38444	7.62300
		3.06861	.41828	7.33629
		3.06861	.41828	7.33629

0 ALTITUDE= 35000. FT TAS= 462.89 KTS MACH NO= .8021

0 RDT&E AND AIRFRAME PRODUCTION COSTS

(1993. DOLLARS)
 0 TOTAL RDT&E COSTS 1083.3055 MILLION
 0 AIRFRAME PRODUCTION COSTS(INCLUDING 10% PROFIT)
 0 500. AIRCRAFT

	WEIGHT(LB)	COST(\$)	COST(\$/LB)
STRUCTURE(4350934.\$)			
WING	5378.	1285076.	238.97
EMPENNAGE	1493.	506664.	339.29
FUSELAGE	6038.	1672142.	276.95
LANDING GEAR	1819.	321079.	176.50
MACELLES	1051.	565972.	538.32
PROPULSION INSTAL(182642.\$)			
ENGINE INSTALLAT.	429.	156026.	364.08
FUEL SYSTEM	188.	26616.	141.74
SYSTEMS(2721797.\$)			
FLIGHT CONTROLS	1081.	507345.	469.41
HYDRAULIC	399.	49720.	124.57
ELECTRICAL	970.	464214.	478.57
AIR CONDITIONING	478.	256070.	535.82
ANTI-ICING	323.	170111.	526.66
AUX. POWER UNIT	372.	207143.	556.42
FURNISHINGS	3410.	796443.	233.56
INSTRUMENTS	262.	217047.	829.44
AVIONICS INSTALL.	250.	49032.	196.13
AUX. ITEMS	20.	4671.	233.56
INTEGRATION(1813843.\$)			
AIRFRAME TOTALS	23960.	9069216.	378.51
ENGINES		2957537.	
PROPELLER		0.	
AVIONICS		4000000.	
A/C COST(NO RD)		16026753.	
R&D PER A/C		2166611.	
TOTAL A/C COST		18193364.	

0 ENGINES NUMBER = 2. TYPE= 7

0 EMPTY WEIGHT= 27385. AIRFRAME WEIGHT= 24210. WEIGHT OF 1 ENGINE= 1587. CRUISE SPEED= 463. KTS
 0 THRUST/ENGINE= 9920.
 0 TOTAL AIRCRAFT COST= 18193364. AIRFRAME COST= 15235827. COST OF 1 ENGINE= 1478769. COST OF 1 PROP.= 0.

Fig. D1 - Conventional Baseline Configuration GASP output file (continued)

```

0          --- COST DATA ---
0          GASP SHORThAUL METHOD
0          DESIGN MISSION
0          OPERATING COST FOR NOR.RATED POWER AND 35000. ALTITUDE
0          *****
0          RANGE=      1250. N.M.    BLOCK FUEL=    7515. LBS    BLOCK TIME=    3.0436 HRS.
0          UTILIZATION
0          FLYING OPERATIONS
0          FLIGHT CREW                380.452
0          FUEL, OIL, AND TAXES (.850$/G)  998.247
0          INSURANCE                  86.521
0          DIRECT MAINTENANCE
0          AIRFRAME                   181.888
0          ENGINE                     292.913
0          MAINTENANCE BURD.          385.784
0          DEPRECIATION               1162.847
0
0          TOTAL DOC ($/TRIP)         3488.654
0          ($/B.HR.)                 1146.219
0          ($/N.MI.)                 2.791

```

Fig. D1 - Conventional Baseline Configuration GASP output file (concluded)

50 PAX TURBOFAN AIRLINER USING SCALED GE CF-34 - THREE-SURF. CONFIG.

ENGINE CYCLE IS G. E. CF-34

INPUT DATA FOLLOW

```

0
0 CONFIG WG      = 44050.          *****GEOMETRY*****
      WGS      = 86.600          KWRITE   = 2          FUSEL SAB  = 4.          ELODN   = 1.000
      PAX      = 50.            IGEAR    = 0          WS       = 20.000         ELODT   = 3.200
      HMCRU    = .800          KCONFG   = 0          AS       = 1.            BML0D   = 14.500
      HNCRU    = 35000.        RTIPX    = 0          WAS     = 19.000         NACELLE KMAC  = 1
      Kanard   = 1            EMP      = 2.          PS      = 31.0          ELN     = .000
      KANARD   = 1            NTYPE    = 7          ELPC    = 11.220        DBARN   = .000
      KANARD   = 1            KPLCT    = 1          HCK     = 2.470          ELRW    = 10.000

0 WING TCT      = .100          HORIZ VBARHX = .0000        VERT VBARVX = .0000        Canard TCcan  = .100
      TCR      = .130          TAIL  TCHT  = .100        TAIL  TCVT  = .120        ARcan   = 3.500
      AR       = 8.300          ARHT   = 4.000          ARVT   = 1.000          SLMcan  = .500
      SLM      = .200          SLMH   = .550          SLMV   = .700          DwpqCa  = 15.000
      DLMC4    = 14.500        DWPOCH = 27.500        DWPOCV = 50.500         EYEcan  = 2.000
      EYEW     = 2.000        COELTH = .000          BOELTV = .000          SWCOSW  = .145
      EYEW     = 2.000        SAH     = 1.000

0
0 CKW      = -1.000          CKHT    = -1.000          GRPE   = .000          DCDSE   = -1.0000
      CKF      = -1.000          CKTP    = -1.000          SCFAC  = .750          CKWc    = -1.000
      CKN      = -1.000          DELCD   = .00150        DLSWSW = .000          cmacw   = -.060
      CKVT     = -1.000          DELFE   = .200          ALPHLO = -1.600         alzerc  = -1.000

0
0 KWCD     = 12             ACLS     = -1.000          -1.000  -1.400  -1.200  .000  .100  .200  .400  .600  .800  1.000  1.200
      ACDCDR  = 2.400          1.466  1.221  1.066  1.005  1.000  1.005  1.046  1.138  1.333  1.743  2.718

0
0 RCLMAX   = 1.200          FLAPS *HIGH LIFT DEVICES*
      ALTFPL  = 5000.        JFLTYE  = 7
      FLAPN   = 1.          DFLPTO  = 15.000        LED CLEOC  = .000
      WCFLAP  = -1.000       DFLEPLD = 40.000        DELLED   = .000
      BENG0B  = .000        CF0C    = .300          DCLMLE   = .930
      BTEOB   = .750        BTEOB   = .750          DELLEO   = 45.000
      DCLMTE  = .000        DCLMTE  = .000
      DCDOTE  = .000        DCDOTE  = .000
      DELTEO  = .000        DELTEO  = .000

0
0 JENGSZ   = 2             HPCRT   = 5000.          RCCRU   = 50.000        RWCRTE  = .970
      IPART   = 1             TDELTO  = 36.           ITORQ   = 99999.       HSCREQ  = 0.
      KODETO  = 5             KODECL  = 7             SMLD    = .500         THIN    = 0.
      KODETR  = 5             KODEAC  = 5             HBTP    = .437        PA      = 1.000

0
0 SKPEI    = .1350         SKY     = .1800          SKB     = 107.000       SKPS    = .0200
      SKLG    = .0380         SKZ     = .2200          SKCC    = 20.000       SKWF    = .4300
      SKMG    = .8000         SKTL    = 1.0000        SKPW    = .4300       SKFT    = .9790
      SKPEs   = .3380         SKMW    = 133.400       SKSAS   = .000        SKMTP   = 1.8900
      WPLK    = .0            YNG     = .2500          EGMRGN  = .0000       LCWING  = 2
      WPEX    = .0            RELP    = .8500          CPMRGN  = .2000
      WFUL    = .0            RELR    = .4500          STMGRN  = .0000
      UWPAX   = 200.0         CATD    = 3.            DELE    = 8.200
      STRUT   = .0000        VMLFSL  = 685.0         YP      = .0000
      DELWFC  = .0            WNAC    = .0            WFLYON  = .0          LDCRMX  = 8.000
      WENG    = .0            UWNAC   = 2.287        WFLYON  = .0          ATMXCQ  = 3.160
      SWSLS   = .160         UWNAC   = 2.287        WFLYON  = .0          DELWST  = .0
      WENG    = .0            UWNAC   = 2.287        WFLYON  = .0          ELQDE   = 3.000
      SWSLS   = .160         UWNAC   = 2.287        WFLYON  = .0          ELQDE   = 3.000

0
0 KSF1xd   = 1             STATIC  = .100          ZCG     = 999.000       CNFAC   = .0020
      CMFLPL  = 999.000       CHALP   = 999.000       TP      = .0           ARVTE   = -1.000
      CMFLPT  = 999.000       CHDEL   = 999.000       CIA     = .520         RV      = .300
      CMPLD   = .000         RH       = .350         DCMCLP  = 9999.000    TAUU    = 999.000
      CMPLD   = .000         DEMAX   = -25.0        HWMING  = 0.           RMVCS   = .990
      CMPLD   = .000         EYET    = .0           dcncpi  = .030         DRMAX   = 25.0
      CMPLD   = .000         TAUH    = 999.000       rc       = .350

0
0 TAXI DELTT = .167          XLFMAX  = 1.100          DVR     = 5.000         TDELTX  = 36.000
      TO      = 1            DELTVR  = 3.500          UM      = .020         HTMAX   = 500.000
      THEMAX  = 15.000       DV1     = 5.000          MUB     = .400         NFAIL   = 0
      H00     = 5000.        VRAT    = 1.10          WTMISN  = 0.

0 CLIMB ICLM   = 1          CRUISE CRMACH = .000          FRESF   = 1.000         FACW1   = .958
      DELH    = 1000.        CRALT   = 0.            RCRARQ  = 1250.0        ISWING  = 0
      VCLMB   = .0          ICRUS   = 1            OFALT   = 25000.        OPEN    = .500
0 LAND  IWLD   = 2          XLDGRQ  = 99999.        VRATT   = 1.300         HAPP    = 50.
      TDELLD  = 36.0        ALTLND  = 5000.        RSMX    = 1000.        SINKTD  = 3.0
      TDELAY  = 1.0         WLPCT   = .9400        TR0TID  = .000         XLFMX   = 1.200
      HTG     = 5.5         TIDLE   = .0          VTDRAT  = 1.1

0
0 NCADE    = 1             HIR     = .005          RI      = .300          CMV     = .800
      CLTAB   = 1993.0       TR      = 2.000         OHR     = 500.000       CCRW    = 0.
      HRI     = 4000000.     PRV     = .100         CRMOH   = 23.000       UCSENG  = .000
      CMP     = .2           DYR     = 15.0        CINP    = 0.           UCSFP   = .000
      TBO     = 3200.0       SRPM    = 0.           CP       = 0.          ALR     = 3.400
      FCSF    = .850
    
```

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file

```

*****
ITERATION TO BALANCE RANGE
RANGE ERROR, RANGE ERROR MINUS 1 .0216 -.1414
GROSS WGT, GROSS WGT MINUS1 45725.7 45981.2

0 *****
0 FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
CLMAX VSTALL,KTS FLAP ANGLE LE ANGLE DELTA CL DELTA CD
FLAPS UP 1.1337 161.7 .0 .0 .0000 .0000
T.O. CONFIG 2.1556 117.4 15.0 .0 1.0109 .0374
LDG. CONFIG 2.8448 102.2 40.0 .0 1.7103 .1664

0 DOUBLE SLOTTED FOWLER FLAPS
OPT ANGLE DELCL AT OPT DELCD AT OPT AREA(FT2) WEIGHT(LB)
FLAPS 30.0 2.2500 .1500 94.7 647.9
0 *****
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK(DEGREES)= 1.610 LIPT= 44353.9 L/D= 13.324 ALTITUDE= 35000.0 MACH= .8000

1 ENGINE SIZING DATA FOLLOW
*****
OVSTLKT= 108.9 KTS EAS VRAT= 1.100 CLTO= 1.7815
VEND = 249.4 KNOTS EAS
0
ROTATION (TIME= 26.6 AND TAS= 132.5 EAS= 118.9)
LIPTOFF (TIME= 28.8 DIST= 3740.4 TAS= 140.1 EAS= 125.6)
DISTANCE TO 35 FT.= 5024.4 TAS= 152.3 EAS= 136.6 V35/V3= 1.2545
GEAR RETRACTION STARTED AT 34.9 SEC, COMPLETE AT 41.9 SEC
FLAP RETRACTION STARTED AT 45.1 SEC, COMPLETE AT 49.6 SEC
OVSTLKT= 108.9 KTS EAS VRAT= 1.100 CLTO= 1.7815
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 206.3 KNOTS EAS
ENGINE FAILURE (TIME= 25.1 AND TAS= 126.9 EAS= 113.9)
0
ROTATION (TIME= 29.8 AND TAS= 132.5 EAS= 118.9)
LIPTOFF (TIME= 33.0 DIST= 4660.7 TAS= 135.0 EAS= 121.1)
DISTANCE TO 35 FT.= 6785.6 TAS= 135.5 EAS= 121.5 V35/V3= 1.1161

ACCELERATE - STOP DISTANCE = 6142.7 FEET.
0 ENGINE OUT DISTANCE TO 35 FT.= 6785.6 FEET
OALL ENGINE DISTANCE TO 35 FT. (L) = 5024.4 FEET
FAR 25 T.O. DISTANCE (1.15XL) = 5778.0 FEET
ALL ENGINE DISTANCE TO 50 FT. = 5258.3 FEET
0 AT END OF TAKEOFF PHASE
TIME= .013 HRS FUEL USED= 74. LBS WEIGHT= 45651. LBS ALT.= 5500. FT.
0TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION ALT (FT) VS KEAS V/V3 V KTAS GRAD (PCT) R/C (PPM) REQ.R/C (PPM) CL L/D
1ST SEG:T.O. FLAPS+LD GEAR EXT - ONE ENG OUT 5000. 109.0 1.1285 137.1 2.152 298.69 1.00 1.700 8.829
2ND SEG: T.O. FLAPS - ONE ENGINE OUT 5250. 109.0 1.2000 146.4 4.208 623.31 355.51 1.503 11.051
FINAL T.O. CRUISE CONFIG - ONE ENG OUT 6500. 149.6 1.2500 213.3 4.762 1028.04 259.05 .736 14.216
APPROACH FLAPS -ONE ENG OUT 5000. 104.3 1.3510 157.0 4.481 712.18 333.74 1.296 11.570
LANDING FLAPS - ALL ENGINES 5000. 94.9 1.3000 137.5 12.955 1802.77 445.30 1.690 7.145

APPROACH FLAP SETTING = 19.7 DEG.

+++ ENGINE-OUT SERVICE CEILING = 23163.7 FT.
BEST RATE OF CLIMB SPEED = 273.9 KTAS
ENGINE-OUT RATE OF CLIMB = 50.0 FPM
WEIGHT AT ALTITUDE = 43896.6 LBS

0 *****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES*****

0PROPULSION SYSTEM WEIGHTS
ENGINE WEIGHT/ENGINE 1426.2
MACELLE WEIGHT/ENGINE 320.7
PYLON WEIGHT/ENGINE 170.4
PROP OR OFAN .0
GEARBOX .0
SHROUD .0

0ENGINE POD DIMENSIONS
ENGINE FACE DIAMETER(FT) 3.86
MACELLE LENGTH(FT) 11.58

OVSTLKT= 108.9 KTS EAS VRAT= 1.100 CLTO= 1.7815
VEND = 247.8 KNOTS EAS
0
ROTATION (TIME= 25.4 AND TAS= 132.5 EAS= 118.9)
LIPTOFF (TIME= 27.6 DIST= 3594.6 TAS= 140.6 EAS= 126.1)
DISTANCE TO 35 FT.= 4856.6 TAS= 153.3 EAS= 137.7 V35/V3= 1.2646
GEAR RETRACTION STARTED AT 33.6 SEC, COMPLETE AT 40.6 SEC
FLAP RETRACTION STARTED AT 43.7 SEC, COMPLETE AT 48.2 SEC
OVSTLKT= 108.9 KTS EAS VRAT= 1.100 CLTO= 1.7815
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 201.5 KNOTS EAS
ENGINE FAILURE (TIME= 24.0 AND TAS= 126.9 EAS= 113.9)
0
ROTATION (TIME= 28.2 AND TAS= 132.5 EAS= 118.9)
LIPTOFF (TIME= 31.4 DIST= 4425.7 TAS= 135.3 EAS= 121.4)
DISTANCE TO 35 FT.= 6243.5 TAS= 136.1 EAS= 122.0 V35/V3= 1.1208

```

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

ACCELERATE - STOP DISTANCE = 6011.0 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 6243.5 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4856.6 FEET
 PAR 25 T.O. DISTANCE (1.15XL) = 5585.0 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 5091.6 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .013 HRS FUEL USED= 75. LBS WEIGHT= 45651. LBS ALT.= 5500. FT.
 0 TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	VS KEAS	V/VS	V KTAS	GRAD (PCT)	R/C (FPM)	REQ.R/C (FPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	109.0	1.1285	137.1	2.462	341.71	1.00	1.700	8.631
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	109.0	1.2000	146.4	4.495	665.81	355.51	1.503	10.727
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	149.6	1.2500	213.3	4.809	1038.06	259.05	.736	13.358
APPROACH FLAPS -ONE ENG OUT	5000.	104.3	1.3510	157.0	4.739	733.13	333.74	1.296	11.186
LANDING FLAPS - ALL ENGINES	5000.	94.9	1.3000	137.5	14.020	1950.93	443.30	1.690	7.108

APPROACH FLAP SETTING = 19.7 DEG.

+++ ENGINE-OUT SERVICE CEILING = 23690.8 FT.
 BEST RATE OF CLIMB SPEED = 272.4 KTAS
 ENGINE-OUT RATE OF CLIMB = 50.0 FPM
 WEIGHT AT ALTITUDE = 43896.6 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 364.33

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R;ALT= 5000.) SLS AIRFLOW= 364.33

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 9290.5 LBS

0 PROPELLSION SYSTEM WEIGHTS

ENGINE WEIGHT/ENGINE 1486.5
 NACELLE WEIGHT/ENGINE 320.7
 FYLON WEIGHT/ENGINE 174.7
 PROP OR CFAM .0
 GEARBOX .0
 SHROUD .0

0 ENGINE POD DIMENSIONS

ENGINE FACE DIAMETER(FT) 3.86
 NACELLE LENGTH(FT) 11.58

0*****

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---

	MOST FWD LOAD		MOST AFT LOAD		DESIGN LOAD	
	WT	CG	WT	CG	WT	CG
A/C OWE	26978.51	44.01	26978.51	44.01	26978.51	44.01
PAX	6120.00		2040.00		8500.00	
BAGGAGE	.00	56.36	1500.00	56.36	1500.00	56.36
WING FUEL	1645.98	45.14	8229.90	45.14	8229.90	45.14
TIP FUEL	.00	.00	.00	.00	.00	.00
FUS FUEL	.00	45.14	.00	45.14	517.27	45.14
TOTAL	34744.48	41.61	38748.40	44.95	43725.67	43.26

0 ---TAIL SIZING SUMMARY---

Static Longitudinal Stability, Stick-fixed, considered

CONDITION	ALPHA	WING		CMac	CANARD		TAIL		DOWN WASH	FLAP CM
		CL	CLA		ALPHA	CLA	CLA	EFF.		
CRUISE	1.7088	.3871	.1170	-.0600	2.7088	.0984	.0762	1.0000		
LIFTOFF	2.0000	1.3256	.0637	-.0600	3.0000	.0753	.0636	1.0000	.3679	-.1031
LANDING	11.8265	2.8448	.0845	-.0600	12.8265	.0755	.0636	1.0000	2.1752	-.2000

CONDITION	--FUSELAGE--		---NACELLE---		-----POWER-----				L.GEAR ROT.POWER		
	DCM	CM	DCM	CM	DCMdh	DCMfine	Cmdth	CMfine	CT	CM	CM
CRUISE	.4488		.1831		.0000	.0300			.0000		
LIFTOFF	.7988	.0000	.1831	.0000			.0000	.0398	.0000	-.6104	4.8510
LANDING	.6215	.5160	.1831	.1520			.0000	.0853			

0 CANARD PARAMETERS
 CMDELTC (CONTROL POWER) = -.02252
 TAUc (EFFECTIVENESS) = .48250
 DcMAX (MAX. CANARD VATOR DEFLEC) = 37.78492

0 ELEVATOR PARAMETERS
 CMDELTE (CONTROL POWER) = -.02759 WING DE/DALPHA = .36786
 TAUH (EFFECTIVENESS) = .48250
 DEMAX (MAX. ELEVATOR DEFLEC.) = -25.00000

	FRACTION MAC	STATION (DATUM NOSE)	CANARD AND HORIZONTAL TAIL SIZES	
			CANARD	HOR. TAIL
NEUTRAL POINT	.4780	45.887		
STATIC MARGIN	.1000			
AFT CG LIMIT (STABILITY)	.3780	45.013		
CG RANGE (LOADING)	.3820		REQUIRED SIZES	69.7529
FWD CG LIMIT (CONTROL)	-.0041	41.674	CANARD AND TAIL ARMS (ELcan, ELTH)	36.1202
				90.5412
				42.8884

0 VERTICAL TAIL AREA = 107.6360 FOR DIRECTIONAL STABILITY OF .00200
 0 RUDDER POWER AT MAX. DEFL. = .0178 PER DEG. RUDDER CL AT MAX. DEFL. = .4461
 0 VERTICAL TAIL AREA = 92.5623 FOR MINIMUM CONTROL SPEED = 107.75 KTS
 0 REQUIRED VERTICAL TAIL AREA = 107.6360 TAIL ARM (ELTV) = 32.1851

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
 ANGLE OF ATTACK (DEGREES) = 1.610 LIPT = 44353.9 L/D = 12.641 ALTITUDE = 35000.0 MACH = .8000

0 WING LOCATION INFO.
 FUSELAGE LENGTH = 79.25 H-TAIL VOL. ARM = 42.89 C.G. LOCATION OF PROPULSION = 67.36
 WING 1/4C LOC. ON C.L. = 40.65 H-TAIL C.G. LOCATION = 87.11 C.G. OF REMAINING WEIGHT = 35.66
 MAC 1/4C LOCATION = 43.83 H-TAIL MAC FROM C.L. = 4.30
 MAC DIST. FROM C.L. = 12.29 H-TAIL LOCAT ON VERT. = 1.00
 WING C.G. LOCATION = 45.58 V-TAIL VOL. ARM = 32.19
 TIP TANKS C.G. LOCATE = .00 V-TAIL C.G. LOCATION = 76.85 DIST. L.E. VERT. TO L.E. HORZ. = 2.41

CANARD 1/4C LOC. ON C.L. = 6.54
 CANARD MAC DIST. FROM C.L. = 4.35
 CANARD VOLUME ARM = 36.12
 CANARD C.G. LOCATION = 8.00

	WING	CANARD	H-TAIL	V-TAIL
AREA	481.052	69.753	90.541	107.636
SPAN	63.188	19.587	19.031	10.375
ASPECT RATIO	8.300	5.500	4.000	1.000
TAPEX RATIO	.200	.500	.550	.700
1/4C. SWEEP	14.500	15.000	27.500	50.500
L.E. SWEEP	18.723	18.188	30.674	52.459
C.L. CHORD	12.688	4.748	6.139	12.206
MEAN CHORD	8.741	3.693	4.891	10.482
TIP CHORD	2.538	2.374	3.376	8.544

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

0 MISSION PERFORMANCE DATA FOLLOWS

0 TAXI AT IDLE THRUST

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	FUEL FLOW (LB/HR)
.000	0.	0.	45726.	5000.	849.
.167	0.	141.	45584.	5000.	849.

OVSTLKT= 106.4 KTS EAS VRAT= 1.100 CLTO= 1.7815
 VWND = 246.7 KNOTS EAS
 0 (TEMP.= 537. DEG:STD.+36.)
 0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (PPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	141.4	45584.	5000.0	.0	.0	.000	10.98	1.3233	.1329	2.00	.00	.0	.00	16478.	5868.	.00
1.0	5.5	143.1	45583.	5000.0	6.5	5.8	.010	10.84	1.3233	.1329	2.00	.00	.0	.00	16280.	5868.	.00
2.0	21.8	144.7	45581.	5000.0	12.9	11.5	.019	10.69	1.3233	.1329	2.00	.00	.0	.00	16087.	5869.	.00
3.0	48.9	146.3	45579.	5000.0	19.2	17.2	.028	10.53	1.3234	.1329	2.00	.00	.0	.00	15896.	5870.	.00
4.0	86.5	148.0	45578.	5000.0	25.4	22.8	.038	10.37	1.3234	.1329	2.00	.00	.0	.00	15709.	5871.	.00
5.0	134.5	149.6	45576.	5000.0	31.5	28.2	.047	10.20	1.3235	.1329	2.00	.00	.0	.00	15525.	5873.	.00
6.0	192.8	151.2	45574.	5000.0	37.5	33.6	.056	10.03	1.3236	.1330	2.00	.00	.0	.00	15345.	5874.	.00
7.0	261.1	152.9	45573.	5000.0	43.4	38.9	.064	9.85	1.3237	.1330	2.00	.00	.0	.00	15168.	5876.	.00
8.0	339.3	154.5	45571.	5000.0	49.2	44.1	.073	9.66	1.3239	.1330	2.00	.00	.0	.00	14993.	5878.	.00
9.0	427.2	156.1	45570.	5000.0	54.9	49.2	.081	9.48	1.3240	.1330	2.00	.00	.0	.00	14822.	5881.	.00
10.0	524.6	157.8	45568.	5000.0	60.5	54.2	.090	9.29	1.3242	.1330	2.00	.00	.0	.00	14655.	5883.	.00
11.0	631.3	159.4	45566.	5000.0	65.9	59.1	.098	9.09	1.3244	.1330	2.00	.00	.0	.00	14491.	5886.	.00
12.0	747.2	161.0	45565.	5000.0	71.3	63.9	.106	8.92	1.3246	.1331	2.00	.00	.0	.00	14337.	5888.	.00
13.0	872.0	162.7	45563.	5000.0	76.5	68.6	.114	8.74	1.3248	.1331	2.00	.00	.0	.00	14235.	5891.	.00
14.0	1005.6	164.3	45561.	5000.0	81.7	73.3	.121	8.57	1.3250	.1331	2.00	.00	.0	.00	14116.	5894.	.00
15.0	1147.8	165.9	45560.	5000.0	86.7	77.8	.129	8.39	1.3252	.1331	2.00	.00	.0	.00	13999.	5898.	.00
16.0	1298.5	167.6	45558.	5000.0	91.6	82.2	.136	8.21	1.3254	.1332	2.00	.00	.0	.00	13885.	5901.	.00
17.0	1457.3	169.2	45556.	5000.0	96.5	86.5	.143	8.03	1.3256	.1332	2.00	.00	.0	.00	13773.	5904.	.00
18.0	1624.3	170.9	45555.	5000.0	101.2	90.8	.150	7.84	1.3259	.1332	2.00	.00	.0	.00	13663.	5908.	.00
19.0	1799.1	172.5	45553.	5000.0	105.8	94.9	.157	7.66	1.3261	.1332	2.00	.00	.0	.00	13557.	5911.	.00
20.0	1981.6	174.1	45551.	5000.0	110.3	99.0	.164	7.48	1.3264	.1333	2.00	.00	.0	.00	13452.	5915.	.00
21.0	2171.6	175.8	45550.	5000.0	114.7	102.9	.170	7.29	1.3266	.1333	2.00	.00	.0	.00	13350.	5919.	.00
22.0	2369.0	177.4	45548.	5000.0	119.0	106.7	.177	7.11	1.3269	.1333	2.00	.00	.0	.00	13251.	5922.	.00
23.0	2573.5	179.1	45547.	5000.0	123.2	110.5	.183	6.93	1.3272	.1333	2.00	.00	.0	.00	13154.	5926.	.00
24.0	2784.9	180.7	45545.	5000.0	127.2	114.1	.189	6.74	1.3274	.1334	2.00	.00	.0	.00	13059.	5930.	.00

ROTATION (TIME= 24.6 AND TAS= 129.8 EAS= 116.4)
 25.0 3003.2 182.4 45543. 5000.0 131.2 117.7 .195 6.53 1.3485 .1357 2.24 .00 .0 .76 12967. 5934. .24
 26.0 3228.0 184.0 45542. 5000.0 134.9 121.1 .200 6.07 1.4782 .1530 3.79 .00 .0 .89 12881. 5937. 1.79

LIFTOFF (TIME= 26.8 DIST= 3412.2 TAS= 137.7 EAS= 123.6)
 27.0 3458.8 185.7 45540. 5000.0 138.4 124.2 .205 5.50 1.6159 .1738 5.48 .01 3.4 1.03 12822. 5941. 3.50
 28.0 3695.2 187.3 45538. 5001.0 141.5 126.9 .210 4.89 1.6424 .1781 5.78 .59 146.5 1.09 12769. 5944. 4.37
 29.0 3936.6 189.0 45537. 5005.1 144.3 129.4 .214 4.50 1.5828 .1688 4.98 1.32 336.9 1.09 12721. 5946. 4.30
 30.0 4182.3 190.6 45535. 5012.3 146.8 131.7 .218 4.11 1.5318 .1611 4.38 2.04 530.1 1.09 12675. 5948. 4.42
 31.0 4432.1 192.3 45533. 5022.7 149.2 133.8 .221 3.73 1.4856 .1543 3.88 2.74 723.0 1.09 12633. 5949. 4.62

DISTANCE TO 35 FT.= 4661.3 TAS= 151.1 EAS= 135.5 V35/V50= 1.2731
 32.0 4685.5 193.9 45532. 5036.4 151.3 135.6 .225 3.33 1.4487 .1490 3.48 3.45 921.4 1.10 12594. 5950. 4.93
 33.0 4942.1 195.6 45530. 5053.4 153.2 137.3 .227 2.95 1.4132 .1441 3.08 4.14 1119.3 1.10 12558. 5950. 5.22

GEAR RETRACTION STARTED AT 32.8 SEC. COMPLETE AT 39.8 SEC
 34.0 5201.5 197.2 45528. 5073.7 154.9 138.8 .230 2.67 1.3872 .1365 2.78 4.81 1316.4 1.10 12525. 5949. 5.59
 35.0 5463.3 198.9 45527. 5097.3 156.4 140.1 .232 2.37 1.3615 .1300 2.48 5.48 1514.6 1.10 12494. 5948. 5.97
 36.0 5727.2 200.5 45525. 5124.2 157.7 141.2 .234 2.09 1.3359 .1238 2.18 6.14 1710.2 1.10 12465. 5946. 6.33
 37.0 5992.9 202.2 45523. 5154.3 158.9 142.2 .236 1.80 1.3189 .1185 1.98 6.80 1907.4 1.10 12438. 5943. 6.79
 38.0 6260.0 203.8 45522. 5187.8 159.9 143.0 .238 1.52 1.3018 .1133 1.78 7.45 2102.1 1.10 12414. 5940. 7.24
 39.0 6528.4 205.5 45520. 5224.4 160.7 143.7 .239 1.26 1.2847 .1081 1.58 8.10 2294.6 1.10 12391. 5936. 7.68
 40.0 6797.5 207.1 45518. 5264.3 161.4 144.2 .240 .97 1.2762 .1045 1.48 8.75 2487.6 1.10 12371. 5931. 8.23
 41.0 7067.1 208.8 45517. 5307.3 161.9 144.6 .241 .61 1.2676 .1036 1.38 9.39 2676.8 1.10 12353. 5926. 8.77
 42.0 7336.9 210.4 45515. 5353.5 162.2 144.7 .241 .27 1.2591 .1027 1.28 10.02 2859.2 1.09 12339. 5920. 9.30
 43.0 7606.5 212.1 45514. 5402.6 162.2 144.7 .241 -.01 1.2533 .1000 .98 10.64 3036.1 1.07 12327. 5914. 9.62

FLAP RETRACTION STARTED AT 42.9 SEC. COMPLETE AT 47.4 SEC
 44.0 7875.7 213.7 45512. 5453.3 162.3 144.5 .241 -.01 1.0873 .1008 2.03 10.60 3025.7 .95 12315. 5907. 10.64
 45.0 8145.3 215.4 45510. 5502.7 162.3 144.4 .241 -.01 1.0133 .1121 3.78 10.03 2863.4 .89 12304. 5901. 11.81

OVSTLKT= 106.4 KTS EAS VRAT= 1.100 CLTO= 1.7815
 0 ENGINE OUT PERFORMANCE FOLLOWS
 VWND = 202.0 KNOTS EAS
 0 (TEMP.= 537. DEG:STD.+36.)
 0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (PPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	141.4	45584.	5000.0	.0	.0	.000	10.98	1.3233	.1329	2.00	.00	.0	.00	16478.	5868.	.00
1.0	5.5	143.1	45583.	5000.0	6.5	5.8	.010	10.84	1.3233	.1329	2.00	.00	.0	.00	16280.	5868.	.00
2.0	21.8	144.7	45581.	5000.0	12.9	11.5	.019	10.69	1.3233	.1329	2.00	.00	.0	.00	16087.	5869.	.00
3.0	48.9	146.3	45579.	5000.0	19.2	17.2	.028	10.53	1.3234	.1329	2.00	.00	.0	.00	15896.	5870.	.00
4.0	86.5	148.0	45578.	5000.0	25.4	22.8	.038	10.37	1.3234	.1329	2.00	.00	.0	.00	15709.	5871.	.00
5.0	134.5	149.6	45576.	5000.0	31.5	28.2	.047	10.20	1.3235	.1329	2.00	.00	.0	.00	15525.	5873.	.00
6.0	192.8	151.2	45574.	5000.0	37.5	33.6	.056	10.03	1.3236	.1330	2.00	.00	.0	.00	15345.	5874.	.00
7.0	261.1	152.9	45573.	5000.0	43.4	38.9	.064	9.85	1.3237	.1330	2.00	.00	.0	.00	15168.	5876.	.00
8.0	339.3	154.5	45571.	5000.0	49.2	44.1	.073	9.66	1.3239	.1330	2.00	.00	.0	.00	14993.	5878.	.00
9.0	427.2	156.1	45570.	5000.0	54.9	49.2	.081	9.48	1.3240	.1330	2.00	.00	.0	.00	14822.	5881.	.00
10.0	524.6	157.8	45568.	5000.0	60.5	54.2	.090	9.29	1.3242	.1330	2.00	.00	.0	.00	14655.	5883.	.00
11.0	631.3	159.4	45566.	5000.0	65.9	59.1	.098	9.09	1.3244	.1330	2.00	.00	.0	.00	14491.	5886.	.00
12.0	747.2	161.0	45565.	5000.0	71.3	63.9	.106	8.92	1.3246	.1331	2.00	.00	.0	.00	14337.	5888.	.00
13.0	872.0	162.7	45563.	5000.0	76.5	68.6	.114	8.74	1.3248	.1331	2.00	.00	.0	.00	14235.	5891.	.00
14.0	1005.6	164.3	45561.	5000.0	81.7	73.3	.121	8.57	1.3250	.1331	2.00	.00	.0	.00	14116.	5894.	.00
15.0	1147.8	165.9	45560.	5000.0	86.7	77.8	.129	8.39	1.3252	.1331	2.00	.00	.0	.00	13999.	5898.	.00
16.0	1298.5	167.6	45558.	5000.0	91.6	82.2	.136	8.21	1.3254	.1332	2.00	.00	.0	.00	13885.	5901.	.00
17.0	1457.3	169.2	45556.	5000.0	96.5	86.5	.143	8.03	1.3256	.1332	2.00	.00	.0	.00	13773.	5904.	.00
18.0	1624.3	170.9	45555.	5000.0	101.2	90.8	.150	7.84	1.3259	.1332	2.00	.00	.0	.00	13663.	5908.	.00
19.0	1799.1	172.5	45553.	5000.0	105.8	94.9	.157	7.66	1.3261	.1332	2.00	.00	.0	.00	13557.	5911.	.00
20.0	1981.6	174.1	45551.	5000.0	110.3	99.0	.164	7.48	1.3264	.1333	2.00	.00	.0	.00	13452.	5915.	.00
21.0	2171.6	175.8	45550.	5000.0	114.7	102.9	.170	7.29	1.3266	.1333	2.00	.00	.0	.00	13350.	5919.	.00
22.0	2369.0	177.4	45548.	5000.0	119.0	106.7	.177	7.11	1.3269	.1333	2.00	.00	.0	.00	13251.	5922.	.00
23.0	2573.5	179.1	45547.	5000.0	123.2	110.5	.183	6.93	1.3272	.1333	2.00	.00	.0	.00	13154.	5926.	.00

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

ENGINE FAILURE (TIME= 23.3 AND TAS= 124.2 EAS= 111.4)																	
24.0	2784.4	180.2	45545.	5000.0	125.8	112.9	.187	2.04	1.3274	.1419	2.00	.00	.0	.00	6546.	2964.	.00
25.0	2997.9	181.1	45545.	5000.0	127.0	113.9	.189	2.00	1.3275	.1417	2.00	.00	.0	.00	6532.	2965.	.00
26.0	3213.4	181.9	45544.	5000.0	128.2	115.0	.190	1.96	1.3275	.1414	2.00	.00	.0	.00	6518.	2965.	.00
27.0	3430.9	182.7	45543.	5000.0	129.3	116.0	.192	1.91	1.3276	.1412	2.00	.00	.0	.00	6505.	2966.	.00
ROTATION (TIME= 27.4 AND TAS= 129.8 EAS= 116.4)																	
28.0	3650.3	183.5	45542.	5000.0	130.5	117.0	.194	1.78	1.3831	.1474	2.65	.00	.0	.78	6492.	2967.	.65
29.0	3871.5	184.4	45541.	5000.0	131.4	117.9	.195	1.45	1.5128	.1655	4.22	.00	.0	.87	6481.	2967.	2.22
30.0	4094.1	185.2	45541.	5000.0	132.2	118.6	.196	1.10	1.6425	.1853	5.83	.00	.0	.95	6472.	2967.	3.83
LIFTOFF (TIME= 30.4 DIST= 4183.5 TAS= 132.4 EAS= 118.8)																	
31.0	4317.9	186.0	45540.	5000.1	132.7	119.1	.197	.68	1.7590	.2047	7.32	.08	17.9	1.03	6466.	2968.	5.40
32.0	4542.3	186.8	45539.	5001.1	133.0	119.3	.197	.36	1.7815	.2086	7.55	.47	111.7	1.05	6462.	2968.	6.02
33.0	4767.1	187.6	45538.	5003.8	133.2	119.4	.198	.10	1.7815	.2087	7.42	.92	217.1	1.06	6460.	2968.	6.34
34.0	4992.0	188.5	45537.	5008.3	133.2	119.5	.198	.02	1.7411	.2018	6.86	1.30	306.4	1.03	6460.	2967.	6.16
35.0	5216.8	189.3	45536.	5013.8	133.2	119.5	.198	.00	1.7156	.1976	6.56	1.49	347.5	1.02	6459.	2967.	6.04
36.0	5441.7	190.1	45536.	5019.7	133.2	119.4	.198	.02	1.6967	.1944	6.36	1.55	364.1	1.00	6458.	2967.	5.91
37.0	5666.6	190.9	45535.	5025.8	133.2	119.4	.198	.01	1.6948	.1941	6.36	1.57	370.6	1.00	6457.	2966.	5.94
38.0	5891.4	191.8	45534.	5032.1	133.2	119.4	.198	.00	1.6933	.1939	6.36	1.59	375.0	1.00	6457.	2966.	5.95
DISTANCE TO 35 FT. = 5997.1 TAS= 133.2 EAS= 119.4 V35/V50= 1.1223																	
39.0	6116.3	192.6	45533.	5038.3	133.2	119.4	.198	.00	1.6923	.1937	6.36	1.60	377.8	1.00	6456.	2965.	5.97
40.0	6341.2	193.4	45532.	5044.6	133.2	119.4	.198	.00	1.6916	.1936	6.36	1.61	379.3	1.00	6455.	2965.	5.97
41.0	6566.1	194.2	45531.	5051.0	133.2	119.4	.198	.00	1.6912	.1936	6.36	1.61	379.9	1.00	6454.	2964.	5.98

ACCELERATE - STOP DISTANCE = 5869.4 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT. = 5997.1 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4661.3 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 5360.5 FEET
 0 ALL ENGINE DISTANCE TO 50 FT. = 4893.9 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .179 HRS FUEL USED= 215. LBS WEIGHT= 45510. LBS ALT.= 5500. FT.

ACCELERATE TO MACH NO. = .412

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.179	.00	215.3	45510.	5500.	157.	144.	.241	.722	12587.	5815.
.188	2.03	270.1	45455.	5500.	268.	247.	.412	.812	10638.	5985.

END OF ACCELERATION SEGMENT
 TIME= .188 HRS FUEL USED= 270.1 LBS WEIGHT= 45455. LBS RANGE= 2. NM
 0 CLIMB TO 35000. FT. AT MAXIMUM RATE OF CLIMB

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	FUS. ANGLE (DEG)	R/C (PFM)	THRUST (LBS)	FUEL FLOW (LB/HR)
.188	2.	270.	45455.	5500.	245.	226.	.377	.803	.4725	.0342	3.71	7.93	9.63	3424.	9523.	5262.
.191	3.	283.	45443.	6000.	246.	225.	.380	.803	.4761	.0343	3.75	7.49	9.23	3250.	9439.	5211.
.196	4.	310.	45416.	7000.	249.	224.	.385	.802	.4797	.0345	3.78	7.14	8.92	3138.	9247.	5107.
.201	5.	337.	45389.	8000.	251.	223.	.390	.802	.4871	.0349	3.85	7.10	8.95	3141.	9069.	5001.
.206	7.	363.	45362.	9000.	260.	228.	.406	.804	.4669	.0338	3.60	5.70	7.29	2620.	8779.	4899.
.213	8.	394.	45331.	10000.	263.	226.	.412	.803	.4715	.0341	3.64	6.39	8.03	2966.	8603.	4790.
.218	10.	421.	45304.	11000.	266.	225.	.417	.803	.4767	.0344	3.69	6.57	8.25	3078.	8427.	4684.
.224	11.	447.	45279.	12000.	268.	223.	.423	.802	.4828	.0347	3.74	5.99	7.73	2836.	8253.	4580.
.230	13.	474.	45252.	13000.	271.	222.	.429	.801	.4886	.0350	3.80	5.79	7.59	2769.	8079.	4478.
.236	14.	501.	45225.	14000.	274.	221.	.435	.801	.4946	.0353	3.85	5.59	7.44	2702.	7907.	4379.
.242	16.	528.	45198.	15000.	276.	219.	.441	.800	.5003	.0356	3.90	5.38	7.28	2626.	7734.	4283.
.248	18.	555.	45171.	16000.	282.	221.	.452	.801	.4957	.0353	3.83	4.77	6.59	2377.	7518.	4182.
.255	20.	584.	45141.	17000.	285.	219.	.458	.800	.5020	.0357	3.88	4.91	6.80	2474.	7332.	4076.
.262	22.	612.	45114.	18000.	288.	218.	.464	.799	.5087	.0360	3.94	4.70	6.64	2391.	7149.	3972.
.269	24.	639.	45086.	19000.	291.	216.	.471	.798	.5153	.0364	4.00	4.49	6.49	2308.	6969.	3871.
.276	26.	667.	45058.	20000.	294.	215.	.477	.797	.5224	.0368	4.06	4.29	6.35	2225.	6792.	3771.
.284	28.	695.	45030.	21000.	297.	213.	.484	.796	.5294	.0372	4.12	4.09	6.21	2142.	6617.	3674.
.291	30.	724.	45002.	22000.	300.	212.	.491	.795	.5364	.0376	4.18	3.89	6.07	2059.	6446.	3578.
.299	33.	753.	44973.	23000.	303.	210.	.498	.795	.5436	.0380	4.24	3.69	5.93	1976.	6277.	3484.
.308	35.	782.	44943.	24000.	310.	212.	.512	.795	.5369	.0376	4.13	3.12	5.25	1711.	6078.	3404.
.318	38.	816.	44910.	25000.	313.	210.	.519	.794	.5457	.0381	4.20	3.28	5.49	1615.	5902.	3319.
.327	41.	846.	44880.	26000.	316.	208.	.526	.793	.5549	.0387	4.28	3.08	5.36	1721.	5729.	3236.
.336	44.	877.	44848.	27000.	318.	206.	.533	.792	.5642	.0392	4.36	2.89	5.25	1627.	5561.	3153.
.347	47.	910.	44816.	28000.	321.	204.	.540	.791	.5736	.0398	4.43	2.70	5.13	1534.	5395.	3072.
.358	51.	943.	44783.	29000.	325.	203.	.548	.790	.5818	.0403	4.49	2.48	4.98	1427.	5231.	2993.
.369	55.	978.	44748.	30000.	329.	201.	.557	.789	.5897	.0408	4.55	2.29	4.84	1332.	5071.	2915.
.382	59.	1014.	44711.	31000.	358.	216.	.610	.798	.5147	.0364	3.60	1.08	2.68	682.	4791.	2862.
.406	67.	1084.	44641.	32000.	361.	213.	.617	.797	.5256	.0370	3.69	1.77	3.45	1126.	4628.	2763.
.421	73.	1125.	44600.	33000.	364.	211.	.624	.795	.5370	.0376	3.78	1.59	3.37	1021.	4468.	2667.
.437	79.	1169.	44557.	34000.	366.	209.	.632	.794	.5486	.0383	3.87	1.42	3.28	918.	4313.	2574.
.455	85.	1216.	44510.	35000.	374.	209.	.648	.794	.5460	.0381	3.78	1.07	2.85	711.	4159.	2491.

0 END OF CLIMB TO 35000. FT
 TIME= .455 HRS FUEL USED= 1216. LBS WEIGHT= 44510. LBS RANGE= 85. NM

0 ALTITUDE= 35000. FT TAS= 466.70 KTS MACH NO= .8087

ACCELERATE TO MACH NO. = .800

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.456	85.41	1215.5	44510.	35000.	374.	209.	.648	.794	4440.	2834.
.503	106.41	1360.0	44366.	35000.	461.	258.	.800	.816	4537.	2964.

END OF ACCELERATION SEGMENT
 TIME= .503 HRS FUEL USED= 1360.0 LBS WEIGHT= 44366. LBS RANGE= 106. NM

ACCELERATE TO MACH NO. = .809

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.456	85.41	1215.5	44510.	35000.	374.	209.	.648	.794	4440.	2834.
.508	108.87	1375.5	44350.	35000.	466.	260.	.809	.818	4550.	2976.

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

END OF ACCELERATION SEGMENT
 TIME= .508 HRS FUEL USED= 1375.5 LBS WEIGHT= 44350. LBS RANGE= 109. NM

ACCELERATE TO MACH NO. = .826

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.456	85.41	1215.5	44510.	35000.	374.	209.	.648	.794	4440.	2834.
.514	111.71	1393.3	44332.	35000.	476.	266.	.826	.819	4563.	2990.

END OF ACCELERATION SEGMENT
 TIME= .514 HRS FUEL USED= 1393.3 LBS WEIGHT= 44332. LBS RANGE= 112. NM

DESIGN CASE
 CRUISE PERFORMANCE SUMMARY
 FOR
 ***** DESIGN PAYLOAD *****
 ***** MAXIMUM PAYLOAD *****
 ***** MAXIMUM FUEL *****
 FUEL AVAILABLE= 8747.

	AT SPECIFIED SPEED		AT NORMAL POWER		AT BEST SPEC. RANGE	
	START CRUISE	END CRUISE	START CRUISE	END CRUISE	START CRUISE	END CRUISE
TIME HRS.	.503	2.966	.508	2.615	.514	2.819
RANGE N.MI	106.	1243.	109.	1092.	112.	1211.
FUEL USED LBS.	1360.	6989.	1376.	6250.	1393.	6912.
WEIGHT LBS.	44366.	38736.	44350.	39475.	44332.	38814.
ALTITUDE FT.	35000.	35000.	35000.	35000.	35000.	35000.
TAS KTS.	461.7	461.7	466.7	466.7	476.7	476.7
EAS KTS.	237.3	237.3	260.1	260.1	265.7	263.7
MACH NO.	.8000	.8000	.8087	.8087	.8260	.8260
DIV. MACH	.8171	.8227	.8180	.8241	.8199	.8250
ANGLE ATTACK DEG.	1.478	1.087	1.378	.963	1.189	.842
FUSE. ANGLE DEG.	-.522	-.913	-.622	-1.037	-.811	-1.158
CL	.3601	.3144	.3522	.3031	.3375	.2955
L/D	12.367	11.429	12.242	11.187	11.989	11.043
FUEL FLOW LB/HR	2343.9	2232.6	2375.0	2256.7	2447.5	2345.2
BREG. FACTOR N.MI.	8745.	8016.	8721.	8169.	8640.	7895.
SPEC. RANGE NM/LB	.19697	.20680	.19651	.20681	.19477	.20327

DESCENT FROM CRUISE AT NORMAL POWER CONDITION
 (U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MMD OR VMO)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ANGLE (DEG)	R/S (FPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
2.628	1098.	6271.	39455.	35000.	467.	261.	.809	.823	.3105	.0272	1.03	-1.62	-2.60	1339.	2344.	1638. R
2.640	1104.	6293.	39433.	34000.	469.	267.	.809	.825	.2961	.0268	.90	-1.57	-2.67	1306.	2483.	1737. R
2.653	1110.	6317.	39409.	33000.	471.	273.	.809	.827	.2824	.0264	.79	-1.53	-2.74	1271.	2629.	1841. R
2.667	1117.	6343.	39382.	32000.	473.	279.	.809	.828	.2695	.0260	.68	-1.48	-2.80	1241.	2779.	1949. R
2.681	1123.	6372.	39354.	31000.	475.	286.	.809	.830	.2573	.0256	.58	-1.44	-2.86	1209.	2936.	2062. R
2.695	1130.	6402.	39323.	30000.	477.	293.	.809	.831	.2457	.0253	.48	-1.40	-2.92	1180.	3097.	2179. R
2.709	1137.	6436.	39290.	29000.	479.	299.	.809	.832	.2347	.0251	.38	-1.36	-2.98	1153.	3263.	2300. R
2.724	1144.	6472.	39254.	28000.	481.	306.	.809	.834	.2243	.0248	.30	-1.32	-3.03	1127.	3435.	2427. R
2.739	1151.	6510.	39215.	27000.	483.	313.	.809	.835	.2144	.0246	.21	-1.29	-3.07	1100.	3616.	2560. R
2.755	1159.	6552.	39173.	26000.	485.	320.	.809	.836	.2050	.0244	.13	-1.25	-3.12	1077.	3816.	2704. R
2.771	1166.	6597.	39128.	25000.	487.	327.	.809	.837	.1961	.0242	.06	-1.22	-3.16	1053.	4008.	2847. R
2.787	1174.	6646.	39080.	24000.	489.	334.	.809	.838	.1876	.0240	-.01	-1.19	-3.21	1032.	4206.	2995. R
2.803	1182.	6697.	39028.	23000.	491.	341.	.809	.839	.1795	.0239	-.08	-1.16	-3.25	1011.	4411.	3149. R
2.820	1191.	6752.	38974.	22000.	489.	346.	.802	.840	.1748	.0238	-.11	-1.15	-3.25	992.	4527.	3246. R
2.837	1199.	6809.	38917.	21000.	483.	347.	.789	.840	.1727	.0237	-.11	-1.14	-3.24	972.	4586.	3303. R
2.842	1201.	6812.	38913.	20000.	408.	299.	.664	.833	.2325	.0250	.66	-4.66	-6.00	3368.	1005.	725. A
2.847	1203.	6816.	38910.	19000.	404.	300.	.654	.833	.2279	.0249	.66	-4.66	-6.00	3324.	1048.	759. A
2.852	1205.	6820.	38905.	18000.	400.	302.	.645	.833	.2293	.0249	.65	-4.65	-6.00	3281.	1092.	794. A
2.857	1207.	6824.	38901.	17000.	395.	304.	.635	.834	.2247	.0248	.63	-4.63	-6.00	3238.	1138.	831. A
2.863	1209.	6829.	38897.	16000.	391.	306.	.626	.834	.2221	.0248	.62	-4.62	-6.00	3195.	1185.	869. A
2.868	1211.	6834.	38892.	15000.	387.	307.	.617	.834	.2195	.0247	.61	-4.61	-6.00	3153.	1234.	908. A
2.873	1213.	6839.	38887.	14000.	383.	309.	.608	.835	.2170	.0246	.60	-4.60	-6.00	3111.	1285.	949. A
2.879	1215.	6844.	38881.	13000.	379.	311.	.600	.835	.2144	.0246	.58	-4.58	-6.00	3070.	1337.	991. A
2.884	1217.	6850.	38876.	12000.	375.	313.	.592	.835	.2118	.0245	.57	-4.57	-6.00	3029.	1390.	1035. A
2.890	1219.	6856.	38870.	11000.	372.	315.	.584	.836	.2092	.0245	.55	-4.55	-6.00	2989.	1446.	1080. A
2.900	1222.	6864.	38861.	10000.	291.	250.	.455	.821	.3318	.0279	2.03	-3.15	-3.13	1621.	1127.	811. S
2.911	1225.	6873.	38852.	9000.	286.	250.	.446	.821	.3317	.0279	2.04	-3.10	-3.06	1568.	1165.	841. S
2.922	1229.	6883.	38843.	8000.	282.	250.	.438	.821	.3316	.0279	2.05	-3.04	-2.99	1515.	1205.	872. S
2.933	1232.	6893.	38833.	7000.	277.	250.	.430	.821	.3316	.0279	2.06	-2.98	-2.92	1463.	1245.	904. S
2.945	1235.	6904.	38821.	6000.	273.	250.	.422	.821	.3315	.0279	2.07	-2.92	-2.85	1411.	1287.	937. S
2.957	1238.	6916.	38810.	5000.	269.	250.	.414	.821	.3314	.0279	2.08	-2.85	-2.77	1359.	1331.	971. S
2.970	1242.	6929.	38797.	4000.	265.	250.	.406	.821	.3313	.0279	2.09	-2.79	-2.70	1308.	1375.	1007. S
2.983	1245.	6943.	38783.	3000.	261.	250.	.399	.821	.3312	.0279	2.10	-2.72	-2.62	1257.	1422.	1044. S
2.997	1249.	6958.	38768.	2000.	257.	250.	.391	.821	.3311	.0279	2.10	-2.65	-2.55	1207.	1469.	1082. S
3.004	1250.	6965.	38760.	1500.	255.	250.	.388	.821	.3310	.0279	2.11	-2.62	-2.51	1182.	1493.	1101. S

END OF DESCENT TO 1500. FT
 TIME= 3.004 HRS FUEL USED= 6965. LBS WEIGHT= 38760. LBS RANGE= 1250. NM

RESERVE FUEL(LBS) 1758. 1781. 1836.
 (45.0 MIN.)

RANGE = 1250. BLOCK TIME= 3.004 USED FOR DESIGN RANGE AND COST

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

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0 *****
0 TEMP.= 537. DEG:STD.+36.
  LANDING ELEVATION= 5000. FT.
  LANDING WING LOADING= 78.04 PSF.
  LANDING WEIGHT = 42982. LBS.

  LANDING DISTANCE FROM 50. FT.= 2698. FT.

  F.A.R. FACTORED FIELD LENGTH = 4496. FT.
0 APPROACH TRANSITION DELAY ROLL
0 DIST= 659. DIST= 192. DIST= 195. DIST= 1651.
  R/S= 1000. XLFMX= 1.200 TDELAY= 1.00 MUB= .4000
  VAPEAS= 116.91 SINKTD= 3.000 TIDLE= 606. TR/TIDLE= .0000
  VAPTAS= 130.45 VSTEAS= 89.93 VDTAS= 115.40 ABAR(G)= .3577
  THETA= 4.34 CLMX= 2.8448
  THRUST= 2838. HFLAR= 20.9
0 *****
0 RANGE OR ENDURANCE ITERATION SUMMARY
  ITERATION GROSS WEIGHT (LB) RANGE(NMI) OR ENDURANCE(HR)
  0 44050.00 1073.205
  1 45981.21 1276.961
  2 45725.67 1250.429
  REQUIRED RG. OR END. = 1250.000
0
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
  ANGLE OF ATTACK(DEGREES)= 1.610 LIFT= 44353.9 L/D= 12.641 ALTITUDE= 35000.0 MACH= .8000
0 GROSS WEIGHT = 45726. PASSENGERS = 50. PLUS CREW
0 FUSELAGE LENGTH (ELF) 79.25 FT
  WIDTH (SWF) 9.25 FT
  WETTED AREA (SF) 1910. SQFT
  DELTA P (DELP) 8.20 PSI
0 WING ASPECT RATIO (AR) 8.30
  AREA (SW) 481.1 SQFT
  SPAN (B) 63.2 FT
  GEOM. MEAN CHORD (CBARW) 8.74 FT
  QUARTER CHORD SWEEP (DLMC4) 14.5 DEG
  TAPER RATIO (SLM) .200
  ROOT THICKNESS (TCR) .130
  TIP THICKNESS (TCT) .100
  WING LOADING (WGS) 83.0 PSF
  WING FUEL VOLUME (VFW) 1230.7 GAL
0 CANARD ASPECT RATIO (ARcan) 5.50
  AREA (Swc) 69.8 SQFT
  SPAN (Bcan) 19.6 FT
  GEOM. MEAN CHORD (CBARc) 3.69 FT
  QUARTER CHORD SWEEP (DwpqCa) 15.0 DEG
  TAPER RATIO (SLMcan) .500
  THICKNESS/CHORD (TCcan) .100
  MOMENT ARM (ELcan) 36.1 FT
  VOLUME COEFF. (VBARc) .599
  CANARD LOADING (WGS) 83.0 PSF
0 HOR. TAIL ASPECT RATIO (ARHT) 4.00
  AREA (SHT) 90.5 SQFT
  SPAN (BHT) 19.03 FT
  MEAN CHORD (CBARHT) 4.89 FT
  THICKNESS/CHORD (TCHT) .100
  MOMENT ARM (ELTH) 42.9 FT
  VOLUME COEFF. (VBARH) .923
0 VERT. TAIL ASPECT RATIO (ARVT) 1.00
  AREA (SVT) 107.6 SQFT
  SPAN (BVT) 10.37 FT
  MEAN CHORD (CBARVT) 10.48 FT
  THICKNESS/CHORD (TCVT) .120
  MOMENT ARM (ELTV) 32.2 FT
  VOLUME COEFF. (VBARV) .114
0 ENG. NACELLES LENGTH (ELN) 11.58 FT
  MEAN DIAMETER (DBARN) 3.86 FT
  NUMBER ENGINES (ENP) 2.0
  WETTED AREA (SN) 280.49 SQFT
  LOCATION ON FUSELAGE
0 VDIVE = 715. KTS VMD = 596. KTS MMD = .900
  ULT. LF = 5.64 MAN. LF = 2.50 GUST LF = 3.76
0 PROPULSION GROUP
  PRIMARY ENGINES (WEP) 2973.
  PRIMARY ENGINE INSTL. (WPEI) 401.
  FUEL SYSTEM (WFSS) 175.
  TOTAL PROP.GROUP WT. (WP) 3549.
0 STRUCTURES GROUP
  WING (WW) 4792.
  CANARD (WWc) 372.
  HOR. TAIL (WHT) 459.
  VERT. TAIL (WVT) 425.
  FUSELAGE (WB) 5980. (INCL. .0 LBS A.T.W.)
  LANDING GEAR (WLG) 1738.
  PRIMARY ENG. SECTION (WPEs) 991.
  GROUP WEIGHT INC. (DELWST) 0.
  TOTAL STRUC.GROUP WT. (WST) 14757.
0 FLIGHT CONTROLS GROUP
  COCKPIT CONTROLS (WCC) 96.
  FIXED WING CONTROLS (WCFW) 892.
  SAS (WSAS) 0.
  GROUP WEIGHT INC. (DELWFC) 0.
  TOTAL CONTROL WT. (WFC) 988.
0 WT. OF FIXED EQUIPMENT (WFE) 6605.

```

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

```

WEIGHT EMPTY          (WE)      25899.
FIXED USEFUL LOAD     (WFUL)     1080. (INC. CREW )
OPERATING WEIGHT EMPTY (OWE)     26979.
0 PAYLOAD              (WPL)     10000. (PAX.VOL.= 50.  DESIGN PAX= 50.)
FUEL                   (WFA)     8747. (WFW= 8230.) (WFTP= 0.)
GROSS WEIGHT          (WG)      45726.

0
0   FIXED EQUIP GROUP          FIXED USEFUL LOAD
0   WAPU      372.27          WCREW ( 2.) 340.00
   WINSTR     241.36          WSTU ( 1.) 130.00
   WHYD       376.77          WCBAG      110.00
   WELEC      970.00          WUF        131.60
   WAV        500.00          WOLL       124.34
   WFUR      3410.00          WSRV       116.00
   WAC        477.91          WH2O       53.00
   WAI        236.26          WEMER      40.00
   WAUXG      20.00          WCATER     35.00
   WPE        6604.57          WFUL       1079.94

0 DESIGN MACH = .800          DESIGN ALTITUDE = 35000.          DESIGN Q (PSP) =224.03
0 DESIGN RE.NUM. PER FT. = 1.922E+06  FLATPLATE CF AT RE=10E7 IS .00274

0 AERODYNAMIC DATA

0
0   DRAG BREAKDOWN          FLATPLATE          WETTED
0   WING                    AREA(SQFT)        CDO          AREA(SQFT)
   CANARD                   .3046            .00092        62.03
   FUSELAGE                  5.4592          .00991       1910.38
   VERT. TAIL                 .6680           .00121        215.27
   HOR. TAIL                   .6074           .00110        181.08
   ENGINE NAC.                1.1846          .00215        280.49
   TIP TANKS                   .0000           .00000         .00
   INCREMENTAL                .8262           .00150         .00
0   TOTAL                   12.4180         .02255       3390.37

   MEAN SKIN FRICTION COEF.= .003663

0 AERODYNAMIC COEFF.          AIRCRAFT          WING          CANARD
                                (except Wing and Canard)
A1                                .8013            .8306
A2                               -.1227           -.1225
A3                                .0383            .0286
A4=.75X(T/C)                     .0906            .0750
A5=CDO--                          .0135
A6                                2.4035           2.6403
A7=1/(PI.SEE.AR)                  .0476            .0677
3-D LIFT SLOPE AT CRUISE MACH (CLALPH) 6.7033 PER RAD. (CLALFc) 5.6370 PER RAD.
OSWALD FACTOR (SEE)                .8063            (SEECAN) .8555

0 CRUISE CD = .0224 + .0501 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
0 RETRACTABLE LANDING GEAR CD INC.= .02727

0 CRUISE DRAG
0CL= .2000
   MACH   CD   L/D   CLALPH   ALPHA
.50000 .02439 8.1991 5.3413 .5454
.55000 .02439 8.1991 5.4739 .4934
.60000 .02439 8.1991 5.6323 .4345
.65000 .02439 8.1991 5.8228 .3680
.70000 .02439 8.1991 6.0544 .2927
.75000 .02439 8.1991 6.3408 .2072
.80000 .02439 8.1991 6.7033 .1095
.85000 .02445 8.1786 7.1781 -.0036
0CL= .3000
   MACH   CD   L/D   CLALPH   ALPHA
.50000 .02704 11.0967 5.3413 1.6181
.55000 .02704 11.0967 5.4739 1.5401
.60000 .02704 11.0967 5.6323 1.4518
.65000 .02704 11.0967 5.8228 1.3520
.70000 .02704 11.0967 6.0544 1.2390
.75000 .02704 11.0967 6.3408 1.1108
.80000 .02704 11.0967 6.7033 .9642
.85000 .02747 10.9209 7.1781 .7946
0CL= .4000
   MACH   CD   L/D   CLALPH   ALPHA
.50000 .03068 13.0381 5.3413 2.6907
.55000 .03068 13.0381 5.4739 2.5868
.60000 .03068 13.0381 5.6323 2.4691
.65000 .03068 13.0381 5.8228 2.3360
.70000 .03068 13.0381 6.0544 2.1854
.75000 .03068 13.0381 6.3408 2.0144
.80000 .03068 13.0381 6.7033 1.8189
.85000 .03209 12.4646 7.1781 1.5928
0CL= .5000
   MACH   CD   L/D   CLALPH   ALPHA
.50000 .03550 14.0862 5.3413 3.7634
.55000 .03550 14.0862 5.4739 3.6335
.60000 .03550 14.0862 5.6323 3.4863
.65000 .03550 14.0862 5.8228 3.3200
.70000 .03550 14.0862 6.0544 3.1317
.75000 .03550 14.0862 6.3408 2.9180
.80000 .03550 14.0862 6.7033 2.6737
.85000 .03878 12.8948 7.1781 2.3910

```

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

OCL= .6000

MACH	CD	L/D	CLALPH	ALPHA
.50000	.04131	14.5229	5.3413	4.8361
.55000	.04131	14.5229	5.4739	4.6802
.60000	.04131	14.5229	5.6323	4.5036
.65000	.04131	14.5229	5.8228	4.3039
.70000	.04131	14.5229	6.0544	4.0781
.75000	.04131	14.5229	6.3408	3.8216
.80000	.04136	14.5056	6.7033	3.5284
.85000	.04764	12.5937	7.1781	3.1892

0 LOW SPEED LIFT/DRAG-GR.UP(IF R)O.G.E.

ALPHA	CL	FLAPS UP		CL	TAKEOFF		CL	LANDING	
		CD	L/D		CD	L/D		CD	L/D
-2.00000	-.03398	.02252	-1.50915	.97692	.07894	12.37531	1.67631	.21771	7.69977
.00000	.13592	.02329	5.83516	1.14682	.09190	12.47889	1.84620	.23452	7.87222
2.00000	.30582	.02722	11.23516	1.31672	.10881	12.10151	2.01610	.25600	7.87536
4.00000	.47571	.03423	13.89603	1.48661	.13092	11.35516	2.18600	.28361	7.70777
6.00000	.64561	.04446	14.52199	1.65651	.15716	10.54028	2.35590	.31460	7.48851
8.00000	.81551	.05811	14.03343	1.82641	.18635	9.80085	2.52579	.34898	7.23771
10.00000	.98541	.07577	13.00598	1.99631	.21850	9.13658	2.69569	.38674	6.97038
11.74615	1.13374	.09606	11.80203	2.14464	.24897	8.61393	2.84402	.42247	6.73193
11.74615	1.13374	.09606	11.80203	2.14464	.24897	8.61393	2.84402	.42247	6.73193

0 DFLAP= .00 DFLAP= 15.00 DFLAP= 40.00
 0 CLMAX= 1.13374 CLMAX= 2.15556 CLMAX= 2.84477

0 LOW SPEED AERO FOR OTHER FLAP DEFECTIONS

FLAP DEFL.	CLMAX	CL	CD	L/D
10.000	1.84325	.67479	.05879	11.47713
		.84469	.06905	12.23225
		1.01458	.08276	12.25894
		1.18448	.10052	11.78341
		1.35438	.12407	10.91610
		1.52428	.15087	10.10297
		1.69417	.18060	9.38088
		1.84325	.20909	8.81572
		1.84325	.20909	8.81572
		1.84325	.20909	8.81572
20.000	2.36712	1.19866	.10262	11.68087
		1.36856	.11707	11.68978
		1.53845	.13554	11.35063
		1.70835	.16015	10.66751
		1.87825	.18773	10.00486
		2.04815	.21830	9.38208
		2.21804	.25186	8.80677
		2.36712	.28375	8.34217
		2.36712	.28375	8.34217
		2.36712	.28375	8.34217
30.000	2.67528	1.50682	.15172	9.93159
		1.67672	.16776	9.99465
		1.84661	.18843	9.80007
		2.01651	.21453	9.39946
		2.18641	.24373	8.97045
		2.35631	.27603	8.53646
		2.52620	.31142	8.11199
		2.67528	.34501	7.75410
		2.67528	.34501	7.75410
		2.67528	.34501	7.75410

0 ALTITUDE= 35000. FT TAS= 471.16 KTS MACH NO= .8164

0 RDT&E AND AIRFRAME PRODUCTION COSTS (1993. DOLLARS)

0 TOTAL RDT&E COSTS 1056.8395 MILLION
 0 AIRFRAME PRODUCTION COSTS(INCLUDING 10% PROFIT) 500. AIRCRAFT

	WEIGHT(LB)	COST(\$)	COST(\$/LB)
STRUCTURE(4191369.\$)			
WING	4792.	1176474.	245.50
CANARD	372.	166251.	446.33
EMPENNAGE	884.	339096.	383.57
FUSELAGE	5980.	1659884.	277.57
LANDING GEAR	1738.	308815.	177.73
NACELLES	991.	540848.	545.04
PROPULSION INSTAL(170920.\$)			
ENGINE INSTALLAT.	401.	146124.	364.08
FUEL SYSTEM	175.	24796.	141.74
SYSTEMS(2612710.\$)			
FLIGHT CONTROLS	988.	463585.	469.41
HYDRAULIC	377.	46933.	124.57
ELECTRICAL	970.	464214.	478.57
AIR CONDITIONING	478.	256070.	535.82
ANTI-ICING	236.	124429.	526.66
AUX. POWER UNIT	372.	207143.	556.42
FURNISHINGS	3410.	796443.	233.56
INSTRUMENTS	241.	200191.	829.44
AVIONICS INSTALL.	250.	49032.	196.13
AUX. ITEMS	20.	4671.	233.56
INTEGRATION(1743750.\$)			
AIRFRAME TOTALS	22676.	8718749.	384.50
ENGINES		2757603.	
PROPELLER		0.	
AVIONICS		4000000.	
A/C COST(NO RD)		15476352.	
R&D PER A/C		2113679.	
TOTAL A/C COST		17590030.	

0 ENGINES NUMBER = 2. TYPE= 7

0 EMPTY WEIGHT= 25899. AIRFRAME WEIGHT= 22926. WEIGHT OF 1 ENGINE= 1486. CRUISE SPEED= 471. KTS

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (continued)

0 THRUST/ENGINE= 9291.
 0 TOTAL AIRCRAFT COST= 17590030. AIRFRAME COST= 14832428. COST OF 1 ENGINE= 1378802. COST OF 1 PROP.= 0.

```

0          --- COST DATA ---
0          GASP SHORTHAUL METHOD
0          DESIGN MISSION
0          OPERATING COST FOR NOR.RATED POWER AND 35000. ALTITUDE
0          .....
0          RANGE= 1250. N.M.   BLOCK FUEL= 6965. LBS   BLOCK TIME= 3.0039 HRS.
0          UTILIZATION          3200.
0          FLYING OPERATIONS
0          FLIGHT CREW          375.489
0          FUEL,OIL,AND TAXES( .850$/G)  925.232
0          INSURANCE           82.561
0          DIRECT MAINTENANCE
0          AIRFRAME            172.472
0          ENGINE              286.704
0          MAINTENANCE BURD.   373.948
0          DEPRECIATION        1109.617

0          TOTAL DOC ($/TRIP)      3326.023
0          ($/B.HR.)              1107.231
0          ($/N.MI.)              2.660

```

Fig. D2 - Three-Lifting Surface Baseline Configuration GASP output file (concluded)

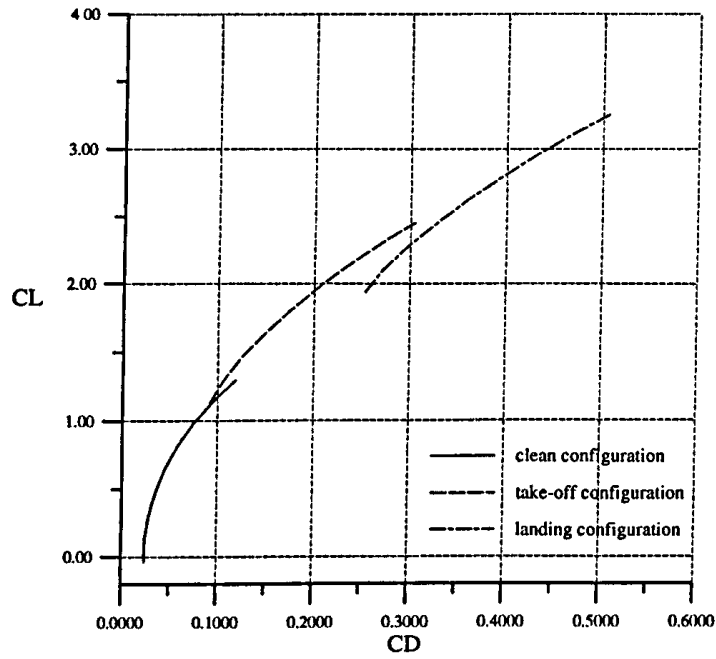


Fig. D3.1 - Conventional baseline concept low speed drag polars

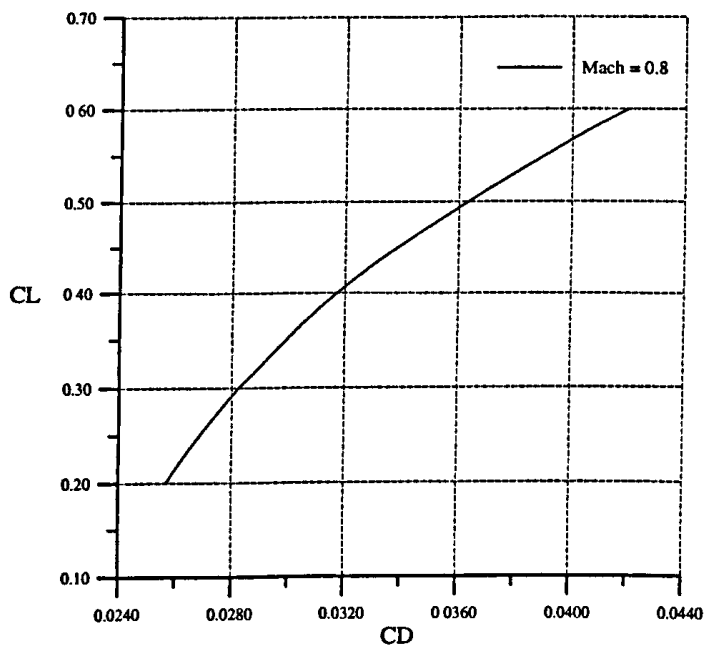


Fig. D3.2 - Conventional baseline concept Cruise drag polar

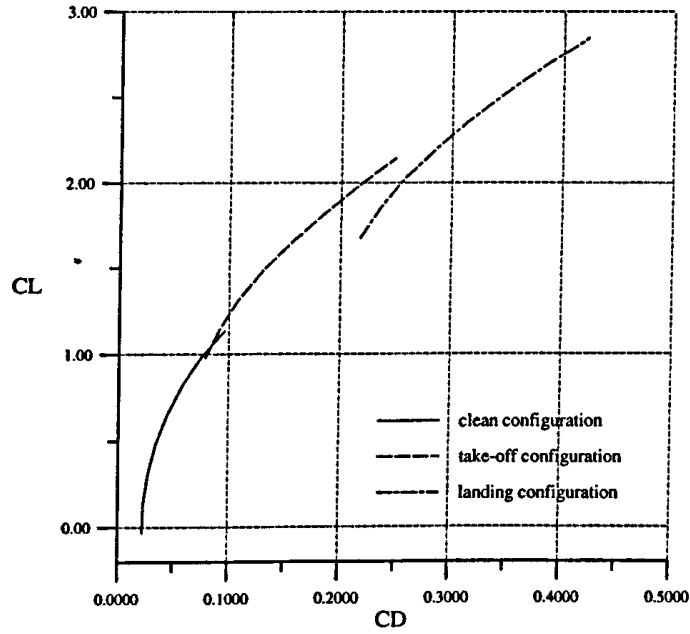


Fig. D4.1 - Three-lifting Surface baseline concept low speed drag polars

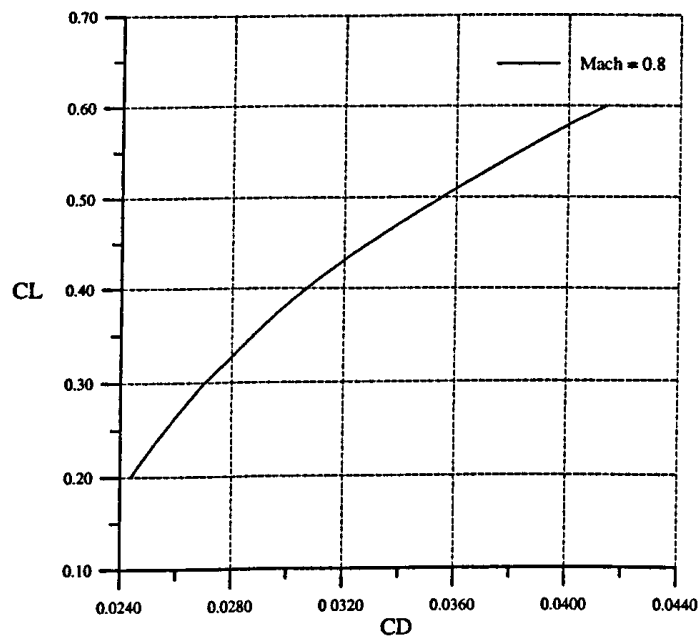


Fig. D4.2 - Three-lifting Surface baseline concept Cruise drag polar

APPENDIX E

The Optimised Designs

Introduction

Information related to the relevant optimisation work performed is included in the present Appendix.

Several local "optimum" solutions were obtained either for minimum DOC and minimum MTOW for both concepts. Fig E1 summarises the "best" solutions achieved and calls them 1st solutions. Listings of the next closest to the "best" are included as well, and are named 2nd and 3rd solutions. In addition to the values corresponding to the initial and the convergence point design variables and respective objective and constraint functions, information on the convergence type, CPU time and number of function evaluations (nfe) per run is given.

Figures E2 through E8, and E9 through E15 group the USERF and USERD RQPMIN user-defined subroutines, the optimiser RQPMIN.DAT input and RQPMIN.RES output files, and the GASP output listings corresponding to both concepts optimisation solutions, regarding respectively the minimum DOC, and the minimum MTOW cases. Figures E16 and E17 illustrate the low speed and cruise drag polars related to the conventional and the three-surface minimum DOC designs.

The user written subroutines USERF and USERD, and the RQPMIN.DAT file were written following the recommendations of ref. E1. This reference should be consulted for details not shown here. USERF assigns the design independent variables, calls the design synthesis program and defines the objective and the selected constraint functions. The independent variables chosen for the optimisations, both for the conventional and the three-surface configurations, were listed in section 5.4.2 together with their lower and upper bounds. Their assignment, as shown in figs E2 and E9, is done using the respective variable names as recognized by GASP program, and listed in Appendix H. The synthesis program is called by the name of its "MAIN" program (figs 3.6 and 3.7). However, the selected objective and the constraint functions were defined by employing the names used by GASP OUTPUT subroutine (figs 3.6 and 3.7). Before printing the results, this subroutine renames the most relevant data and incorporates them in an array called DATOUT(i). The objective and the constraint functions were defined in section 5.4.2, nevertheless, they are reproduced here for the sake of clarity:

Direct Operating Cost optimisation cases (fig E2)

Objective Function:
DATOUT(133) - Direct Operating Cost [US\$/NM]

Maximum Take-off Weight optimisation cases (fig E9)

Objective Function:
DATOUT(5) - Maximum Take-off Weight [Lb]

The constraint functions, reflecting the low speed field performances and cruise performance boundary limits, are expressed in the form of inequalities. The assignment of these functions is done in terms of their residuals with regard to the mission requirements

(most taken as extreme values, where the cruise Mach number was allowed to vary between $M=0.76$ and $M=0.86$). The same constraint functions were used in all optimisation cases (figs E2 and E9):

Constraint Functions:

- DATOUT(92) - FAR Part 25 take-off distance [ft], (maximum value = 6000)
- DATOUT(49) - FAR Part 25 landing distance [ft], (maximum value = 5000)
- DATOUT(51) - approach speed [knots], EAS, (maximum value = 125)
- DATOUT(109) - cruise Mach number, (min value = 0.76, max value = 0.86)

The starting point, or initial estimate of the solution, for all the optimisations performed and defined in the RQPMIN.DAT input file, corresponds to that of the baseline configurations. These are feasible designs, satisfying all the constraints, as obtained with GASP when working as a stand-alone program.

The optimisation of Three-surface configurations requires, in the present research, more design variables than the conventional aircraft. The variables allowed to be optimised are controlled in the RQPMIN.DAT file through a variable status definition controller (4th character place of a variable definition record) which is set accordingly (figs E3, E6, E10, and E13).

No analytical derivatives exist for the problem functions. An empty USERD subroutine was included and the driver evaluated the objective and constraint functions derivatives with respect to the design variables, by finite differences when necessary.

During its operation, RQPMIN produces progress reports and warnings which are sent to the user's terminal and to an output file (RQPMIN.RES). The frequency of the progress reports is controlled by a keyword given in the input file and their context relates to the successive stages of the optimisation process. A description of these reports was given in section 4.2.

Detailed GASP result listings of the two optimised configurations both for minimum DOC (figs E5 and E8), and minimum MTOW (figs E12 and E15), are included. The low speed and cruise drag polars related to the minimum DOC conventional and the three-surface designs are illustrated respectively in figs. E16 and E17.

In the main text, table 5.1 presents a summary of their main characteristics together with the initial parametric analysis results and the baseline designs data. Figures 5.4, 5.5, 5.6 and 5.7 show the airliner three view sketches corresponding to the four optimised designs.

References:

- E1 Skrobanski,J.J.
User Guide for RQPMIN (A Program for Constrained Optimisation)
TM Aero 2059, Royal Aircraft Establishment, Farnborough, Hants, 1986

Relevant Design Optimisation Results**Direct Operating Costs Minimization (D.O.C.)****Conventional Configuration**1st Solution

Convergence type : B
 cpu time : 53:36.58

Initial Point

icallf = 0 nfe = 0 weight [Lb] = 47880.4336

Merit Function

d.o.c. [\$/NM] = 2.7904

Independent Variables

wing loading [lb/sqft] = 83.000
 wing aspect ratio = 8.300
 wing quarter chord sweep angle [degrees] = 14.500
 wing taper ratio = .200
 horizontal tail aspect ratio = 4.000
 horizontal tail quarter chord sweep angle [degrees] = 27.500
 vertical tail aspect ratio = 1.000
 vertical tail quarter chord sweep angle [degrees] = 50.500

Constraint Functions

FAR 25 take-off distance [ft] = 4633.977
 FAR 25 landing distance [ft] = 4016.758
 approach speed [knots],EAS = 109.133
 cruise Mach number = .795

Convergence Point

icallf = 3 nfe = 759 weight [Lb] = 45706.8047

Merit Function

d.o.c. [\$/NM] = 2.6205

Independent Variables

wing loading [lb/sqft] = 105.000
 wing aspect ratio = 8.879
 wing quarter chord sweep angle [degrees] = 14.878
 wing taper ratio = .198
 horizontal tail aspect ratio = 4.153
 horizontal tail quarter chord sweep angle [degrees] = 25.253
 vertical tail aspect ratio = 1.012
 vertical tail quarter chord sweep angle [degrees] = 52.725

Constraint Functions

FAR 25 take-off distance [ft] = 5475.669
 FAR 25 landing distance [ft] = 4807.549
 approach speed [knots],EAS = 122.153
 cruise Mach number = .830

Fig E1 - Relevant Design Optimisation Solutions

2nd Solution

Convergence type : B
 cpu time : 42:05.58

Initial Point

icallf = 0 nfe = 0 weight [Lb] = 47899.9258

Merit Function

d.o.c. [\$/NM] = 2.7902

Independent Variables

wing loading [lb/sqft] = 83.000
 wing aspect ratio = 8.300
 wing quarter chord sweep angle [degrees] = 14.500
 wing taper ratio = .200
 horizontal tail aspect ratio = 4.000
 horizontal tail quarter chord sweep angle [degrees] = 27.500
 vertical tail aspect ratio = 1.000
 vertical tail quarter chord sweep angle [degrees] = 50.500

Constraint Functions

FAR 25 take-off distance [ft] = 4637.342
 FAR 25 landing distance [ft] = 4016.663
 approach speed [knots],EAS = 109.132
 cruise Mach number = .795

Convergence Point

icallf = 3 nfe = 606 weight [Lb] = 45594.4063

Merit Function

d.o.c. [\$/NM] = 2.6259

Independent Variables

wing loading [lb/sqft] = 105.000
 wing aspect ratio = 8.240
 wing quarter chord sweep angle [degrees] = 12.193
 wing taper ratio = .165
 horizontal tail aspect ratio = 3.922
 horizontal tail quarter chord sweep angle [degrees] = 20.951
 vertical tail aspect ratio = 1.165
 vertical tail quarter chord sweep angle [degrees] = 50.762

Constraint Functions

FAR 25 take-off distance [ft] = 5412.435
 FAR 25 landing distance [ft] = 4779.025
 approach speed [knots],EAS = 121.689
 cruise Mach number = .828

Fig E1 - Relevant Design Optimisation Solutions (continued)

Three-Surface Configuration1st Solution

Convergence type : B
 cpu time : 37:49.32

Initial Point

icallf = 0 nfe = 0 weight [Lb] = 46598.3594

Merit Function

d.o.c. [\$/NM] = 2.7339

Independent Variables

wing loading [lb/sqft] = 70.378
 wing aspect ratio = 8.300
 wing quarter chord sweep angle [degrees] = 14.500
 wing taper ratio = .200
 canard aspect ratio = 5.500
 canard quarter chord sweep angle [degrees] = 15.000
 canard taper ratio = .500
 canard incidence angle [degrees] = 2.000
 horizontal tail aspect ratio = 4.000
 horizontal tail quarter chord sweep angle [degrees] = 27.500
 vertical tail aspect ratio = 1.000
 vertical tail quarter chord sweep angle [degrees] = 50.500
 canard over wing area ratio = .145
 engine c.g. location as a fraction of fuselage length = .750

Constraint Functions

FAR 25 take-off distance [ft] = 4668.619
 FAR 25 landing distance [ft] = 3943.402
 approach speed [knots],EAS = 107.597
 cruise Mach number = .793

Convergence Point

icallf = 3 nfe = 619 weight [Lb] = 44050.0000

Merit Function

d.o.c. [\$/NM] = 2.6132

Independent Variables

wing loading [lb/sqft] = 92.966
 wing aspect ratio = 8.397
 wing quarter chord sweep angle [degrees] = 14.508
 wing taper ratio = .202
 canard aspect ratio = 6.097
 canard quarter chord sweep angle [degrees] = 20.545
 canard taper ratio = .503
 canard incidence angle [degrees] = 2.033
 horizontal tail aspect ratio = 3.908
 horizontal tail quarter chord sweep angle [degrees] = 24.435
 vertical tail aspect ratio = .894
 vertical tail quarter chord sweep angle [degrees] = 50.097
 canard over wing area ratio = .158
 engine c.g. location as a fraction of fuselage length = .758

Constraint Functions

FAR 25 take-off distance [ft] = 5994.771
 FAR 25 landing distance [ft] = 4965.626
 approach speed [knots],EAS = 124.453
 cruise Mach number = .796

Fig E1 - Relevant Design Optimisation Solutions (continued)

2nd Solution

Convergence type : B
 cpu time : 38:51.2

Initial Point

icallf = 0 nfe = 0 weight [Lb] = 46594.3008

Merit Function
 d.o.c. [\$/NM] = 2.7354

Independent Variables

wing loading [lb/sqft]	=	70.379
wing aspect ratio	=	8.300
wing quarter chord sweep angle [degrees]	=	14.500
wing taper ratio	=	.200
canard aspect ratio	=	5.500
canard quarter chord sweep angle [degrees]	=	15.000
canard taper ratio	=	.500
canard incidence angle [degrees]	=	2.000
horizontal tail aspect ratio	=	4.000
horizontal tail quarter chord sweep angle [degrees]	=	27.500
vertical tail aspect ratio	=	1.000
vertical tail quarter chord sweep angle [degrees]	=	50.500
canard over wing area ratio	=	.145
engine c.g. location as a fraction of fuselage length	=	.750

Constraint Functions

FAR 25 take-off distance [ft]	=	4668.039
FAR 25 landing distance [ft]	=	3943.466
approach speed [knots],EAS	=	107.598
cruise Mach number	=	.793

Convergence Point

icallf = 3 nfe = 503 weight [Lb] = 45354.3438

Merit Function
 d.o.c. [\$/NM] = 2.6564

Independent Variables

wing loading [lb/sqft]	=	83.813
wing aspect ratio	=	8.535
wing quarter chord sweep angle [degrees]	=	17.395
wing taper ratio	=	.200
canard aspect ratio	=	6.118
canard quarter chord sweep angle [degrees]	=	16.717
canard taper ratio	=	.503
canard incidence angle [degrees]	=	2.060
horizontal tail aspect ratio	=	4.173
horizontal tail quarter chord sweep angle [degrees]	=	28.664
vertical tail aspect ratio	=	1.056
vertical tail quarter chord sweep angle [degrees]	=	52.969
canard over wing area ratio	=	.158
engine c.g. location as a fraction of fuselage length	=	.849

Constraint Functions

FAR 25 take-off distance [ft]	=	5607.999
FAR 25 landing distance [ft]	=	4642.339
approach speed [knots],EAS	=	119.277
cruise Mach number	=	.799

Fig E1 - Relevant Design Optimisation Solutions (continued)

Maximum Take-off Weight Minimization**Conventional Configuration**1st solution

Convergence type : B
 cpu time : 1:30:27.13

Initial Point

icallf = 0 nfe = 0 d.o.c. [\$/NM] = 2.7901
Merit Function
 weight [Lb] = 47875.8320
Independent Variables
 wing loading [lb/sqft] = 83.000
 wing aspect ratio = 8.300
 wing quarter chord sweep angle [degrees] = 14.500
 wing taper ratio = .200
 horizontal tail aspect ratio = 4.000
 horizontal tail quarter chord sweep angle [degrees] = 27.500
 vertical tail aspect ratio = 1.000
 vertical tail quarter chord sweep angle [degrees] = 50.500
Constraint Functions
 FAR 25 take-off distance [ft] = 4638.922
 FAR 25 landing distance [ft] = 4016.783
 approach speed [knots], EAS = 109.133
 cruise Mach number = .795

Convergence Point

icallf = 3 nfe = 1163 d.o.c. [\$/NM] = 2.6163
Merit Function
 weight [Lb] = 45638.7422
Independent Variables
 wing loading [lb/sqft] = 104.995
 wing aspect ratio = 8.717
 wing quarter chord sweep angle [degrees] = 18.569
 wing taper ratio = .170
 horizontal tail aspect ratio = 4.036
 horizontal tail quarter chord sweep angle [degrees] = 23.943
 vertical tail aspect ratio = 1.041
 vertical tail quarter chord sweep angle [degrees] = 52.626
Constraint Functions
 FAR 25 take-off distance [ft] = 5598.113
 FAR 25 landing distance [ft] = 4940.534
 approach speed [knots], EAS = 124.209
 cruise Mach number = .836

Fig E1 - Relevant Design Optimisation Solutions (continued)

2nd Solution

Convergence type : B
 cpu time : 1:39:51.80

Initial Point

icallf = 0 nfe = 0 d.o.c. [\$/NM] = 2.7906

Merit Function
 weight [Lb] = 47872.9883

Independent Variables

wgs [lb/sqft]	=	83.000
wing aspect ratio	=	8.300
wing quarter chord sweep angle [degrees]	=	14.500
wing taper ratio	=	.200
horizontal tail aspect ratio	=	4.000
horizontal tail quarter chord sweep angle [degrees]	=	27.500
vertical tail aspect ratio	=	1.000
vertical tail quarter chord sweep angle [degrees]	=	50.500

Constraint Functions

FAR 25 take-off distance [ft]	=	4637.960
FAR 25 landing distance [ft]	=	4016.793
approach speed [knots],EAS	=	109.133
cruise Mach number	=	.795

Convergence Point

icallf = 3 nfe = 1178 d.o.c. [\$/NM] = 2.6338

Merit Function
 weight [Lb] = 45792.0430

Independent Variables

wing loading [lb/sqft]	=	104.970
wing aspect ratio	=	9.173
wing quarter chord sweep angle [degrees]	=	15.494
wing taper ratio	=	.185
horizontal tail aspect ratio	=	4.083
horizontal tail quarter chord sweep angle [degrees]	=	28.425
vertical tail aspect ratio	=	1.136
vertical tail quarter chord sweep angle [degrees]	=	45.386

Constraint Functions

FAR 25 take-off distance [ft]	=	5481.575
FAR 25 landing distance [ft]	=	4798.645
approach speed [knots],EAS	=	122.029
cruise Mach number	=	.829

Fig E1 - Relevant Design Optimisation Solutions (continued)

Three-Surface Configuration1st Solution

Convergence type : B
 cpu time : 1:39:57.20

Initial Point

icallf = 0 nfe = 0 d.o.c. [\$/NM] = 2.7356

Merit Function
 weight [Lb] = 46568.8633

Independent Variables

wing loading [lb/sqft] = 70.386
 wing aspect ratio = 8.300
 wing quarter chord sweep angle [degrees] = 14.500
 wing taper ratio = .200
 canard aspect ratio = 5.500
 canard quarter chord sweep angle [degrees] = 15.000
 canard taper ratio = .500
 canard incidence angle [degrees] = 2.000
 horizontal tail aspect ratio = 4.000
 horizontal tail quarter chord sweep angle [degrees] = 27.500
 vertical tail aspect ratio = 1.000
 vertical tail quarter chord sweep angle [degrees] = 50.500
 canard over wing area ratio = .145
 engine c.g. location as a fraction of fuselage length = .750

Constraint Functions

FAR 25 take-off distance [ft] = 4666.837
 FAR 25 landing distance [ft] = 3943.893
 approach speed [knots],EAS = 107.605
 cruise Mach number = .793

Convergence Point

icallf = 3 nfe = 1348 d.o.c. [\$/NM] = 2.6373

Merit Function
 weight [Lb] = 44575.9922

Independent Variables

wing loading [lb/sqft] = 90.788
 wing aspect ratio = 8.841
 wing quarter chord sweep angle [degrees] = 16.116
 wing taper ratio = .183
 canard aspect ratio = 6.005
 canard quarter chord sweep angle [degrees] = 18.238
 canard taper ratio = .496
 canard incidence angle [degrees] = 2.028
 horizontal tail aspect ratio = 3.983
 horizontal tail quarter chord sweep angle [degrees] = 26.344
 vertical tail aspect ratio = 1.142
 vertical tail quarter chord sweep angle [degrees] = 40.000
 canard over wing area ratio = .172
 engine c.g. location as a fraction of fuselage length = .811

Constraint Functions

FAR 25 take-off distance [ft] = 6004.885
 FAR 25 landing distance [ft] = 4911.794
 approach speed [knots],EAS = 123.602
 cruise Mach number = .792

Fig E1 - Relevant Design Optimisation Solutions (continued)

2nd Solution

Convergence type : A
 cpu time : 19:05.65

Initial Point

icallf = 0 nfe = 0 d.o.c. [\$/NM] = 2.7356

Merit Function
 weight [Lb] = 46569.1445

Independent Variables

wing loading [lb/sqft]	=	70.386
wing aspect ratio	=	8.300
wing quarter chord sweep angle [degrees]	=	14.500
wing taper ratio	=	.200
canard aspect ratio	=	5.500
canard quarter chord sweep angle [degrees]	=	15.000
canard taper ratio	=	.500
canard incidence angle [degrees]	=	2.000
horizontal tail aspect ratio	=	4.000
horizontal tail quarter chord sweep angle [degrees]	=	27.500
vertical tail aspect ratio	=	1.000
vertical tail quarter chord sweep angle [degrees]	=	50.500
canard over wing area ratio	=	.145
engine c.g. location as a fraction of fuselage length	=	.750

Constraint Functions

FAR 25 take-off distance [ft]	=	4666.874
FAR 25 landing distance [ft]	=	3943.885
approach speed [knots],EAS	=	107.605
cruise Mach number	=	.793

Convergence Point

icallf = 3 nfe = 255 d.o.c. [\$/NM] = 2.6164

Merit Function
 weight [Lb] = 44580.5117

Independent Variables

wing loading [lb/sqft]	=	92.180
wing aspect ratio	=	9.331
wing quarter chord sweep angle [degrees]	=	18.556
wing taper ratio	=	.160
canard aspect ratio	=	6.694
canard quarter chord sweep angle [degrees]	=	15.930
canard taper ratio	=	.552
canard incidence angle [degrees]	=	2.146
horizontal tail aspect ratio	=	3.975
horizontal tail quarter chord sweep angle [degrees]	=	33.387
vertical tail aspect ratio	=	1.058
vertical tail quarter chord sweep angle [degrees]	=	46.045
canard over wing area ratio	=	.148
engine c.g. location as a fraction of fuselage length	=	.825

Constraint Functions

FAR 25 take-off distance [ft]	=	6023.916
FAR 25 landing distance [ft]	=	4934.055
approach speed [knots],EAS	=	123.992
cruise Mach number	=	.798

Fig E1 - Relevant Design Optimisation Solutions (continued)

3rd Solution

Convergence type : A
 cpu time : 37:39.55

Initial Point

icallf = 0 nfe = 0 d.o.c. [\$/NM] = 2.7354

Merit Function
 weight [Lb] = 46594.3008

Independent Variables

wing loading [lb/sqft]	=	70.379
wing aspect ratio	=	8.300
wing quarter chord sweep angle [degrees]	=	14.500
wing taper ratio	=	.200
canard aspect ratio	=	5.500
canard quarter chord sweep angle [degrees]	=	15.000
canard taper ratio	=	.500
canard incidence angle [degrees]	=	2.000
horizontal tail aspect ratio	=	4.000
horizontal tail quarter chord sweep angle [degrees]	=	27.500
vertical tail aspect ratio	=	1.000
vertical tail quarter chord sweep angle [degrees]	=	50.500
canard over wing area ratio	=	.145
engine c.g. location as a fraction of fuselage length	=	.750

Constraint Functions

FAR 25 take-off distance [ft]	=	4668.039
FAR 25 landing distance [ft]	=	3943.466
approach speed [knots],EAS	=	107.598
cruise Mach number	=	.793

Convergence Point

icallf = 3 nfe = 474 d.o.c. [\$/NM] = 2.6132

Merit Function
 weight [Lb] = 44585.0195

Independent Variables

wing loading [lb/sqft]	=	91.003
wing aspect ratio	=	8.917
wing quarter chord sweep angle [degrees]	=	19.818
wing taper ratio	=	.198
canard aspect ratio	=	6.224
canard quarter chord sweep angle [degrees]	=	16.453
canard taper ratio	=	.519
canard incidence angle [degrees]	=	2.230
horizontal tail aspect ratio	=	3.835
horizontal tail quarter chord sweep angle [degrees]	=	23.007
vertical tail aspect ratio	=	1.200
vertical tail quarter chord sweep angle [degrees]	=	49.247
canard over wing area ratio	=	.147
engine c.g. location as a fraction of fuselage length	=	.822

Constraint Functions

FAR 25 take-off distance [ft]	=	6023.080
FAR 25 landing distance [ft]	=	4978.010
approach speed [knots],EAS	=	124.623
cruise Mach number	=	.803

Fig E1 - Relevant Design Optimisation Solutions (concluded)

C
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SUBROUTINES USERF & USERD

BY

J.NUNES

1993

College of Aeronautics

CRANFIELD INSTITUTE OF TECHNOLOGY

SUBROUTINE USERF(x,func,iocode,nprob,icallf,nfe)

integer iocode(76)
real x(50),func(76)

C Variable declarations:

.....
.....

C Common Block declarations:

.....
.....

C Assignment of the Independent Variable values:

WGS = X(1)
AR = X(2)
DLMC4 = X(3)
SLM = X(4)
ARHT = X(5)
DWPQCH = X(6)
ARVT = X(7)
DWPQCV = X(8)
ARcan = X(9)
DwpqCa = X(10)
SLMcan = X(11)
EYEcan = X(12)
SWcOSW = X(13)
RELP = X(14)

C Execution of the Design Synthesis subroutine.

CALL MAIN(icallf,nfe)

C Objective Function:

FUNC(1) = DATOUT(133)

C Inequality Constraints:

FUNC(2) = 6000. - DATOUT(92)
FUNC(3) = 5000. - DATOUT(49)
FUNC(4) = 125. - DATOUT(51)
FUNC(5) = DATOUT(109) - .76
FUNC(6) = .86 - DATOUT(109)

DO I=2,6
FUNC(I) = -FUNC(I)

Fig E2 - USERF.F and USERD.F subroutines used for the Direct Operating Cost optimisation cases

```
END DO

RETURN
END

SUBROUTINE USERD(x,gradcd,iocode,nprob)

integer iocode(76)
real x(50),gradcd(50)

WRITE(2,100)
100 . FORMAT( 'SUBROUTINE USERD CALLED, NO DERIVATIVES AVAILABLE')
END
```

Fig E2 - USERF.F and USERD.F subroutines used for the Direct Operating Cost optimisation cases (concluded)

*....data for 50 Pax turbofan airliner

```

VARIABLES
01 1 95.0          83.000          80.000          105.000
02 1  9.0          8.300           8.000           10.000
03 1 23.0          14.500          11.000          35.000
04 1  .235         .200            .160            .310
05 1  4.0          4.000           3.800           4.300
06 1 27.5          27.500          20.000          35.000
07 1  1.0          1.000           .800            1.200
08 1 46.5          50.500          40.000          53.000
09 0  6.0          5.500           4.000           8.000
10 0 23.0          15.000          10.000          35.000
11 0  .43          .500            .160            .700
12 0  1.5          2.000           .000            3.000
13 0  .15          .15             .145            .175
14 0  .8           .75             .75             .85
FUNCTIONS
01 00 00  3.0          1
02 -1 00 6000.0
03 -1 00 5000.0
04 -1 00 120.0
05 -1 00  .8
06 -1 00  .8
CONTROLS
XTOLU = .0001
XTOLV = .0001
OFRM = 1
OFREQ = 10
RFREQ = 50
NFEMAX = 20000
RUN
END

```

Fig E3 - RQPMIN.DAT file for the Conventional D.O.C. optimisation case

!Program RQPMIN Version 1.0 for VAX

ANALYSIS OF INPUT FILE DATA AND CONTROL PARAMETERS

Input file: rqpmin.dat
Output file: rqpmin.res

Variable data

Number of variables = 14

Index	Status	Scale	Starting value	Lower bound	Upper bound
1	1	.9500000E+02	.8736842E+00	.8421053E+00	.1105263E+01
2	1	.9000000E+01	.9222223E+00	.8888889E+00	.1111111E+01
3	1	.2300000E+02	.6304348E+00	.4782608E+00	.1521739E+01
4	1	.2350000E+00	.8510638E+00	.6808510E+00	.1319149E+01
5	1	.4000000E+01	.1000000E+01	.9500000E+00	.1075000E+01
6	1	.2750000E+02	.1000000E+01	.7272727E+00	.1272727E+01
7	1	.1000000E+01	.1000000E+01	.8000000E+00	.1200000E+01
8	1	.4650000E+02	.1086022E+01	.8602151E+00	.1139785E+01
9	0	.6000000E+01	.9166667E+00	.6666667E+00	.1333333E+01
10	0	.2300000E+02	.6521739E+00	.4347826E+00	.1521739E+01
11	0	.4300000E+00	.1162791E+01	.3720930E+00	.1627907E+01
12	0	.1500000E+01	.1333333E+01	.0000000E+00	.2000000E+01
13	0	.1500000E+00	.1000000E+01	.9666666E+00	.1166667E+01
14	0	.8000000E+00	.9375000E+00	.9375000E+00	.1062500E+01

Problem function data

Number of constraints = 5

Index	Status	Type	Scale	Index	Status	Type	Scale
1	0	0	.3000000E+01	2	-1	0	.6000000E+04
3	-1	0	.5000000E+04	4	-1	0	.1200000E+03
5	-1	0	.8000000E+00	6	-1	0	.8000000E+00

objective is function 1 problem number = 1

Control parameters

nfemax = 20000 nimax = 1000 nsmax = 20
nsetc = 4 nsetcf = 8 nsetv = 4 nsetvf = 8
ofreq = 10 ofrom = 1 rfreq = 50 rfrom = 1

centrl = F fdset = F norep = F cheats = T fast = T quasi = T
fixrp = F timid = F monitr = F nofreq = F yesbc = F shrnk = T projct = T

xtol = .1000000E-05 xtolu = .1000000E-03 xtolv = .1000000E-03 gtol = .1000000E-02
rtol = .1000000E+00 omegar = .1000000E+00 rpmax = .2000000E+00
umin = .1000000E-05 vminf = .1000000E-02 vminc = .1000000E-05 ctol = .1000000E-02
umax = .1000000E+00 vmax = .1000000E+00 omega = .1000000E+00 mu = .1000000E-03
bdtol = .1000000E+00 lmtol = .1000000E+00 mtol = .5000000E+00 cmax = .1000000E-01
subtol = .1000000E-02 qrtol = .1000000E+02 bstol = .1000000E-05 diftol = .5000000E-03
stol = .1000000E-29

End of input data

!Program RQPMIN Version 1.0 for VAX

STARTING POINT

free variables

1 .8736842E+00 2 .9222223E+00 3 .6304348E+00 4 .8510638E+00 5 .1000000E+01 6 .1000000E+01 7 .1000000E+01
8 .1086022E+01

objective function

f(x) = .9301342E+00

inactive inequality constraints

2 -.2276705E+00 3 -.1966485E+00 4 -.1322241E+00 5 -.4364401E-01 6 -.8135602E-01
!Program RQPMIN Version 1.0 for VAX 16-Feb-94

end of iteration number 1

end of a successful minimization step
one or more variables fixed on their bounds
number of calls made to user function so far = 18

Fig E4 - RQPMIN.RES file for the Conventional D.O.C. optimisation case

```

free variables
-----
 1  .8736842E+00  2  .9311035E+00  3  .6295375E+00  4  .8493608E+00  5  .1001428E+01  6  .9994873E+00  7  .1001758E+01

variables fixed at or near their upper bounds
-----
 8  .1139785E+0_

objective function
-----
f(x) =  .9276107E+00

inactive inequality constraints
-----
 2  -.2278682E+00  3  -.1980603E+00  4  -.1332310E+00  5  -.4590059E-01  6  -.7901944E-01

Partial derivatives of Lagrangian function
-----
 1  -.1035213E+01  2  .4851818E-01  3  .1358986E-01  4  .2229214E-01  5  .4729032E+00  6  .6914138E-02  7  -.2348423E-01
 8  .8585452E+00

convergence criteria
-----
pdatum = .9276107E+00  ldatum = .9276107E+00  gdatum = .0000000E+00
nu      = .0000000E+00  numax  = infinite
unormx  = .0000000E+00  unormd = .0000000E+00  rtol   = .1000000E+00  xtolu  = .1000000E-03
vnormx  = .6999969E+00  vnorm  = .1000000E+00  xtoly  = .1000000E-03  grdldn = .1035213E+01
nde     = 0             ndef   = 2             ndec   = 0             ncalls = 4             nfuncs = 2
1Program RQPMIN Version 1.0 for VAX

end of iteration number 11
-----

end of a successful minimization step
one or more variables fixed on their bounds
number of calls made to user function so far = 249

free variables
-----
 5  .1003972E+01  2  .9842719E+00  3  .6453965E+00  4  .8434670E+00  7  .9974220E+00  6  .9884853E+00

variables fixed at or near their upper bounds
-----
 8  .1139785E+01  1  .1105263E+01

objective function
-----
f(x) =  .8741906E+00

inactive inequality constraints
-----
 2  -.8674577E-01  3  -.3816914E-01  4  -.2350896E-01  5  -.8725725E-01  6  -.3774278E-01

Partial derivatives of Lagrangian function
-----
 5  .6669760E-01  2  .2850890E+00  3  .1919269E+00  4  -.2670288E-01  7  -.1195669E+00  6  .3973841E+00  8  -.2726912E+00
 1  .2765655E-01

convergence criteria
-----
pdatum = .8741906E+00  ldatum = .8741906E+00  gdatum = .0000000E+00
nu      = .0000000E+00  numax  = infinite
unormx  = .0000000E+00  unormd = .0000000E+00  rtol   = .1000000E+00  xtolu  = .1000000E-03
vnormx  = .5421638E+00  vnorm  = .1000000E+00  xtoly  = .1000000E-03  grdldn = .3973841E+00
nde     = 0             ndef   = 24            ndec   = 2             ncalls = 51            nfuncs = 25
1Program RQPMIN Version 1.0 for VAX 16-Feb-94

end of iteration number 19
-----

CONVERGENCE DETECTED [ Code B ] after 760 calls to user routine

```

Fig E4 - RQPMIN.RES file for the Conventional D.O.C. optimisation case (continued)


```

free variables
-----
 5  .1038232E+01  2  .9865924E+00  3  .6468687E+00  4  .8411893E+00  7  .1011612E+01  6  .9182830E+00  8  .1133873E+01
 1  .1105263E+01

objective function
-----
f(x) =  .8734975E+00

inactive inequality constraints
-----
 2  -.8738843E-01  3  -.3849024E-01  4  -.2372239E-01  5  -.8806892E-01  6  -.3693111E-01

Partial derivatives of Lagrangian function
-----
 5  .3544688E+00  2  .9655952E-02  3  -.1156330E+00  4  .2655983E+00  7  .4523992E-01  6  .1238584E+00  8  -.8141994E-01
 1  .2880096E+00

convergence criteria
-----
pdatum =  .8734975E+00  ldatum =  .8734975E+00  gdatum =  .0000000E+00
nu      =  .0000000E+00  numax  =  infinite
unormx =  .0000000E+00  unormd =  .0000000E+00  rtol   =  .1000000E+00  xtolu  =  .1000000E-03
vnormx =  .3544688E+00  vnorm  =  .1000000E+00  xtolv  =  .1000000E-03  grdlidn =  .3544688E+00
nde    =  0      ndef   =  24      ndec   =  32      ncalls =  112      nfuncs =  56

```

Fig E4 - RQPMIN.RES file for the Conventional D.O.C. optimisation case (concluded)

50 PAX TURBOFAN AIRLINER USING SCALED GE CP-34 - CONVENTIONAL CONFIG.
ENGINE CYCLE IS G. E. CP-34
INPUT DATA FOLLOW

```

0
0 CONFIG WG = 44050.          *****GEOMETRY*****
      WGS = 105.000         KWRITE = 2          FUSEL SAB = 4.          ELODN = 1.000
      PAX = 50.             IGEAR = 0          WS = 20.000         ELOOT = 3.200
      EMCRU = .800          KCONFG = 0         AS = 1.             BMLOD = 14.500
      HNCRU = 35000.        KTIPI = 0         WAS = 19.000        NACELLE KNAC = 1
      Kanard = 0            ENP = 2.           PS = 31.0           ELN = 11.848
      Kcanard = 0           MTYE = 7          ELPC = 11.220       DBARN = 3.949
      Kcanard = 0           KPLOT = 1         HCK = 2.470         ELRW = 10.000

0 WING TCT = .100          HORIZ VBARHX = .0000  VERT VBARVX = .0000  Canard TCcan = .100
      TCR = .130          TAIL TCNT = .100    TAIL TCVT = .120    ARcan = 5.500
      AR = 8.879          ARHT = 4.153       ARVT = 1.012       SLMcan = .500
      SLM = .198          SLMH = .887        SLMV = .700        DwpqCa = 15.000
      DIMC4 = 14.878      DWPOCH = 25.253   DWPOCV = 52.725    EYecan = 2.000
      EYEW = 2.000       COELTH = 1.000    BOELTV = .000      Swc05W = .150

0
0      *          *****AERODYNAMICS*****
      CKM = -1.000        CKMT = -1.000      GRPE = .000         DCDSE = -1.0000
      CKF = -1.000        CKTP = -1.000      SCFAC = .750        CKMc = 2.497
      CKN = -1.000        DELCD = .00150     DLSSW = .000        cmacw = -.060
      CRVT = -1.000       DELPE = .200       ALPHLO = -1.600     alzerc = -1.000

0      KWCD = 12
      ACLS = -1.000      -.600  -.400  -.200  .000  .100  .200  .400  .600  .800  1.000  1.200
      ACDCDR = 2.400    1.466  1.221  1.066  1.005  1.000  1.005  1.046  1.138  1.333  1.743  2.718

0      *HIGH LIFT DEVICES*
      RCLMAX = 1.200     FLAPS JFLTYP = 7          LED CLEOC = .000
      ALFLP = 5000.      DFLETO = 15.000        DELLED = .000
      FLAPM = 1.         DFLEPD = 40.000       DCLMLE = .930
      WCFLAP = -1.000    CFOC = .300           DELLEO = 45.000
      BENG0B = .000      STEOB = .750
                        DCINTE = .000
                        DCDOTE = .000
                        DELTEO = .000

0
0      *****PROPULSION*****
      JENGSZ = 2         HPORT = 5000.        RCCRU = 50.000      RMCRTX = .970
      IPART = 1          TDELTO = 36.         XTORQ = 99999.     HSCREQ = 0.
      KODETO = 5         KODECL = 7           SMID = .500        THIN = 0.
      KODETR = 5         KODEAC = 5           HBTB = .437        PR = 1.000

0
0      *****WEIGHTS*****
      SKPEI = .1350      SKY = .1800          SKB = 107.000       SKFB = .0200
      SKLG = .0380      SKZ = .2200          SKCC = 20.000       SKFW = .4300
      SKMG = .8000      SKTL = 1.0000        SKFW = .4300       SKFT = .9790
      SKPES = .3380     SKMW = 133.400       SKSAS = .000       SKWTP = 1.8900
      WPLY = .0          YMG = .2500         EGMRGN = .0000     LCWING = 2
      WPEI = .0          RELP = .7500        CPMRGN = .2000
      WPUL = 1078.3     RELR = .4500        STMGRN = .0000
      UWPAI = 200.0     CATD = 3.           DELP = 8.200       LDCMXI = 8.000
      STRUT = .0000     VMFPSL = 685.0      YP = .0000         ATMOC = 3.160
      DELWPC = .0       WMAC = .0           WPYLON = .0        DELWST = .0
0 ENGINE WENG = .0       UWNAC = 2.287       WPYL = .700        ILQDE = 3.000
      SWSLS = .160

0
0      *STABILITY AND CONTROL*
      KSFixd = 1         STATIC = .100        ZCG = 5.500         CNPAC = .0020
      CMPLPL = 999.000  CHALP = 999.000     TP = .0             ARVTE = -1.000
      CMPLPT = 999.000  CHDEL = 999.000    CXA = .520         RV = .300
      CMPLD = .000     RH = .350           DCMCLP = .000      TAUV = 999.000
                        DEMAX = -25.0      HMING = 0.         RVMCS = .990
                        EYET = .0         dcmcpi = .030     DRMAX = 25.0
                        TAUH = 999.000    rc = .350

0
0      *****PERFORMANCE*****
      TAXI DELTT = .167  XLFMAX = 1.100      DVR = 5.000         TDELTX = 36.000
      TO IFLY = 1       DELTVR = 3.500     UM = .020          HTMAX = 500.000
      THEMAY = 15.000  DVL = 5.000        MUB = .400         NFAIL = 0
      H00 = 3000.      VRAT = 1.10       WTMISN = 0.

0 CLIMB ICLM = 1        CRUISE CRMACH = .800  PRESF = 1.000       FACW1 = .920
      DELH = 1000.     CRALT = 35000.     RCRRQ = 1250.0     ISWING = 0
      VCLMB = .0       ICRAU = 1          OFALT = 25000.     OFEM = .500
0 LAND IILD = 2         ILDGRQ = 99999.    VRATT = 1.300      HAFP = 50.
      TDELD = 36.0     ALTLD = 5000.     RSMX = 1000.       SINKTD = 3.0
      TDELAY = 1.0     WLPCT = .9400     TROTID = .000     XLFMx = 1.200
      HTG = 5.5        TIDLE = .0        VTDRAT = 1.1

0
0      *****COST*****
      NCADE = 1          HIR = .005          RI = .300           CMV = .800
      CLIAS = 1993.0    TR = 2.000          OHR = 500.000      CCRW = 0.
      HRI = 4000000.    PRV = .100         CRWOH = 23.000     UCSENG = .000
      CMP = .2          DYR = 15.0         CIMP = 0.          UCSPP = .000
      TBO = 3200.0     SRPM = .0          CP = 0.            ALR = 1.120
      FCSF = .850
  
```

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution

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*****
ITERATION TO BALANCE RANGE
RANGE ERROR, RANGE ERROR MINUS 1 .1790 -.1365
GROSS WGT, GROSS WGT MINUS1 45706.8 47880.4

0 *****
0 FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
  CLMAX VSTALL,KTS FLAP ANGLE LE ANGLE DELTA CL DELTA CD
FLAPS UP 1.3173 165.5 .0 .0 .0000 .0000
T.O. CONFIG 2.3033 120.0 15.0 .0 1.1756 .0429
LDG. CONFIG 3.2957 104.7 40.0 .0 1.9834 .1911

0 DOUBLE SLOTTED FOWLER FLAPS
  OPT ANGLE DELCL AT OPT DELCD AT OPT AREA(FT2) WEIGHT(LB)
FLAPS 30.0 2.2500 .1500 90.1 644.3
0 *****
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
  ANGLE OF ATTACK(DEGREES)= 2.215 LIFT= 44335.6 L/D= 12.669 ALTITUDE= 35000.0 MACH= .8000

1 ENGINE SIZING DATA FOLLOW
*****
OVSTLKT= 111.2 KTS EAS VRAT= 1.100 CLTO= 2.0688
VEND = 250.0 KNOTS EAS
0
ROTATION (TIME= 25.3 AND TAS= 135.1 EAS= 121.2)
LIFTOFF (TIME= 27.4 DIST= 3604.2 TAS= 143.5 EAS= 128.8)
DISTANCE TO 35 FT.= 4944.7 TAS= 158.2 EAS= 141.9 V35/VS= 1.2753
GEAR RETRACTION STARTED AT 33.5 SEC, COMPLETE AT 40.5 SEC
FLAP RETRACTION STARTED AT 43.7 SEC, COMPLETE AT 48.2 SEC
OVSTLKT= 111.2 KTS EAS VRAT= 1.100 CLTO= 2.0688
0 ENGINE OUT PERFORMANCE FOLLOWS
  VEND = 212.7 KNOTS EAS
ENGINE FAILURE (TIME= 23.9 AND TAS= 129.6 EAS= 116.2)
0
ROTATION (TIME= 27.6 AND TAS= 135.1 EAS= 121.2)
LIFTOFF (TIME= 30.6 DIST= 4319.6 TAS= 138.8 EAS= 124.5)
DISTANCE TO 35 FT.= 5991.1 TAS= 140.6 EAS= 126.1 V35/VS= 1.1333

ACCELERATE - STOP DISTANCE = 6227.4 FEET.
0 ENGINE OUT DISTANCE TO 35 FT.= 5991.1 FEET
DALL ENGINE DISTANCE TO 35 FT. (L) = 4944.7 FEET
PAR 25 T.O. DISTANCE (1.15XL) = 5686.3 FEET
ALL ENGINE DISTANCE TO 50 FT. = 5187.3 FEET
0 AT END OF TAKEOFF PHASE
TIME= .013 HRS FUEL USED= 76. LBS WEIGHT= 45631. LBS ALT.= 5500. FT.
0 TAKE OFF RATE OF CLIMB REQUIREMENTS - PAR PART 25
  AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION ALT (FT) VS KEAS V/VS V KTAS GRAD (PCT) R/C (PPM) REQ.R/C (PPM) CL L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT 5000. 111.4 1.1257 139.8 1.968 278.43 1.00 1.984 8.247
2ND SEG: T.O. FLAPS - ONE ENGINE OUT 5250. 111.4 1.2000 149.6 4.140 626.56 363.26 1.745 10.297
FINAL T.O. CRUISE CONFIG - ONE ENG OUT 6500. 152.9 1.2500 218.1 4.668 1030.29 264.86 .853 13.118
APPROACH FLAPS - ONE ENG OUT 5000. 106.7 1.3997 166.5 4.681 788.47 353.74 1.398 11.218
LANDING FLAPS - ALL ENGINES 5000. 97.1 1.3000 140.7 13.961 1987.52 455.55 1.957 7.042

APPROACH FLAP SETTING = 19.8 DEG.

+++ ENGINE-OUT SERVICE CEILING = 22097.6 FT.
BEST RATE OF CLIMB SPEED = 276.2 KTAS
ENGINE-OUT RATE OF CLIMB = 49.6 FPM
WEIGHT AT ALTITUDE = 43878.5 LBS

0 *****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED MACELLES*****
0 PROPELLSION SYSTEM WEIGHTS
ENGINE WEIGHT/ENGINE 1496.0
MACELLE WEIGHT/ENGINE 336.4
PYLON WEIGHT/ENGINE 176.5
PROP OR QFAN .0
GEARBOX .0
SHROUD .0

0 ENGINE POD DIMENSIONS
ENGINE FACE DIAMETER(FT) 3.95
MACELLE LENGTH(FT) 11.86

OVSTLKT= 111.2 KTS EAS VRAT= 1.100 CLTO= 2.0688
VEND = 249.8 KNOTS EAS
0
ROTATION (TIME= 24.1 AND TAS= 135.1 EAS= 121.2)
LIFTOFF (TIME= 26.2 DIST= 3451.2 TAS= 143.9 EAS= 129.1)
DISTANCE TO 35 FT.= 4789.4 TAS= 159.5 EAS= 143.0 V35/VS= 1.2860
GEAR RETRACTION STARTED AT 32.3 SEC, COMPLETE AT 39.3 SEC
FLAP RETRACTION STARTED AT 42.4 SEC, COMPLETE AT 46.9 SEC
OVSTLKT= 111.2 KTS EAS VRAT= 1.100 CLTO= 2.0688
0 ENGINE OUT PERFORMANCE FOLLOWS
  VEND = 207.3 KNOTS EAS
ENGINE FAILURE (TIME= 22.8 AND TAS= 129.6 EAS= 116.2)
0
ROTATION (TIME= 26.0 AND TAS= 135.1 EAS= 121.2)
LIFTOFF (TIME= 29.0 DIST= 4078.5 TAS= 139.1 EAS= 124.8)
DISTANCE TO 35 FT.= 5580.5 TAS= 141.2 EAS= 126.6 V35/VS= 1.1378

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Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution (continued)

ACCELERATE - STOP DISTANCE = 6101.6 FEET.
 O ENGINE OUT DISTANCE TO 35 FT.= 5580.5 FEET
 OALL ENGINE DISTANCE TO 35 FT. (L) = 4789.4 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 5507.8 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 5034.4 FEET
 O AT END OF TAKEOFF PHASE
 TIME= .012 HRS FUEL USED= 77. LBS WEIGHT= 45630. LBS ALT.= 5500. FT.
 O TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	VS KEAS	V/VVS	V KTAS	GRAD (PCT)	R/C (PPM)	REQ.R/C (PPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	111.4	1.1257	139.8	2.312	326.96	1.00	1.984	8.068
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	111.4	1.2000	149.6	4.457	674.55	363.26	1.745	10.004
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	152.9	1.2500	218.1	4.726	1043.12	264.86	.853	12.348
APPROACH FLAPS -ONE ENG OUT	5000.	106.7	1.3997	166.5	4.946	833.20	353.74	1.398	10.823
LANDING FLAPS - ALL ENGINES	5000.	97.1	1.3000	140.7	15.101	2149.73	455.55	1.957	7.001

APPROACH FLAP SETTING = 19.8 DEG.

+++ ENGINE-OUT SERVICE CEILING = 22627.0 FT.
 BEST RATE OF CLIMB SPEED = 277.6 KTAS
 ENGINE-OUT RATE OF CLIMB = 50.0 PPM
 WEIGHT AT ALTITUDE = 43878.5 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 382.59

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R;ALT= 5000.) SLS AIRFLOW= 382.59

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 9756.0 LBS

OPROPULSION SYSTEM WEIGHTS
 ENGINE WEIGHT/ENGINE 1561.0
 NACELLE WEIGHT/ENGINE 336.4
 FYLON WEIGHT/ENGINE 181.1
 PROP OR OPAN .0
 GEARBOX .0
 SHROUD .0

ENGINE POD DIMENSIONS
 ENGINE FACE DIAMETER(FT) 3.95
 NACELLE LENGTH(FT) 11.86

0*****

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution (continued)

---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---

	MOST FWD LOAD		MOST AFT LOAD		DESIGN LOAD	
	WT	CG	WT	CG	WT	CG
A/C OWE	26632.33	43.75	26632.33	43.75	26632.33	43.75
PAX	6120.00		2040.00		8500.00	
BAGGAGE	.00	56.36	1500.00	56.36	1500.00	56.36
WING FUEL	1370.17	44.55	6850.87	44.55	6850.87	44.55
TIP FUEL	.00	.00	.00	.00	.00	.00
FUS FUEL	.00	44.55	.00	44.55	2223.61	44.55
TOTAL	34122.50	41.32	37023.20	44.65	45706.80	43.00

0 ---TAIL SIZING SUMMARY---

Static Longitudinal Stability, Stick-fixed, considered

CONDITION	ALPHA	WING		CMac	CANARD		TAIL		DOWN WASH	FLAP CM
		CL	CLA		ALPHA	CLA	CLA	EFF.		
CRUISE	2.3333	.4694	.1193	-.0600	.0000	.0000	.0792	1.0000		
LIFTOFF	2.0000	1.4887	.0665	-.0600	.0000	.0000	.0653	1.0000	.3417	-.1031
LANDING	13.7355	3.2957	.0856	-.0600	.0000	.0000	.0653	1.0000	2.3468	-.2000

CONDITION	--FUSELAGE--		---NACELLE---		-----POWER-----			CT	L.GEAR ROT.POWER	
	DCM	CM	DCM	CM	DCMth	DCMfinc	CMdth		CMfinc	CM
CRUISE	.5211		.1250		.0000	.0300			.0000	
LIFTOFF	.9347	.0000	.1250	.0000			.0000	.0447	.0000	-.7071 5.5738
LANDING	.7267	.7297	.1250	.1255			.0000	.0989		

0 ELEVATOR PARAMETERS
 CMDELTA(CONTROL POWER) = -.06425 WING DE/DALPHA = .34172
 TAUH(EFFECTIVENESS) = .48250
 DEMAX(MAX.ELEVATOR DEPLEC.) = -25.00000

	FRACTION	STATION (DATUM NOSE)	HORIZONTAL TAIL SIZES	
			MAC	
NEUTRAL POINT	.4650	45.211	STATIC STABILITY AND LANDING TRIM	161.6600
STATIC MARGIN	.1000		STATIC STABILITY AND LIFTOFF ROT.	165.0607
AFT CG LIMIT(STABILITY)	.3650	44.406		
CG RANGE(LOADING)	.4130		REQUIRED TAIL SIZE	165.0607
FWD CG LIMIT(CONTROL)	-.0481	41.069	TAIL ARM(ELTH)	44.1978

0 VERTICAL TAIL AREA = 99.7735 FOR DIRECTIONAL STABILITY OF .00200
 0 RUDDER POWER AT MAX.DEFL.= .0180 PER DEG. RUDDER CL AT MAX.DEFL.= .4491
 0 VERTICAL TAIL AREA= 89.6395 FOR MINIMUM CONTROL SPEED = 110.10 KTS
 0 REQUIRED VERTICAL TAIL AREA = 99.7735 TAIL ARM(ELTV) = 33.1082

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
 ANGLE OF ATTACK(DEGREES)= 2.215 LIFT= 44335.6 L/D= 12.153 ALTITUDE= 35000.0 MACH= .8000

0 WING LOCATION INFO.			
FUSELAGE LENGTH =	79.25	H-TAIL VOL. ARM =	44.20
WING 1/4C LOC.ON C.L.=	40.38	H-TAIL C.G.LOCATION =	88.29
MAC 1/4C LOCATION =	43.59	H-TAIL MAC FROM C.L. =	6.41
MAC DIST.FROM C.L. =	12.07	H-TAIL LOCAT ON VERT.=	1.00
WING C.G.LOCATION =	45.20	V-TAIL VOL. ARM =	33.11
TIP TANKS C.G.LOCATE =	.00	V-TAIL C.G.LOCATION =	77.50
		DIST.L.E.VERT.TO L.E.HORZ.=	1.50

	WING	H-TAIL	V-TAIL
AREA	435.303	165.061	99.774
SPAN	62.171	26.182	10.046
ASPECT RATIO	8.879	4.153	1.012
TAPER RATIO	.198	.887	.700
1/4C. SWEEP	14.878	25.253	52.725
L.E. SWEEP	18.835	25.924	54.483
C.L. CHORD	11.692	6.682	11.684
MEAN CHORD	8.049	6.312	10.034
TIP CHORD	2.311	5.927	8.179

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution (continued)

MISSION PERFORMANCE DATA FOLLOWS

0 TAXI AT IDLE THRUST

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	FUEL FLOW (LB/HR)
.000	0.	0.	45707.	5000.	892.
.167	0.	149.	45558.	5000.	892.

OVSTLKT= 111.0 KTS EAS VRAT= 1.100 CLTO= 2.0688
 VEND = 250.0 KNOTS EAS
 (TEMP.= 537. DEG:STD.+36.)
 0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (PPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	148.5	45558.	5000.0	.0	.0	.000	11.57	1.4863	.1309	2.00	.00	.0	.00	17303.	6162.	.00
1.0	5.8	150.2	45557.	5000.0	6.8	6.1	.010	11.41	1.4863	.1309	2.00	.00	.0	.00	17085.	6162.	.00
2.0	23.0	152.0	45555.	5000.0	13.5	12.2	.020	11.25	1.4864	.1309	2.00	.00	.0	.00	16871.	6163.	.00
3.0	51.5	153.7	45553.	5000.0	20.2	18.1	.030	11.08	1.4864	.1309	2.00	.00	.0	.00	16660.	6164.	.00
4.0	91.1	155.4	45551.	5000.0	26.7	24.0	.040	10.91	1.4865	.1309	2.00	.00	.0	.00	16454.	6165.	.00
5.0	141.6	157.1	45550.	5000.0	33.1	29.7	.049	10.74	1.4866	.1309	2.00	.00	.0	.00	16251.	6167.	.00
6.0	203.0	158.8	45548.	5000.0	39.5	35.4	.059	10.56	1.4867	.1309	2.00	.00	.0	.00	16052.	6169.	.00
7.0	274.9	160.5	45546.	5000.0	45.7	41.0	.068	10.37	1.4868	.1310	2.00	.00	.0	.00	15855.	6172.	.00
8.0	357.2	162.2	45545.	5000.0	51.8	46.5	.077	10.19	1.4870	.1310	2.00	.00	.0	.00	15662.	6174.	.00
9.0	449.8	164.0	45543.	5000.0	57.8	51.8	.086	10.00	1.4872	.1310	2.00	.00	.0	.00	15473.	6176.	.00
10.0	552.4	165.7	45541.	5000.0	63.7	57.1	.095	9.81	1.4873	.1310	2.00	.00	.0	.00	15288.	6179.	.00
11.0	664.9	167.4	45539.	5000.0	69.5	62.3	.103	9.63	1.4875	.1310	2.00	.00	.0	.00	15120.	6182.	.00
12.0	787.0	169.1	45538.	5000.0	75.1	67.4	.112	9.46	1.4877	.1310	2.00	.00	.0	.00	14982.	6186.	.00
13.0	918.6	170.8	45536.	5000.0	80.7	72.4	.120	9.29	1.4880	.1310	2.00	.00	.0	.00	14847.	6189.	.00
14.0	1059.5	172.5	45534.	5000.0	86.2	77.3	.128	9.12	1.4882	.1311	2.00	.00	.0	.00	14713.	6193.	.00
15.0	1209.6	174.3	45532.	5000.0	91.5	82.1	.136	8.94	1.4885	.1311	2.00	.00	.0	.00	14583.	6196.	.00
16.0	1368.6	176.0	45531.	5000.0	96.8	86.8	.144	8.77	1.4887	.1311	2.00	.00	.0	.00	14455.	6200.	.00
17.0	1536.5	177.7	45529.	5000.0	102.0	91.5	.151	8.59	1.4890	.1311	2.00	.00	.0	.00	14329.	6204.	.00
18.0	1713.0	179.4	45527.	5000.0	107.0	96.0	.159	8.42	1.4893	.1311	2.00	.00	.0	.00	14206.	6209.	.00
19.0	1897.9	181.2	45526.	5000.0	112.0	100.4	.166	8.24	1.4895	.1312	2.00	.00	.0	.00	14086.	6213.	.00
20.0	2091.1	182.9	45524.	5000.0	116.8	104.8	.173	8.06	1.4898	.1312	2.00	.00	.0	.00	13968.	6217.	.00
21.0	2292.4	184.6	45522.	5000.0	121.6	109.1	.180	7.89	1.4901	.1312	2.00	.00	.0	.00	13852.	6222.	.00
22.0	2501.7	186.3	45520.	5000.0	126.2	113.2	.187	7.71	1.4904	.1312	2.00	.00	.0	.00	13739.	6226.	.00
23.0	2718.7	188.1	45519.	5000.0	130.7	117.3	.194	7.53	1.4907	.1313	2.00	.00	.0	.00	13628.	6231.	.00
24.0	2943.2	189.8	45517.	5000.0	135.2	121.2	.201	7.36	1.4911	.1313	2.00	.00	.0	.00	13523.	6235.	.00

0 ROTATION (TIME= 23.9 AND TAS= 134.9 EAS= 121.0)
 25.0 3175.1 191.5 45515. 5000.0 139.5 125.1 .207 7.06 1.6315 .1429 3.67 .00 .0 .83 13446. 6240. 1.67
 26.0 3414.1 193.3 45513. 5000.0 143.5 128.8 .213 6.69 1.7966 .1577 5.70 .00 .0 .97 13373. 6244. 3.70

LIPTOFF (TIME= 26.0 DIST= 3414.1 TAS= 143.5 EAS= 128.8)
 27.0 3659.9 195.0 45512. 5000.4 147.4 132.2 .219 6.14 1.9022 .1687 7.02 .30 77.0 1.09 13304. 6249. 5.31
 28.0 3911.8 196.7 45510. 5003.3 150.9 135.3 .224 5.52 1.8264 .1699 5.92 1.01 270.4 1.10 13241. 6252. 4.93
 29.0 4169.1 198.5 45508. 5009.4 153.9 138.1 .229 4.89 1.7658 .1760 5.12 1.71 465.5 1.10 13184. 6255. 4.83
 30.0 4431.3 200.2 45507. 5018.8 156.7 140.5 .233 4.25 1.7041 .1781 4.42 2.39 661.8 1.10 13133. 6257. 4.81
 31.0 4697.6 202.0 45505. 5031.5 159.0 142.6 .236 3.74 1.6583 .1776 3.92 3.07 862.4 1.10 13087. 6258. 4.98

DISTANCE TO 35 FT.= 4761.5 TAS= 159.6 EAS= 143.1 V35/V30= 1.2883
 32.0 4967.6 203.7 45503. 5047.5 161.2 144.5 .239 3.31 1.6135 .1741 3.42 3.73 1063.0 1.10 13046. 6258. 5.15

GEAR RETRACTION STARTED AT 32.1 SEC, COMPLETE AT 39.1 SEC
 33.0 5240.7 205.4 45501. 5066.9 163.0 146.1 .242 3.00 1.5783 .1667 3.02 4.38 1261.9 1.10 13007. 6258. 5.40
 34.0 5516.6 207.2 45500. 5089.6 164.8 147.6 .245 2.74 1.5435 .1580 2.62 5.02 1461.3 1.09 12971. 6257. 5.64
 35.0 5795.0 208.9 45498. 5115.6 166.3 148.9 .247 2.47 1.5176 .1504 2.32 5.65 1659.7 1.10 12937. 6255. 5.97
 36.0 6075.6 210.6 45496. 5144.9 167.7 150.1 .249 2.23 1.4916 .1427 2.02 6.28 1858.0 1.09 12906. 6253. 6.29
 37.0 6358.1 212.4 45494. 5177.5 169.0 151.2 .251 1.97 1.4743 .1362 1.82 6.89 2054.8 1.10 12875. 6250. 6.71
 38.0 6642.2 214.1 45493. 5213.4 170.1 152.1 .253 1.73 1.4569 .1297 1.62 7.51 2252.7 1.10 12847. 6247. 7.13
 39.0 6927.7 215.8 45491. 5252.6 171.1 152.9 .254 1.49 1.4395 .1232 1.42 8.12 2449.7 1.10 12821. 6243. 7.54
 40.0 7214.3 217.6 45489. 5295.1 171.9 153.5 .255 1.17 1.4221 .1207 1.22 8.73 2644.1 1.09 12797. 6238. 7.95
 41.0 7501.6 219.3 45487. 5340.7 172.5 154.0 .256 .83 1.4134 .1198 1.12 9.33 2833.2 1.10 12776. 6232. 8.44
 42.0 7789.2 221.0 45486. 5389.5 172.9 154.2 .257 .50 1.4047 .1189 1.02 9.93 3021.1 1.09 12757. 6226. 8.94

FLAP RETRACTION STARTED AT 42.2 SEC, COMPLETE AT 46.7 SEC
 43.0 8076.9 222.8 45484. 5441.1 173.2 154.3 .257 .35 1.2501 .1173 1.62 10.25 3122.8 .98 12741. 6219. 9.87
 44.0 8365.0 224.5 45482. 5492.3 173.4 154.4 .258 .27 1.1465 .1293 3.42 9.83 3001.0 .91 12726. 6212. 11.25

OVSTLKT= 111.0 KTS EAS VRAT= 1.100 CLTO= 2.0688
 0 ENGINE OUT PERFORMANCE FOLLOWS
 VEND = 207.1 KNOTS EAS
 (TEMP.= 537. DEG:STD.+36.)
 0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (PPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	148.5	45558.	5000.0	.0	.0	.000	11.57	1.4863	.1309	2.00	.00	.0	.00	17303.	6162.	.00
1.0	5.8	150.2	45557.	5000.0	6.8	6.1	.010	11.41	1.4863	.1309	2.00	.00	.0	.00	17085.	6162.	.00
2.0	23.0	152.0	45555.	5000.0	13.5	12.2	.020	11.25	1.4864	.1309	2.00	.00	.0	.00	16871.	6163.	.00
3.0	51.5	153.7	45553.	5000.0	20.2	18.1	.030	11.08	1.4864	.1309	2.00	.00	.0	.00	16660.	6164.	.00
4.0	91.1	155.4	45551.	5000.0	26.7	24.0	.040	10.91	1.4865	.1309	2.00	.00	.0	.00	16454.	6165.	.00
5.0	141.6	157.1	45550.	5000.0	33.1	29.7	.049	10.74	1.4866	.1309	2.00	.00	.0	.00	16251.	6167.	.00
6.0	203.0	158.8	45548.	5000.0	39.5	35.4	.059	10.56	1.4867	.1309	2.00	.00	.0	.00	16052.	6169.	.00
7.0	274.9	160.5	45546.	5000.0	45.7	41.0	.068	10.37	1.4868	.1310	2.00	.00	.0	.00	15855.	6172.	.00
8.0	357.2	162.2	45545.	5000.0	51.8	46.5	.077	10.19	1.4870	.1310	2.00	.00	.0	.00	15662.	6174.	.00
9.0	449.8	164.0	45543.	5000.0	57.8	51.8	.086	10.00	1.4872	.1310	2.00	.00	.0	.00	15473.	6176.	.00
10.0	552.4	165.7	45541.	5000.0	63.7	57.1	.095	9.81	1.4873	.1310	2.00	.00	.0	.00	15288.	6179.	.00
11.0	664.9	167.4	45539.	5000.0	69.5	62.3	.103	9.63	1.4875	.1310	2.00	.00	.0	.00	15120.	6182.	.00
12.0	787.0	169.1	45538.	5000.0	75.1	67.4	.112	9.46	1.4877	.1310	2.00	.00	.0	.00	14982.	6186.	.00
13.0	918.6	170.8	45536.	5000.0	80.7	72.4	.120	9.29	1.4880	.1310	2.00	.00	.0	.00	14847.	6189.	.00
14.0	1059.5	172.5	45534.	5000.0	86.2	77.3	.128	9.12	1.4882	.1311	2.00	.00	.0	.00	14713.	6193.	.00
15.0	1209.6	174.3	45532.	5000.0	91.5	82.1	.136	8.94	1.4885	.1311	2.00	.00	.0	.00	14583.	6196.	.00
16.0	1368.6	176.0	45531.	5000.0	96.8	86.8	.144	8.77	1.4887	.1311	2.00	.00	.0	.00	14455.	6200.	.00
17.0	1536.5	177.7	45529.	5000.0	102.0	91.5	.151	8.59	1.4890	.1311	2.00	.00	.0	.00	14329.	6204.	.00
18.0	1713.0	179.4	45527.	5000.0	107.0	96.0	.159	8.42	1.4893	.1311	2.00	.00	.0	.00	14206.	6209.	.00
19.0	1897.9	181.2	45526.	5000.0	112.0	100.4	.166	8.24	1.4895	.1312	2.00	.00	.0	.00	14086.	6213.	.00
20.0	2091.1	182.9	45524.	5000.0	116.8	104.8	.173	8.06	1.4898	.1312	2.00	.00	.0	.00	13968.	6217.	.00
21.0	2292.4	184.6	45522.	5000.0	121.6	109.1	.180	7.89	1.4901	.1312	2.00	.00	.0	.00	13852.	6222.	.00
22.0	2501.7	186.3	45520.	5000.0	126.2	113.2	.187	7.71	1.4904	.1312	2.00	.00	.0	.00	13739.	6226.	.00

ENGINE FAILURE (TIME= 22.7 AND TAS= 129.4 EAS= 116.0)
 23.0 2718.7 187.9 45519. 5000.0 130.5 117.1 .194 2.59 1.4907 .1407 2.00 .00 .0 .00 6817. 3115. .00
 24.0 2940.2 188.8 45518. 5000.0 132.0 118.4 .196 2.55 1.4909 .1403 2.00 .00 .0 .00 6799. 3116. .00
 25.0 3164.4 189.6 45517. 5000.0 133.5 119.7 .198 2.50 1.4910 .1400 2.00 .00 .0 .00 6781. 3117. .00
 26.0 3391.0 190.5 45516. 5000.0 134.9 121.1 .200 2.46 1.4911 .1397 2.00 .00 .0 .00 6763. 3117. .00

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution
 (continued)

0

ROTATION (TIME=	26.0	AND TAS=	134.9	EAS=	121.0)														
27.0	3620.2	191.4	45515.	5000.0	136.4	122.3	.202	2.29	1.6236	.1504	3.58	.00	.0	.79	6751.	3118.	1.58		
28.0	3851.6	192.2	45515.	5000.0	137.7	123.5	.204	2.06	1.7886	.1649	5.61	.00	.0	.89	6739.	3119.	3.61		
29.0	4085.1	193.1	45514.	5000.0	138.8	124.5	.206	1.81	1.9537	.1807	7.72	.00	.0	.99	6729.	3120.	5.72		
LIFTOFF (TIME=	29.0	DIST=	4085.1	TAS=	138.8	EAS=	124.5)												
30.0	4320.3	194.0	45513.	5000.4	139.8	125.4	.208	1.42	2.0574	.1924	9.06	.26	64.2	1.06	6720.	3120.	7.31		
31.0	4557.0	194.8	45512.	5002.6	140.5	126.0	.209	.88	2.0688	.2032	8.96	.85	211.0	1.08	6714.	3120.	7.81		
32.0	4794.5	195.7	45511.	5007.5	140.8	126.3	.209	.22	2.0688	.2197	8.73	1.51	374.7	1.09	6710.	3120.	8.23		
33.0	5032.2	196.6	45510.	5014.9	140.8	126.3	.209	-.01	1.9508	.2172	7.29	1.97	491.1	1.02	6709.	3120.	7.26		
34.0	5269.9	197.4	45509.	5023.2	140.8	126.3	.209	.01	1.8889	.2159	6.59	1.99	495.1	.99	6708.	3119.	6.57		
35.0	5507.6	198.3	45509.	5031.3	140.8	126.3	.209	-.01	1.8873	.2199	6.59	1.90	472.9	.99	6707.	3118.	6.49		
DISTANCE TO 35 FT.=	5620.7	TAS=	140.8	EAS=	126.3	V35/V30=	1.1370												
36.0	5745.3	199.2	45508.	5039.0	140.8	126.3	.209	.01	1.8863	.2221	6.59	1.80	449.2	.99	6706.	3118.	6.39		
37.0	5983.0	200.0	45507.	5046.3	140.8	126.2	.209	.00	1.8944	.2249	6.69	1.73	430.8	.99	6705.	3117.	6.42		

ACCELERATE - STOP DISTANCE = 6086.0 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT. = 5620.7 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4761.5 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 5475.7 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 5004.8 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .179 HRS FUEL USED= 225. LBS WEIGHT= 45482. LBS ALT.= 5500. FT.

ACCELERATE TO MACH NO. = .418

0

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.179	.00	224.8	45482.	5500.	167.	154.	.258	.702	13019.	6122.
.187	1.88	276.8	45430.	5500.	271.	250.	.418	.800	11135.	6286.

END OF ACCELERATION SEGMENT
 TIME= .187 HRS FUEL USED= 276.8 LBS WEIGHT= 45430. LBS RANGE= 2. NM
 0 CLIMB TO 35000. FT. AT MAXIMUM RATE OF CLIMB

0

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	FUS. ANGLE (DEG)	R/C (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
.187	2.	277.	45430.	5500.	251.	232.	.387	.792	.5680	.0433	4.67	8.18	10.85	3622.	9887.	5534.
.189	2.	289.	45417.	6000.	252.	231.	.389	.791	.5726	.0435	4.72	7.73	10.45	3440.	9800.	5481.
.194	4.	316.	45391.	7000.	261.	235.	.404	.794	.5520	.0423	4.46	6.34	8.80	2923.	9505.	5373.
.200	5.	347.	45360.	8000.	265.	235.	.411	.794	.5533	.0424	4.46	6.85	9.31	3199.	9307.	5254.
.205	7.	374.	45333.	9000.	267.	234.	.417	.793	.5593	.0427	4.51	6.78	9.29	3197.	9123.	5139.
.210	8.	401.	45306.	10000.	270.	232.	.423	.792	.5656	.0431	4.57	6.57	9.14	3129.	8940.	5026.
.216	9.	428.	45279.	11000.	273.	231.	.428	.791	.5716	.0435	4.62	6.77	9.39	3259.	8758.	4917.
.221	11.	453.	45254.	12000.	275.	230.	.434	.790	.5788	.0438	4.69	6.15	8.83	2988.	8576.	4810.
.226	12.	480.	45227.	13000.	278.	228.	.440	.790	.5856	.0442	4.74	5.94	8.68	2916.	8396.	4705.
.232	14.	506.	45200.	14000.	281.	227.	.447	.789	.5908	.0445	4.79	5.67	8.45	2816.	8212.	4603.
.238	15.	534.	45173.	15000.	285.	226.	.455	.789	.5945	.0447	4.81	5.39	8.20	2714.	8025.	4505.
.244	17.	561.	45145.	16000.	291.	227.	.466	.789	.5900	.0445	4.73	4.88	7.74	2510.	7810.	4406.
.251	19.	591.	45116.	17000.	294.	226.	.473	.788	.5959	.0448	4.77	4.96	7.74	2579.	7614.	4296.
.257	21.	618.	45088.	18000.	298.	225.	.481	.788	.6004	.0451	4.80	4.67	7.47	2460.	7416.	4189.
.264	23.	647.	45060.	19000.	302.	225.	.489	.787	.6040	.0453	4.81	4.42	7.23	2358.	7221.	4085.
.271	25.	676.	45031.	20000.	306.	223.	.497	.787	.6097	.0457	4.85	4.26	7.11	2299.	7033.	3983.
.278	27.	705.	45002.	21000.	309.	222.	.505	.786	.6164	.0461	4.90	4.06	6.96	2220.	6851.	3882.
.286	30.	734.	44973.	22000.	313.	221.	.513	.785	.6224	.0465	4.94	3.83	6.77	2118.	6670.	3784.
.294	32.	763.	44943.	23000.	316.	220.	.520	.784	.6306	.0470	5.00	3.68	6.68	2056.	6496.	3686.
.302	35.	793.	44913.	24000.	321.	219.	.530	.784	.6342	.0473	5.00	3.36	6.37	1906.	6317.	3594.
.310	38.	825.	44882.	25000.	328.	220.	.544	.784	.6288	.0469	4.90	2.94	5.84	1701.	6112.	3513.
.320	41.	859.	44848.	26000.	331.	218.	.551	.783	.6390	.0476	4.98	3.05	6.04	1785.	5934.	3425.
.330	44.	891.	44816.	27000.	334.	216.	.559	.782	.6497	.0483	5.06	2.85	5.91	1682.	5760.	3339.
.340	47.	924.	44782.	28000.	365.	232.	.613	.792	.5646	.0430	4.01	1.33	3.33	855.	5479.	3308.
.359	54.	989.	44718.	29000.	368.	230.	.621	.791	.5734	.0436	4.06	2.24	4.30	1458.	5338.	3223.
.370	58.	1026.	44681.	30000.	371.	228.	.630	.790	.5830	.0441	4.12	2.09	4.21	1374.	5198.	3143.
.383	63.	1064.	44643.	31000.	376.	226.	.640	.789	.5908	.0445	4.16	1.86	4.02	1238.	5022.	3040.
.396	68.	1105.	44602.	32000.	380.	225.	.650	.788	.5984	.0450	4.19	1.68	3.87	1126.	4851.	2939.
.411	74.	1148.	44559.	33000.	385.	224.	.662	.787	.6040	.0453	4.19	1.46	3.65	996.	4683.	2843.
.428	80.	1196.	44511.	34000.	391.	223.	.675	.787	.6077	.0456	4.17	1.26	3.43	873.	4519.	2750.
.447	88.	1248.	44458.	35000.	395.	220.	.684	.785	.6201	.0464	4.24	1.20	3.44	837.	4360.	2655.

0 END OF CLIMB TO 35000. FT
 TIME= .447 HRS FUEL USED= 1248. LBS WEIGHT= 44458. LBS RANGE= 88. NM

0 ALTITUDE= 35000. FT TAS= 479.27 KTS MACH NO= .8305

ACCELERATE TO MACH NO. = .800

0

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.447	87.58	1248.2	44458.	35000.	394.	220.	.684	.785	4680.	3009.
.480	102.77	1356.2	44351.	35000.	461.	258.	.800	.805	4765.	3114.

END OF ACCELERATION SEGMENT
 TIME= .480 HRS FUEL USED= 1356.2 LBS WEIGHT= 44351. LBS RANGE= 103. NM

ACCELERATE TO MACH NO. = .830

0

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.447	87.58	1248.2	44458.	35000.	394.	220.	.684	.785	4680.	3009.
.491	108.17	1391.8	44315.	35000.	479.	267.	.830	.809	4792.	3149.

END OF ACCELERATION SEGMENT
 TIME= .491 HRS FUEL USED= 1391.8 LBS WEIGHT= 44315. LBS RANGE= 108. NM

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution (continued)

ACCELERATE TO MACH NO. = .848

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.447	87.58	1248.2	44458.	35000.	394.	220.	.684	.785	4680.	3009.
.497	110.86	1409.2	44297.	35000.	489.	273.	.848	.811	4794.	3171.

END OF ACCELERATION SEGMENT
 TIME= .497 HRS FUEL USED= 1409.2 LBS WEIGHT= 44297. LBS RANGE= 111. NM

DESIGN CASE
 CRUISE PERFORMANCE SUMMARY
 FOR
 ***** DESIGN PAYLOAD *****
 ***** MAXIMUM PAYLOAD *****
 ***** MAXIMUM FUEL *****
 FUEL AVAILABLE= 9074.

TIME	HRS.	AT SPECIFIED		AT NORMAL		AT BEST SPEC.		RANGE	
		START	END	START	END	START	END	START	END
		CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE
		.480	3.035	.491	2.564	.497	2.712		
RANGE	N.MI	103.	1282.	108.	1101.	111.	1195.		
FUEL USED	LBS.	1356.	7274.	1392.	6431.	1409.	7091.		
WEIGHT	LBS.	44351.	38433.	44315.	39276.	44297.	38616.		
ALTITUDE	FT.	35000.	35000.	35000.	35000.	35000.	35000.		
TAS	KTS.	461.7	461.7	479.3	479.3	489.3	489.3		
EAS	KTS.	257.3	257.3	267.1	267.1	272.7	272.7		
MACH NO.		.8000	.8000	.8305	.8305	.8478	.8478		
DIV. MACH		.8055	.8130	.8096	.8171	.8117	.8181		
ANGLE ATTACK	DEG.	2.217	1.707	1.797	1.304	1.575	1.168		
FUSE. ANGLE	DEG.	.217	-.293	-.203	-.696	-.425	-.832		
CL		.4554	.3947	.4223	.3610	.4051	.3531		
L/D		12.155	11.314	11.721	10.776	11.195	10.469		
FUEL FLOW	LB/HR	2400.7	2237.5	2516.6	2351.4	2644.7	2489.3		
BREG. FACTOR	N.MI.	8535.	7935.	8445.	8011.	8200.	7595.		
SPEC. RANGE	NM/LB	.19231	.20634	.19044	.20382	.18500	.19655		

0 DESCENT FROM CRUISE AT NORMAL POWER CONDITION (U=NO CONSTRAINT; R= 500. PPM CABIN; A= -6.00 FUS. ANGLE; S=MMD OR VMD)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ANGLE (DEG)	R/S (FPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
2.576	1107.	6453.	39254.	35000.	479.	268.	.830	.816	.3705	.0337	1.38	-1.58	-2.20	1339.	2491.	1763. R
2.589	1113.	6477.	39230.	34000.	481.	274.	.830	.818	.3533	.0331	1.24	-1.53	-2.29	1306.	2625.	1863. R
2.602	1120.	6503.	39204.	33000.	484.	280.	.830	.820	.3370	.0325	1.11	-1.49	-2.37	1271.	2768.	1968. R
2.615	1126.	6530.	39176.	32000.	486.	287.	.830	.822	.3216	.0320	.99	-1.44	-2.46	1241.	2914.	2078. R
2.629	1133.	6561.	39146.	31000.	488.	294.	.830	.824	.3070	.0316	.87	-1.40	-2.53	1209.	3069.	2194. R
2.643	1140.	6593.	39113.	30000.	490.	300.	.830	.825	.2931	.0312	.76	-1.36	-2.60	1180.	3228.	2314. R
2.658	1147.	6629.	39078.	29000.	492.	307.	.830	.827	.2800	.0308	.65	-1.32	-2.67	1153.	3393.	2439. R
2.673	1154.	6667.	39040.	28000.	494.	314.	.830	.829	.2675	.0305	.55	-1.29	-2.74	1127.	3566.	2570. R
2.688	1162.	6708.	38999.	27000.	496.	321.	.830	.830	.2557	.0302	.46	-1.25	-2.79	1100.	3764.	2715. R
2.703	1170.	6752.	38955.	26000.	498.	328.	.830	.831	.2445	.0299	.37	-1.22	-2.85	1077.	3947.	2856. R
2.719	1178.	6800.	38907.	25000.	500.	336.	.830	.833	.2338	.0296	.28	-1.19	-2.91	1053.	4138.	3003. R
2.735	1186.	6850.	38856.	24000.	502.	343.	.830	.834	.2237	.0294	.20	-1.16	-2.96	1032.	4334.	3155. R
2.752	1194.	6905.	38802.	23000.	505.	350.	.830	.835	.2141	.0292	.12	-1.13	-3.01	1011.	4537.	3313. R
2.768	1203.	6963.	38744.	22000.	503.	355.	.825	.836	.2078	.0291	.09	-1.11	-3.03	992.	4670.	3425. R
2.786	1211.	7022.	38684.	21000.	497.	357.	.812	.836	.2051	.0290	.09	-1.10	-3.01	972.	4730.	3484. R
2.790	1213.	7026.	38681.	20000.	427.	312.	.694	.829	.2677	.0305	.90	-4.90	-6.00	3699.	1079.	781. A
2.795	1215.	7030.	38677.	19000.	422.	314.	.684	.829	.2645	.0304	.89	-4.89	-6.00	3652.	1125.	817. A
2.799	1217.	7034.	38673.	18000.	418.	316.	.674	.829	.2614	.0303	.88	-4.88	-6.00	3606.	1172.	855. A
2.804	1219.	7038.	38669.	17000.	413.	318.	.664	.830	.2583	.0302	.87	-4.87	-6.00	3560.	1222.	895. A
2.809	1221.	7042.	38664.	16000.	409.	320.	.655	.830	.2552	.0301	.86	-4.86	-6.00	3514.	1272.	935. A
2.814	1223.	7047.	38660.	15000.	405.	322.	.646	.831	.2491	.0300	.83	-4.83	-6.00	3469.	1325.	978. A
2.818	1225.	7052.	38655.	14000.	401.	323.	.637	.831	.2460	.0299	.82	-4.82	-6.00	3424.	1379.	1021. A
2.823	1227.	7057.	38650.	13000.	397.	325.	.628	.832	.2430	.0298	.80	-4.80	-6.00	3379.	1435.	1067. A
2.828	1229.	7063.	38644.	12000.	393.	327.	.620	.832	.2400	.0298	.78	-4.78	-6.00	3335.	1493.	1114. A
2.833	1230.	7069.	38638.	11000.	389.	329.	.611	.832	.2370	.0298	.78	-4.78	-6.00	3291.	1552.	1163. A
2.844	1234.	7078.	38629.	10000.	291.	250.	.455	.810	.4171	.0355	2.09	-3.10	-2.21	1595.	1103.	851. S
2.855	1237.	7087.	38620.	9000.	286.	250.	.446	.810	.4170	.0354	2.91	-3.04	-2.13	1540.	1224.	883. S
2.866	1240.	7097.	38609.	8000.	282.	250.	.438	.810	.4169	.0354	2.92	-2.98	-2.06	1486.	1265.	915. S
2.878	1243.	7108.	38598.	7000.	277.	250.	.430	.810	.4168	.0354	2.93	-2.92	-1.98	1433.	1308.	949. S
2.890	1246.	7120.	38586.	6000.	273.	250.	.422	.810	.4167	.0354	2.95	-2.85	-1.91	1379.	1352.	984. S
2.902	1250.	7133.	38574.	5000.	269.	250.	.414	.810	.4166	.0354	2.96	-2.79	-1.83	1327.	1397.	1020. S
2.915	1253.	7147.	38560.	4000.	265.	250.	.406	.810	.4164	.0354	2.97	-2.72	-1.75	1274.	1444.	1057. S
2.929	1257.	7162.	38545.	3000.	261.	250.	.398	.810	.4163	.0354	2.98	-2.64	-1.67	1222.	1493.	1096. S
2.943	1260.	7178.	38529.	2000.	257.	250.	.391	.810	.4161	.0354	2.99	-2.57	-1.58	1171.	1543.	1136. S
2.950	1262.	7186.	38520.	1500.	255.	250.	.388	.810	.4159	.0354	2.99	-2.53	-1.54	1145.	1568.	1157. S

0 END OF DSCNT TO 1500. FT
 TIME= 2.950 HRS FUEL USED= 7186. LBS WEIGHT= 38520. LBS RANGE= 1262. NM

0 RESERVE FUEL(LBS) 1801.
 (45.0 MIN.) 1887.

0 RANGE = 1262. BLOCK TIME= 2.950 USED FOR DESIGN RANGE AND COST

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution
 (continued)


```

0 *****
0      TEMP.= 537. DEG.STD.+36.
      LANDING ELEVATION= 5000. FT.
      LANDING WING LOADING= 98.70 ESP.
      LANDING WEIGHT = 42964. LBS.

      LANDING DISTANCE FROM 50. FT.= 2885. FT.

      F.A.R. FACTORED FIELD LENGTH = 4808. FT.
0      APPROACH      TRANSITION      DELAY      ROLL
0      DIST= 689.    DIST= 201.    DIST= 204.    DIST= 1791.
      R/S= 1000.    XLPX= 1.200  TDELAY= 1.00  MUB= .4000
      VAPEAS= 122.15 SINKTD= 3.000  TIDLE= 638.  TR/TIDLE= .0000
      VAPTAS= 136.30 VSTEA= 93.96  VDTAS= 120.57 ABAR(G)= .3600
      THETA= 4.15    CLMX= 3.2957
      THRUST= 3055.  HPLAR= 20.9
0 *****
0      RANGE OR ENDURANCE ITERATION SUMMARY
      ITERATION      GROSS WEIGHT (LB)      RANGE (NMI) OR
                        ENDURANCE (HR)
      0      44050.00      1079.430
      1      47880.43      1473.778
      2      45706.80      1262.253
      REQUIRED RG. OR END. = 1250.000
0
0      SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
      ANGLE OF ATTACK(DEGREES)= 2.215  LIFT= 44335.6  L/D= 12.153  ALTITUDE= 35000.0  MACH= .8000
0      GROSS WEIGHT = 45707.    PASSENGERS = 50. PLUS CREW
0      FUSELAGE      LENGTH      (ELP)      79.25  FT
                        WIDTH      (SWP)      9.25  FT
                        WETTED AREA (SF)      1910. SQFT
                        DELTA P      (DELP)      8.20  PSI
0      WING      ASPECT RATIO (AR)      8.88
                        AREA      (SW)      435.3  SQFT
                        SPAN      (B)      62.2  FT
                        GEOM. MEAN CHORD (CBARM) 8.05  FT
                        QUARTER CHORD SWEEP (DLMC4) 14.9  DEG
                        TAPER RATIO (SLM)      .198
                        ROOT THICKNESS (TCR)      .130
                        TIP THICKNESS (TCT)      .100
                        WING LOADING (WGS) 105.0  PSF
                        WING FUEL VOLUME (VFW) 1024.5  GAL
0      HOR. TAIL      ASPECT RATIO (ARHT) 4.15
                        AREA      (SHT)      165.1  SQFT
                        SPAN      (BHT)      26.18  FT
                        MEAN CHORD (CBARHT) 6.31  FT
                        THICKNESS/CHORD (TCHT) .100
                        MOMENT ARM (ELTH) 44.2  FT
                        VOLUME COEFF. (VBARH) 2.082
0      VERT. TAIL      ASPECT RATIO (ARVT) 1.01
                        AREA      (SVT)      99.8  SQFT
                        SPAN      (BVT)      10.05  FT
                        MEAN CHORD (CBARVT) 10.03  FT
                        THICKNESS/CHORD (TCVT) .120
                        MOMENT ARM (ELTV) 33.1  FT
                        VOLUME COEFF. (VBARV) .122
0      ENG. NACELLES LENGTH (ELN) 11.86  FT
                        MEAN DIAMETER (DBARN) 3.95  FT
                        NUMBER ENGINES (ENF) 2.0
                        WETTED AREA (SN) 294.21  SQFT
                        LOCATION      ON FUSELAGE
0      VDIVE = 715. KTS  VMD = 596. KTS  MMD = .900
      ULT. LP = 4.98  MAN. LP = 2.50  GUST LP = 3.32
0      PROPULSION GROUP
      PRIMARY ENGINES (WEP) 3122.
      PRIMARY ENGINE INSTL. (WPEI) 421.
      FUEL SYSTEM (WFSS) 181.
      TOTAL PROP. GROUP WT. (WP) 3725.
0      STRUCTURES GROUP
      WING (WH) 4386.
      HOR. TAIL (WHT) 743.
      VERT. TAIL (WVT) 452.
      FUSELAGE (WB) 6008. (INCL. .0 LBS A.T.W.)
      LANDING GEAR (WLG) 1737.
      PRIMARY ENG. SECTION (WPES) 1035.
      GROUP WEIGHT INC. (DELWST) 0.
      TOTAL STRUC. GROUP WT. (WST) 14361.
0      FLIGHT CONTROLS GROUP
      COCKPIT CONTROLS (WCC) 96.
      FIXED WING CONTROLS (WCFW) 800.
      SAS (WSAS) 0.
      GROUP WEIGHT INC. (DELWPC) 0.
      TOTAL CONTROL WT. (WFC) 896.
0      WT. OF FIXED EQUIPMENT (WFE) 6573.

      WEIGHT EMPTY (WE) 25554.

      FIXED USEFUL LOAD (WFUL) 1079. (INC. CREW )

      OPERATING WEIGHT EMPTY (OWE) 26632.
      PAYLOAD (WPL) 10000. (PAX.VOL.= 50.  DESIGN PAX= 50.)

      FUEL (WFA) 9074. (WFM= 6851.) (WFTP= 0.)

      GROSS WEIGHT (WG) 45707.

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Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution (continued)

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0      FIXED EQUIP GROUP                FIXED USEFUL LOAD
0      WAPU          372.27              WCREW ( 2.)          340.00
0      WINSTR        238.60              WSTU ( 1.)          130.00
0      WHYD          367.47              WCBAG                110.00
0      WELEC         970.00              WUF                  125.18
0      WAV           500.00              WOIL                 129.37
0      WFUR          3410.00             WSRV                 116.00
0      WAC           477.91              WHZO                  53.00
0      WAI           216.32              WEMER                 40.00
0      WAUXG         20.00              WCATER                35.00

0      WPE           6572.56             WPUL                  1078.55

0  DESIGN MACH = .800          DESIGN ALTITUDE = 35000.          DESIGN Q (PSP) =224.03
0  DESIGN RE.NUM. PER FT.    = 1.922E+06          FLATPLATE CF AT RE=10EX7 IS .00274

0  AERODYNAMIC DATA

0      DRAG BREAKDOWN          FLATPLATE          CDO          WETTED
0      WING                    AREA(SQFT)         .00667        AREA(SQFT)
0      FUSELAGE                5.4592            .01254        1910.38
0      VERT. TAIL               .6234             .00143        199.55
0      HOR. TAIL                1.0629           .00244        330.12
0      ENGINE MAC.             1.1868           .00273        294.21
0      TIP TANKS               .0000            .00000        .00
0      INCREMENTAL            .6530            .00150        .00
0      TOTAL                   11.8896          .02731        3401.47

0      MEAN SKIN FRICTION COEF.= .003495

0  AERODYNAMIC COEFF.
0      A1                      .8014
0      A2                      -.1227
0      A3                      .0383
0      A4=.75X(T/C)            .0906
0      A5=CDO--                .0179
0      A6                      2.4351
0      A7=1/(PI.SEE.AR)        .0466
0      3-D LIFT SLOPE AT CRUISE MACH (CLALPH) 6.8371 PER RADIAN
0      OSWALD FACTOR          (SEE) .7694

0  CRUISE CD = .0273 + .0466 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
0  RETRACTABLE LANDING GEAR CD INC.= .03450

0  CRUISE DRAG
0  OCL= .2000
0      MACH    CD    L/D    CLALPH    ALPHA
0      .50000  .02921  6.8468  5.4228  .5132
0      .55000  .02921  6.8468  5.5598  .4611
0      .60000  .02921  6.8468  5.7237  .4021
0      .65000  .02921  6.8468  5.9210  .3353
0      .70000  .02921  6.8468  6.1613  .2598
0      .75000  .02921  6.8468  6.4591  .1741
0      .80000  .02921  6.8468  6.8371  .0760
0      .85000  .02927  6.8330  7.3339  -.0375
0  OCL= .3000
0      MACH    CD    L/D    CLALPH    ALPHA
0      .50000  .03168  9.4706  5.4228  1.5697
0      .55000  .03168  9.4706  5.5598  1.4916
0      .60000  .03168  9.4706  5.7237  1.4031
0      .65000  .03168  9.4706  5.9210  1.3030
0      .70000  .03168  9.4706  6.1613  1.1898
0      .75000  .03168  9.4706  6.4591  1.0611
0      .80000  .03168  9.4706  6.8371  .9140
0      .85000  .03211  9.3443  7.3339  .7437
0  OCL= .4000
0      MACH    CD    L/D    CLALPH    ALPHA
0      .50000  .03508  11.4040  5.4228  2.6263
0      .55000  .03508  11.4040  5.5598  2.5221
0      .60000  .03508  11.4040  5.7237  2.4041
0      .65000  .03508  11.4040  5.9210  2.2707
0      .70000  .03508  11.4040  6.1613  2.1197
0      .75000  .03508  11.4040  6.4591  1.9482
0      .80000  .03508  11.4040  6.8371  1.7521
0      .85000  .03647  10.9673  7.3339  1.5250
0  OCL= .5000
0      MACH    CD    L/D    CLALPH    ALPHA
0      .50000  .03958  12.6339  5.4228  3.6829
0      .55000  .03958  12.6339  5.5598  3.5527
0      .60000  .03958  12.6339  5.7237  3.4052
0      .65000  .03958  12.6339  5.9210  3.2384
0      .70000  .03958  12.6339  6.1613  3.0496
0      .75000  .03958  12.6339  6.4591  2.8352
0      .80000  .03958  12.6339  6.8371  2.5901
0      .85000  .04283  11.6741  7.3339  2.3062
0  OCL= .6000
0      MACH    CD    L/D    CLALPH    ALPHA
0      .50000  .04501  13.3309  5.4228  4.7395
0      .55000  .04501  13.3309  5.5598  4.5832
0      .60000  .04501  13.3309  5.7237  4.4062
0      .65000  .04501  13.3309  5.9210  4.2060
0      .70000  .04501  13.3309  6.1613  3.9795
0      .75000  .04501  13.3309  6.4591  3.7223
0      .80000  .04506  13.3167  6.8371  3.4281
0      .85000  .05130  11.6963  7.3339  3.0875

```

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution
(continued)

0 LOW SPEED LIFT/DRAG-GR.UP(IF R)O.G.E.

		FLAPS UP			TAKEOFF			LANDING		
ALPHA	CL	CD	L/D	CL	CD	L/D	CL	CD	L/D	
-2.00000	-.03445	.02747	-1.25382	1.14118	.09514	11.99513	1.94895	.25534	7.63264	
.00000	.13778	.02821	4.88401	1.31340	.10966	11.97737	2.12118	.27430	7.73315	
2.00000	.31001	.03198	9.69522	1.48563	.12856	11.55621	2.29340	.29919	7.66541	
4.00000	.48223	.03871	12.45812	1.65786	.15268	10.85840	2.46563	.32786	7.52029	
6.00000	.65446	.04855	13.48126	1.83008	.17962	10.18846	2.63786	.35977	7.33203	
8.00000	.82669	.06174	13.38901	2.00231	.20939	9.56272	2.81008	.39491	7.11571	
10.00000	.99891	.07875	12.68468	2.17454	.24197	8.98674	2.98231	.43329	6.88300	
12.00000	1.17114	.10175	11.51049	2.34676	.27738	8.46056	3.15453	.47489	6.64262	
13.63969	1.31729	.12345	10.67105	2.49291	.30963	8.05116	3.29573	.51142	6.44433	
13.63969	1.31729	.12345	10.67105	2.49291	.30963	8.05116	3.29573	.51142	6.44433	

0 DFLAP= .00 DFLAP= 15.00 DFLAP= 40.00
 0 CLMAX= 1.31729 CLMAX= 2.50326 CLMAX= 3.29573

0 LOW SPEED AERO FOR OTHER FLAP DEFLECTIONS

FLAP DEFL.	CLMAX	CL	CD	L/D
10.000	2.13428	.78750	.07073	11.13381
		.95973	.08206	11.69606
		1.13196	.09703	11.66553
		1.30418	.11666	11.17959
		1.47641	.14100	10.47092
		1.64863	.16814	9.80534
		1.82086	.19806	9.19329
		1.99309	.23078	8.63616
		2.13428	.25969	8.21853
		2.13428	.25969	8.21853
20.000	2.74181	1.39503	.12267	11.37225
		1.56726	.13905	11.27104
		1.73948	.16069	10.82487
		1.91171	.18621	10.26623
		2.08393	.21458	9.71159
		2.25616	.24580	9.17880
		2.42839	.27987	8.67684
		2.60061	.31679	8.20931
		2.74181	.34918	7.85211
		2.74181	.34918	7.85211
30.000	3.09918	1.75240	.17966	9.75411
		1.92462	.19762	9.73889
		2.09685	.22170	9.45784
		2.26908	.24883	9.11902
		2.44130	.27891	8.75303
		2.61353	.31195	8.37814
		2.78576	.34794	8.00644
		2.95798	.38689	7.64556
		3.09918	.42103	7.36100
		3.09918	.42103	7.36100

0 ALTITUDE= 35000. FT TAS= 482.40 KTS MACH NO= .8359

0 RDT&E AND AIRFRAME PRODUCTION COSTS

(1993. DOLLARS)

0 TOTAL RDT&E COSTS 1068.2820 MILLION
 0 AIRFRAME PRODUCTION COSTS(INCLUDING 10% PROFIT)
 500. AIRCRAFT

	WEIGHT(LB)	COST(\$)	COST(\$/LB)
STRUCTURE(4060151.\$)			
WING	4386.	1099279.	250.64
EMPELLAGE	1195.	427073.	357.47
FUSELAGE	6008.	1665887.	277.26
LANDING GEAR	1737.	308707.	177.74
MACELLES	1035.	559205.	540.31
PROPULSION INSTAL(179169.\$)			
ENGINE INSTALLAT.	421.	153445.	364.08
FUEL SYSTEM	181.	25724.	141.74
SYSTEMS(2555619.\$)			
FLIGHT CONTROLS	896.	420442.	469.41
HYDRAULIC	367.	45774.	124.57
ELECTRICAL	970.	464214.	478.57
AIR CONDITIONING	478.	256070.	535.82
ANTI-ICING	216.	113925.	526.66
AUX. POWER UNIT	372.	207143.	556.42
FURNISHINGS	3410.	796443.	233.56
INSTRUMENTS	239.	197905.	829.44
AVIONICS INSTALL.	250.	49032.	196.13
AUX. ITEMS	20.	4671.	233.56
INTEGRATION(1698735.\$)			
AIRFRAME TOTALS	22182.	8493674.	382.91
ENGINES		2905339.	
PROPELLER		0.	
AVIONICS		4000000.	
A/C COST(NO RD)		15399012.	
R&D PER A/C		2136564.	
TOTAL A/C COST		17535576.	

0 ENGINES NUMBER = 2. TYPE= 7

0 EMPTY WEIGHT= 25554. AIRFRAME WEIGHT= 22432. WEIGHT OF 1 ENGINE= 1561. CRUISE SPEED= 482. KTS
 0 THRUST/ENGINE= 9756.
 0 TOTAL AIRCRAFT COST= 17535576. AIRFRAME COST= 14630238. COST OF 1 ENGINE= 1452669. COST OF 1 PROP.= 0.

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution (continued)

```

0          --- COST DATA ---
0          GASP SHORThAUL METHOD
0          DESIGN MISSION
0          OPERATING COST FOR NOR.RATED POWER AND 35000. ALTITUDE
0          *****
0          RANGE= 1262. N.M.   BLOCK FUEL= 7186. LBS   BLOCK TIME= 2.9504 HRS.
0          UTILIZATION
0          3200.
0          FLYING OPERATIONS
0          FLIGHT CREW          368.800
0          FUEL, OIL, AND TAXES( .850$/G) 954.597
0          INSURANCE          80.839
0          DIRECT MAINTENANCE
0          AIRFRAME          167.142
0          ENGINE            284.465
0          MAINTENANCE BURD.  365.406
0          DEPRECIATION      1086.476
0
0          TOTAL DOC ($/TRIP)  3307.725
0          ($/B.HR.)         1121.111
0          ($/N.MI.)         2.620
0          .

```

Fig E5 - Conventional Configuration optimised for minimum D.O.C. - GASP solution
(concluded)

*....data for 50 Pax turbofan airliner

VARIABLES

01	1	95.0	86.750	80.000	105.000
02	1	9.0	8.300	8.000	10.000
03	1	23.0	14.500	11.000	35.000
04	1	.235	.200	.160	.310
05	1	4.0	4.000	3.800	4.300
06	1	27.5	27.500	20.000	35.000
07	1	1.0	1.000	.800	1.200
08	1	46.5	50.500	40.000	53.000
09	1	6.0	5.500	4.000	8.000
10	1	23.0	15.000	10.000	35.000
11	1	.43	.500	.160	.700
12	1	1.5	2.000	.000	3.000
13	1	.15	.15	.145	.175
14	1	.8	.75	.75	.85

FUNCTIONS

01	00	00	3.0	1
02	-1	00	6000.0	
03	-1	00	5000.0	
04	-1	00	120.0	
05	-1	00	.8	
06	-1	00	.8	

CONTROLS

XTOLU = .0001
 XTOLV = .0001
 OFROM = 1
 OFREQ = 10
 RFREQ = 50
 NFEMAX = 20000
 RUN
 END

Fig E6 - RQPMIN.DAT file for the Three-Lifting Surface D.O.C. optimisation case

!Program RQPMIN Version 1.0 for VAX

ANALYSIS OF INPUT FILE DATA AND CONTROL PARAMETERS

Input file: rqpmin.dat
Output file: rqpmin.res

Variable data

Number of variables = 14

Index	Status	Scale	Starting value	Lower bound	Upper bound
1	1	.9500000E+02	.9131579E+00	.8421053E+00	.1105263E+01
2	1	.9000000E+01	.9222223E+00	.8888889E+00	.1111111E+01
3	1	.2300000E+02	.6304348E+00	.4782609E+00	.1521739E+01
4	1	.2350000E+00	.8510638E+00	.6808510E+00	.1319149E+01
5	1	.4000000E+01	.1000000E+01	.9500000E+00	.1075000E+01
6	1	.2750000E+02	.1000000E+01	.7272727E+00	.1272727E+01
7	1	.1000000E+01	.1000000E+01	.8000000E+00	.1200000E+01
8	1	.4650000E+02	.1086022E+01	.8602151E+00	.1139785E+01
9	1	.6000000E+01	.9166667E+00	.6666667E+00	.1333333E+01
10	1	.2300000E+02	.6521739E+00	.4347826E+00	.1521739E+01
11	1	.4300000E+00	.1162791E+01	.3720930E+00	.1627907E+01
12	1	.1500000E+01	.1333333E+01	.0000000E+00	.2000000E+01
13	1	.1500000E+00	.1000000E+01	.9666666E+00	.1166667E+01
14	1	.8000000E+00	.9375000E+00	.9375000E+00	.1062500E+01

Problem function data

Number of constraints = 5

Index	Status	Type	Scale	Index	Status	Type	Scale
1	0	0	.3000000E+01	2	-1	0	.6000000E+04
3	-1	0	.5000000E+04	4	-1	0	.1200000E+03
5	-1	0	.8000000E+00	6	-1	0	.8000000E+00

objective is function 1 problem number = 1

Control parameters

```

nfemax = 20000    nimax = 1000    nsmax = 20
nsetc = 4         nsetcf = 8      nsetv = 4      nsetvf = 8
ofreq = 10       ofrom = 1      rfreq = 50     rfrom = 1

centrl = F      fdset = F      norep = F      cheats = T      fast = T      quasi = T
fixrp = F      timid = F      monitr = F     nofreq = F     yesbc = F     shrnk = T      projet = T

xtol = .1000000E-05    xtolu = .1000000E-03    xtolv = .1000000E-03    gtol = .1000000E-02
rtol = .1000000E+00    omegar = .1000000E+00    rpsmax = .2000000E+00
umin = .1000000E-05    vminf = .1000000E-02    vminc = .1000000E-05    ctol = .1000000E-02
umax = .1000000E+00    vmax = .1000000E+00    omega = .1000000E+00    mu = .1000000E-03
bdtol = .1000000E+00    lmtol = .1000000E+00    mtol = .5000000E+00    cmax = .1000000E-01
subtol = .1000000E-02    qrtol = .1000000E+02    bfatol = .1000000E-05    diftol = .5000000E-03
xtol = .1000000E-29

```

End of input data

!Program RQPMIN Version 1.0 for VAX

STARTING POINT

free variables

1	.9131579E+00	2	.9222223E+00	3	.6304348E+00	4	.8510638E+00	5	.1000000E+01	6	.1000000E+01	7	.1000000E+01
8	.1086022E+01	9	.9166667E+00	10	.6521739E+00	11	.1162791E+01	12	.1333333E+01	13	.1000000E+01	14	.9375000E+00

objective function

f(x) = .9113006E+00

inactive inequality constraints

2 -.2218968E+00 3 -.2113195E+00 4 -.1450278E+00 5 -.4114293E-01 6 -.8385710E-01

!Program RQPMIN Version 1.0 for VAX

end of iteration number 1

end of a successful minimization step
number of calls made to user function so far = 60

Fig E7 - RQPMIN.RES file for the Three-Lifting Surface D.O.C. optimisation case

```

free variables
-----
 1 .9056399E+00  2 .9381056E+00  3 .6405770E+00  4 .8631462E+00  5 .1012208E+01  6 .1013268E+01  7 .1013431E+01
 8 .1096338E+01  9 .9415752E+00 10 .6654051E+00 11 .1176070E+01 12 .1343306E+01 13 .1013591E+01 14 .9520572E+00

objective function
-----
f(x) = .9111835E+00

inactive inequality constraints
-----
 2 -.2080367E+00  3 -.2018121E+00  4 -.1381598E+00  5 -.3883965E-01  6 -.8616038E-01

Partial derivatives of Lagrangian function
-----
 1 .5422831E+00  2 .5409718E+00  3 .4446506E+00  4 -.5501509E+00  5 .7889270E+00  6 .5812645E+00  7 .4202127E+00
 8 .4251003E+00  9 .4136562E+00 10 -.8766651E+00 11 -.5730391E+00 12 .8237361E+00 13 .1140833E+00 14 .6394657E+00

convergence criteria
-----
pdatum = .9111835E+00  ldatum = .9111835E+00  gdatum = .0000000E+00
nu      = .0000000E+00  numax  = infinite
unormx  = .0000000E+00  unormd = .0000000E+00  rtol   = .1000000E+00  xtolu  = .1000000E-03
vnormx  = .3181815E+01  vnorm  = .1000000E+00  xtolv  = .1000000E-03  grdidn = .8766651E+00
nde     = 0  ndef  = 4  ndec  = 0  ncalls = 8  nfuncs = 4
1Program RQPMIN Version 1.0 for VAX 16-Feb-94

end of iteration number 11
-----
end of a successful minimization step
number of calls made to user function so far = 415

free variables
-----
 1 .1088571E+01 14 .9481185E+00  3 .6307811E+00  4 .8588357E+00  5 .9769369E+00  6 .8885419E+00  7 .8941292E+00
 8 .1077350E+01  9 .1016114E+01 10 .8932611E+00 11 .1168866E+01 12 .1355567E+01 13 .1055593E+01  2 .9329544E+00

objective function
-----
f(x) = .8704389E+00

inactive inequality constraints
-----
 2 -.8533529E-03  3 -.8119043E-02  4 -.5353101E-02  5 -.4506424E-01  6 -.7993579E-01

Partial derivatives of Lagrangian function
-----
 1 -.2833009E+00 14 -.7754564E-01  3 .3156066E+00  4 .1972914E-01  5 .5561113E-01  6 .9113549E-01  7 -.4224777E+00
 8 -.6240606E-01  9 -.6906986E+00 10 .9131431E-01 11 .5384684E+00 12 .6685852E+00 13 -.5574226E+00  2 -.1536608E+00

convergence criteria
-----
pdatum = .8704389E+00  ldatum = .8704389E+00  gdatum = .0000000E+00
nu      = .0000000E+00  numax  = infinite
unormx  = .0000000E+00  unormd = .0000000E+00  rtol   = .1000000E+00  xtolu  = .1000000E-03
vnormx  = .4304282E+01  vnorm  = .1000000E+00  xtolv  = .1000000E-03  grdidn = .6906986E+00
nde     = 0  ndef  = 14  ndec  = 7  ncalls = 44  nfuncs = 23
1Program RQPMIN Version 1.0 for VAX 16-Feb-94

end of iteration number 13
-----
CONVERGENCE DETECTED [ Code B ] after 620 calls to user routine

```

Fig E7 - RQPMIN.RES file for the Three-Lifting Surface D.O.C. optimisation case
(continued)

free variables

```

-----
 1 .1088571E+01 14 .9481185E+00 3 .6307811E+00 4 .8588357E+00 5 .9769369E+00 6 .8885419E+00 7 .8941292E+00
 8 .1077350E+01 9 .1016114E+01 10 .8932611E+00 11 .1168866E+01 12 .1355567E+01 13 .1055593E+01 2 .9329544E+00

```

objective function

```

-----
f(x) = .8710610E+00

```

inactive inequality constraints

```

-----
 2 -.8714193E-03 3 -.6874707E-02 4 -.4561170E-02 5 -.4492499E-01 6 -.8007504E-01

```

Partial derivatives of Lagrangian function

```

-----
 1 -.2833009E+00 14 -.7754564E-01 3 .3156066E+00 4 .1972914E-01 5 .5561113E-01 6 .9113549E-01 7 -.4224777E+00
 8 -.6240606E-01 9 -.6906986E+00 10 .9131431E-01 11 .5384684E+00 12 .6685852E+00 13 -.5374226E+00 2 -.1536608E+00

```

convergence criteria

```

-----
pdatum = .8704389E+00   ldatum = .8704389E+00   gdatum = .0000000E+00
nu      = .0000000E+00   numax  = infinite
unormx  = .0000000E+00   unormd = .0000000E+00   rtol   = .1000000E+00   xtolu  = .1000000E-03
vnormx  = .6906986E+00   vnorm  = .1000000E+00   xtolv  = .1000000E-03   grdldn = .6906986E+00
nde     = 0             ndef   = 14             ndac   = 14             ncalls = 60             nfuncs = 32

```

Fig E7 - RQPMIN.RES file for the Three-Lifting Surface D.O.C. optimisation case
(concluded)


```

0          50 PAX TURBOPAN AIRLINER USING SCALED GE CF-34 - THREE-SURF. CONFIG.
          ENGINE CYCLE IS G. E. CF-34
          INPUT DATA FOLLOW
          *****
0
0 CONFIG  WG      = 44050.          *****GEOMETRY*****
          WGS      = 103.414        KWRITE   = 2          FUSEL  SAB      = 4.          EICDN  = 1.000
          FAX      = 50.            IGEAR    = 0          WS      = 20.000         ELODT  = 3.200
          EMCRU    = .800           KCONFG   = 0          AS      = 1.            BML0D  = 14.500
          HNCRU    = 35000.         RTIFK    = 0          MAS     = 19.000        MACELLE KNAC   = 1
          Kanard   = 1              ENP      = 2.          PS      = 31.0         ELN     = 11.330
          KPL0T    = 1              NTYE     = 7          ELPC    = 11.220        DBARN  = 3.777
          KPL0T    = 1              KPL0T    = 1          HCK     = 2.470         ELRW   = 10.000
0 WING    TCT      = .100          HORIZ  VBARHX = .0000        VERT   VBARVX  = .0000        Canard  TCcan   = .100
          TCR      = .130          TAIL   TCHT   = .100        TAIL   TCVT   = .120        ARcan  = 6.097
          AR       = 8.397          ARHT   = 3.908        ARVT   = .894          SIMcan = .303
          SLM      = .202          SLMH   = .550          SLMV   = .700          DwpqCa = 20.545
          DLMC4    = 14.508         DWPOCH = 24.435        DWPCV  = 50.097        EYecan = 2.033
          EYEW     = 2.000         COELTH = .000          BOELTV = .000         SWcOSW = .158
          SAH      = 1.000
0          ***AERODYNAMICS***
0          CKW      = -1.000        CKHT    = -1.000        GRPE   = .000          DCDSE  = -1.0000
          CKF      = -1.000        CKTP    = -1.000        SCFAC  = .750          CRMc   = 2.497
          CKN      = -1.000        DELCD   = .00150       DLWSW  = .000          cmacw  = -.060
          CKVT     = -1.000        DELPE   = .200         ALPHL0 = -1.600        elzerc = -1.000
0          KWCD     = 12
          ACLS     = -1.000        -.600  -.400  -.200  .000  .100  .200  .400  .600  .800  1.000  1.200
          ACDCDR  = 2.400        1.466  1.221  1.066  1.005  1.000  1.005  1.046  1.138  1.333  1.743  2.718
0          *HIGH LIFT DEVICES*
0          RCLMAX  = 1.200          FLAPS  JFLTYF = 7          LED    CLEOC   = .000
          ALIFLP  = 5000.         DFLPTO = 15.000        DELLED = .000
          FLAPN   = 1.            DFLPLD = 40.000       DCLMLE = .930
          WCFLAP  = -1.000        CF0C    = .300         DELLEO = 45.000
          BENG0B  = .000          BTEOB   = .750
          DCLMTE  = .000
          DCDOTE  = .000
          DELTEO  = .000
0          *****PROPULSION*****
0          JENG5Z   = 2            HPORT   = 5000.        RCCRU  = 50.000        RWCRTX = .970
          IPART    = 1            TDELTO  = 36.         XTORQ  = 99999.       HSCREQ = 0.
          KODETO   = 5            KODECL  = 7           SMLD   = .500         THIN   = 0.
          KODETR   = 5            KODEAC  = 5           HBTf   = .437        PR      = 1.000
0          *****WEIGHTS*****
0          SKPEI   = .1350         SKY      = .1800        SKB     = 107.000       SKFS   = .0200
          SKLG    = .0380         SKZ      = .2200        SKCC    = 20.000       SKFW   = .4300
          SKMG    = .8000         SKTL     = 1.0000       SKFW    = .4300       SKFT   = .9790
          SKPFS   = .3380         SKKW     = 133.400     SKSAS   = .000        SKMTF  = 1.8900
          WPLX    = .0             YMG      = .2500        EGMRGN = .0000       LCMWNG = 2
          WPEX    = .0             RELP     = .7585       CPMRGN = .2000
          WFUL    = 1065.5         RELR     = .4500       STMGRN  = .0000       LDCRMX = 8.000
          UWPAI   = 200.0         CATD     = 3.          DELP    = 8.200       ATMKQC = 3.160
          STRUT   = .0000         VMLFSL  = 685.0       YP      = .0000       DELWST = .0
0 ENGINE  WENG     = .0           WNAC    = .0           WPYLON = .0
          WWSLS  = .160         UWNAC   = 2.287       FPYL    = .700        ILQDE  = 3.000
0          *STABILITY AND CONTROL*
0          KSPind   = 1            STATIC  = .100        ZCG     = 5.500        CNPAC  = .0020
          CMPLPL  = 999.000       CHALP   = 999.000     TP      = .0           ARVTE  = -1.000
          CMPLRT  = 999.000       CHDEL   = 999.000     CXA     = .520        RV      = .300
          CMPLD   = .000         RH       = .350        DCMCLP = .000       TAUV   = 999.000
          EYET    = .0            DEMAX   = -25.0       HMING  = .0           RVNCS  = .990
          TAUN    = 999.000       EYET    = .0          dcmcpi = .030        DRMAX  = 25.0
          rc      = .350
0          ***PERFORMANCE***
0 TAXI    DELTT   = .167          XLFMAX  = 1.100        DVR     = 5.000        TDELTX = 36.000
          TO      IFPL   = 1          DELTVR  = 3.500        UM      = .020        HTMAX  = 500.000
          THEMAX  = 15.000         DVI     = 5.000        HUB     = .400        NFAIL  = 0
          H00     = 5000.         VRAT    = 1.10       WTMISN = 0.
0 CLIMB  ICLM    = 1            CRUISE  CRMACH  = .800        PRESF   = 1.000        FACVI  = .985
          DELH    = 1000.         CRALT   = 3500.       RCRAQ   = 1250.0     ISWING = 0
          VCLMB   = .0            ICRUS   = 1          OFALT   = 25000.      OPEN   = .500
0 LAND   IWL0    = 2            XLDGRQ  = 99999.       VRATT   = 1.300        HAPP   = 50.
          TDELLD  = 36.0         ALTLDN  = 5000.       RSMX    = 1000.      SINKTD = 3.0
          TDELAY  = 1.0          WLPCT   = .9400       TROTID  = .000        XLFMX  = 1.200
          HTG     = 5.5          TIDLE   = .0         VTDRAT  = 1.1
0          *****COST*****
0          NCADE   = 1            HIR     = .005        RI      = .300        CMV    = .800
          CLLAB  = 1993.0         TR      = 2.000       CHR     = 500.000     CCRW   = 0.
          HRI    = 4000000.       PRV     = .100       CRMOH  = 23.000      UCSENG = .000
          CMF     = .2            DYA     = 15.0       CIMP    = 0.          UCSPP  = .000
          TBO    = 3200.0         SRPM    = .0         CP      = 0.          ALR    = 1.120
          FCSF   = .850

```

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution

```

0 *****
0 FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
      CLMAX      VSTALL,KTS  FLAP ANGLE  LE ANGLE  DELTA CL  DELTA CD
FLAPS UP      1.1248      177.4      .0      .0      .0000      .0000
T.O. CONFIG   2.1363      128.9      15.0     .0      .9974      .0366
LDG. CONFIG   2.8112      112.3      40.0     .0      1.6844      .1630
0
0 DOUBLE SLOTTED FOWLER FLAPS
      OPT ANGLE  DELCL AT OPT  DELCD AT OPT  AREA(FT2)  WEIGHT(LB)
FLAPS        30.0      2.2500      .1500      74.2      607.4
0 *****
0 TEMP.= 537. DEG:STD.+36.
  LANDING ELEVATION= 5000. FT.
  LANDING WING LOADING= 97.21 RSP.
  LANDING WEIGHT = 41407. LBS.
  LANDING DISTANCE FROM 50. FT.= 3097. FT.
  F.A.R. FACTORED FIELD LENGTH = 5161. FT.
0 APPROACH TRANSITION DELAY ROLL
0 DIS= 740. DIST= 216. DIST= 219. DIST= 1922.
  R/S= 1000. XLFIX= 1.200 TDELAY= 1.00 MUB= .4000
  VAPAS= 131.26 SINKTD= 3.000 TIDLE= 0. TR/TIDLE= .0000
  VAPTAS= 146.46 VSTEAS= 100.97 VTDAS= 129.56 ABAR(G)= .3874
  THETA= 3.86 CLMX= 2.8112
  THRUST= 3172. HFLAR= 20.9
0 *****
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
  ANGLE OF ATTACK(DEGREES)= 2.218 LIFT= 42728.5 L/D= 13.405 ALTITUDE= 35000.0 MACH= .8000
1 ENGINE SIZING DATA FOLLOW
*****
0VSTLKT= 119.5 KTS EAS VRAT= 1.100 CLTO= 1.7655
  VEND = 250.0 KNOTS EAS
0 ROTATION (TIME= 29.7 AND TAS= 144.3 EAS= 129.5)
  LIPTOFF (TIME= 32.2 DIST= 4583.0 TAS= 152.4 EAS= 136.7)
  DISTANCE TO 35 FT.= 5963.2 TAS= 163.6 EAS= 146.7 V35/V3= 1.2274
  GEAR RETRACTION STARTED AT 38.3 SEC, COMPLETE AT 45.3 SEC
  FLAP RETRACTION STARTED AT 48.5 SEC, COMPLETE AT 53.0 SEC
0VSTLKT= 119.5 KTS EAS VRAT= 1.100 CLTO= 1.7655
0 ENGINE OUT PERFORMANCE FOLLOWS
  VEND = 216.4 KNOTS EAS
  ENGINE FAILURE (TIME= 28.2 AND TAS= 138.8 EAS= 124.5)
0 ROTATION (TIME= 33.7 AND TAS= 144.3 EAS= 129.5)
  LIPTOFF (TIME= 37.0 DIST= 5726.4 TAS= 146.5 EAS= 131.4)
  DISTANCE TO 35 FT.= 9180.4 TAS= 147.1 EAS= 131.9 V35/V3= 1.1040
  ACCELERATE - STOP DISTANCE = 7327.3 FEET.
0 ENGINE OUT DISTANCE TO 35 FT. = 9180.4 FEET
  OALL ENGINE DISTANCE TO 35 FT. (L) = 5963.2 FEET
  FAR 25 T.O. DISTANCE (1.15XL) = 6857.7 FEET
  ALL ENGINE DISTANCE TO 50 FT. = 6215.2 FEET
0 AT END OF TAKEOFF PHASE
  TIME= .014 HRS FUEL USED= 76. LBS WEIGHT= 43974. LBS ALT.= 5500. FT.
  TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
  AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F
0
0 CONFIGURATION ALT (FT) VS KEAS V/V3 KIAS V GRAD (PCT) R/C (PPM) REQ.R/C (PPM) CL L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT 5000. 119.6 1.1170 149.0 1.291 194.71 1.00 1.719 8.404
2ND SEG: T.O. FLAPS - ONE ENGINE OUT 5250. 119.6 1.2000 160.7 3.722 605.15 390.24 1.489 10.862
FINAL T.O. CRUISE CONFIG - ONE ENG OUT 6500. 163.8 1.2500 233.7 4.009 948.18 283.80 .732 13.577
APPROACH FLAPS - ONE ENG OUT 5000. 114.6 1.3464 172.0 3.951 687.82 365.63 1.289 11.323
LANDING FLAPS - ALL ENGINES 5000. 104.3 1.3000 151.2 12.031 1840.36 489.51 1.670 7.002
  APPROACH FLAP SETTING = 19.7 DEG.
  +++ ENGINE-OUT SERVICE CEILING = 20789.0 FT.
  BEST RATE OF CLIMB SPEED = 275.2 KTAS
  ENGINE-OUT RATE OF CLIMB = 49.8 PPM
  WEIGHT AT ALTITUDE = 42288.0 LBS
0 *****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES*****
0VSTLKT= 119.5 KTS EAS VRAT= 1.100 CLTO= 1.7655
  VEND = 250.0 KNOTS EAS
0 ROTATION (TIME= 28.3 AND TAS= 144.3 EAS= 129.5)
  LIPTOFF (TIME= 30.8 DIST= 4389.6 TAS= 152.8 EAS= 137.1)
  DISTANCE TO 35 FT.= 5763.6 TAS= 164.9 EAS= 147.8 V35/V3= 1.2372
  GEAR RETRACTION STARTED AT 36.8 SEC, COMPLETE AT 43.8 SEC
  FLAP RETRACTION STARTED AT 47.0 SEC, COMPLETE AT 51.3 SEC
0VSTLKT= 119.5 KTS EAS VRAT= 1.100 CLTO= 1.7655
0 ENGINE OUT PERFORMANCE FOLLOWS
  VEND = 207.4 KNOTS EAS
  ENGINE FAILURE (TIME= 26.9 AND TAS= 138.8 EAS= 124.5)
0 ROTATION (TIME= 31.5 AND TAS= 144.3 EAS= 129.5)
  LIPTOFF (TIME= 34.8 DIST= 5342.8 TAS= 146.9 EAS= 131.8)
  DISTANCE TO 35 FT.= 7956.8 TAS= 147.8 EAS= 132.5 V35/V3= 1.1087
  ACCELERATE - STOP DISTANCE = 7160.5 FEET.
0 ENGINE OUT DISTANCE TO 35 FT. = 7956.8 FEET
  OALL ENGINE DISTANCE TO 35 FT. (L) = 5763.6 FEET
  FAR 25 T.O. DISTANCE (1.15XL) = 6628.1 FEET
  ALL ENGINE DISTANCE TO 50 FT. = 6017.3 FEET

```

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (continued)

0 AT END OF TAKEOFF PHASE
 TIME= .014 HRS FUEL USED= 77. LBS WEIGHT= 43973. LBS ALT.= 5500. FT.
 TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	VS KEAS	V/VS	V KTAS	GRAD (PCT)	R/C (PPM)	REQ. R/C (PPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	119.6	1.1170	149.0	1.532	230.97	1.00	1.719	8.186
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	119.6	1.2000	160.7	3.935	639.79	390.24	1.489	10.482
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	163.8	1.2500	233.7	3.954	935.05	283.80	.732	12.656
APPROACH FLAPS -ONE ENG OUT	5000.	114.6	1.3232	169.1	4.168	713.23	359.33	1.335	10.859
LANDING FLAPS - ALL ENGINES	5000.	104.3	1.3000	151.2	13.054	1996.88	489.51	1.670	6.959

APPROACH FLAP SETTING = 19.7 DEG.

+++ ENGINE-OUT SERVICE CEILING = 21343.0 FT.
 BEST RATE OF CLIMB SPEED = 274.3 KTAS
 ENGINE-OUT RATE OF CLIMB = 49.7 FPM
 WEIGHT AT ALTITUDE = 42288.0 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 348.98

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R;ALT= 5000.) SLS AIRFLOW= 348.98

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 8899.1 LBS

PROPULSION SYSTEM WEIGHTS
 ENGINE WEIGHT/ENGINE 1423.9
 NACELLE WEIGHT/ENGINE 307.2
 PYLON WEIGHT/ENGINE 169.2
 PROP OR OPAN .0
 GEARBOX .0
 SHROUD .0

ENGINE POD DIMENSIONS
 ENGINE FACE DIAMETER(FT) 3.78
 NACELLE LENGTH(FT) 11.33

0*****

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (continued)

---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---

	MOST FWD LOAD		MOST AFT LOAD		DESIGN LOAD	
	WT	CG	WT	CG	WT	CG
A/C OWE	25677.90	41.87	25677.90	41.87	25677.90	41.87
PAX	5440.00		2040.00		8500.00	
BAGGAGE	.00	56.36	1500.00	56.36	1500.00	56.36
WING FUEL	1278.90	42.37	1278.90	42.37	6394.48	42.37
TIP FUEL	.00	.00	.00	.00	.00	.00
FUS FUEL	.00	42.37	.00	42.37	1977.62	42.37
TOTAL	32396.79	39.69	30496.79	43.02	44050.00	41.45

0 ---TAIL SIZING SUMMARY---

Static Longitudinal Stability, Stick-fixed, considered

CONDITION	WING			CANARD		TAIL		DOWN WASH	FLAP CM
	ALPHA	CL	CLA	C _{Mac}	ALPHA	CLA	CLA		
CRUISE	2.3358	.4623	.1174	-.0600	3.3691	.0990	.0771	1.0000	
LIFTOFF	2.0000	1.3135	.0681	-.0600	3.0333	.0764	.0640	1.0000	.3505
LANDING	11.6750	2.8112	.0849	-.0600	12.7083	.0765	.0640	1.0000	2.0458

CONDITION	--FUSELAGE--		---NACELLE---		-----POWER-----		L. GEAR	ROT. POWER
	DCM	CM	DCM	CM	DCM _{th}	DCM _{fine}		
CRUISE	.4954	.1487	.1487	.0000	.0000	.0300		.0000
LIFTOFF	.8549	.0000	.1487	.0000				.0000
LANDING	.6855	.5629	.1487	.1221				-.3882

0 CANARD PARAMETERS

CMDELTC (CONTROL POWER) = -.02539

TAUc (EFFECTIVENESS) = .48250

DcMAX (MAX. CANARD VATOR DEFLEC) = 37.47721

0 ELEVATOR PARAMETERS

CMDELTE (CONTROL POWER) = -.03079

TAUH (EFFECTIVENESS) = .48250

DEMAX (MAX. ELEVATOR DEFLEC.) = -25.00000

WING DE/DALPHA = .35046

	FRACTION MAC	STATION (DATUM NOSE)	CANARD AND HORIZONTAL TAIL SIZES	
			CANARD	HOR. TAIL
NEUTRAL POINT	.5812	43.973	STATIC STABILITY AND LANDING TRIM	
STATIC MARGIN	.1000		STATIC STABILITY AND LIFTOFF ROT.	
AFT CG LIMIT (STABILITY)	.4812	43.172	REQUIRED SIZES	
CG RANGE (LOADING)	.4164		CANARD AND TAIL ARMS (ELCen, ELTH)	64.7705
FWD CG LIMIT (CONTROL)	.0648	39.838		77.2809

0 VERTICAL TAIL AREA = 100.8787 FOR DIRECTIONAL STABILITY OF .00200

0 RUDDER POWER AT MAX. DEFL. = .0168 PER DEG. RUDDER CL AT MAX. DEFL. = .4190

0 VERTICAL TAIL AREA = 74.1509 FOR MINIMUM CONTROL SPEED = 118.28 KTS

0 REQUIRED VERTICAL TAIL AREA = 100.8787 TAIL ARM (ELTV) = 34.0464

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE

ANGLE OF ATTACK (DEGREES) = 2.218 LIFT = 42728.5 L/D = 12.793 ALTITUDE = 35000.0 MACH = .8000

0 WING LOCATION INFO.			
FUSELAGE LENGTH	= 79.25	H-TAIL VOL. ARM	= 44.10
WING 1/4C LOC. ON C.L.	= 38.22	H-TAIL C.G. LOCATION	= 85.64
MAC 1/4C LOCATION	= 41.17	H-TAIL MAC FROM C.L.	= 3.92
MAC DIST. FROM C.L.	= 11.41	H-TAIL LOCAT ON VERT.	= 1.00
WING C.G. LOCATION	= 42.77	V-TAIL VOL. ARM	= 34.05
TIP TANKS C.G. LOCATE	= .00	V-TAIL C.G. LOCATION	= 76.08

C.G. LOCATION OF PROPULSION = 60.11	
C.G. OF REMAINING WEIGHT	= 35.66
DIST. L.E. VERT. TO L.E. HORIZ.	= 3.01

CANARD 1/4C LOC. ON C.L.	= 6.56
CANARD MAC DIST. FROM C.L.	= 4.42
CANARD VOLUME ARM	= 32.95
CANARD C.G. LOCATION	= 8.49

	WING	CANARD	H-TAIL	V-TAIL
AREA	409.061	64.770	77.281	100.879
SPAN	58.606	19.872	17.378	9.497
ASPECT RATIO	8.397	6.097	3.908	.894
TAPER RATIO	.202	.503	.550	.700
1/4C SWEEP	14.508	20.545	24.435	50.097
L.E. SWEEP	18.668	23.223	27.863	52.314
C.L. CHORD	11.615	4.338	5.738	12.496
MEAN CHORD	8.006	3.378	4.572	10.732
TIP CHORD	2.344	2.181	3.156	8.747

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (continued)

MISSION PERFORMANCE DATA FOLLOWS

TAXI AT IDLE THRUST

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	FUEL FLOW (LB/HR)
.000	0.	0.	44050.	5000.	813.
.167	0.	135.	43915.	5000.	813.

OVSTLKT= 113.1 KTS EAS VRAT= 1.100 CLTO= 1.7655
 VEND = 248.2 KNOTS EAS
 (TEMP.= 537. DEG:STD.+36.)
 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (PPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	135.5	43915.	5000.0	.0	.0	.000	10.92	1.3108	.1363	2.00	.00	.0	.00	15783.	5621.	.00
1.0	5.4	137.0	43913.	5000.0	6.4	5.8	.010	10.77	1.3108	.1363	2.00	.00	.0	.00	15596.	5621.	.00
2.0	21.7	138.6	43911.	5000.0	12.8	11.5	.019	10.63	1.3108	.1363	2.00	.00	.0	.00	15411.	5621.	.00
3.0	48.6	140.2	43910.	5000.0	19.1	17.1	.028	10.47	1.3109	.1363	2.00	.00	.0	.00	15230.	5622.	.00
4.0	86.0	141.7	43908.	5000.0	25.2	22.6	.037	10.31	1.3109	.1363	2.00	.00	.0	.00	15051.	5624.	.00
5.0	133.7	143.3	43907.	5000.0	31.3	28.1	.046	10.15	1.3110	.1364	2.00	.00	.0	.00	14876.	5625.	.00
6.0	191.7	144.9	43905.	5000.0	37.3	33.4	.055	9.98	1.3111	.1364	2.00	.00	.0	.00	14705.	5627.	.00
7.0	259.6	146.4	43904.	5000.0	43.2	38.7	.064	9.81	1.3112	.1364	2.00	.00	.0	.00	14535.	5629.	.00
8.0	337.4	148.0	43902.	5000.0	48.9	43.9	.073	9.63	1.3114	.1364	2.00	.00	.0	.00	14369.	5631.	.00
9.0	424.9	149.5	43900.	5000.0	54.6	49.0	.081	9.45	1.3115	.1364	2.00	.00	.0	.00	14206.	5633.	.00
10.0	521.8	151.1	43899.	5000.0	60.2	54.0	.089	9.27	1.3117	.1364	2.00	.00	.0	.00	14046.	5635.	.00
11.0	628.1	152.7	43897.	5000.0	65.6	58.9	.097	9.08	1.3118	.1364	2.00	.00	.0	.00	13889.	5637.	.00
12.0	743.4	154.2	43896.	5000.0	71.0	63.7	.105	8.91	1.3120	.1365	2.00	.00	.0	.00	13759.	5640.	.00
13.0	867.8	155.8	43894.	5000.0	76.2	68.4	.113	8.75	1.3122	.1365	2.00	.00	.0	.00	13642.	5643.	.00
14.0	1000.9	157.4	43893.	5000.0	81.4	73.0	.121	8.58	1.3124	.1365	2.00	.00	.0	.00	13528.	5646.	.00
15.0	1142.6	158.9	43891.	5000.0	86.4	77.5	.128	8.41	1.3126	.1365	2.00	.00	.0	.00	13416.	5649.	.00
16.0	1292.7	160.5	43890.	5000.0	91.4	82.0	.136	8.23	1.3129	.1366	2.00	.00	.0	.00	13306.	5652.	.00
17.0	1451.1	162.1	43888.	5000.0	96.2	86.3	.143	8.06	1.3131	.1366	2.00	.00	.0	.00	13198.	5655.	.00
18.0	1617.7	163.7	43886.	5000.0	101.0	90.6	.150	7.89	1.3133	.1366	2.00	.00	.0	.00	13093.	5659.	.00
19.0	1792.1	165.2	43885.	5000.0	105.6	94.7	.157	7.71	1.3136	.1366	2.00	.00	.0	.00	12990.	5662.	.00
20.0	1974.3	166.8	43883.	5000.0	110.1	98.8	.163	7.53	1.3139	.1367	2.00	.00	.0	.00	12899.	5666.	.00
21.0	2164.0	168.4	43882.	5000.0	114.6	102.8	.170	7.36	1.3141	.1367	2.00	.00	.0	.00	12791.	5669.	.00
22.0	2361.2	170.0	43880.	5000.0	118.9	106.6	.176	7.18	1.3144	.1367	2.00	.00	.0	.00	12695.	5673.	.00
23.0	2565.5	171.5	43878.	5000.0	123.1	110.4	.183	7.01	1.3146	.1368	2.00	.00	.0	.00	12601.	5676.	.00
24.0	2776.9	173.1	43877.	5000.0	127.2	114.1	.189	6.83	1.3149	.1368	2.00	.00	.0	.00	12509.	5680.	.00
25.0	2995.2	174.7	43875.	5000.0	131.2	117.7	.195	6.66	1.3152	.1368	2.00	.00	.0	.00	12420.	5684.	.00
26.0	3220.1	176.3	43874.	5000.0	135.1	121.2	.201	6.49	1.3155	.1368	2.00	.00	.0	.00	12335.	5688.	.00

ROTATION (TIME= 26.5 AND TAS= 137.2 EAS= 123.1)
 27.0 3451.6 177.8 43872. 5000.0 139.0 124.7 .206 6.28 1.3480 .1405 2.38 .00 .0 .76 12273. 5691. .38
 28.0 3689.4 179.4 43871. 5000.0 142.6 127.9 .212 5.84 1.4766 .1577 3.90 .00 .0 .88 12214. 5695. 1.90

LIFTOFF (TIME= 28.8 DIST= 3883.9 TAS= 145.3 EAS= 130.3)
 29.0 3933.0 181.0 43869. 5000.0 145.9 130.9 .217 5.30 1.6132 .1783 5.56 .01 2.1 1.02 12159. 5698. 3.57
 30.0 4182.0 182.6 43867. 5000.9 148.9 133.5 .221 4.67 1.6640 .1865 6.16 .50 131.3 1.10 12111. 5701. 4.66
 31.0 4435.7 184.2 43866. 5004.7 151.5 135.9 .225 4.30 1.6043 .1771 5.36 1.21 323.2 1.09 12066. 5704. 4.56
 32.0 4693.6 185.8 43864. 5011.6 154.0 138.1 .229 3.90 1.5616 .1706 4.86 1.90 517.2 1.10 12025. 5705. 4.76
 33.0 4955.4 187.4 43863. 5021.9 156.2 140.1 .232 3.54 1.5151 .1636 4.36 2.58 713.4 1.10 11986. 5706. 4.94

DISTANCE TO 35 FT.= 5212.8 TAS= 158.2 EAS= 141.8 V35/V5= 1.2535
 34.0 5220.6 188.9 43861. 5035.4 158.2 141.9 .235 3.17 1.4780 .1581 3.96 3.25 910.0 1.10 11951. 5707. 5.21
 35.0 5488.8 190.5 43860. 5052.2 160.0 144.4 .238 2.79 1.4510 .1543 3.66 3.91 1105.2 1.10 11918. 5707. 5.57

GEAR RETRACTION STARTED AT 34.9 SEC, COMPLETE AT 41.9 SEC
 36.0 5759.7 192.1 43858. 5072.3 161.6 144.8 .240 2.56 1.4164 .1451 3.26 4.56 1302.5 1.09 11887. 5706. 5.82
 37.0 6032.8 193.7 43856. 5095.6 163.0 146.1 .242 2.27 1.3993 .1390 3.06 5.21 1499.4 1.10 11859. 5705. 6.27
 38.0 6308.0 195.3 43855. 5122.3 164.3 147.1 .244 2.02 1.3736 .1317 2.76 5.86 1699.1 1.10 11832. 5703. 6.62
 39.0 6584.9 196.9 43853. 5152.2 165.5 148.1 .246 1.75 1.3565 .1259 2.56 6.49 1894.9 1.10 11807. 5700. 7.05
 40.0 6863.3 198.4 43852. 5185.5 166.4 148.9 .247 1.50 1.3394 .1202 2.36 7.12 2090.0 1.10 11785. 5697. 7.48
 41.0 7142.7 200.0 43850. 5221.9 167.3 149.6 .249 1.24 1.3309 .1155 2.26 7.74 2283.9 1.10 11763. 5694. 8.00
 42.0 7423.1 201.6 43848. 5261.6 168.0 150.1 .250 1.00 1.3137 .1102 2.06 8.36 2474.6 1.09 11744. 5689. 8.42
 43.0 7703.9 203.2 43847. 5304.4 168.4 150.4 .250 .65 1.3051 .1093 1.96 8.98 2663.2 1.09 11727. 5684. 8.93
 44.0 7985.0 204.8 43845. 5350.4 168.7 150.6 .251 .30 1.3052 .1093 1.96 9.59 2850.0 1.10 11713. 5679. 9.55
 45.0 8265.8 206.3 43844. 5399.4 168.8 150.5 .251 .01 1.2879 .1075 1.76 10.19 3028.1 1.09 11701. 5673. 9.95

FLAP RETRACTION STARTED AT 45.0 SEC, COMPLETE AT 49.5 SEC
 46.0 8546.4 207.9 43842. 5450.4 168.9 150.4 .251 .01 1.1295 .1061 2.46 10.26 3046.3 .95 11690. 5666. 10.71
 47.0 8827.2 209.5 43841. 5500.1 168.9 150.3 .251 -.01 1.0506 .1173 4.11 9.73 2892.5 .89 11680. 5660. 11.84

OVSTLKT= 113.1 KTS EAS VRAT= 1.100 CLTO= 1.7655

ENGINE OUT PERFORMANCE FOLLOWS

VEND = 204.1 KNOTS EAS
 (TEMP.= 537. DEG:STD.+36.)

TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (PPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	135.5	43915.	5000.0	.0	.0	.000	10.92	1.3108	.1363	2.00	.00	.0	.00	15783.	5621.	.00
1.0	5.4	137.0	43913.	5000.0	6.4	5.8	.010	10.77	1.3108	.1363	2.00	.00	.0	.00	15596.	5621.	.00
2.0	21.7	138.6	43911.	5000.0	12.8	11.5	.019	10.63	1.3108	.1363	2.00	.00	.0	.00	15411.	5621.	.00
3.0	48.6	140.2	43910.	5000.0	19.1	17.1	.028	10.47	1.3109	.1363	2.00	.00	.0	.00	15230.	5622.	.00
4.0	86.0	141.7	43908.	5000.0	25.2	22.6	.037	10.31	1.3109	.1363	2.00	.00	.0	.00	15051.	5624.	.00
5.0	133.7	143.3	43907.	5000.0	31.3	28.1	.046	10.15	1.3110	.1364	2.00	.00	.0	.00	14876.	5625.	.00
6.0	191.7	144.9	43905.	5000.0	37.3	33.4	.055	9.98	1.3111	.1364	2.00	.00	.0	.00	14705.	5627.	.00
7.0	259.6	146.4	43904.	5000.0	43.2	38.7	.064	9.81	1.3112	.1364	2.00	.00	.0	.00	14535.	5629.	.00
8.0	337.4	148.0	43902.	5000.0	48.9	43.9	.073	9.63	1.3114	.1364	2.00	.00	.0	.00	14369.	5631.	.00
9.0	424.9	149.5	43900.	5000.0	54.6	49.0	.081	9.45	1.3115	.1364	2.00	.00	.0	.00	14206.	5633.	.00
10.0	521.8	151.1	43899.	5000.0	60.2	54.0	.089	9.27	1.3117	.1364	2.00	.00	.0	.00	14046.	5635.	.00
11.0	628.1	152.7	43897.	5000.0	65.6	58.9	.097	9.08	1.3118	.1364	2.00	.00	.0	.00	13889.	5637.	.00
12.0	743.4	154.2	43896.	5000.0	71.0	63.7	.105	8.91	1.3120	.1365	2.00	.00	.0	.00	13759.	5640.	.00
13.0	867.8	155.8	43894.	5000.0	76.2	68.4	.113	8.75	1.3122	.1365	2.00	.00	.0	.00	13642.	5643.	.00
14.0	1000.9	157.4	43893.	5000.0	81.4	73.0	.121	8.58	1.3124	.1365	2.00	.00	.0	.00	13528.	5646.	.00
15.0	1142.6	158.9	43891.	5000.0	86.4	77.5	.128	8.41	1.3126	.1365	2.00	.00	.0	.00	13416.	5649.	.00
16.0	1292.7	160.5	43890.	5000.0	91.4	82.0	.136	8.23	1.3129	.1366	2.00	.00	.0	.00	13306.	5652.	.00
17.0	1451.1	162.1	43888.	5000.0	96.2	86.3	.143	8.06	1.3131	.1366	2.00	.00	.0	.00	13198.	5655.	.00
18.0	1617.7	163.7	43886.	5000.0	101.0	90.6	.150	7.89	1.3133	.1366	2.00	.00	.0	.00	13093.	5659.	.00
19.0	1792.1	165.2	43885.	5000.0	105.6	94.7	.157	7.71	1.3136	.1366	2.00	.00	.0	.00	12990.	5662.	.00
20.0	1974.3	166.8	43883.	5000.0	110.1	98.8	.163	7.53	1.3139	.1367	2.00	.00	.0	.00	12899.	5666.	.00
21.0	2164.0	168.4	43882.	5000.0	114.6	102.8	.170	7.36	1.3141	.1367	2.00	.00	.0	.00	12791.	5669.	.00
22.0	2361.2	170.0	43880.	5000.0	118.9	106.6	.176	7.18	1.3144	.1367	2.00	.00	.0	.00	12695.	5673.	.00
23.0	2565.5	171.5	43878.	5000.0	123.1	110.4	.183	7.01	1.3146	.1368	2.00	.00	.0	.00	12601.	5676.	.00
24.0	2776.9	173.1	43877.	5000.0	127.2	114.1	.189	6.83	1.3149	.1368	2.00	.00	.0	.00	12509.	5680.	.00
25.0	2995.2	174.7															

ENGINE FAILURE (TIME= 25.1 AND TAS= 131.7 EAS= 118.1)																	
26.0	3219.0	175.6	43874.	5000.0	133.2	119.5	.198	1.90	1.3154	.1450	2.00	.00	.0	.00	6188.	2843.	.00
27.0	3444.9	176.4	43874.	5000.0	134.3	120.5	.199	1.86	1.3155	.1448	2.00	.00	.0	.00	6176.	2843.	.00
28.0	3672.7	177.2	43873.	5000.0	135.4	121.5	.201	1.82	1.3155	.1446	2.00	.00	.0	.00	6165.	2844.	.00
29.0	3902.4	178.0	43872.	5000.0	136.5	122.5	.203	1.78	1.3156	.1444	2.00	.00	.0	.00	6157.	2844.	.00
0																	
ROTATION (TIME= 29.7 AND TAS= 137.2 EAS= 123.1)																	
30.0	4133.8	178.8	43871.	5000.0	137.5	123.4	.204	1.73	1.3274	.1455	2.14	.00	.0	.74	6148.	2845.	.14
31.0	4366.9	179.6	43870.	5000.0	138.5	124.2	.206	1.44	1.4559	.1619	3.66	.00	.0	.82	6140.	2845.	1.66
32.0	4601.5	180.4	43870.	5000.0	139.3	124.9	.207	1.11	1.5845	.1809	5.21	.00	.0	.91	6134.	2846.	3.21
33.0	4837.2	181.2	43869.	5000.0	139.8	125.4	.208	.74	1.7130	.2016	6.82	.00	.0	1.00	6130.	2846.	4.82
0																	
LIPTOFF (TIME= 33.0 DIST= 4837.2 TAS= 139.8 EAS= 125.4)																	
34.0	5073.6	182.0	43868.	5000.3	140.1	125.7	.208	.44	1.7655	.2106	7.47	.20	49.4	1.03	6127.	2846.	5.67
35.0	5310.5	182.7	43867.	5001.7	140.3	125.9	.208	.27	1.7655	.2106	7.39	.48	119.0	1.04	6125.	2846.	5.87
36.0	5547.6	183.5	43867.	5004.3	140.5	126.0	.209	.09	1.7655	.2107	7.31	.78	193.3	1.04	6124.	2846.	6.08
37.0	5784.9	184.3	43866.	5008.1	140.5	126.0	.209	.02	1.7405	.2065	6.97	1.05	260.7	1.02	6123.	2846.	6.02
38.0	6022.1	185.1	43865.	5012.8	140.5	126.0	.209	.00	1.7229	.2036	6.77	1.19	294.5	1.01	6123.	2846.	5.96
39.0	6259.3	185.9	43864.	5017.9	140.5	126.0	.209	.02	1.7040	.2004	6.57	1.25	309.9	1.00	6122.	2845.	5.82
40.0	6496.5	186.7	43863.	5023.1	140.5	126.0	.209	.02	1.7023	.2001	6.57	1.26	313.5	1.00	6121.	2845.	5.83
41.0	6733.8	187.5	43863.	5028.3	140.5	126.0	.209	.02	1.7009	.1999	6.57	1.27	314.9	1.00	6121.	2845.	5.84
42.0	6971.1	188.3	43862.	5033.6	140.5	126.0	.209	.02	1.6999	.1998	6.57	1.27	315.0	1.00	6120.	2844.	5.84
0																	
DISTANCE TO 35 FT.= 7036.4 TAS= 140.5 EAS= 126.0 V35/V5= 1.1140																	
43.0	7208.4	189.1	43861.	5038.8	140.5	126.0	.209	.02	1.6992	.1996	6.57	1.27	315.1	1.00	6119.	2844.	5.84
44.0	7445.7	189.9	43860.	5044.1	140.6	126.0	.209	.02	1.6987	.1996	6.57	1.27	315.4	1.00	6119.	2844.	5.84
45.0	7683.1	190.7	43860.	5049.3	140.6	126.0	.209	.02	1.6983	.1995	6.57	1.27	316.1	1.00	6118.	2843.	5.84

ACCELERATE - STOP DISTANCE = 6762.3 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 7036.4 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 5212.8 FEET
 PAR 25 T.O. DISTANCE (1.15XL) = 5994.8 FEET
 0 ALL ENGINE DISTANCE TO 50 FT. = 5455.8 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .180 HRS FUEL USED= 209. LBS WEIGHT= 43841. LBS ALT.= 5500. FT.

ACCELERATE TO MACH NO. = .415

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.180	.00	209.5	43841.	5500.	163.	150.	.251	.724	11950.	5579.
.188	1.99	260.3	43790.	5500.	269.	248.	.415	.806	10197.	5733.

END OF ACCELERATION SEGMENT
 TIME= .188 HRS FUEL USED= 260.3 LBS WEIGHT= 43790. LBS RANGE= 2. NM
 0 CLIMB TO 35000. FT. AT MAXIMUM RATE OF CLIMB

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	PUS. ANGLE (DEG)	R/C (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
.188	2.	260.	43790.	5500.	247.	228.	.380	.798	.5214	.0389	4.24	7.68	9.92	3344.	9091.	5042.
.191	3.	273.	43777.	6000.	248.	227.	.382	.797	.5255	.0391	4.28	7.27	9.55	3179.	9011.	4994.
.196	4.	299.	43751.	7000.	251.	226.	.388	.797	.5291	.0393	4.31	6.89	9.20	3051.	8826.	4895.
.202	5.	326.	43724.	8000.	254.	225.	.394	.797	.5331	.0395	4.34	6.68	9.02	2993.	8640.	4795.
.207	7.	352.	43698.	9000.	263.	229.	.409	.799	.5448	.0385	4.11	5.61	7.71	2598.	8383.	4691.
.214	8.	383.	43667.	10000.	265.	228.	.415	.798	.5498	.0388	4.15	6.16	8.31	2884.	8214.	4587.
.219	10.	409.	43641.	11000.	268.	227.	.421	.797	.5524	.0391	4.20	6.34	8.54	2994.	8047.	4486.
.225	11.	434.	43616.	12000.	270.	225.	.426	.797	.5519	.0395	4.26	5.76	8.02	2751.	7880.	4387.
.231	13.	461.	43589.	13000.	273.	224.	.432	.796	.5581	.0398	4.32	5.56	7.88	2683.	7714.	4290.
.237	15.	487.	43563.	14000.	276.	223.	.438	.795	.5645	.0402	4.38	5.37	7.74	2614.	7549.	4196.
.244	16.	514.	43536.	15000.	279.	221.	.444	.794	.5510	.0406	4.43	5.17	7.60	2543.	7385.	4104.
.250	18.	541.	43509.	16000.	285.	222.	.456	.795	.5453	.0402	4.34	4.55	6.90	2289.	7179.	4009.
.257	20.	570.	43480.	17000.	288.	221.	.462	.794	.5522	.0406	4.40	4.69	7.10	2384.	7001.	3908.
.264	22.	597.	43453.	18000.	290.	220.	.469	.793	.5594	.0411	4.46	4.48	6.95	2300.	6826.	3809.
.272	24.	625.	43425.	19000.	293.	218.	.475	.792	.5666	.0415	4.53	4.27	6.80	2215.	6654.	3712.
.279	27.	653.	43397.	20000.	296.	217.	.482	.791	.5739	.0419	4.59	4.07	6.66	2131.	6485.	3617.
.287	29.	681.	43369.	21000.	299.	215.	.489	.791	.5814	.0424	4.65	3.87	6.52	2047.	6318.	3524.
.295	31.	710.	43340.	22000.	303.	214.	.497	.790	.5861	.0427	4.68	3.59	6.27	1927.	6149.	3434.
.304	34.	740.	43310.	23000.	307.	213.	.505	.789	.5920	.0430	4.72	3.42	6.14	1857.	5985.	3346.
.313	37.	770.	43280.	24000.	314.	214.	.519	.790	.5861	.0427	4.61	2.95	5.56	1635.	5800.	3267.
.323	40.	803.	43247.	25000.	318.	213.	.527	.789	.5923	.0431	4.65	2.99	5.64	1676.	5628.	3187.
.333	43.	835.	43215.	26000.	321.	212.	.535	.788	.5992	.0435	4.70	2.79	5.49	1586.	5460.	3109.
.343	46.	867.	43183.	27000.	326.	211.	.546	.788	.6030	.0437	4.71	2.53	5.24	1457.	5291.	3033.
.355	50.	902.	43148.	28000.	330.	210.	.554	.787	.6098	.0442	4.75	2.39	5.14	1394.	5130.	2957.
.367	54.	937.	43113.	29000.	334.	209.	.564	.786	.6164	.0446	4.79	2.20	4.98	1296.	4972.	2882.
.380	58.	974.	43076.	30000.	361.	221.	.611	.795	.5482	.0404	3.92	1.13	3.05	721.	4747.	2847.
.403	67.	1040.	43010.	31000.	363.	219.	.618	.793	.5596	.0411	4.01	1.76	3.77	1129.	4587.	2750.
.418	72.	1081.	42969.	32000.	366.	216.	.626	.792	.5715	.0418	4.10	1.58	3.68	1021.	4431.	2656.
.434	78.	1124.	42926.	33000.	369.	214.	.634	.790	.5835	.0425	4.19	1.40	3.59	916.	4278.	2564.
.452	85.	1171.	42879.	34000.	374.	213.	.645	.789	.5902	.0429	4.21	1.17	3.38	771.	4128.	2478.
.474	93.	1224.	42826.	35000.	378.	211.	.656	.789	.5971	.0434	4.23	1.01	3.24	673.	3982.	2393.

0 END OF CLIMB TO 35000. FT
 TIME= .474 HRS FUEL USED= 1224. LBS WEIGHT= 42826. LBS RANGE= 93. NM
 0 ALTITUDE= 35000. FT TAS= 459.35 KTS MACH NO= .7959

ACCELERATE TO MACH NO. = .800

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.474	92.90	1224.5	42826.	35000.	378.	211.	.656	.788	4255.	2721.
.525	115.47	1372.4	42678.	35000.	461.	258.	.800	.812	4348.	2842.

END OF ACCELERATION SEGMENT
 TIME= .525 HRS FUEL USED= 1372.4 LBS WEIGHT= 42678. LBS RANGE= 115. NM
 SPECIFIED MACH NUMBER CONDITION CAN NOT BE PERFORMED AT NORMAL RATED POWER CONDITION

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (continued)

ACCELERATE TO MACH NO. = .796

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.474	92.90	1224.5	42826.	35000.	378.	211.	.656	.788	4255.	2721.
.523	114.77	1368.2	42682.	35000.	459.	256.	.796	.812	4345.	2839.

END OF ACCELERATION SEGMENT
 TIME= .523 HRS FUEL USED= 1368.2 LBS WEIGHT= 42682. LBS RANGE= 115. NM

ACCELERATE TO MACH NO. = .813

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.474	92.90	1224.5	42826.	35000.	378.	211.	.656	.788	4255.	2721.
.529	117.77	1386.4	42664.	35000.	469.	262.	.813	.813	4359.	2851.

END OF ACCELERATION SEGMENT
 TIME= .529 HRS FUEL USED= 1386.4 LBS WEIGHT= 42664. LBS RANGE= 118. NM

DESIGN CASE
 CRUISE PERFORMANCE SUMMARY
 FOR
 ***** DESIGN PAYLOAD *****
 ***** MAXIMUM PAYLOAD *****
 ***** MAXIMUM FUEL *****
 FUEL AVAILABLE= 8372.

		AT SPECIFIED SPEED		AT NORMAL POWER		AT BEST SPEC. RANGE	
		START CRUISE	END CRUISE	START CRUISE	END CRUISE	START CRUISE	END CRUISE
TIME	HRS.	.000	.000	.523	2.634	.529	2.838
RANGE	N.MI	0.	0.	115.	1084.	118.	1202.
FUEL USED	LBS.	0.	0.	1368.	6008.	1386.	6627.
WEIGHT	LBS.	0.	0.	42682.	38042.	42664.	37423.
ALTITUDE	FT.	0.	0.	35000.	35000.	35000.	35000.
TAS	KTS.	.0	.0	459.3	459.3	469.3	469.3
EAS	KTS.	.0	.0	256.0	256.0	261.6	261.6
MACH NO.		.0000	.0000	.7959	.7959	.8133	.8133
DIV. MACH		.0000	.0000	.8120	.8188	.8141	.8199
ANGLE ATTACK	DEG.	.000	.000	1.880	1.403	1.661	1.260
FUSE. ANGLE	DEG.	.000	.000	-.120	-.597	-.339	-.740
CL		.0000	.0000	.4068	.3509	.3895	.3416
L/D		.000	.000	12.261	11.328	12.042	11.188
FUEL FLOW	LB/HR	.0	.0	2262.5	2137.6	2327.1	2216.9
BREG. FACTOR	N.MI.	0.	0.	8671.	8180.	8610.	7928.
SPEC. RANGE	NM/LB	.00000	.00000	.20303	.21489	.20169	.21172

DESCENT FROM CRUISE AT NORMAL POWER CONDITION
 (U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MMO OR VMO)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ANGLE (DEG)	R/S (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
2.647	1090.	6027.	38023.	35000.	459.	256.	.796	.818	.3589	.0312	1.47	-1.65	-2.18	1339.	2209.	1538. R
2.659	1096.	6048.	38002.	34000.	461.	263.	.796	.820	.3422	.0306	1.33	-1.60	-2.27	1306.	2332.	1627. R
2.672	1102.	6071.	37979.	33000.	463.	269.	.796	.822	.3265	.0300	1.19	-1.53	-2.36	1271.	2463.	1721. R
2.686	1108.	6095.	37955.	32000.	465.	275.	.796	.824	.3115	.0295	1.07	-1.51	-2.44	1241.	2597.	1819. R
2.700	1115.	6121.	37929.	31000.	468.	281.	.796	.825	.2974	.0291	.94	-1.46	-2.52	1209.	2739.	1922. R
2.714	1121.	6150.	37900.	30000.	470.	288.	.796	.827	.2840	.0287	.83	-1.42	-2.59	1180.	2885.	2029. R
2.728	1128.	6181.	37869.	29000.	472.	295.	.796	.829	.2713	.0283	.72	-1.38	-2.66	1153.	3035.	2140. R
2.743	1135.	6214.	37836.	28000.	474.	301.	.796	.830	.2593	.0280	.62	-1.34	-2.73	1127.	3190.	2255. R
2.758	1143.	6250.	37800.	27000.	476.	308.	.796	.831	.2478	.0277	.52	-1.31	-2.79	1100.	3354.	2377. R
2.774	1150.	6289.	37761.	26000.	478.	315.	.796	.833	.2370	.0274	.43	-1.27	-2.85	1077.	3537.	2509. R
2.789	1158.	6331.	37719.	25000.	480.	322.	.796	.834	.2267	.0271	.34	-1.24	-2.90	1053.	3711.	2640. R
2.806	1165.	6376.	37674.	24000.	482.	329.	.796	.835	.2169	.0269	.26	-1.21	-2.96	1032.	3889.	2775. R
2.822	1173.	6424.	37626.	23000.	484.	336.	.796	.836	.2075	.0267	.18	-1.18	-3.01	1011.	4075.	2916. R
2.839	1181.	6475.	37575.	22000.	486.	343.	.796	.837	.1987	.0265	.10	-1.15	-3.05	992.	4265.	3062. R
2.856	1190.	6530.	37520.	21000.	484.	348.	.790	.838	.1900	.0264	.06	-1.13	-3.07	972.	4460.	3215. R
2.861	1192.	6533.	37517.	20000.	415.	303.	.675	.831	.2525	.0278	.83	-4.83	-6.00	3543.	951.	685. A
2.866	1194.	6536.	37514.	19000.	410.	305.	.665	.831	.2497	.0277	.82	-4.82	-6.00	3498.	991.	717. A
2.870	1196.	6540.	37510.	18000.	406.	307.	.655	.832	.2469	.0276	.81	-4.81	-6.00	3452.	1033.	750. A
2.875	1198.	6544.	37506.	17000.	401.	308.	.645	.832	.2442	.0276	.80	-4.80	-6.00	3407.	1076.	784. A
2.880	1200.	6548.	37502.	16000.	397.	310.	.636	.832	.2414	.0275	.79	-4.79	-6.00	3363.	1121.	820. A
2.885	1202.	6552.	37498.	15000.	393.	312.	.626	.833	.2387	.0274	.78	-4.78	-6.00	3319.	1167.	857. A
2.890	1203.	6557.	37495.	14000.	389.	314.	.618	.833	.2359	.0273	.77	-4.77	-6.00	3275.	1215.	895. A
2.895	1205.	6562.	37488.	13000.	385.	316.	.609	.833	.2332	.0273	.75	-4.75	-6.00	3232.	1264.	935. A
2.901	1207.	6567.	37483.	12000.	381.	317.	.601	.834	.2304	.0272	.74	-4.74	-6.00	3189.	1315.	977. A
2.906	1209.	6572.	37478.	11000.	377.	319.	.592	.834	.2277	.0271	.72	-4.72	-6.00	3147.	1368.	1020. A
2.916	1212.	6580.	37470.	10000.	291.	250.	.446	.816	.3717	.0316	2.45	-3.21	-2.76	1653.	1079.	776. S
2.926	1215.	6588.	37462.	9000.	286.	250.	.438	.816	.3716	.0316	2.47	-3.16	-2.69	1599.	1116.	805. S
2.937	1218.	6597.	37453.	8000.	282.	250.	.438	.816	.3716	.0316	2.48	-3.10	-2.62	1546.	1154.	835. S
2.948	1222.	6607.	37443.	7000.	277.	250.	.430	.816	.3715	.0316	2.49	-3.04	-2.55	1493.	1193.	866. S
2.960	1225.	6617.	37433.	6000.	273.	250.	.422	.816	.3714	.0316	2.50	-2.98	-2.48	1441.	1233.	898. S
2.972	1228.	6628.	37422.	5000.	269.	250.	.414	.816	.3713	.0316	2.51	-2.92	-2.41	1389.	1275.	930. S
2.984	1231.	6640.	37410.	4000.	265.	250.	.406	.816	.3712	.0316	2.52	-2.85	-2.33	1338.	1318.	965. S
2.997	1235.	6653.	37397.	3000.	261.	250.	.399	.816	.3711	.0316	2.53	-2.78	-2.25	1287.	1362.	1000. S
3.011	1238.	6667.	37383.	2000.	257.	250.	.391	.816	.3710	.0316	2.54	-2.72	-2.18	1236.	1407.	1036. S
3.018	1240.	6675.	37375.	1500.	255.	250.	.388	.816	.3708	.0316	2.54	-2.68	-2.14	1211.	1430.	1055. S

END OF DSCNT TO 1500. FT
 TIME= 3.018 HRS FUEL USED= 6675. LBS WEIGHT= 37375. LBS RANGE= 1240. NM

RESERVE FUEL(LBS) 0. 1697. 1745.
 (45.0 MIN.)

RANGE = 1240. BLOCK TIME= 3.018 USED FOR DESIGN RANGE AND COST

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (continued)

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0 .....
0 TEMP.= 537. DEG:STD.+36.
  LANDING ELEVATION= 5000. FT.
  LANDING WING LOADING= 87.39 PSF.
  LANDING WEIGHT = 41407. LBS.

  LANDING DISTANCE FROM 50. FT.= 2979. FT.

  F.A.R. FACTORED FIELD LENGTH = 4966. FT.
0 APPROACH TRANSITION DELAY ROLL
0 DIST= 702. DIST= 205. DIST= 207. DIST= 1865.
  N/S= 1000. XLFMT= 1.200 TDELAY= 1.00 MUB= .4000
  VAPEAS= 124.45 SINKTD= 3.000 TIDLE= 583. TR/TIDLE= .0000
  VARTAS= 138.87 VSTEAS= 95.73 VTDAS= 122.84 ABAR(G)= .3588
  THETA= 4.07 CLMX= 2.8112
  THRUST= 3004. HPLAR= 20.9
0 .....
0 .....
0 RANGE OR ENDURANCE ITERATION SUMMARY
  GROSS RANGE(MCI) OR
  ITERATION WEIGHT(LB) ENDURANCE(HS)
  0 44050.00 1239.808
  REQUIRED RG. OR END. = 1250.000

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
  ANGLE OF ATTACK(DEGREES)= 2.218 LIFT= 42728.5 L/D= 12.793 ALTITUDE= 35000.0 MACH= .8000

0 GROSS WEIGHT = 44050. PASSENGERS = 50. PLUS CREW

0 FUSELAGE LENGTH (ELF) 79.25 FT
  WIDTH (SWF) 9.25 FT
  WETTED AREA (SF) 1910. SQFT
  DELTA P (DELP) 8.20 PSI

0 WING ASPECT RATIO (AR) 8.40
  AREA (SW) 409.1 SQFT
  SPAN (S) 58.6 FT
  GEOM. MEAN CHORD (CBARM) 8.01 FT
  QUARTER CHORD SWEEP (DLMC4) 14.5 DEG
  TAPER RATIO (SLM) .202
  ROOT THICKNESS (TCR) .130
  TIP THICKNESS (TCT) .100
  WING LOADING (WGS) 93.0 PSF
  WING FUEL VOLUME (VFW) 956.3 GAL

0 CANARD ASPECT RATIO (ARcan) 6.10
  AREA (SWc) 64.8 SQFT
  SPAN (Bcan) 19.9 FT
  GEOM. MEAN CHORD (CBARc) 3.38 FT
  QUARTER CHORD SWEEP (DwpqCa) 20.5 DEG
  TAPER RATIO (SLMcan) .503
  THICKNESS/CHORD (TCcan) .100
  MOMENT ARM (ELcan) 33.0 FT
  VOLUME COEFF. (VBARc) .652
  CANARD LOADING (WGS) 93.0 PSF

0 HOR. TAIL ASPECT RATIO (ARHT) 3.91
  AREA (SHT) 77.3 SQFT
  SPAN (BHT) 17.38 FT
  MEAN CHORD (CBARHT) 4.57 FT
  THICKNESS/CHORD (TCHT) .100
  MOMENT ARM (ELTH) 44.1 FT
  VOLUME COEFF. (VBARH) 1.041

0 VERT. TAIL ASPECT RATIO (ARVT) .89
  AREA (SVT) 100.9 SQFT
  SPAN (BVT) 9.50 FT
  MEAN CHORD (CBARVT) 10.73 FT
  THICKNESS/CHORD (TCVT) .120
  MOMENT ARM (ELTV) 34.0 FT
  VOLUME COEFF. (VBARV) .143

0 ENG. NACELLES LENGTH (ELN) 11.33 FT
  MEAN DIAMETER (DBARN) 3.78 FT
  NUMBER ENGINES (ENP) 2.0
  WETTED AREA (SN) 268.67 SQFT

  LOCATION ON FUSELAGE

0 VDIVE = 715. KTS VM0 = 596. KTS MMO = .900
  ULT. LP = 5.06 MAN. LP = 2.50 GUST LP = 3.37

0 PROPULSION GROUP
  PRIMARY ENGINES (WEP) 2848.
  PRIMARY ENGINE INSTL. (WPEI) 384.
  FUEL SYSTEM (WFSS) 167.
  TOTAL PROP.GROUP WT. (WP) 3400.

0 STRUCTURES GROUP
  WING (WM) 4097.
  CANARD (WMC) 391.
  HOR. TAIL (WHT) 402.
  VERT. TAIL (WVT) 364.
  FUSELAGE (WB) 5941. (INCL. .0 LBS A.T.W.)
  LANDING GEAR (WLG) 1674.
  PRIMARY ENG. SECTION (WPE5) 953.
  GROUP WEIGHT INC. (DELWST) 0.
  TOTAL STRUC.GROUP WT. (WST) 13822.

0 FLIGHT CONTROLS GROUP
  COCKPIT CONTROLS (WCC) 94.
  FIXED WING CONTROLS (WCFW) 772.
  SAS (WSAS) 0.
  GROUP WEIGHT INC. (DELWFC) 0.
  TOTAL CONTROL WT. (WPC) 866.

0 WT. OF FIXED EQUIPMENT (WFE) 6525.

```

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (continued)


```

WEIGHT EMPTY          (WE)      24612.
FIXED USEFUL LOAD     (WFUL)     1065. (INC. CREW )
OPERATING WEIGHT EMPTY (OWE)     25678.
0 PAYLOAD              (WPL)     10000. (PAK.VOL.= 50.  DESIGN PAX= 50.)
FUEL                   (WFA)     8372. (WFW= 6394.) (WTFP= 0.)
GROSS WEIGHT          (WG)      44050.
0 FIXED EQUIP GROUP   (WG)      44050.
0 WAFU                 372.27      WCREW ( 2.)      340.00
  WINSTR               225.76      WSTU ( 1.)      130.00
  WHYD                 354.45      WCBAG            110.00
  WELEC                970.00      WUF             121.36
  WAV                  500.00      WOIL            120.11
  WFUR                 3410.00     WSRV            116.00
  WAC                  477.91      WH2O            53.00
  WAI                  194.63      WEMER           40.00
  MAUXG                20.00      WCATER          35.00
  WFE                  6525.03     WFUL            1065.47
  
```

```

0 DESIGN MACH = .800          DESIGN ALTITUDE = 35000.          DESIGN Q (PSF) =224.03
0 DESIGN RE.NUM. PER FT.    = 1.922E+06    PLATPLATE CF AT RE=10EX7 IS .00274
0 AERODYNAMIC DATA
  
```

```

0 DRAG BREAKDOWN          FLATPLATE          WETTED
0 WING                    AREA(SQFT)      CDO          AREA(SQFT)
  CANARD                   .4755          .00100       58.57
  FUSELAGE                 5.4592        .01152      1910.38
  VERT. TAIL               .6238         .00132       201.76
  HOR. TAIL                .5241         .00111       154.56
  ENGINE NAC.             1.2147        .00256       268.67
  TIP TANKS                .0000         .00000        .00
  INCREMENTAL             .7107         .00150        .00
0 TOTAL                   11.7367       .02477      3210.72
  
```

MEAN SKIN FRICTION COEF. = .003655

```

0 AERODYNAMIC COEFF.          AIRCRAFT          WING          CANARD
                                (except Wing and Canard)
  A1                          .8019
  A2                          -.1227          -.8441
  A3                          .0381          -.1244
  A4=-.75X(T/C)              .0902          .0263
  A5=CDO--                   .0152          .0750
  A6                          2.4345          2.6794
  A7=1/(PI.SEE.AR)           .0478          .0625
  3-D LIFT SLOPE AT CRUISE MACH (CLALPH) 6.7297 PER RAD. (CLALFcc) 5.6718 PER RAD.
  OSWALD FACTOR              (SEE)         .7932          (SEEcann) .8353
  
```

```

0 CRUISE CD = .0246 + .0498 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
0 RETRACTABLE LANDING GEAR CD INC. = .03079
  
```

```

0 CRUISE DRAG
OCL= .2000
  MACH  CD  L/D  CLALPH  ALPHA
.50000 .02659 7.5214 5.3570 .5391
.55000 .02659 7.5214 5.4905 .4871
.60000 .02659 7.5214 5.6500 .4282
.65000 .02659 7.5214 5.8418 .3616
.70000 .02659 7.5214 6.0753 .2862
.75000 .02659 7.5214 6.3640 .2006
.80000 .02659 7.5214 6.7297 .1028
.85000 .02664 7.5064 7.2091 -.0105
OCL= .3000
  MACH  CD  L/D  CLALPH  ALPHA
.50000 .02922 10.2671 5.3570 1.6086
.55000 .02922 10.2671 5.4905 1.5306
.60000 .02922 10.2671 5.6500 1.4423
.65000 .02922 10.2671 5.8418 1.3423
.70000 .02922 10.2671 6.0753 1.2293
.75000 .02922 10.2671 6.3640 1.1009
.80000 .02922 10.2671 6.7297 .9542
.85000 .02962 10.1268 7.2091 .7843
OCL= .4000
  MACH  CD  L/D  CLALPH  ALPHA
.50000 .03284 12.1786 5.3570 2.6782
.55000 .03284 12.1786 5.4905 2.5742
.60000 .03284 12.1786 5.6500 2.4563
.65000 .03284 12.1786 5.8418 2.3231
.70000 .03284 12.1786 6.0753 2.1724
.75000 .03284 12.1786 6.3640 2.0012
.80000 .03284 12.1786 6.7297 1.8056
.85000 .03419 11.6999 7.2091 1.5791
OCL= .5000
  MACH  CD  L/D  CLALPH  ALPHA
.50000 .03764 13.2845 5.3570 3.7477
.55000 .03764 13.2845 5.4905 3.6177
.60000 .03764 13.2845 5.6500 3.4704
.65000 .03764 13.2845 5.8418 3.3039
.70000 .03764 13.2845 6.0753 3.1155
.75000 .03764 13.2845 6.3640 2.9016
.80000 .03764 13.2845 6.7297 2.6569
.85000 .04080 12.2559 7.2091 2.3739
  
```

Fig E8 - Three-Lifting Surface Configuration load optimised for minimum D.O.C. -GASP solution (continued)

OCL= .6000

MACH	CD	L/D	CLALPH	ALPHA
.50000	.04343	13.8161	5.3570	4.8173
.55000	.04343	13.8161	5.4905	4.6613
.60000	.04343	13.8161	5.6500	4.4845
.65000	.04343	13.8161	5.8418	4.2847
.70000	.04343	13.8161	6.0753	4.0586
.75000	.04343	13.8161	6.3640	3.8019
.80000	.04347	13.8027	6.7297	3.5083
.85000	.04957	12.1050	7.2091	3.1686

0 LOW SPEED LIFT/DRAG-GR. UP (IF R) O.G.E.

FLAPS UP					TAKEOFF			LANDING		
ALPHA	CL	CD	L/D	CL	CD	L/D	CL	CD	L/D	
-2.00000	-.03407	.02473	-1.37780	.96336	.07973	12.08279	1.65029	.21535	7.66337	
.00000	.13627	.02550	5.34366	1.13371	.09249	12.25703	1.82063	.23184	7.85291	
2.00000	.30662	.02943	10.41896	1.30405	.10919	11.94293	1.99097	.25290	7.87242	
4.00000	.47696	.03645	13.08700	1.47439	.13105	11.25101	2.16131	.28033	7.70978	
6.00000	.64730	.04668	13.86744	1.64473	.15719	10.46357	2.33166	.31114	7.49381	
8.00000	.81764	.06036	13.54670	1.81507	.18628	9.74394	2.50200	.34533	7.24514	
10.00000	.98798	.07804	12.66043	1.98542	.21832	9.09418	2.67234	.38291	6.97911	
11.60582	1.12475	.09671	11.63045	2.12219	.24618	8.62057	2.80911	.41552	6.76050	
11.60582	1.12475	.09671	11.63045	2.12219	.24618	8.62057	2.80911	.41552	6.76050	
11.60582	1.12475	.09671	11.63045	2.12219	.24618	8.62057	2.80911	.41552	6.76050	

0 DFLAP= .00 DFLAP= 15.00 DFLAP= 40.00
 0 CLMAX= 1.12475 CLMAX= 2.13630 CLMAX= 2.81117

0 LOW SPEED AERO FOR OTHER FLAP DEFLECTIONS

FLAP DEFL.	CLMAX	CD	L/D
10.000	1.82484	.66395	.06004 11.05910
		.83430	.07012 11.89819
		1.00464	.08363 12.01243
		1.17498	.10126 11.60323
		1.34532	.12461 10.79634
		1.51566	.15133 10.01548
		1.68601	.18097 9.31626
		1.82484	.20729 8.80317
		1.82484	.20729 8.80317
		1.82484	.20729 8.80317
20.000	2.34077	1.17988	.10274 11.48397
		1.35022	.11692 11.54853
		1.52057	.13515 11.25095
		1.69091	.15947 10.60310
		1.86125	.18692 9.95752
		2.03159	.21734 9.34732
		2.20193	.25075 8.78138
		2.34077	.28018 8.35450
		2.34077	.28018 8.35450
		2.34077	.28018 8.35450
30.000	2.64425	1.48337	.15076 9.83947
		1.65371	.16650 9.93248
		1.82405	.18676 9.76676
		1.99440	.21270 9.37637
		2.16474	.24174 8.95486
		2.33508	.27386 8.52641
		2.50542	.30908 8.10603
		2.64425	.34007 7.77562
		2.64425	.34007 7.77562
		2.64425	.34007 7.77562

0 ALTITUDE= 35000. FT TAS= 464.69 KTS MACH NO= .8052

0 RDT&E AND AIRFRAME PRODUCTION COSTS

(1993. DOLLARS)
 TOTAL RDT&E COSTS 993.3629 MILLION
 AIRFRAME PRODUCTION COSTS (INCLUDING 10% PROFIT) 500. AIRCRAFT

	WEIGHT (LB)	COST (\$)	COST (\$/LB)
STRUCTURE(3995327.\$)			
WING	4097.	1043440.	254.67
CANARD	391.	172598.	441.25
EMPELLAGE	765.	303602.	396.75
FUSELAGE	5941.	1651581.	277.99
LANDING GEAR	1674.	299190.	178.74
NACELLES	953.	524917.	550.85
PROPULSION INSTAL(163700.\$)			
ENGINE INSTALLAT.	384.	139967.	364.08
FUEL SYSTEM	167.	23733.	141.74
SYSTEMS(2518139.\$)			
FLIGHT CONTROLS	866.	406655.	469.41
HYDRAULIC	354.	44153.	124.57
ELECTRICAL	970.	464214.	478.37
AIR CONDITIONING	478.	256070.	535.82
ANTI-ICING	195.	102504.	526.66
AUX. POWER UNIT	372.	207143.	556.42
FURNISHINGS	3410.	796443.	233.56
INSTRUMENTS	226.	187254.	829.44
AVIONICS INSTALL.	250.	49032.	196.13
AUX. ITEMS	20.	4671.	233.56
INTEGRATION(1669292.\$)			
AIRFRAME TOTALS	21515.	8346460.	387.94
ENGINES		2633756.	
PROPELLER		0.	
AVIONICS		4000000.	
A/C COST (NO RD)		14880216.	
R&D PER A/C		1986726.	
TOTAL A/C COST		16966942.	

0 ENGINES NUMBER = 2. TYPE= 7

0 EMPTY WEIGHT= 24612. AIRFRAME WEIGHT= 21765. WEIGHT OF 1 ENGINE= 1424. CRUISE SPEED= 465. KTS

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (continued)

0 THRUST/ENGINE= 8899.
 0 TOTAL AIRCRAFT COST= 16966942. AIRFRAME COST= 14333186. COST OF 1 ENGINE= 1316878. COST OF 1 PROP.= 0.

```

0          --- COST DATA ---
0          GASP SHORThAUL METHOD
0          DESIGN MISSION
0          OPERATING COST FOR NOR.RATED POWER AND 35000. ALTITUDE
0          *****
0          RANGE= 1240. N.M.   BLOCK FUEL= 6675. LBS   BLOCK TIME= 3.0178 HRS.
0          UTILIZATION
0          3200.
0          FLYING OPERATIONS
0          FLIGHT CREW          377.221
0          FUEL, OIL, AND TAXES( .850$/G) 886.612
0          INSURANCE          80.003
0          DIRECT MAINTENANCE
0          AIRFRAME          166.277
0          ENGINE            285.988
0          MAINTENANCE BURD.  368.498
0          DEPRECIATION      1075.247
0          TOTAL DOC ($/TRIP)  3239.846
0          ($/B.HR.)         1073.592
0          ($/N.MI.)         2.613
  
```

Fig E8 - Three-Lifting Surface Configuration optimised for minimum D.O.C. -GASP solution (concluded)

```
C
C
C          SUBROUTINES USERF & USERD
C
C          BY
C
C          J.NUNES
C
C          1993
C
C          College of Aeronautics
C
C          CRANFIELD INSTITUTE OF TECHNOLOGY
C
```

```
SUBROUTINE USERF(x,func,iocode,nprob,icallf,nfe)
```

```
integer iocode(76)
real x(50),func(76)
```

```
C Variable declarations:
```

```
.....
.....
```

```
C Common Block declarations:
```

```
.....
.....
```

```
C Assignment of the Independent Variable values:
```

```
WGS      = X(1)
AR       = X(2)
DLMC4    = X(3)
SLM      = X(4)
ARHT     = X(5)
DWPQCH   = X(6)
ARVT     = X(7)
DWPQCV   = X(8)
ARcan    = X(9)
DwpqCa   = X(10)
SLMcan   = X(11)
EYEcan   = X(12)
SWCOSW   = X(13)
RELP     = X(14)
```

```
C Execution of the Design Synthesis subroutine.
```

```
CALL MAIN(icallf,nfe)
```

```
C Objective Function:
```

```
FUNC(1) = DATOUT(5)
```

```
C Inequality Constraints:
```

```
FUNC(2) = 6000. - DATOUT(92)
FUNC(3) = 5000. - DATOUT(49)
FUNC(4) = 125. - DATOUT(51)
FUNC(5) = DATOUT(109) - .76
FUNC(6) = .86 - DATOUT(109)
```

```
DO I=2,6
FUNC(I) = -FUNC(I)
```

Fig E9 - USERF.F and USERD.F subroutines used for the Maximum Take-off Weight optimisation cases

```
END DO

RETURN
END

SUBROUTINE USERD(x,gradcd,iocode,nprob)

integer iocode(76)
real x(50),gradcd(50)

WRITE(2,100)
100 FORMAT( 'SUBROUTINE USERD CALLED, NO DERIVATIVES AVAILABLE')
END
```

Fig E9 - USERF.F and USERD.F subroutines used for the Maximum Take-off Weight optimisation cases (concluded)

*....data for 50 Pax turbofan airliner

VARIABLES

01	1	95.0	83.000	80.000	105.000
02	1	9.0	8.300	8.000	10.000
03	1	23.0	14.500	11.000	35.000
04	1	.235	.200	.160	.310
05	1	4.0	4.000	3.800	4.300
06	1	27.5	27.500	20.000	35.000
07	1	1.0	1.000	.800	1.200
08	1	46.5	50.500	40.000	53.000
09	0	6.0	5.500	4.000	8.000
10	0	23.0	15.000	10.000	35.000
11	0	.43	.500	.160	.700
12	0	1.5	2.000	.000	3.000
13	0	.15	.15	.145	.175
14	0	.8	.75	.75	.85

FUNCTIONS

01	00	0045000.0	1
02	-1	00 6000.0	
03	-1	00 5000.0	
04	-1	00 120.0	
05	-1	00 .8	
06	-1	00 .8	

CONTROLS

XTOLU = .0001
 XTOLV = .0001
 OFROM = 1
 OFREQ = 10
 RFREQ = 50
 NFEMAX = 20000
 RUN
 END

Fig E10 - RQPMIN.DAT file for the Conventional M.T.O.W. optimisation case

1Program RQPMIN Version 1.0 for VAX

ANALYSIS OF INPUT FILE DATA AND CONTROL PARAMETERS

Input file: rqpmin.dat
Output file: rqpmin.res

Variable data

Number of variables = 14

Index	Status	Scale	Starting value	Lower bound	Upper bound
1	1	.9500000E+02	.8736842E+00	.8421053E+00	.1105263E+01
2	1	.9000000E+01	.9222223E+00	.8888889E+00	.1111111E+01
3	1	.2300000E+02	.6304348E+00	.4782609E+00	.1521739E+01
4	1	.2350000E+00	.8510638E+00	.6808510E+00	.1319149E+01
5	1	.4000000E+01	.1000000E+01	.9500000E+00	.1075000E+01
6	1	.2750000E+02	.1000000E+01	.7272727E+00	.1272727E+01
7	1	.1000000E+01	.1000000E+01	.8000000E+00	.1200000E+01
8	1	.4650000E+02	.1086022E+01	.8602151E+00	.1139785E+01
9	0	.6000000E+01	.9166667E+00	.6666667E+00	.1333333E+01
10	0	.2300000E+02	.6521739E+00	.4347826E+00	.1521739E+01
11	0	.4300000E+00	.1162791E+01	.3720930E+00	.1627907E+01
12	0	.1500000E+01	.1333333E+01	.0000000E+00	.2000000E+01
13	0	.1500000E+00	.1000000E+01	.9666666E+00	.1166667E+01
14	0	.8000000E+00	.9375000E+00	.9375000E+00	.1062500E+01

Problem function data

Number of constraints = 5

Index	Status	Type	Scale	Index	Status	Type	Scale
1	0	0	.5000000E+04	2	-1	0	.6000000E+04
3	-1	0	.5000000E+04	4	-1	0	.1200000E+03
5	-1	0	.8000000E+00	6	-1	0	.8000000E+00

objective is function 1 problem number = 1

Control parameters

nfemax = 20000 nimax = 1000 nsmax = 20
nsetc = 4 nsetcf = 8 nsetv = 4 nsetvf = 8
ofreq = 10 ofrom = 1 rfreq = 50 rfrom = 1

centrl = F fdset = F norep = F cheats = T fast = T quasi = T
fixrp = F timid = F monitr = F nofreq = F yesbc = F shrnk = T projet = T

xtol = .1000000E-05 xtolu = .1000000E-03 xtolv = .1000000E-03 gtol = .1000000E-02
rtol = .1000000E+00 omegar = .1000000E+00 rpmax = .2000000E+00
umin = .1000000E-05 vminf = .1000000E-02 vminc = .1000000E-05 ctol = .1000000E-02
umax = .1000000E+00 vmax = .1000000E+00 omega = .1000000E+00 mu = .1000000E-03
bdtol = .1000000E+00 lmtol = .1000000E+00 mtol = .5000000E+00 cmx = .1000000E-01
subtol = .1000000E-02 qrtol = .1000000E+02 bftol = .1000000E-05 diftol = .5000000E-03
ztol = .1000000E-29

End of input data

1Program RQPMIN Version 1.0 for VAX

STARTING POINT

free variables

1 .8736842E+00 2 .9222223E+00 3 .6304348E+00 4 .8510638E+00 5 .1000000E+01 6 .1000000E+01 7 .1000000E+01
8 .1086022E+01

objective function

f(x) = .9575167E+01

inactive inequality constraints

2 -.2268463E+00 3 -.1966434E+00 4 -.1322222E+00 5 -.4365869E-01 6 -.8134134E-01
1Program RQPMIN Version 1.0 for VAX

end of iteration number 1

end of a successful minimization step
number of calls made to user function so far = 27

Fig E11 - RQPMIN.RES file for the Conventional M.T.O.W. optimisation case

```

free variables
-----
 1 .8736842E+00 2 .9392896E+00 3 .6464515E+00 4 .8668453E+00 5 .1000924E+01 6 .1016447E+01 7 .1018135E+01
 8 .1112819E+01

objective function
-----
f(x) = .9570577E+01

inactive inequality constraints
-----
 2 -.2270100E+00 3 -.1968953E+00 4 -.1324241E+00 5 -.4551008E-01 6 -.7948995E-01

Partial derivatives of Lagrangian function
-----
 1 -.1502991E+01 2 .1175308E+02 3 .1850128E+00 4 .4781723E+01 5 -.1098633E+01 6 .5340576E+00 *7 -.8049011E+00
 8 .1109314E+02

convergence criteria
-----
pdatum = .9570577E+01   ldatum = .9570577E+01   gdatum = .0000000E+00
nu      = .0000000E+00   numax  = infinite
unormx  = .0000000E+00   unormd = .0000000E+00   rtol   = .1000000E+00   xtolu  = .1000000E-03
vnormx  = .8903503E+01   vnorm  = .1000000E+00   xtoly  = .1000000E-03   grdidn = .1175308E+02
nde     = 0             ndef   = 3             ndec   = 0             ncalls = 6             nfuncs = 3

!Program RQPMIN Version 1.0 for VAX

-----
end of iteration number 11
-----

minimization step has failed
number of calls made to user function so far = 297

free variables
-----
 1 .9627149E+00 8 .1082364E+01 3 .8325341E+00 4 .8193237E+00 5 .1045072E+01 6 .1029811E+01 2 .1069379E+01
 7 .1200000E+01

objective function
-----
f(x) = .9472170E+01

inactive inequality constraints
-----
 2 -.1665633E+00 3 -.1197927E+00 4 -.7908026E-01 5 -.8440509E-01 6 -.4059494E-01

Partial derivatives of Lagrangian function
-----
 1 .2964020E+01 8 .7272720E+01 3 .7078170E+01 4 .1119614E+01 5 .1642609E+02 6 .1851082E+02 2 .7215499E+01
 7 .1245308E+02

convergence criteria
-----
pdatum = .9472170E+01   ldatum = .9472170E+01   gdatum = .0000000E+00
nu      = .0000000E+00   numax  = infinite
unormx  = .0000000E+00   unormd = .0000000E+00   rtol   = .1000000E+00   xtolu  = .1000000E-03
vnormx  = .1851082E+02   vnorm  = .1000000E+00   xtoly  = .1000000E-03   grdidn = .1851082E+02
nde     = 0             ndef   = 33            ndec   = 0             ncalls = 66            nfuncs = 33

!Program RQPMIN Version 1.0 for VAX

-----
end of iteration number 21
-----

end of a successful minimization step
number of calls made to user function so far = 738

```

Fig E11 - RQPMIN.RES file for the Conventional M.T.O.W. optimisation case (continued)


```

free variables
-----
 2 .9725208E+00 7 .1057822E+01 3 .8046101E+00 4 .7233416E+00 5 .1012133E+01 6 .8519230E+00 8 .1124150E+01

variables fixed at or near their upper bounds
-----
 1 .1105263E+01

objective function
-----
f(x) = .9131113E+01

inactive inequality constraints
-----
 2 -.6815552E-01 3 -.1309531E-01 4 -.7352257E-02 5 -.9465128E-01 6 -.3034875E-01

Partial derivatives of Lagrangian function
-----
 2 .4110336E+00 7 .3074646E+01 3 -.1782417E+01 4 .1993179E+00 5 .2183914E+00 6 -.1083755E+02 8 -.4628181E+01
 1 -.9355544E+00

convergence criteria
-----
pdatum = .9131113E+01 ldatum = .9131113E+01 gdatum = .0000000E+00
nu = .0000000E+00 numax = infinite
unormx = .0000000E+00 unormd = .0000000E+00 rtol = .1000000E+00 xtolu = .1000000E-03
vnormx = .2496624E+02 vnorm = .1000000E+00 xtoly = .1000000E-03 grdldn = .1083755E+02
nde = 0 ndef = 33 ndec = 26 ncalls = 117 nfuncs = 58
!Program RQPMIN Version 1.0 for VAX 18-Feb-94

```

```

end of iteration number 27
-----
CONVERGENCE DETECTED [ Code B ] after 1164 calls to user routine

```

```

free variables
-----
 2 .9686060E+00 7 .1041446E+01 3 .8073457E+00 4 .7236404E+00 5 .1009009E+01 6 .8706698E+00 8 .1131737E+01
 1 .1105215E+01

objective function
-----
f(x) = .9127748E+01

inactive inequality constraints
-----
 2 -.6698120E-01 3 -.1189326E-01 4 -.6593640E-02 5 -.9479500E-01 6 -.3020503E-01

Partial derivatives of Lagrangian function
-----
 2 .3111744E+02 7 -.1266479E+01 3 -.2857399E+02 4 .1151085E+01 5 .1411438E+01 6 .1898765E+01 8 -.2594280E+02
 1 -.4071236E+01

convergence criteria
-----
pdatum = .9127748E+01 ldatum = .9127748E+01 gdatum = .0000000E+00
nu = .0000000E+00 numax = infinite
unormx = .0000000E+00 unormd = .0000000E+00 rtol = .1000000E+00 xtolu = .1000000E-03
vnormx = .3111744E+02 vnorm = .1000000E+00 xtoly = .1000000E-03 grdldn = .3111744E+02
nde = 0 ndef = 33 ndec = 51 ncalls = 168 nfuncs = 84

```

Fig E11 - RQPMIN.RES file for the Conventional M.T.O.W. optimisation case (concluded)

50 PAX TURBOFAN AIRLINER USING SCALED GE CP-34 - CONVENTIONAL CONFIG.
ENGINE CYCLE IS G. E. CP-34
INPUT DATA FOLLOW

```

0
0 CONFIG WG = 44050.          *****GEOMETRY*****
    WGS = 104.995          KWRITE = 2          FUSEL SAB = 4.          ELODN = 1.000
    PAX = 50.              IGEAR = 0          WS = 20.000          ELODT = 3.200
    HMCRU = .800          KCONFG = 0          AS = 1.              BML0D = 14.500
    HNCRU = 35000.        KTIPE = 0          WAS = 19.000        NACELLE KNAC = 1
    Kanard = 0            ENP = 2.           PS = 31.0           ELN = 11.874
    KPELOT = 7            NTYE = 7          ELPC = 11.220       DEARN = 3.958
    KFLPLOT = 1          KPELOT = 1        HCK = 2.470         ELRW = 10.000

0 WING TCT = .100          HORIZ VBARHX = .0000    VERT VBARVX = .0000    Canard TCcan = .100
    TCR = .130          TAIL TCMT = .100      TAIL TCVT = .120     ARcan = 5.500
    AR = 8.717         ARHT = 4.036        ARVT = 1.041        SLMcan = .500
    SLM = .170         SLMH = 1.000        SLMV = .700         DwpqCa = 15.000
    DLMC4 = 18.569     DWPOCH = 23.943    DWPOCV = 52.626     EYEcan = 2.000
    EYEW = 2.000      COELTH = .000      BOELTV = .000       SwcOSW = .150
    SAH = 1.000

0 *****AERODYNAMICS*****
0 CKW = -1.000          CRHT = -1.000        GRPE = .000          DCDSE = -1.0000
    CKP = -1.000        CRTP = -1.000        SCFAC = .750         CMWc = 2.497
    CKN = -1.000        DELCD = .00150      DLSWSW = .000        cmacw = -.060
    CKVT = -1.000      DELPE = .200        ALPHLO = -1.600     alzerc = -1.000

0 KWCD = 12
0 ACLS = -1.000        -.600 -.400 -.200 .000 .100 .200 .400 .600 .800 1.000 1.200
    ACDCDR = 2.400    1.466 1.221 1.066 1.005 1.000 1.005 1.046 1.138 1.333 1.743 2.718

0 *****HIGH LIFT DEVICES*****
0 RCLMAX = 1.200        FLAPS JFLTYP = 7          LED CLEOC = .000
    ALTFLE = 5000.      DFLETO = 15.000     DELLED = .000
    FLAPN = 1.          DFLELD = 40.000    DCLMLE = .930
    WCFLAP = -1.000    CPOC = .300        DELLEO = 45.000
    BENGOR = .000      BTEOB = .750
    DCLMTE = .000
    DCDOTE = .000
    DELTEO = .000

0 *****PROPULSION*****
0 JENGSZ = 2            HPCRT = 5000.        ACCRU = 50.000       RWCRTI = .970
    IPART = 1            TDELTO = 36.        XTORQ = 99999.      HSCREQ = 0.
    KODETO = 5           KODECL = 7          SMID = .500         THIN = 0.
    KODETR = 5           KODEAC = 5          HBTP = .437         PR = 1.000

0 *****WEIGHTS*****
0 SKPEI = .1350        SKY = .1800          SKB = 107.000        SKFS = .0200
    SKLG = .0380        SKZ = .2200          SKCC = 20.000        SKWP = .4300
    SKMG = .8000        SKTL = 1.0000       SKFW = .4300        SKFT = .9790
    SKPES = .3380      SKWW = 133.400     SKSAS = .000        SKMTP = 1.8900
    WELX = .0           YMG = .2500         EGMRGN = .0000     LCWING = 2
    WPEX = .0           RELP = .7500        CPMRGN = .2000
    WPUL = 1078.9      RELR = .4500        STMGRN = .0000
    UWPAX = 200.0      CATD = 3.           DELP = 8.200
    STRUT = .0000      VMLPSL = 685.0     YP = .0000
    DELWFC = .0        WNAC = .0           WPYLON = .0
    WENG = .0          UWNAC = 2.287       FPYL = .700        XLQDE = 3.000
    SWSLS = .160

0 *****STABILITY AND CONTROL*****
0 KSFLND = 1           STATIC = .100        ZCG = 5.500          CNPAC = .0020
    CMFLBL = 999.000   CHALF = 999.000     TP = .0              ARVTE = -1.000
    CMFLET = 999.000   CHDEL = 999.000    CXA = .520          RV = .300
    CMPLD = .000      RH = .350           DCMCLP = .000       TAUV = 999.000
    DEMAX = -25.0     EYET = .0           HWING = 0.          RVMCS = .990
    EYET = .0         TAUH = 999.000     dcmcpi = .030      DRMAX = 25.0
    rc = .350

0 *****PERFORMANCE*****
0 TAXI DELTT = .167     XLFMAX = 1.100       DVR = 5.000          TDELTX = 36.000
    TO IFLY = 1         DELTVR = 3.500      UM = .020           HTMAX = 500.000
    THEMAX = 15.000   DVI = 5.000        MUB = .400          NFAIL = 0
    HOO = 5000.      VRAT = 1.10

0 CLIMB ICLM = 1       CRUISE CRMACH = .800   FRESF = 1.000        FACW1 = .820
    DELH = 1000.     CRALT = 35000.     RCRRQ = 1250.0      ISWING = 0
    VCLMB = .0       ICRUS = 1          OPALT = 25000.      OFEM = .500
    IWL D = 2        XLDGRQ = 99999.   VRATT = 1.300       HAPB = 50.
    TDELLD = 36.0    ALTLND = 5000.    RSMX = 1000.        SINKTD = 3.0
    TDELAY = 1.0     WLPCT = .9400     TROTID = .000       XLFMX = 1.200
    HTG = 5.5        TIDLE = .0

0 *****COST*****
0 NCADE = 1           MIR = .005          RI = .300           CMV = .800
    CLIAB = 1993.0    TR = 2.000         OHR = 500.000       CCRW = 0.
    HRI = 4000000.   PRV = .100        CRWOH = 23.000     UCSSENG = .000
    CMF = .2         DYR = 15.0        CINP = 0.           UCSPP = .000
    TBO = 3200.0     SRPM = .0          CP = 0.             ALR = 1.120
    FCSF = .850
    
```

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution

```

*****
ITERATION TO BALANCE RANGE
RANGE ERROR, RANGE ERROR MINUS 1 .0115 .6741
GROSS WGT, GROSS WGT MINUS1 45638.7 45776.5

0 *****
0 FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
CLMA1
VSTALL,KTS FLAP ANGLE LE ANGLE DELTA CL DELTA CD
FLAPS UP 1.3109 165.9 .0 .0 .0000 .0000
T.O. CONFIG 2.4320 121.7 15.0 .0 1.1077 .0428
LDG. CONFIG 3.1874 106.3 40.0 .0 1.8745 .1904

0 DOUBLE SLOTTED FOWLER FLAPS
OPT ANGLE DELCL AT OPT DELCD AT OPT AREA(FT2) WEIGHT(LB)
FLAPS 30.0 2.2500 .1500 89.9 668.5
0 *****
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK(DEGREES)= 2.362 LIFT= 44269.6 L/D= 12.612 ALTITUDE= 35000.0 MACH= .8000

1 ENGINE SIZING DATA FOLLOW
*****
OVSTLKT= 112.8 KTS EAS VRAT= 1.100 CLTO= 2.0099
VEND = 250.0 KNOTS EAS
0
ROTATION (TIME= 25.6 AND TAS= 136.9 EAS= 122.8)
LIFTOFF (TIME= 27.8 DIST= 3719.0 TAS= 145.0 EAS= 130.8)
DISTANCE TO 35 FT.= 5055.5 TAS= 160.1 EAS= 143.5 V35/V5= 1.2718
GEAR RETRACTION STARTED AT 33.9 SEC, COMPLETE AT 40.9 SEC
FLAP RETRACTION STARTED AT 44.0 SEC, COMPLETE AT 48.5 SEC
OVSTLKT= 112.8 KTS EAS VRAT= 1.100 CLTO= 2.0099
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 211.2 KNOTS EAS
ENGINE FAILURE (TIME= 24.2 AND TAS= 131.4 EAS= 117.8)
0
ROTATION (TIME= 27.6 AND TAS= 136.9 EAS= 122.8)
LIFTOFF (TIME= 30.6 DIST= 4351.3 TAS= 140.5 EAS= 126.0)
DISTANCE TO 35 FT.= 6115.9 TAS= 142.4 EAS= 127.7 V35/V5= 1.1318

ACCELERATE - STOP DISTANCE = 6350.3 FEET.
0 ENGINE OUT DISTANCE TO 35 FT.= 6115.9 FEET
OALL ENGINE DISTANCE TO 35 FT. (L) = 5055.5 FEET
PAR 25 T.O. DISTANCE (1.15XL) = 5813.9 FEET
ALL ENGINE DISTANCE TO 50 FT. = 5301.5 FEET
0 AT END OF TAKEOFF PHASE
TIME= .013 HRS FUEL USED= 76. LBS WEIGHT= 45563. LBS ALT.= 5500. FT.
0 TAKE OFF RATE OF CLIMB REQUIREMENTS - PAR PART 25
AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION ALT (FT) VS KEAS V/V5 V KTAS GRAD (PCT) R/C (PPM) REQ. R/C (PPM) CL L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT 5000. 113.0 1.1239 141.6 1.835 262.86 1.00 1.933 8.139
2ND SEG: T.O. FLAPS - ONE ENGINE OUT 5250. 113.0 1.2000 151.7 4.041 620.45 368.54 1.696 10.173
FINAL T.O. CRUISE CONFIG - ONE ENG OUT 6500. 153.1 1.2500 218.4 4.655 1028.65 265.18 .851 13.013
APPROACH FLAPS - ONE ENG OUT 5000. 108.4 1.3736 166.1 4.521 759.86 352.95 1.403 10.941
LANDING FLAPS - ALL ENGINES 5000. 98.7 1.3000 143.0 13.519 1956.94 463.21 1.893 6.814

APPROACH FLAP SETTING = 19.5 DEG.

+++ ENGINE-OUT SERVICE CEILING = 21958.9 FT.
BEST RATE OF CLIMB SPEED = 275.9 KTAS
ENGINE-OUT RATE OF CLIMB = 49.6 FPM
WEIGHT AT ALTITUDE = 43813.2 LBS

0 *****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES*****
0 PROPUSSION SYSTEM WEIGHTS
ENGINE WEIGHT/ENGINE 1500.2
NACELLE WEIGHT/ENGINE 337.4
PYLON WEIGHT/ENGINE 176.8
PROP OR OFAN .0
GEARBOX .0
SHROUD .0

0 ENGINE POD DIMENSIONS
ENGINE FACE DIAMETER(FT) 3.96
NACELLE LENGTH(FT) 11.87

OVSTLKT= 112.8 KTS EAS VRAT= 1.100 CLTO= 2.0099
VEND = 250.0 KNOTS EAS
0
ROTATION (TIME= 24.4 AND TAS= 136.9 EAS= 122.8)
LIFTOFF (TIME= 26.6 DIST= 3565.8 TAS= 146.2 EAS= 131.2)
DISTANCE TO 35 FT.= 4893.9 TAS= 161.4 EAS= 144.7 V35/V5= 1.2821
GEAR RETRACTION STARTED AT 32.6 SEC, COMPLETE AT 39.6 SEC
FLAP RETRACTION STARTED AT 42.7 SEC, COMPLETE AT 47.2 SEC
OVSTLKT= 112.8 KTS EAS VRAT= 1.100 CLTO= 2.0099
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 205.4 KNOTS EAS
ENGINE FAILURE (TIME= 23.1 AND TAS= 131.4 EAS= 117.8)
0
ROTATION (TIME= 26.4 AND TAS= 136.9 EAS= 122.8)
LIFTOFF (TIME= 29.4 DIST= 4198.6 TAS= 140.9 EAS= 126.4)
DISTANCE TO 35 FT.= 5756.8 TAS= 143.0 EAS= 128.2 V35/V5= 1.1359

```

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution
(continued)

ACCELERATE - STOP DISTANCE = 6220.5 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 5756.8 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4893.9 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 5628.0 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 5141.0 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .012 HRS FUEL USED= 77. LBS WEIGHT= 45561. LBS ALT.= 5500. FT.
 0 TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 3000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	VS KEAS	V/VS	V KTAS	GRAD (PCT)	R/C (PPM)	REQ.R/C (PPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	113.0	1.1239	141.6	2.176	311.79	1.00	1.933	7.962
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	113.0	1.2000	151.7	4.354	668.58	368.54	1.696	9.881
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	153.1	1.2500	218.4	4.712	1041.31	265.18	.851	12.248
APPROACH FLAPS -ONE ENG OUT	5000.	108.4	1.3736	166.1	4.790	805.04	352.95	1.405	10.564
LANDING FLAPS - ALL ENGINES	5000.	98.7	1.3000	143.0	14.660	2122.02	463.21	1.893	6.774

APPROACH FLAP SETTING = 19.5 DEG.

+++ ENGINE-OUT SERVICE CEILING = 22502.2 FT.
 BEST RATE OF CLIMB SPEED = 277.3 KTAS
 ENGINE-OUT RATE OF CLIMB = 50.1 FPM
 WEIGHT AT ALTITUDE = 43813.2 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 383.71

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R;ALT= 5000.) SLS AIRFLOW= 383.71

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 9784.7 LBS

0 PROPULSION SYSTEM WEIGHTS

ENGINE WEIGHT/ENGINE	1565.6
NACELLE WEIGHT/ENGINE	337.4
PYLON WEIGHT/ENGINE	181.4
PROP OR QFAN	.0
GEARBOX	.0
SHROUD	.0

0 ENGINE POD DIMENSIONS

ENGINE FACE DIAMETER(FT)	3.96
NACELLE LENGTH(FT)	11.87

0

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution (continued)

---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---

	MOST FWD LOAD		MOST AFT LOAD		DESIGN LOAD	
	WT	CG	WT	CG	WT	CG
A/C OWE	26618.58	43.82	26618.58	43.82	26618.58	43.82
PAX	6120.00		2040.00		8500.00	
BAGGAGE	.00	56.36	1500.00	56.36	1500.00	56.36
WING FUEL	1394.15	44.75	6970.73	44.75	6970.73	44.75
TIP FUEL	.00	.00	.00	.00	.00	.00
FUS FUEL	.00	44.75	.00	44.75	2049.43	44.75
TOTAL	34132.73	41.39	37129.31	44.74	45638.74	43.08

0 ---TAIL SIZING SUMMARY---

Static Longitudinal Stability, Stick-fixed, considered

CONDITION	ALPHA	WING		CMac	CANARD		TAIL		DOWN WASH	FLAP CM
		CL	CLA		ALPHA	CLA	CLA	EFF.		
CRUISE	2.4843	.4693	.1149	-.0600	.0000	.0000	.0788	1.0000		
LIFTOFF	2.0000	1.4182	.0661	-.0600	.0000	.0000	.0650	1.0000	.3391	-.1031
LANDING	14.0334	3.1874	.0840	-.0600	.0000	.0000	.0650	1.0000	2.3793	-.2000

CONDITION	--FUSELAGE--		---MACELLE---		-----POWER-----				L. GEAR	ROT. POWER	
	DCM	CM	DCM	CM	DCMdh	DCMfinc	CMdh	CMfinc			CT
CRUISE	.5211		.1222		.0000	.0300			.0000		
LIFTOFF	.9056	.0000	.1222	.0000			.0000	.0425	.0000	-.7098	5.2860
LANDING	.7130	.7205	.1222	.1235			.0000	.0956			

0 ELEVATOR PARAMETERS
 CMDELTA (CONTROL POWER) = -.06030 WING DE/DALPHA = .33909
 TAUN (EFFECTIVENESS) = .48250
 DEMAX (MAX. ELEVATOR DEPLEC.) = -25.00000

	FRACTION		STATION (DATUM NOSE)	HORIZONTAL TAIL SIZES	
	MAC	MAC		STATIC STABILITY AND LANDING TRIM	STATIC STABILITY AND LIFTOFF ROT.
NEUTRAL POINT	.4484		45.293	158.9859	158.8368
STATIC MARGIN	.1000				
AFT CG LIMIT (STABILITY)	.3484		44.468		
CG RANGE (LOADING)	.4061			158.9859	
FWD CG LIMIT (CONTROL)	-.0576		41.160	44.1675	

0 VERTICAL TAIL AREA = 96.9749 FOR DIRECTIONAL STABILITY OF .00200
 0 RUDDER POWER AT MAX. DEFL. = .0183 PER DEG. RUDDER CL AT MAX. DEFL. = .4568
 0 VERTICAL TAIL AREA = 85.2550 FOR MINIMUM CONTROL SPEED = 111.70 KTS
 0 REQUIRED VERTICAL TAIL AREA = 96.9749 TAIL ARM (ELTV) = 33.1806

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
 ANGLE OF ATTACK (DEGREES) = 2.362 LIFT = 44269.6 L/D = 12.137 ALTITUDE = 35000.0 MACH = .8000

0 WING LOCATION INFO.					
FUSELAGE LENGTH =	79.25	H-TAIL VOL. ARM =	44.17	C.G. LOCATION OF PROPULSION =	59.43
WING 1/4C LOC. ON C.L. =	39.79	H-TAIL C.G. LOCATION =	88.41	C.G. OF REMAINING WEIGHT =	35.66
MAC 1/4C LOCATION =	43.74	H-TAIL MAC FROM C.L. =	6.33		
MAC DIST. FROM C.L. =	11.75	H-TAIL LOCAT ON VERT. =	1.00		
WING C.G. LOCATION =	45.39	V-TAIL VOL. ARM =	33.18		
TIP TANKS C.G. LOCATE =	.00	V-TAIL C.G. LOCATION =	77.70	DIST. L.E. VERT. TO L.E. HORZ. =	1.67

	WING	H-TAIL	V-TAIL
AREA	434.674	158.986	96.975
SPAN	61.557	25.331	10.050
ASPECT RATIO	8.717	4.036	1.041
TAPER RATIO	.170	1.000	.700
1/4C. SWEEP	18.569	23.943	52.626
L.E. SWEEP	22.651	23.943	54.343
C.L. CHORD	12.070	6.276	11.353
MEAN CHORD	8.246	6.276	9.750
TIP CHORD	2.053	6.276	7.947

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution
 (continued)

MISSION PERFORMANCE DATA FOLLOWS

0 TAXI AT IDLE THRUST

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	FUEL FLOW (LB/HR)
.000	0.	0.	45639.	5000.	894.
.167	0.	149.	45490.	5000.	894.

OVSTLKT= 112.7 KTS EAS VRAT= 1.100 CLTC= 2.0099
VEND = 230.0 KNOTS EAS
(TEMP.= 537. DEG:STD.+36.)
0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	149.0	45490.	5000.0	.0	.0	.000	11.63	1.4158	.1276	2.00	.00	.0	.00	17354.	6180.	.00
1.0	5.8	150.7	45488.	5000.0	6.8	6.1	.010	11.47	1.4158	.1276	2.00	.00	.0	.00	17134.	6180.	.00
2.0	23.1	152.4	45486.	5000.0	13.6	12.2	.020	11.30	1.4158	.1276	2.00	.00	.0	.00	16918.	6181.	.00
3.0	51.7	154.1	45485.	5000.0	20.3	18.2	.030	11.13	1.4159	.1276	2.00	.00	.0	.00	16706.	6182.	.00
4.0	91.5	155.8	45483.	5000.0	26.8	24.1	.040	10.96	1.4160	.1276	2.00	.00	.0	.00	16498.	6184.	.00
5.0	142.3	157.6	45481.	5000.0	33.3	29.9	.049	10.79	1.4161	.1276	2.00	.00	.0	.00	16294.	6186.	.00
6.0	203.9	159.3	45479.	5000.0	39.6	35.6	.059	10.61	1.4162	.1276	2.00	.00	.0	.00	16093.	6188.	.00
7.0	276.2	161.0	45478.	5000.0	45.9	41.2	.068	10.42	1.4163	.1276	2.00	.00	.0	.00	15895.	6190.	.00
8.0	358.9	162.7	45476.	5000.0	52.0	46.7	.077	10.23	1.4164	.1277	2.00	.00	.0	.00	15701.	6192.	.00
9.0	451.9	164.4	45474.	5000.0	58.1	52.1	.086	10.04	1.4166	.1277	2.00	.00	.0	.00	15510.	6195.	.00
10.0	554.9	166.2	45473.	5000.0	64.0	57.4	.095	9.85	1.4168	.1277	2.00	.00	.0	.00	15323.	6198.	.00
11.0	667.9	167.9	45471.	5000.0	69.8	62.6	.104	9.67	1.4170	.1277	2.00	.00	.0	.00	15157.	6201.	.00
12.0	790.6	169.6	45469.	5000.0	75.5	67.7	.112	9.50	1.4172	.1277	2.00	.00	.0	.00	15018.	6204.	.00
13.0	922.8	171.3	45467.	5000.0	81.1	72.7	.120	9.33	1.4174	.1277	2.00	.00	.0	.00	14881.	6207.	.00
14.0	1064.3	173.0	45466.	5000.0	86.6	77.7	.129	9.16	1.4176	.1277	2.00	.00	.0	.00	14747.	6211.	.00
15.0	1215.1	174.8	45464.	5000.0	92.0	82.5	.137	8.99	1.4178	.1278	2.00	.00	.0	.00	14615.	6215.	.00
16.0	1374.9	176.5	45462.	5000.0	97.3	87.2	.144	8.82	1.4181	.1278	2.00	.00	.0	.00	14486.	6219.	.00
17.0	1543.6	178.2	45461.	5000.0	102.4	91.9	.152	8.64	1.4183	.1278	2.00	.00	.0	.00	14360.	6223.	.00
18.0	1720.9	180.0	45459.	5000.0	107.5	96.5	.160	8.46	1.4186	.1278	2.00	.00	.0	.00	14236.	6227.	.00
19.0	1906.7	181.7	45457.	5000.0	112.5	100.9	.167	8.29	1.4189	.1278	2.00	.00	.0	.00	14114.	6232.	.00
20.0	2100.8	183.4	45455.	5000.0	117.4	105.3	.174	8.11	1.4192	.1279	2.00	.00	.0	.00	13995.	6236.	.00
21.0	2303.1	185.2	45454.	5000.0	122.1	109.6	.181	7.93	1.4195	.1279	2.00	.00	.0	.00	13878.	6240.	.00
22.0	2513.4	186.9	45452.	5000.0	126.8	113.8	.188	7.75	1.4197	.1279	2.00	.00	.0	.00	13764.	6245.	.00
23.0	2731.4	188.6	45450.	5000.0	131.4	117.9	.195	7.58	1.4200	.1279	2.00	.00	.0	.00	13653.	6250.	.00
24.0	2957.1	190.4	45448.	5000.0	135.8	121.8	.202	7.40	1.4203	.1280	2.00	.00	.0	.00	13551.	6254.	.00

0 ROTATION (TIME= 24.2 AND TAS= 136.7 EAS= 122.7)
25.0 3190.2 192.1 45447. 5000.0 140.2 125.7 .208 7.15 1.5204 .1360 3.20 .00 .0 .78 13473. 6259. 1.20
26.0 3430.4 193.8 45445. 5000.0 144.3 129.5 .214 6.79 1.6888 .1507 5.27 .00 .0 .92 13398. 6264. 3.27

LIPTOFF (TIME= 26.4 DIST= 3528.5 TAS= 145.9 EAS= 130.9)
27.0 3677.5 195.6 45443. 5000.1 148.2 133.0 .220 6.30 1.8291 .1640 7.05 .13 35.0 1.06 13328. 6268. 5.18
28.0 3930.9 197.3 45441. 5002.1 151.8 136.2 .225 5.68 1.7985 .1670 6.55 .80 214.4 1.09 13263. 6272. 5.34
29.0 4189.9 199.1 45440. 5007.3 155.0 139.0 .230 5.01 1.7332 .1724 5.65 1.48 405.7 1.10 13205. 6275. 5.33
30.0 4454.0 200.8 45438. 5015.7 157.8 141.5 .234 4.39 1.6732 .1759 4.95 2.16 603.5 1.10 13152. 6277. 5.11
31.0 4722.3 202.6 45436. 5027.4 160.2 143.7 .238 3.86 1.6275 .1765 4.45 2.82 800.1 1.10 13105. 6279. 5.27

DISTANCE TO 35 FT.= 4867.9 TAS= 161.4 EAS= 144.8 V35/V30= 1.2849
32.0 4994.4 204.3 45434. 5042.3 162.4 145.6 .241 3.43 1.5828 .1736 3.95 3.47 997.6 1.09 13062. 6279. 5.42

GEAR RETRACTION STARTED AT 32.4 SEC, COMPLETE AT 39.4 SEC
33.0 5269.8 206.0 45433. 5060.6 164.4 147.3 .244 3.08 1.5479 .1678 3.55 4.12 1196.3 1.10 13023. 6279. 5.66
34.0 5548.1 207.8 45431. 5082.2 166.1 148.9 .247 2.79 1.5223 .1605 3.25 4.75 1394.8 1.10 12987. 6278. 6.00
35.0 5829.0 209.5 45429. 5107.1 167.7 150.2 .249 2.55 1.4883 .1518 2.85 5.39 1596.1 1.09 12952. 6277. 6.23
36.0 6112.1 211.3 45428. 5135.4 169.2 151.5 .251 2.30 1.4628 .1441 2.55 6.01 1794.3 1.09 12919. 6275. 6.55
37.0 6397.3 213.0 45426. 5166.9 170.5 152.6 .253 2.05 1.4459 .1376 2.35 6.62 1991.7 1.10 12889. 6272. 6.97
38.0 6684.2 214.8 45424. 5201.8 171.7 153.5 .255 1.80 1.4289 .1312 2.15 7.23 2189.9 1.10 12860. 6269. 7.37
39.0 6972.5 216.5 45422. 5239.9 172.7 154.4 .257 1.57 1.4119 .1248 1.95 7.84 2386.0 1.10 12833. 6265. 7.78
40.0 7262.0 218.2 45421. 5281.3 173.6 155.1 .258 1.28 1.3948 .1210 1.75 8.44 2581.5 1.10 12808. 6260. 8.19
41.0 7552.4 220.0 45419. 5325.9 174.3 155.6 .259 .94 1.3863 .1201 1.65 9.04 2774.4 1.10 12785. 6255. 8.68
42.0 7843.3 221.7 45417. 5373.8 174.8 155.9 .260 .61 1.3778 .1192 1.55 9.63 2963.0 1.10 12766. 6249. 9.18

FLAP RETRACTION STARTED AT 42.5 SEC, COMPLETE AT 47.0 SEC
43.0 8134.3 223.4 45415. 5424.6 175.0 156.0 .260 .36 1.2860 .1174 1.85 10.13 3119.1 1.03 12749. 6242. 9.97
44.0 8425.5 225.2 45414. 5476.5 175.3 156.1 .261 .28 1.1601 .1238 3.25 9.96 3070.9 .94 12733. 6235. 11.20

OVSTLKT= 112.7 KTS EAS VRAT= 1.100 CLTC= 2.0099
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 208.9 KNOTS EAS
(TEMP.= 537. DEG:STD.+36.)
0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	149.0	45490.	5000.0	.0	.0	.000	11.63	1.4158	.1276	2.00	.00	.0	.00	17354.	6180.	.00
1.0	5.8	150.7	45488.	5000.0	6.8	6.1	.010	11.47	1.4158	.1276	2.00	.00	.0	.00	17134.	6180.	.00
2.0	23.1	152.4	45486.	5000.0	13.6	12.2	.020	11.30	1.4158	.1276	2.00	.00	.0	.00	16918.	6181.	.00
3.0	51.7	154.1	45485.	5000.0	20.3	18.2	.030	11.13	1.4159	.1276	2.00	.00	.0	.00	16706.	6182.	.00
4.0	91.5	155.8	45483.	5000.0	26.8	24.1	.040	10.96	1.4160	.1276	2.00	.00	.0	.00	16498.	6184.	.00
5.0	142.3	157.6	45481.	5000.0	33.3	29.9	.049	10.79	1.4161	.1276	2.00	.00	.0	.00	16294.	6186.	.00
6.0	203.9	159.3	45479.	5000.0	39.6	35.6	.059	10.61	1.4162	.1276	2.00	.00	.0	.00	16093.	6188.	.00
7.0	276.2	161.0	45478.	5000.0	45.9	41.2	.068	10.42	1.4163	.1276	2.00	.00	.0	.00	15895.	6190.	.00
8.0	358.9	162.7	45476.	5000.0	52.0	46.7	.077	10.23	1.4164	.1277	2.00	.00	.0	.00	15701.	6192.	.00
9.0	451.9	164.4	45474.	5000.0	58.1	52.1	.086	10.04	1.4166	.1277	2.00	.00	.0	.00	15510.	6195.	.00
10.0	554.9	166.2	45473.	5000.0	64.0	57.4	.095	9.85	1.4168	.1277	2.00	.00	.0	.00	15323.	6198.	.00
11.0	667.9	167.9	45471.	5000.0	69.8	62.6	.104	9.67	1.4170	.1277	2.00	.00	.0	.00	15157.	6201.	.00
12.0	790.6	169.6	45469.	5000.0	75.5	67.7	.112	9.50	1.4172	.1277	2.00	.00	.0	.00	15018.	6204.	.00
13.0	922.8	171.3	45467.	5000.0	81.1	72.7	.120	9.33	1.4174	.1277	2.00	.00	.0	.00	14881.	6207.	.00
14.0	1064.3	173.0	45466.	5000.0	86.6	77.7	.129	9.16	1.4176	.1277	2.00	.00	.0	.00	14747.	6211.	.00
15.0	1215.1	174.8	45464.	5000.0	92.0	82.5	.137	8.99	1.4178	.1278	2.00	.00	.0	.00	14615.	6215.	.00
16.0	1374.9	176.5	45462.	5000.0	97.3	87.2	.144	8.82	1.4181	.1278	2.00	.00	.0	.00	14486.	6219.	.00
17.0	1543.6	178.2	45461.	5000.0	102.4	91.9	.152	8.64	1.4183	.1278	2.00	.00	.0	.00	14360.	6223.	.00
18.0	1720.9	180.0	45459.	5000.0	107.5	96.5	.160	8.46	1.4186	.1278	2.00	.00	.0	.00	14236.	6227.	.00
19.0	1906.7	181.7	45457.	5000.0	112.5	100.9	.167	8.29	1.4189	.1278	2.00	.00	.0	.00	14114.	6232.	.00
20.0	2100.8	183.4	45455.	5000.0	117.4	105.3	.174	8.11	1.4192	.1279	2.00	.00	.0	.00	13995.	6236.	.00
21.0	2303.1	185.2	45454.	5000.0	122.1	109.6	.181	7.93	1.4195	.1279	2.00	.00	.0	.00	13878.	6240.	.00
22.0	2513.4	186.9	45452.	5000.0	126.8	113.8	.188	7.75	1.4197	.1279	2.00	.00	.0	.00	13764.	6245.	.00
23.0	2731.4	188.6	45450.	5000.0	131.4	117.9	.195	7.58	1.4200	.1279	2.00	.00	.0	.00	13653.	6250.	.00

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution (continued)

ENGINE FAILURE (TIME= 23.0 AND TAS= 131.2 EAS= 117.7)																	
24.0	2955.1	189.5	45449.	5000.0	133.2	119.5	.198	2.56	1.4202	.1367	2.00	.00	.0	.00	6804.	3126.	.00
25.0	3181.3	190.4	45448.	5000.0	134.7	120.8	.200	2.51	1.4203	.1364	2.00	.00	.0	.00	6785.	3127.	.00
26.0	3410.1	191.2	45448.	5000.0	136.2	122.2	.202	2.47	1.4204	.1362	2.00	.00	.0	.00	6772.	3127.	.00
ROTATION (TIME= 26.4 AND TAS= 136.7 EAS= 122.7)																	
27.0	3641.3	192.1	45447.	5000.0	137.6	123.5	.204	2.36	1.4929	.1417	2.87	.00	.0	.74	6759.	3128.	.87
28.0	3874.9	193.0	45446.	5000.0	139.0	124.7	.206	2.14	1.6613	.1559	4.93	.00	.0	.84	6747.	3129.	2.93
29.0	4110.7	193.8	45445.	5000.0	140.2	125.8	.208	1.89	1.8297	.1715	7.07	.00	.0	.95	6736.	3129.	5.07
LIFTOFF (TIME= 29.4 DIST= 4205.6 TAS= 140.6 EAS= 126.1)																	
30.0	4348.4	194.7	45444.	5000.1	141.2	126.7	.210	1.58	1.9684	.1854	8.90	.09	22.8	1.04	6727.	3130.	6.99
31.0	4587.6	195.6	45443.	5001.4	142.0	127.4	.211	1.11	2.0099	.1948	9.32	.57	143.1	1.07	6720.	3130.	7.89
32.0	4827.9	196.4	45442.	5005.0	142.5	127.8	.212	.51	2.0099	.2088	9.06	1.17	296.0	1.08	6715.	3130.	8.24
33.0	5068.6	197.3	45441.	5011.3	142.6	127.9	.212	.00	1.9598	.2176	8.35	1.79	451.5	1.06	6713.	3130.	8.14
34.0	5309.3	198.2	45441.	5019.3	142.6	127.9	.212	-.01	1.8576	.2130	7.15	1.95	491.7	1.00	6712.	3129.	7.10
35.0	5550.1	199.1	45440.	5027.3	142.6	127.9	.212	-.01	1.8383	.2155	6.95	1.88	474.3	.99	6711.	3129.	6.83
DISTANCE TO 35 FT.= 5789.4 TAS= 142.6 EAS= 127.9 VS= 1.1351																	
36.0	5790.8	199.9	45439.	5035.0	142.6	127.9	.212	.00	1.8368	.2183	6.95	1.78	449.5	.99	6710.	3128.	6.74
37.0	6031.6	200.8	45438.	5042.3	142.6	127.9	.212	-.01	1.8444	.2212	7.05	1.69	427.4	.99	6709.	3128.	6.75
38.0	6272.4	201.7	45437.	5049.3	142.6	127.9	.212	.01	1.8439	.2222	7.05	1.63	411.3	.99	6708.	3127.	6.68

ACCELERATE - STOP DISTANCE = 6204.4 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 5789.4 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4867.9 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 5598.1 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 5115.5 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .179 HRS FUEL USED= 226. LBS WEIGHT= 45413. LBS ALT.= 5500. FT.

ACCELERATE TO MACH NO. = .418

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.179	.00	226.0	45413.	5500.	169.	156.	.261	.713	13022.	6143.
.187	1.84	276.9	45362.	5500.	271.	250.	.418	.808	11170.	6304.

END OF ACCELERATION SEGMENT
 TIME= .187 HRS FUEL USED= 276.9 LBS WEIGHT= 45362. LBS RANGE= 2. NM
 0 CLIMB TO 35000. FT. AT MAXIMUM RATE OF CLIMB

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	PUS. ANGLE (DEG)	R/C (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
.187	2.	277.	45362.	5500.	252.	232.	.388	.801	.5650	.0432	4.77	8.20	10.97	3641.	9904.	5551.
.189	2.	290.	45349.	6000.	253.	231.	.390	.800	.5696	.0435	4.82	7.75	10.57	3457.	9817.	5498.
.194	4.	316.	45323.	7000.	262.	236.	.406	.803	.5482	.0422	4.55	6.32	8.87	2923.	9520.	5388.
.200	5.	347.	45292.	8000.	265.	235.	.412	.802	.5503	.0424	4.56	6.90	9.46	3231.	9324.	5268.
.205	6.	374.	45265.	9000.	268.	234.	.418	.802	.5563	.0427	4.61	6.79	9.41	3213.	9140.	5133.
.210	8.	401.	45238.	10000.	271.	233.	.424	.801	.5625	.0431	4.67	6.58	9.25	3144.	8957.	5041.
.215	9.	427.	45211.	11000.	273.	231.	.430	.800	.5685	.0434	4.72	6.79	9.51	3276.	8774.	4931.
.220	11.	453.	45186.	12000.	276.	230.	.435	.799	.5755	.0438	4.79	6.16	8.95	3002.	8592.	4824.
.226	12.	479.	45159.	13000.	279.	229.	.441	.798	.5823	.0442	4.85	5.95	8.80	2930.	8411.	4719.
.232	14.	506.	45133.	14000.	282.	228.	.448	.798	.5878	.0445	4.89	5.69	8.58	2834.	8228.	4617.
.238	15.	533.	45105.	15000.	286.	227.	.456	.797	.5919	.0447	4.92	5.42	8.34	2734.	8042.	4518.
.244	17.	561.	45078.	16000.	291.	228.	.467	.798	.5878	.0445	4.85	4.91	7.76	2526.	7828.	4419.
.250	19.	590.	45049.	17000.	295.	226.	.473	.797	.5840	.0449	4.90	4.99	7.88	2595.	7632.	4309.
.257	21.	618.	45021.	18000.	298.	226.	.482	.797	.5979	.0451	4.92	4.67	7.59	2465.	7433.	4203.
.263	23.	646.	44993.	19000.	302.	225.	.490	.796	.6019	.0454	4.94	4.44	7.38	2375.	7238.	4098.
.270	25.	675.	44964.	20000.	306.	224.	.498	.795	.6076	.0457	4.98	4.27	7.25	2310.	7050.	3995.
.278	27.	704.	44935.	21000.	310.	223.	.506	.795	.6137	.0461	5.02	4.06	7.08	2221.	6866.	3895.
.285	30.	733.	44906.	22000.	314.	222.	.514	.794	.6187	.0464	5.05	3.81	6.86	2114.	6682.	3797.
.293	32.	763.	44876.	23000.	317.	220.	.522	.793	.6267	.0470	5.11	3.68	6.80	2064.	6508.	3699.
.301	35.	793.	44846.	24000.	321.	219.	.531	.792	.6321	.0473	5.14	3.41	6.55	1936.	6332.	3606.
.310	37.	824.	44815.	25000.	325.	219.	.546	.793	.6246	.0468	5.01	2.90	5.91	1686.	6124.	3523.
.320	41.	859.	44780.	26000.	332.	219.	.553	.792	.6348	.0475	5.10	3.06	6.15	1793.	5945.	3437.
.329	44.	891.	44748.	27000.	335.	217.	.560	.791	.6453	.0482	5.18	2.85	6.03	1688.	5771.	3351.
.339	47.	924.	44715.	28000.	366.	233.	.615	.801	.5595	.0429	4.10	1.31	3.41	851.	5494.	3321.
.358	54.	989.	44650.	29000.	370.	231.	.624	.800	.5682	.0434	4.15	2.24	4.40	1466.	5353.	3238.
.370	58.	1026.	44613.	30000.	373.	229.	.633	.799	.5777	.0439	4.22	2.09	4.31	1381.	5212.	3156.
.382	63.	1064.	44575.	31000.	377.	227.	.641	.798	.5880	.0445	4.29	1.92	4.20	1276.	5037.	3050.
.395	68.	1103.	44535.	32000.	381.	225.	.652	.797	.5952	.0450	4.32	1.67	3.99	1128.	4865.	2950.
.410	73.	1147.	44492.	33000.	386.	224.	.663	.796	.6017	.0454	4.33	1.48	3.81	1011.	4697.	2853.
.426	80.	1194.	44445.	34000.	392.	223.	.676	.796	.6056	.0456	4.31	1.27	3.58	880.	4532.	2759.
.445	87.	1246.	44392.	35000.	396.	221.	.687	.794	.6149	.0462	4.36	1.16	3.52	816.	4373.	2666.

END OF CLIMB TO 35000. FT
 TIME= .445 HRS FUEL USED= 1246. LBS WEIGHT= 44392. LBS RANGE= 87. NM

0 ALTITUDE= 35000. FT TAS= 482.37 KTS MACH NO= .8358

ACCELERATE TO MACH NO. = .800

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.445	87.27	1246.3	44392.	35000.	396.	221.	.687	.794	4695.	3020.
.478	102.03	1351.4	44287.	35000.	461.	258.	.800	.813	4780.	3123.

END OF ACCELERATION SEGMENT
 TIME= .478 HRS FUEL USED= 1351.4 LBS WEIGHT= 44287. LBS RANGE= 102. NM

ACCELERATE TO MACH NO. = .836

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.445	87.27	1246.3	44392.	35000.	396.	221.	.687	.794	4695.	3020.
.490	108.21	1392.2	44247.	35000.	482.	269.	.836	.819	4807.	3167.

END OF ACCELERATION SEGMENT
 TIME= .490 HRS FUEL USED= 1392.2 LBS WEIGHT= 44247. LBS RANGE= 108. NM

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution (continued)

ACCELERATE TO MACH NO. = .853

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.445	87.27	1246.3	44392.	35000.	396.	221.	.687	.794	4695.	3020.
.495	110.91	1409.6	44229.	35000.	492.	275.	.853	.820	4809.	3189.

END OF ACCELERATION SEGMENT
 TIME= .495 HRS FUEL USED= 1409.6 LBS WEIGHT= 44229. LBS RANGE= 111. NM

DESIGN CASE
 CRUISE PERFORMANCE SUMMARY
 FOR
 ***** DESIGN PAYLOAD *****
 ***** MAXIMUM PAYLOAD *****
 ***** MAXIMUM FUEL *****
 FUEL AVAILABLE= 9020.

		AT SPECIFIED SPEED		AT NORMAL POWER		AT BEST SPEC. RANGE	
		START CRUISE	END CRUISE	START CRUISE	END CRUISE	START CRUISE	END CRUISE
TIME	HRS.	.478	3.010	.490	2.520	.495	2.689
RANGE	N.MI	102.	1271.	108.	1088.	111.	1191.
FUEL USED	LBS.	1351.	7219.	1392.	6360.	1410.	7037.
WEIGHT	LBS.	44287.	38420.	44247.	39279.	44229.	38602.
ALTITUDE	FT.	35000.	35000.	35000.	35000.	35000.	35000.
TAS	KTS.	461.7	461.7	482.4	482.4	492.4	492.4
EAS	KTS.	257.3	257.3	268.8	268.8	274.4	274.4
MACH NO.		.8000	.8000	.8358	.8358	.8532	.8532
DIV. MACH		.8142	.8217	.8190	.8264	.8211	.8274
ANGLE ATTACK	DEG.	2.363	1.838	1.869	1.369	1.649	1.236
FUSE. ANGLE	DEG.	.363	-.162	-.131	-.631	-.351	-.764
CL		.4554	.3951	.4168	.3568	.3999	.3490
L/D		12.139	11.317	11.684	10.725	11.237	10.480
FUEL FLOW	LB/HR	2402.1	2236.1	2530.3	2368.5	2644.1	2492.7
BREG. FACTOR	N.MI.	8518.	7938.	8441.	8005.	8242.	7630.
SPEC. RANGE	NM/LB	.19220	.20647	.19064	.20366	.18622	.19753

0 DESCENT FROM CRUISE AT NORMAL POWER CONDITION
 (U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MMD OR VMD)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	FUS. ANGLE (DEG)	R/S (FPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
2.533	1094.	6382.	39256.	35000.	482.	269.	.836	.825	.3662	.0335	1.45	-1.57	-2.12	1339.	2513.	1782. R
2.546	1100.	6406.	39232.	34000.	485.	276.	.836	.827	.3492	.0329	1.31	-1.52	-2.22	1306.	2649.	1884. R
2.559	1106.	6433.	39206.	33000.	487.	282.	.836	.829	.3331	.0323	1.17	-1.48	-2.30	1271.	2794.	1991. R
2.572	1113.	6461.	39178.	32000.	489.	289.	.836	.831	.3179	.0318	1.05	-1.43	-2.39	1241.	2942.	2102. R
2.586	1119.	6491.	39147.	31000.	491.	296.	.836	.833	.3035	.0314	.93	-1.39	-2.47	1209.	3098.	2219. R
2.600	1126.	6524.	39114.	30000.	493.	302.	.836	.835	.2898	.0310	.81	-1.35	-2.54	1180.	3258.	2340. R
2.615	1134.	6560.	39079.	29000.	495.	309.	.836	.836	.2768	.0306	.70	-1.32	-2.61	1153.	3424.	2466. R
2.629	1141.	6598.	39040.	28000.	497.	316.	.836	.838	.2645	.0303	.60	-1.28	-2.68	1127.	3598.	2598. R
2.645	1149.	6640.	38999.	27000.	499.	323.	.836	.839	.2528	.0300	.50	-1.24	-2.74	1100.	3797.	2745. R
2.660	1156.	6685.	38954.	26000.	502.	331.	.836	.841	.2417	.0297	.41	-1.21	-2.80	1077.	3981.	2887. R
2.676	1164.	6733.	38906.	25000.	504.	338.	.836	.842	.2311	.0295	.32	-1.18	-2.86	1053.	4173.	3035. R
2.692	1172.	6784.	38855.	24000.	506.	345.	.836	.843	.2211	.0292	.24	-1.15	-2.91	1032.	4370.	3188. R
2.708	1181.	6839.	38799.	23000.	508.	353.	.836	.844	.2116	.0290	.16	-1.13	-2.96	1011.	4573.	3348. R
2.725	1189.	6897.	38742.	22000.	505.	357.	.827	.845	.2068	.0289	.14	-1.11	-2.97	992.	4674.	3437. R
2.742	1198.	6957.	38682.	21000.	499.	359.	.814	.845	.2041	.0289	.15	-1.10	-2.95	972.	4734.	3496. R
2.747	1200.	6961.	38678.	20000.	430.	314.	.699	.838	.2642	.0303	.93	-4.93	-6.00	3750.	1088.	788. A
2.751	1202.	6964.	38674.	19000.	425.	316.	.689	.838	.2611	.0302	.93	-4.93	-6.00	3703.	1135.	825. A
2.756	1204.	6968.	38670.	18000.	421.	318.	.679	.839	.2581	.0301	.92	-4.92	-6.00	3655.	1182.	863. A
2.761	1206.	6973.	38666.	17000.	416.	320.	.669	.839	.2550	.0301	.90	-4.90	-6.00	3608.	1232.	903. A
2.765	1207.	6977.	38662.	16000.	412.	322.	.659	.839	.2520	.0300	.89	-4.89	-6.00	3561.	1283.	944. A
2.770	1209.	6982.	38657.	15000.	408.	324.	.650	.840	.2490	.0299	.88	-4.88	-6.00	3515.	1336.	987. A
2.775	1212.	7002.	38637.	14000.	511.	413.	.812	.852	.1537	.0280	-.28	-3.61	-5.89	3262.	4601.	3933. A
2.780	1214.	7007.	38632.	13000.	399.	328.	.632	.841	.2430	.0298	.85	-4.85	-6.00	3422.	1447.	1077. A
2.785	1216.	7013.	38626.	12000.	396.	330.	.624	.841	.2400	.0297	.83	-4.83	-6.00	3377.	1505.	1124. A
2.790	1218.	7018.	38620.	11000.	392.	332.	.615	.841	.2370	.0296	.81	-4.81	-6.00	3333.	1565.	1174. A
2.800	1221.	7027.	38611.	10000.	291.	250.	.455	.819	.4175	.0355	3.00	-3.09	-2.09	1590.	1187.	854. S
2.811	1224.	7037.	38602.	9000.	286.	250.	.446	.819	.4174	.0355	3.02	-3.03	-2.02	1535.	1227.	885. S
2.822	1227.	7047.	38592.	8000.	282.	250.	.438	.819	.4173	.0354	3.03	-2.97	-1.94	1481.	1269.	918. S
2.834	1230.	7058.	38580.	7000.	277.	250.	.430	.819	.4172	.0354	3.04	-2.91	-1.87	1427.	1312.	952. S
2.846	1234.	7070.	38568.	6000.	273.	250.	.422	.819	.4171	.0354	3.05	-2.84	-1.79	1374.	1356.	987. S
2.859	1237.	7083.	38556.	5000.	269.	250.	.414	.819	.4169	.0354	3.06	-2.77	-1.71	1321.	1402.	1023. S
2.872	1241.	7097.	38542.	4000.	265.	250.	.406	.819	.4168	.0354	3.07	-2.71	-1.63	1269.	1449.	1061. S
2.886	1244.	7112.	38527.	3000.	261.	250.	.399	.819	.4166	.0354	3.08	-2.63	-1.55	1217.	1497.	1099. S
2.900	1248.	7129.	38510.	2000.	257.	250.	.391	.819	.4165	.0354	3.09	-2.56	-1.47	1165.	1547.	1139. S
2.907	1250.	7137.	38502.	1500.	255.	250.	.388	.819	.4163	.0354	3.10	-2.52	-1.43	1139.	1573.	1160. S

0 END OF DSCNT TO 1500. FT
 TIME= 2.907 HRS FUEL USED= 7137. LBS WEIGHT= 38502. LBS RANGE= 1250. NM

0 RESERVE FUEL(LBS) 1802. 1898. 1983.
 (45.0 MIN.)

0 RANGE = 1250. BLOCK TIME= 2.907 USED FOR DESIGN RANGE AND COST

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution (continued)


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0 .....
0 TEMP.= 537. DEG:STD.+36.
  LANDING ELEVATION= 5000. FT.
  LANDING WING LOADING= 98.70 PSF.
  LANDING WEIGHT = 42900. LBS.

  LANDING DISTANCE FROM 50. FT.= 2964. FT.

  F.A.R. FACTORED FIELD LENGTH = 4941. FT.
0 APPROACH TRANSITION DELAY ROLL
0 DIST= 700. DIST= 204. DIST= 207. DIST= 1853.
  R/S= 1000. XLPK= 1.200 TDELAY= 1.00 MUB= .4000
  VAPEAS= 124.21 SINKTD= 3.000 TIDLE= 640. TR/TIDLE= .0000
  VAPTAS= 138.59 VSTEAS= 95.55 VTDTAS= 122.60 ABAR(G)= .3599
  THETA= 4.08 CLMX= 3.1874
  THRUST= 3304. HFLAR= 20.9
0 .....
0 .....
0 RANGE OR ENDURANCE ITERATION SUMMARY
  ITERATION GROSS RANGE (NMI) OR
  WEIGHT (LB) ENDURANCE (HR)
0 44050.00 1066.847
1 53719.51 2092.646
2 45776.46 1264.360
3 45638.74 1249.734
  REQUIRED RG. OR END. = 1250.000

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
  ANGLE OF ATTACK(DEGREES)= 2.362 LIFT= 44269.6 L/D= 12.137 ALTITUDE= 35000.0 MACH= .8000

0 GROSS WEIGHT = 45639. PASSENGERS = 50. PLUS CREW

0 FUSELAGE LENGTH (ELF) 79.25 FT
  WIDTH (SWF) 9.25 FT
  WETTED AREA (SF) 191.0 SQFT
  DELTA P (DELP) 8.20 PSI

0 WING ASPECT RATIO (AR) 8.72
  AREA (SM) 434.7 SQFT
  SPAN (B) 61.6 FT
  GEOM. MEAN CHORD (CBARM) 8.25 FT
  QUARTER CHORD SWEEP (DLWC4) 18.6 DEG
  TAPER RATIO (SLM) .170
  ROOT THICKNESS (TCR) .130
  TIP THICKNESS (TCT) .100
  WING LOADING (WGS) 105.0 PSF
  WING FUEL VOLUME (VFW) 1042.4 GAL

0 HOR. TAIL ASPECT RATIO (ARHT) 4.04
  AREA (SHT) 159.0 SQFT
  SPAN (BHT) 25.33 FT
  MEAN CHORD (CBARHT) 6.28 FT
  THICKNESS/CHORD (TCHT) .100
  MOMENT ARM (ELTH) 44.2 FT
  VOLUME COEFF. (VBARH) 1.959

0 VERT. TAIL ASPECT RATIO (ARVT) 1.04
  AREA (SVT) 97.0 SQFT
  SPAN (BVT) 10.05 FT
  MEAN CHORD (CBARVT) 9.75 FT
  THICKNESS/CHORD (TCVT) .120
  MOMENT ARM (ELTV) 33.2 FT
  VOLUME COEFF. (VBARV) .120

0 ENG. NACELLES LENGTH (ELN) 11.87 FT
  MEAN DIAMETER (DBARN) 3.96 FT
  NUMBER ENGINES (ENB) 2.0
  WETTED AREA (SN) 295.05 SQFT

  LOCATION ON FUSELAGE
0 VDIVE = 715. KTS VMO = 596. KTS MMO = .900
  ULT. LP = 4.94 MAN. LP = 2.50 GUST LP = 3.30

0 PROPULSION GROUP
  PRIMARY ENGINES (WEP) 3131.
  PRIMARY ENGINE INSTL. (WPEI) 423.
  FUEL SYSTEM (WFSS) 180.
  TOTAL PROP.GROUP WT. (WP) 3734.

0 STRUCTURES GROUP
  WING (WW) 4389.
  HOR. TAIL (WHT) 748.
  VERT. TAIL (WVT) 449.
  FUSELAGE (WB) 5990. (INCL. .0 LBS A.T.W.)
  LANDING GEAR (WLG) 1734.
  PRIMARY ENG. SECTION (WPES) 1038.
  GROUP WEIGHT INC. (DELWST) 0.
  TOTAL STRUC.GROUP WT. (WST) 14348.

0 FLIGHT CONTROLS GROUP
  COCKPIT CONTROLS (WCC) 96.
  FIXED WING CONTROLS (WCFW) 796.
  SAS (WSAS) 0.
  GROUP WEIGHT INC. (DELWFC) 0.
  TOTAL CONTROL WT. (WFC) 891.

0 WT. OF FIXED EQUIPMENT (WFE) 6566.

  WEIGHT EMPTY (WE) 25540.
  FIXED USEFUL LOAD (WFUL) 1079. (INC. CREW )
  OPERATING WEIGHT EMPTY (OWE) 26619.
0 PAYLOAD (WPL) 10000. (PAX.VOL.= 50. DESIGN PAX= 50.)
  FUEL (WFA) 9020. (WFW= 6971.) (WFTP= 0.)
  GROSS WEIGHT (WG) 45639.

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Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution (continued)

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0          FIXED EQUIP GROUP                FIXED USEFUL LOAD
0  WAPU          372.27          WCREW ( 2.)          340.00
0  WINSTR        236.82          WSTU ( 1.)          130.00
0  WHYD          366.62          WCBAG              110.00
0  WELEC         970.00          WUF                125.09
0  WAV           500.00          WOIL              129.68
0  WFUN          3410.00         WSRV              116.00
0  WAC           477.91          WHZO              53.00
0  WAI           212.29         WEMER             40.00
0  WAUXG         20.00          WCATER            35.00

0  WPE           6565.91         WFUL              1078.77

0  DESIGN MACH = .800          DESIGN ALTITUDE = 35000.          DESIGN Q (PSF) =224.03
0  DESIGN RE.NUM. PER FT. = 1.922E+06          FLATPLATE CP AT RE=10EX7 IS .00274

0  AERODYNAMIC DATA
0
0  DRAG BREAKDOWN          FLATPLATE          CDO          WETTED
0  WING                    AREA(SQFT)          .00665          AREA(SQFT)
0  FUSELAGE                2.8925             .01256          659.97
0  VERT. TAIL              5.4592             .00140          1910.38
0  HOR. TAIL               .6086              .00236          193.95
0  ENGINE MAC.            1.0247             .00274          317.97
0  TIP TANKS              1.1899             .00000          295.05
0  INCREMENTAL            .0000              .00150          .00
0  TOTAL                   .6520              .02721          3377.32

0  MEAN SKIN FRICTION COEF.= .003502

0  AERODYNAMIC COEFF.
0  A1                      .8107
0  A2                     -.1242
0  A3                      .0360
0  A4=.75X(T/C)           .0910
0  A5=CDO--               .0178
0  A6                      2.4286
0  A7=1/(PI.SEE.AR)       .0473
0  3-D LIFT SLOPE AT CRUISE MACH (CLALPH) 6.5841 PER RADIAN
0  OSWALD FACTOR (SEE)    .7712

0  CRUISE CD = .0272 + .0473 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
0  RETRACTABLE LANDING GEAR CD INC.= .03451

0  CRUISE DRAG
0CL=.2000
0  MACH   CD   L/D   CLALPH   ALPHA
0  .50000 .02914 6.8644 5.2969 .5634
0  .55000 .02914 6.8644 5.4242 .5126
0  .60000 .02914 6.8644 5.5757 .4552
0  .65000 .02914 6.8644 5.7572 .3904
0  .70000 .02914 6.8644 5.9767 .3173
0  .75000 .02914 6.8644 6.2462 .2346
0  .80000 .02914 6.8644 6.5841 .1404
0  .85000 .02914 6.8640 7.0206 .0322
0CL=.3000
0  MACH   CD   L/D   CLALPH   ALPHA
0  .50000 .03164 9.4818 5.2969 1.6451
0  .55000 .03164 9.4818 5.4242 1.5689
0  .60000 .03164 9.4818 5.5757 1.4828
0  .65000 .03164 9.4818 5.7572 1.3856
0  .70000 .03164 9.4818 5.9767 1.2759
0  .75000 .03164 9.4818 6.2462 1.1519
0  .80000 .03164 9.4818 6.5841 1.0106
0  .85000 .03176 9.4467 7.0206 .8483
0CL=.4000
0  MACH   CD   L/D   CLALPH   ALPHA
0  .50000 .03509 11.3992 5.2969 2.7268
0  .55000 .03509 11.3992 5.4242 2.6252
0  .60000 .03509 11.3992 5.5757 2.5104
0  .65000 .03509 11.3992 5.7572 2.3808
0  .70000 .03509 11.3992 5.9767 2.2346
0  .75000 .03509 11.3992 6.2462 2.0691
0  .80000 .03509 11.3992 6.5841 1.8809
0  .85000 .03572 11.1971 7.0206 1.6644
0CL=.5000
0  MACH   CD   L/D   CLALPH   ALPHA
0  .50000 .03966 12.6080 5.2969 3.8085
0  .55000 .03966 12.6080 5.4242 3.6815
0  .60000 .03966 12.6080 5.5757 3.5380
0  .65000 .03966 12.6080 5.7572 3.3760
0  .70000 .03966 12.6080 5.9767 3.1932
0  .75000 .03966 12.6080 6.2462 2.9864
0  .80000 .03966 12.6080 6.5841 2.7511
0  .85000 .04151 12.0464 7.0206 2.4805
0CL=.6000
0  MACH   CD   L/D   CLALPH   ALPHA
0  .50000 .04517 13.2827 5.2969 4.8902
0  .55000 .04517 13.2827 5.4242 4.7378
0  .60000 .04517 13.2827 5.5757 4.5656
0  .65000 .04517 13.2827 5.7572 4.3712
0  .70000 .04517 13.2827 5.9767 4.1519
0  .75000 .04517 13.2827 6.2462 3.9037
0  .80000 .04517 13.2823 6.5841 3.6213
0  .85000 .04924 12.1861 7.0206 3.2966

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Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution
(continued)

0 LOW SPEED LIFT/DRAG-GR.UP(IF R)O.G.E.

FLAPS UP		TAKEOFF		LANDING					
ALPHA	CL	CD	L/D	CL	L/D				
-2.00000	-.03378	.02736	-1.23449	1.07389	.09225	11.64121	1.84073	.25101	7.33333
.00000	-.13512	.02808	4.81130	1.24279	.10567	11.76150	2.00964	.26866	7.48034
2.00000	.30403	.03176	9.57267	1.41170	.12285	11.49101	2.17854	.29151	7.47326
4.00000	.47293	.03833	12.33925	1.58061	.14590	10.83338	2.34745	.31899	7.35910
6.00000	.64184	.04790	13.39877	1.74951	.17178	10.18484	2.51636	.34962	7.19741
8.00000	.81075	.06069	13.35837	1.91842	.20041	9.57260	2.68526	.38341	7.00358
10.00000	.97965	.07731	12.67110	2.08732	.23179	9.00504	2.85417	.42037	6.78973
12.00000	1.14856	.09943	11.55143	2.25623	.26594	8.48400	3.02307	.46048	6.56508
13.92202	1.31088	.12360	10.60608	2.41855	.30135	8.02572	3.18539	.50200	6.34536
13.92202	1.31088	.12360	10.60608	2.41855	.30135	8.02572	3.18539	.50200	6.34536

0 DFLAP=.00 DFLAP= 15.00 DFLAP= 40.00
 0 CLMAX= 1.31088 CLMAX= 2.43199 CLMAX= 3.18742

0 LOW SPEED AERO FOR OTHER FLAP DEFLECTIONS

FLAP DEFL.	CLMAX	CL	CD	L/D
10.000	2.08973	.74305	.06904	10.76197
		.91195	.07966	11.44762
		1.08086	.09370	11.53470
		1.24976	.11179	11.17940
		1.41867	.13525	10.48931
		1.58757	.16144	9.83412
		1.75648	.19035	9.22762
		1.92538	.22199	8.67314
		2.08973	.25540	8.18210
		2.08973	.25540	8.18210
20.000	2.66391	1.31722	.11933	11.03880
		1.48613	.13455	11.04532
		1.65503	.15432	10.72435
		1.82394	.17880	10.20125
		1.99284	.20605	9.67158
		2.16175	.23609	9.15637
		2.33065	.26892	8.66678
		2.49956	.30453	8.20795
		2.66391	.34185	7.79257
		2.66391	.34185	7.79257
30.000	3.00166	1.65497	.17549	9.43078
		1.82388	.19236	9.48172
		1.99278	.21444	9.29303
		2.16169	.24043	8.99096
		2.33059	.26931	8.65398
		2.49950	.30108	8.30183
		2.66840	.33574	7.94792
		2.83731	.37328	7.60094
		3.00166	.41259	7.27512
		3.00166	.41259	7.27512

0 ALTITUDE= 35000. FT TAS= 485.85 KTS MACH NO= .8419

0 RDT&E AND AIRFRAME PRODUCTION COSTS
 0 (1993. DOLLARS)
 0 TOTAL RDT&E COSTS 1076.8734 MILLION
 0 AIRFRAME PRODUCTION COSTS(INCLUDING 10% PROFIT)
 0 500. AIRCRAFT

STRUCTURE(4058313.\$)	WEIGHT(LB)	COST(\$)	COST(\$/LB)
WING	4389.	1099938.	250.60
EMENNAGE	1197.	427746.	357.30
FUSELAGE	5990.	1661996.	277.46
LANDING GEAR	1734.	308317.	177.78
NACELLES	1038.	560318.	539.98
PROPULSION INSTAL(179467.\$)			
ENGINE INSTALLAT.	423.	153896.	364.08
FUEL SYSTEM	180.	25570.	141.74
SYSTEMS(2549885.\$)			
FLIGHT CONTROLS	891.	418411.	469.41
HYDRAULIC	367.	45668.	124.57
ELECTRICAL	970.	464214.	478.57
AIR CONDITIONING	478.	256070.	535.82
ANTI-ICING	212.	111802.	526.66
AUX. POWER UNIT	372.	207143.	556.42
FURNISHINGS	3410.	796443.	233.56
INSTRUMENTS	237.	196430.	829.44
AVIONICS INSTALL.	250.	49032.	196.13
AUX. ITEMS	20.	4671.	233.56
INTEGRATION(1696917.\$)			
AIRFRAME TOTALS	22159.	8484584.	382.90
ENGINES		2914463.	
PROPELLER		0.	
AVIONICS		4000000.	
A/C COST(NO RD)		15399047.	
R&D PER A/C		2153747.	
TOTAL A/C COST		17552794.	

0 ENGINES NUMBER = 2. TYPE= 7

0 EMPTY WEIGHT= 25540. AIRFRAME WEIGHT= 22409. WEIGHT OF 1 ENGINE= 1566. CRUISE SPEED= 486. KTS
 0 THRUST/ENGINE= 9785.
 0 TOTAL AIRCRAFT COST= 17552794. AIRFRAME COST= 14638331. COST OF 1 ENGINE= 1457232. COST OF 1 PROP.= 0.

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution (continued)

```

0          --- COST DATA ---
0          GASP SHORThAUL METHOD
0          DESIGN MISSION
0          OPERATING COST FOR NOR. RATED POWER AND 35000. ALTITUDE
0          .....
0          RANGE= 1250. N.M.   BLOCK FUEL= 7137. LBS   BLOCK TIME= 2.9073 HRS.
0          UTILIZATION          3200.
0          FLYING OPERATIONS
0          FLIGHT CREW          363.415
0          FUEL, OIL, AND TAXES( .850$/G) 948.029
0          INSURANCE           79.737
0          DIRECT MAINTENANCE
0          AIRFRAME            165.025
0          ENGINE              281.055
0          MAINTENANCE BURD.    360.700
0          DEPRECIATION        1071.663
0          TOTAL DOC ($/TRIP)    3269.624
0          ($/B.HR.)           1124.618
0          ($/N.MI.)           2.616

```

Fig E12 - Conventional Configuration optimised for minimum M.T.O.W. - GASP solution (concluded)

*....data for 50 Pax turbofan airliner

```

VARIABLES
01 1 95.0      86.750      80.000      105.000
02 1 9.0       8.300       8.000       10.000
03 1 23.0     14.500     11.000     35.000
04 1 .235      .200       .160       .310
05 1 4.0       4.000      3.800      4.300
06 1 27.5     27.500    20.000    35.000
07 1 1.0       1.000      .800      1.200
08 1 46.5     50.500    40.000    53.000
09 1 6.0       5.500      4.000      8.000
10 1 23.0     15.000    10.000    35.000
11 1 .43        .500       .160       .700
12 1 1.5       2.000      .000       3.000
13 1 .15       .15        .145      .175
14 1 .8        .75        .75       .85
FUNCTIONS
01 00 0045000.0      1
02 -1 00 6000.0
03 -1 00 5000.0
04 -1 00 120.0
05 -1 00 .8
06 -1 00 .8
CONTROLS
XTOLU = .0001
XTOLV = .0001
OFRM = 1
OFREQ = 10
RFREQ = 50
NFEMAX = 20000
RUN
END

```

Fig E13 - RQPMIN.DAT file for the Three-Lifting Surface M.T.O.W. optimisation case

!Program RQPMIN Version 1.0 for VAX

ANALYSIS OF INPUT FILE DATA AND CONTROL PARAMETERS

Input file: rqpmin.dat
Output file: rqpmin.res

Variable data

Number of variables = 14

Index	Status	Scale	Starting value	Lower bound	Upper bound
1	1	.9500000E+02	.9131579E+00	.8421053E+00	.1105263E+01
2	1	.9000000E+01	.9222223E+00	.8888889E+00	.1111111E+01
3	1	.2300000E+02	.6304348E+00	.4782609E+00	.1521739E+01
4	1	.2350000E+00	.8510638E+00	.6808510E+00	.1319149E+01
5	1	.4000000E+01	.1000000E+01	.9500000E+00	.1075000E+01
6	1	.2750000E+02	.1000000E+01	.7272727E+00	.1272727E+01
7	1	.1000000E+01	.1000000E+01	.8000000E+00	.1200000E+01
8	1	.4650000E+02	.1086022E+01	.8602151E+00	.1139785E+01
9	1	.6000000E+01	.9166667E+00	.6666667E+00	.1333333E+01
10	1	.2300000E+02	.6521739E+00	.4347826E+00	.1521739E+01
11	1	.4300000E+00	.1162791E+01	.3720930E+00	.1627907E+01
12	1	.1500000E+01	.1333333E+01	.0000000E+00	.2000000E+01
13	1	.1500000E+00	.1000000E+01	.9666666E+00	.1166667E+01
14	1	.8000000E+00	.9375000E+00	.9375000E+00	.1062500E+01

Problem function data

Number of constraints = 5

Index	Status	Type	Scale	Index	Status	Type	Scale
1	0	0	.5000000E+04	2	-1	0	.6000000E+04
3	-1	0	.5000000E+04	4	-1	0	.1200000E+03
5	-1	0	.8000000E+00	6	-1	0	.8000000E+00

objective is function 1 problem number = 1

Control parameters

nfemax = 20000 nimax = 1000 nsmx = 20 nsetv = 4 nsetcf = 8 nsetv = 4 nsetvf = 8
ofreq = 10 ofrom = 1 rfreq = 50 rfrom = 1

centrl = F fdset = F norep = F cheats = T fast = T quasi = T
fixrp = F timid = F monitr = F nofreq = F yesbc = F shrnk = T project = T

xtol = .1000000E-05 xtolu = .1000000E-03 xtoly = .1000000E-03 gtol = .1000000E-02
rtol = .1000000E+00 omegar = .1000000E+00 rmax = .2000000E+00
umax = .1000000E-05 vmainf = .1000000E-02 vminc = .1000000E-05 ctol = .1000000E-02
umax = .1000000E+00 vmax = .1000000E+00 omega = .1000000E+00 mu = .1000000E-03
bdtol = .1000000E+00 latal = .1000000E+00 wtol = .5000000E+00 cmax = .1000000E-01
subtol = .1000000E-02 qrtol = .1000000E+02 btstol = .1000000E-05 diftol = .5000000E-03
stol = .1000000E-29

End of input data

!Program RQPMIN Version 1.0 for VAX

STARTING POINT

free variables

1	.9131579E+00	2	.9222223E+00	3	.6304348E+00	4	.8510638E+00	5	.1000000E+01	6	.1000000E+01	7	.1000000E+01	8	.1086022E+01	9	.9166667E+00	10	.6521739E+00	11	.1162791E+01	12	.1333333E+01	13	.1000000E+01	14	.9375000E+00
---	--------------	---	--------------	---	--------------	---	--------------	---	--------------	---	--------------	---	--------------	---	--------------	---	--------------	----	--------------	----	--------------	----	--------------	----	--------------	----	--------------

objective function

f(x) = .9313772E+01

inactive inequality constraints

2	-.2221938E+00	3	-.2112215E+00	4	-.1449613E+00	5	-.4113428E-01	6	-.8386575E-01
---	---------------	---	---------------	---	---------------	---	---------------	---	---------------

!Program RQPMIN Version 1.0 for VAX

end of iteration number 1

end of a successful minimization step
number of calls made to user function so far = 30

Fig E14 - RQPMIN.RES file for the Three-Lifting Surface M.T.O.W. optimisation case

```

free variables
-----
 1 .9153786E+00 2 .9999178E+00 3 .6547356E+00 4 .9143497E+00 5 .1063544E+01 6 .9908860E+00 7 .1100000E+01
 8 .1136797E+01 9 .9806426E+00 10 .7156005E+00 11 .1226368E+01 12 .1417440E+01 13 .1064629E+01

variables fixed at or near their lower bounds
-----
14 .9375000E+01

objective function
-----
f(x) = .9300725E+01

inactive inequality constraints
-----
 2 -.2105103E+00 3 -.2153489E+00 4 -.1476603E+00 5 -.2702467E-01 6 -.9797536E-01

Partial derivatives of Lagrangian function
-----
 1 .3650665E+01 2 .7869720E+01 3 -.8361816E+01 4 .2096939E+02 5 .3242493E-01 6 .3051758E-01 7 -.8201598E-01
 8 -.2193451E+00 9 -.2079010E+00 10 -.2254867E+02 11 .2670288E-01 12 .2079582E+02 13 -.5836487E+00 14 -.1087189E+01

convergence criteria
-----
pdatum = .9300725E+01   ldatum = .9300725E+01   gdatum = .0000000E+00
nu       = .0000000E+00   numax  = infinite
unormax  = .0000000E+00   unormd = .0000000E+00   rtol   = .1000000E+00   xtolu  = .1000000E-03
vnormax  = .5694389E+02   vnorma = .1000000E+00   xtolv  = .1000000E-03   grldn  = .2254867E+02
nda      = 0   ndef   = 2   ndec   = 0   ncalls = 4   nfuncs = 2
1Program RQPMIN Version 1.0 for VAX      16-Feb-94

end of iteration number 11
-----
restart after premature convergence
number of calls made to user function so far = 388

free variables
-----
 1 .9228305E+00 2 .9185433E+00 3 .6036867E+00 4 .8181030E+00 5 .9551157E+00 6 .9431822E+00 7 .1073791E+01
13 .1006602E+01 9 .9015445E+00 10 .6543043E+00 11 .1170526E+01 12 .1330351E+01 8 .1119945E+01

variables fixed at or near their lower bounds
-----
14 .9375000E+00

objective function
-----
f(x) = .9224617E+01

inactive inequality constraints
-----
 2 -.2036912E+00 3 -.1951350E+00 4 -.1333703E+00 5 -.4177324E-01 6 -.8322679E-01

Partial derivatives of Lagrangian function
-----
 1 -.3369331E+01 2 -.3032684E+01 3 -.2365112E+01 4 -.1057911E+02 5 -.2176571E+02 6 .1144409E-01 7 -.8740425E+01
13 -.7804870E+01 9 -.3172874E+01 10 .1029968E+00 11 .7896423E+01 12 .9975433E+01 8 .1761913E+02 14 -.1115131E+02

convergence criteria
-----
pdatum = .9224617E+01   ldatum = .9224617E+01   gdatum = .0000000E+00
nu       = .0000000E+00   numax  = infinite
unormax  = .0000000E+00   unormd = .0000000E+00   rtol   = .1000000E+00   xtolu  = .1000000E-03
vnormax  = .3566933E+02   vnorma = .1000000E+00   xtolv  = .1000000E-03   grldn  = .2176571E+02
nda      = 0   ndef   = 24   ndec   = 1   ncalls = 49   nfuncs = 24
1Program RQPMIN Version 1.0 for VAX      16-Feb-94

end of iteration number 21
-----
end of a successful minimization step
number of calls made to user function so far = 1029

```

Fig E14 - RQPMIN.RES file for the Three-Lifting Surface M.T.O.W. optimisation case
(continued)

```

free variables
-----
 1 .1010227E+01 2 .9823352E+00 3 .7007083E+00 4 .7784299E+00 14 .1014215E+01 6 .9579575E+00 7 .1142082E+01
13 .1143976E+01 9 .1000860E+01 10 .7929409E+00 11 .1152595E+01 12 .1352062E+01 5 .9956403E+00

variables fixed at or near their lower bounds
-----
 8 .8602151E+00

objective function
-----
f(x) = .8915198E+01

inactive inequality constraints
-----
 2 .8142090E-03 3 -.1764121E-01 4 -.1165155E-01 5 -.4023626E-01 6 -.8476377E-01

Partial derivatives of Lagrangian function
-----
 1 .2312088E+02 2 .5202293E+01 3 .3226280E+02 4 .2381706E+02 14 .3458881E+02 6 .0000000E+00 7 -.5254745E+00
13 -.2198696E+02 9 -.3209496E+02 10 .0000000E+00 11 -.2177524E+02 12 .0000000E+00 5 .0000000E+00 8 -.1465797E+01

convergence criteria
-----
pdatum = .8915198E+01 ldatum = .8915198E+01 gdatum = .0000000E+00
nu = .0000000E+00 numax = infinite
unormax = .0000000E+00 unormd = .0000000E+00 rtol = .1000000E+00 xtolu = .1000000E-03
vnormax = .5574258E+01 vnorm = .1000000E+00 xtolv = .1000000E-03 grldn = .3458881E+02
nde = 0 ndef = 24 ndec = 23 ncalls = 96 nfuncs = 49
IProgram RQPMIN Version 1.0 for VAX 16-Feb-94

end of iteration number 23
-----
CONVERGENCE DETECTED [ Code B ] after 1349 calls to user routine

```

```

free variables
-----
 1 .1010227E+01 2 .9823352E+00 3 .7007083E+00 4 .7784299E+00 14 .1014215E+01 6 .9579575E+00 7 .1142082E+01
13 .1143976E+01 9 .1000860E+01 10 .7929409E+00 11 .1152595E+01 12 .1352062E+01 5 .9956403E+00

variables fixed at or near their lower bounds
-----
 8 .8602151E+00

objective function
-----
f(x) = .8915198E+01

inactive inequality constraints
-----
 2 .8142090E-03 3 -.1764121E-01 4 -.1165155E-01 5 -.4023626E-01 6 -.8476377E-01

Partial derivatives of Lagrangian function
-----
 1 .2312088E+02 2 .5202293E+01 3 .3226280E+02 4 .2381706E+02 14 .3458881E+02 6 .0000000E+00 7 -.5254745E+00
13 -.2198696E+02 9 -.3209496E+02 10 .0000000E+00 11 -.2177524E+02 12 .0000000E+00 5 .0000000E+00 8 -.1465797E+01

convergence criteria
-----
pdatum = .8915198E+01 ldatum = .8915198E+01 gdatum = .0000000E+00
nu = .0000000E+00 numax = infinite
unormax = .0000000E+00 unormd = .0000000E+00 rtol = .1000000E+00 xtolu = .1000000E-03
vnormax = .3458881E+02 vnorm = .1000000E+00 xtolv = .1000000E-03 grldn = .3458881E+02
nde = 0 ndef = 24 ndec = 34 ncalls = 119 nfuncs = 61

```

Fig E14 - RQPMIN.RES file for the Three-Lifting Surface M.T.O.W. optimisation case (concluded)

50 PAX TURBOFAN AIRLINER USING SCALED G2 CF-34 - THREE-SURF. CONFIG.

ENGINE CYCLE IS G. R. CF-34

INPUT DATA FOLLOW

```

0
0 CONFIG WG = 44050.          *****GEOMETRY*****
      WGS = 95.972          KWRITE = 2          FUSEL SAB = 4.          ELODM = 1.000
      PAX = 50.             IGEAR = 0          WS = 20.000          ELODT = 3.200
      ENCRU = .800          KCONPG = 0          AS = 1.             BMLOD = 14.500
      HNCRU = 35000.        KTRIX = 0          WAS = 19.000        NACELLE KNAC = 1
      Kanard = 1            ENP = 2.           PS = 31.0           ELN = 11.295
                        WTYE = 7          ELPC = 11.220       DBARN = 3.765
                        KFLOT = 1        HCK = 2.470        ELRW = 10.000

0 WING TCT = .100          HORIZ VBARHX = .0000        VERT VBARVX = .0000        Canard TCcan = .100
      TCR = .130          TAIL YCHT = .100          TAIL TCVT = .120        ARcan = 6.005
      AR = 8.841          ARHT = 3.983          ARVT = 1.142          SLMcan = .496
      SLM = .183          SLMH = .550          SLMV = .700          DwpqCa = 18.238
      DLMC4 = 16.116      DMPOCH = 26.344      DWPCV = 40.000       EYecan = 2.028
      EYEW = 2.000        COELH = .000          BOELTV = .000        SWcOSW = .172

0
0 CKM = -1.000          ***AERODYNAMICS***          GRPE = .000          DCDSE = -1.0000
      CKP = -1.000          CKHT = -1.000          SCFAC = .750         CKMc = 2.497
      CKN = -1.000          CKTP = -1.000          DISWSW = .000        cmacw = -.060
      CKVT = -1.000        DELCD = .00150        ALPHL0 = -1.600      alzerc = -1.000

0
0 KWCD = 12            *HIGH LIFT DEVICES*          LED CLEOC = .000
      ACLS = -1.000      FLAPS JFLTYF = 7          DELLE = .000
      ACDCDR = 2.400    DFLLPTO = 15.000        DCLMLE = .930
                        DFLPLD = 40.000        DELLEO = 45.000
                        CFCO = .300
                        BTEOB = .750
                        DCLMTE = .000
                        DCDOTE = .000
                        DELTEO = .000

0
0 JENGZ = 2            ***PROPULSION***          RCCRU = 50.000        RWCRTX = .970
      IPART = 1          NPORT = 5000.          XTORQ = 99999.       HSCREQ = 0.
      KODETO = 5         TDELTO = 36.          SMLD = .500          THIN = 0.
      KODETR = 5         KODECL = 7            HBTP = .437          PR = 1.000
                        KODEAC = 5

0
0 SKPEI = .1350        ***WEIGHTS***          SKB = 107.000        SKFS = .0200
      SKLG = .0380        SKY = .1800           SKCC = 20.000        SKWP = .4300
      SKMG = .8000        SKZ = .2200           SKTL = 1.0000        SKFP = .9790
      SKPS = .3380        SKTL = 1.0000        SKRW = 133.400       SKSAS = .000
      WPLX = .0           YMG = .2500           EGMGRN = .0000        CMRGRN = .2000
      WPEI = .0           RELP = .8114          CMRGRN = .0000        STWRGN = .0000
      WPUL = 1066.3       RELA = .4500          DELP = 8.200         IDCPMX = 8.000
      WMPAI = 200.0       CATD = 3.             YP = .0000           ATMRCQ = 3.160
      STRUT = .0000        VMLPSL = 685.0        WBYLON = .0          DELWST = .0
      DELMPC = .0         WMAC = .0             WBYL = .700          XLQDE = 3.000
      WENG = .0           UWNAC = 2.287        ZCG = 5.500         CNPAC = .0020
      WWSLS = .160        STATIC = .100         TP = .0              ARVTE = -1.000
                        CHALP = 999.000        CXA = .520           RV = .300
                        CHDEL = 999.000       DCMCLP = .000        TAUV = 999.000
                        RH = .350           HMING = 0.           RVMS = .990
                        DEMAX = -25.0        dcmcpi = .030       DRMAX = 25.0
                        EYET = .0           rc = .350

0
0 KSPfxd = 1          ***PERFORMANCE***          DVR = 5.000          TDELTX = 36.000
      CMFLPL = 999.000   XLFMAX = 1.100        UM = .020            HTMAX = 500.000
      CMFLPT = 999.000   DELTVR = 3.500        MUB = .400           NFAIL = 0
      CMPLD = .000       DVI = 5.000          WTMISN = 0.
                        VRAT = 1.10

0 CLIMB ICLM = 1          CRUISE CRMACH = .800        FRESF = 1.000        FACWI = .988
      DELH = 1000.       CRALT = 35000.        RCRRQ = 1250.0       ISWING = 0
      VCLMB = .0         ICRUS = 1            OPALT = 25000.       OFEM = .500
0 LAND IMLD = 2          ILDGRQ = 99999.        VRATT = 1.300        HAPP = 50.
      TDELD = 36.0       ALTLD = 5000.        RSMX = 1000.         SINKTD = 3.0
      TDELAY = 1.0       WLPCT = .9400        TROTID = .000       XLFMZ = 1.200
      HTG = 5.5          TIDLE = .0           VTDRAI = 1.1

0
0 NCADE = 1            *****COST*****          RI = .300            CMV = .800
      CLIAB = 1993.0     HIR = .005           OHR = 500.000        CCRW = 0.
      HRI = 4000000.     TR = 2.000           CRWOH = 23.000       UCSENG = .000
      CMP = .2           PRV = .100           CINF = 0.            UCSPP = .000
      TBO = 3200.0       DYR = 15.0          CP = 0.              ALR = 1.120
      PCSF = .850       SRPM = .0
  
```

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
- GASP solution

```

*****
ITERATION TO BALANCE RANGE
RANGE ERROR, RANGE ERROR MINUS 1  -.0569  1.0000
GROSS WGT, GROSS WGT MINUS1  44576.0  44050.0

0 *****
0          FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
          CLMAX  VSTALL,KTS  FLAP ANGLE  LE ANGLE  DELTA CL  DELTA CD
FLAPS UP      1.1243      170.9      .0      .0      .0000      .0000
T.O. CONFIG   2.1192      124.7      15.0    .0      .9844      .0365
LDG. CONFIG   2.7832      108.8      40.0    .0      1.6611      .1626

0          DOUBLE SLOTTED POWLER FLAPS
          OPT ANGLE  DELCL AT OPT  DELCD AT OPT  AREA(FT2)  WEIGHT(LB)
FLAPS         30.0      2.2500      .1500      81.5      628.1
0 *****
0
SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK(DEGREES)=  1.927  LIFT= 43238.7  L/D= 13.657  ALTITUDE= 35000.0  MACH= .8000

1          ENGINE SIZING DATA FOLLOW
          *****
0VSTLKT= 115.6 KTS EAS  VRAT= 1.100  CLTO= 1.7514
VEND = 250.0 KNOTS EAS
0
ROTATION (TIME= 29.2 AND TAS= 140.0 EAS= 125.6)
LIFTOFF (TIME= 31.6 DIST= 4352.3 TAS= 147.8 EAS= 132.6)
DISTANCE TO 35 FT.= 5691.0  TAS= 159.1 EAS= 142.6 V35/V5= 1.2343
GEAR RETRACTION STARTED AT 37.7 SEC, COMPLETE AT 44.7 SEC
FLAP RETRACTION STARTED AT 47.9 SEC, COMPLETE AT 52.4 SEC
0VSTLKT= 115.6 KTS EAS  VRAT= 1.100  CLTO= 1.7514
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 212.1 KNOTS EAS
ENGINE FAILURE (TIME= 27.6 AND TAS= 134.4 EAS= 120.6)
0
ROTATION (TIME= 32.5 AND TAS= 140.0 EAS= 125.6)
LIFTOFF (TIME= 35.8 DIST= 5323.3 TAS= 142.2 EAS= 127.6)
DISTANCE TO 35 FT.= 8098.9  TAS= 142.9 EAS= 128.1 V35/V5= 1.1086

ACCELERATE - STOP DISTANCE = 6952.9 FEET.
0 ENGINE OUT DISTANCE TO 35 FT.= 8098.9 FEET
0 ALL ENGINE DISTANCE TO 35 FT. (L) = 5691.0 FEET
PAR 25 T.O. DISTANCE (1.15XL) = 6544.7 FEET
ALL ENGINE DISTANCE TO 50 FT. = 5936.6 FEET
0 AT END OF TAKEOFF PHASE
TIME= .014 HRS  FUEL USED= 75. LBS  WEIGHT= 44501. LBS  ALT.= 5500. FT.
0 TAKE OFF RATE OF CLIMB REQUIREMENTS - PAR PART 25
AIRPORT ALTITUDE= 5000. FT;  AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION          ALT (FT)  VS KEAS  V/V5  V KTAS  GRAD (PCT)  R/C (PPM)  REQ.R/C (PPM)  CL  L/D
1ST SEG:T.O. FLAPS+LD GEAR EXT - ONE ENG OUT  5000.  115.7  1.1210  144.6  1.661  243.05  1.00  1.694  8.792
2ND SEG: T.O. FLAPS - ONE ENGINE OUT         5250.  115.7  1.2000  155.4  3.902  613.68  377.45  1.478  11.250
FINAL T.O. CRUISE CONFIG - ONE ENG OUT      6500.  158.1  1.2500  225.5  4.287  978.39  273.87  .729  14.231
APPROACH FLAPS -ONE ENG OUT                 5000.  111.0  1.3240  163.8  4.068  674.28  348.09  1.320  11.583
LANDING FLAPS - ALL ENGINES                 5000.  101.0  1.3000  146.3  11.861  1756.68  473.92  1.653  7.065

APPROACH FLAP SETTING = 19.7 DEG.

+++ ENGINE-OUT SERVICE CEILING = 21989.1 FT.
BEST RATE OF CLIMB SPEED = 273.4 KTAS
ENGINE-OUT RATE OF CLIMB = 49.7 FPM
WEIGHT AT ALTITUDE = 42793.0 LBS

0          ****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES****
0PROPULSION SYSTEM WEIGHTS
ENGINE WEIGHT/ENGINE      1358.0
NACELLE WEIGHT/ENGINE     305.4
PYLON WEIGHT/ENGINE       164.3
PROP OR QFAN              .0
GEARBOX                   .0
SHROUD                    .0

0ENGINE POD DIMENSIONS
ENGINE FACE DIAMETER(FT)  3.77
NACELLE LENGTH(FT)       11.30

0VSTLKT= 115.6 KTS EAS  VRAT= 1.100  CLTO= 1.7514
VEND = 250.0 KNOTS EAS
0
ROTATION (TIME= 27.8 AND TAS= 140.0 EAS= 125.6)
LIFTOFF (TIME= 30.2 DIST= 4160.3 TAS= 148.1 EAS= 132.9)
DISTANCE TO 35 FT.= 5501.7  TAS= 160.3 EAS= 143.8 V35/V5= 1.2438
GEAR RETRACTION STARTED AT 36.2 SEC, COMPLETE AT 43.2 SEC
FLAP RETRACTION STARTED AT 46.4 SEC, COMPLETE AT 50.9 SEC
0VSTLKT= 115.6 KTS EAS  VRAT= 1.100  CLTO= 1.7514
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 206.8 KNOTS EAS
ENGINE FAILURE (TIME= 26.3 AND TAS= 134.4 EAS= 120.6)
0
ROTATION (TIME= 31.1 AND TAS= 140.0 EAS= 125.6)
LIFTOFF (TIME= 34.4 DIST= 5131.5 TAS= 142.6 EAS= 127.9)
DISTANCE TO 35 FT.= 7378.4  TAS= 143.4 EAS= 128.6 V35/V5= 1.1127

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Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
 - GASP solution (continued)

ACCELERATE - STOP DISTANCE = 6797.7 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT. = 7378.4 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 5501.7 FEET
 PAR 25 T.O. DISTANCE (1.15XL) = 6327.0 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 5748.4 FEET
 0 AT END OF TAKEOFF PHASE
 TIME = .013 HRS FUEL USED = 76. LBS WEIGHT = 44500. LBS ALT. = 5500. FT.
 0 TAKE OFF RATE OF CLIMB REQUIREMENTS - PAR PART 25
 AIRPORT ALTITUDE = 5000. FT; AMBIENT TEMP ABOVE STD. DAY = 36.0 DEG F

CONFIGURATION	ALT (FT)	VS KEAS	V/VS	V KTAS	GRAD (PCT)	R/C (FPM)	REQ. R/C (FPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	115.7	1.1210	144.6	1.940	283.96	1.00	1.694	8.593
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	115.7	1.2000	155.4	4.153	653.19	377.45	1.478	10.903
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	158.1	1.2500	225.5	4.280	976.81	273.87	.729	13.323
APPROACH FLAPS - ONE ENG OUT	5000.	111.0	1.3240	163.8	4.295	711.92	348.09	1.320	11.191
LANDING FLAPS - ALL ENGINES	5000.	101.0	1.3000	146.3	12.866	1905.50	473.92	1.653	7.025

APPROACH FLAP SETTING = 19.7 DEG.

+++ ENGINE-OUT SERVICE CEILING = 22512.9 FT.
 BEST RATE OF CLIMB SPEED = 273.8 KTAS
 ENGINE-OUT RATE OF CLIMB = 50.0 FPM
 WEIGHT AT ALTITUDE = 42793.0 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW = 346.74

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R; ALT = 5000.) SLS AIRFLOW = 346.74

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE = 8841.9 LBS

0 PROPULSION SYSTEM WEIGHTS

ENGINE WEIGHT/ENGINE	1414.7
NACELLE WEIGHT/ENGINE	305.4
PYLON WEIGHT/ENGINE	168.4
PROP OR QFAN	.0
GEARBOX	.0
SHROUD	.0

0 ENGINE POD DIMENSIONS

ENGINE FACE DIAMETER (FT)	3.77
NACELLE LENGTH (FT)	11.30

0

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
 - GASP solution (continued)

---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---

	MOST FWD LOAD		MOST AFT LOAD		DESIGN LOAD	
	WT	CG	WT	CG	WT	CG
A/C ONE	26235.95	42.56	26235.95	42.56	26235.95	42.56
PAX	5440.00		2040.00		8500.00	
BAGGAGE	.00	56.36	1500.00	56.36	1500.00	56.36
WING FUEL	1303.62	42.32	1303.62	42.32	6518.08	42.32
TIP FUEL	.00	.00	.00	.00	.00	.00
FUS FUEL	.00	42.32	.00	42.32	1821.97	42.32
TOTAL	32979.56	40.27	31079.56	43.58	44575.99	41.85

0 ---TAIL SIZING SUMMARY---

Static Longitudinal Stability, Stick-fixed, considered

CONDITION	ALPHA	WING		CANARD		TAIL		DOWN WASH	FLAP CM
		CL	CLA	CMac	ALPHA	CLA	CLA		
CRUISE	2.0363	.4290	.1180	-.0600	3.0644	.1002	.0768	1.0000	
LIFTOFF	2.0000	1.3020	.0682	-.0600	3.0281	.0768	.0639	1.0000	.3440
LANDING	11.5540	2.7832	.0853	-.0600	12.5821	.0769	.0639	1.0000	1.9871

CONDITION	---FUSELAGE---		---NACELLE---		-----POWER-----			L. GEAR	ROT. POWER		
	DCM	CM	DCM	CM	DCMth	DCMfine	CMth			CMfine	CT
CRUISE	.4731		.2109		.0000	.0300			.0000		
LIFTOFF	.8178	.0000	.2109	.0000			.0000	.0391	.0000	-.3324	5.2752
LANDING	.6543	.5332	.2109	.1719			.0000	.0835			

0 CANARD PARAMETERS

CMDELTC (CONTROL POWER)	=	-.02832
TAUC (EFFECTIVENESS)	=	.48250
DCMAX (MAX. CANARD VATOR DEFLEC.)	=	37.32742

0 ELEVATOR PARAMETERS

CMDELTE (CONTROL POWER)	=	-.03419	WING DE/DALPHA =	.34396
TAUH (EFFECTIVENESS)	=	.48250		
DEMAX (MAX. ELEVATOR DEFLEC.)	=	-25.00000		

	FRACTION MAC	STATION (DATUM NOSE)	CANARD AND HORIZONTAL TAIL SIZES	
			CANARD	HOR. TAIL
NEUTRAL POINT	.6584	44.458	STATIC STABILITY AND LANDING TRIM	
STATIC MARGIN	.1000		STATIC STABILITY AND LIFTOFF ROT.	
AFT CG LIMIT (STABILITY)	.5584	43.660		
CG RANGE (LOADING)	.4144		REQUIRED SIZES	71.9126
FWD CG LIMIT (CONTROL)	.1439	40.353	CANARD AND TAIL ARMS (ELcan, ELTH)	33.0524
				94.4135
				41.7515

0 VERTICAL TAIL AREA = 90.3807 FOR DIRECTIONAL STABILITY OF .00200

0 RUDDER POWER AT MAX. DEFL. = .0193 PER DEG. RUDDER CL AT MAX. DEFL. = .4826

0 VERTICAL TAIL AREA = 69.4408 FOR MINIMUM CONTROL SPEED = 114.40 KTS

0 REQUIRED VERTICAL TAIL AREA = 90.3807 TAIL ARM (ELTV) = 34.2879

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE

ANGLE OF ATTACK (DEGREES) = 1.927 LIFT = 43238.7 L/D = 12.729 ALTITUDE = 35000.0 MACH = .8000

0 WING LOCATION INFO.

FUSELAGE LENGTH	=	79.25	H-TAIL VOL. ARM	=	41.75	C.G. LOCATION OF PROPULSION =	64.30
WING 1/4C LOC. ON C.L.	=	37.74	H-TAIL C.G. LOCATION	=	83.27	C.G. OF REMAINING WEIGHT =	35.66
MAC 1/4C LOCATION	=	41.12	H-TAIL MAC FROM C.L.	=	4.38		
MAC DIST. FROM C.L.	=	11.71	H-TAIL LOCAT ON VERT.	=	1.00		
WING C.G. LOCATION	=	42.72	V-TAIL VOL. ARM	=	34.29		
TIP TANKS C.G. LOCATE	=	.00	V-TAIL C.G. LOCATION	=	76.13	DIST. L.E. VERT. TO L.E. HORZ. =	1.04

CANARD 1/4C LOC. ON C.L.	=	6.55
CANARD MAC DIST. FROM C.L.	=	4.61
CANARD VOLUME ARM	=	33.05
CANARD C.G. LOCATION	=	8.36

	WING	CANARD	H-TAIL	V-TAIL
AREA	419.080	71.913	94.414	90.381
SPAN	60.869	20.781	19.391	10.160
ASPECT RATIO	8.841	6.005	3.983	1.142
TAPER RATIO	.183	.496	.550	.700
1/4C SWEEP	16.116	18.238	26.344	40.000
L.E. SWEEP	20.156	21.090	29.600	42.500
C.L. CHORD	11.640	4.628	6.283	10.466
MEAN CHORD	7.980	3.592	5.006	8.988
TIP CHORD	2.129	2.293	3.455	7.326

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
- GASP solution (continued)

MISSION PERFORMANCE DATA FOLLOWS

0
0 TAXI AT IDLE THRUST

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	FUEL FLOW (LB/HR)
.000	0.	0.	44576.	5000.	808.
.167	0.	135.	44441.	5000.	808.
OVSTLKT= 112.2 KTS EAS VRAT= 1.100 CLTO= 1.7514					
VEND = 246.7 KNOTS EAS					
(TEMP.= 537. DEG. STD.+36.)					
0 TAKEOFF (ELEVATION= 5000. FT)					

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS ²)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	134.6	44441.	5000.0	.0	.0	.000	10.70	1.2994	.1329	2.00	.00	.0	.00	15682.	5585.	.00
1.0	5.3	136.2	44440.	5000.0	6.3	5.7	.009	10.57	1.2994	.1329	2.00	.00	.0	.00	15499.	5585.	.00
2.0	21.3	137.7	44438.	5000.0	12.5	11.3	.019	10.43	1.2995	.1329	2.00	.00	.0	.00	15319.	5585.	.00
3.0	47.7	139.3	44437.	5000.0	18.7	16.8	.028	10.28	1.2995	.1330	2.00	.00	.0	.00	15142.	5586.	.00
4.0	84.4	140.8	44435.	5000.0	24.7	22.2	.037	10.13	1.2996	.1330	2.00	.00	.0	.00	14968.	5587.	.00
5.0	131.2	142.4	44434.	5000.0	30.7	27.6	.046	9.97	1.2996	.1330	2.00	.00	.0	.00	14797.	5589.	.00
6.0	188.1	143.9	44432.	5000.0	36.6	32.8	.054	9.81	1.2997	.1330	2.00	.00	.0	.00	14630.	5591.	.00
7.0	254.7	145.5	44431.	5000.0	42.4	38.0	.063	9.64	1.2999	.1330	2.00	.00	.0	.00	14465.	5592.	.00
8.0	331.1	147.0	44429.	5000.0	48.0	43.1	.071	9.47	1.3000	.1330	2.00	.00	.0	.00	14302.	5594.	.00
9.0	417.0	148.6	44427.	5000.0	53.6	48.1	.080	9.30	1.3001	.1330	2.00	.00	.0	.00	14143.	5596.	.00
10.0	512.2	150.1	44426.	5000.0	59.1	53.0	.088	9.12	1.3003	.1330	2.00	.00	.0	.00	13986.	5598.	.00
11.0	616.5	151.7	44424.	5000.0	64.5	57.8	.096	8.94	1.3005	.1331	2.00	.00	.0	.00	13833.	5601.	.00
12.0	729.9	153.3	44423.	5000.0	69.7	62.5	.104	8.77	1.3006	.1331	2.00	.00	.0	.00	13698.	5603.	.00
13.0	852.0	154.8	44421.	5000.0	74.9	67.2	.111	8.61	1.3008	.1331	2.00	.00	.0	.00	13584.	5606.	.00
14.0	982.8	156.4	44420.	5000.0	80.0	71.7	.119	8.45	1.3010	.1331	2.00	.00	.0	.00	13472.	5609.	.00
15.0	1122.0	157.9	44418.	5000.0	84.9	76.2	.126	8.28	1.3012	.1331	2.00	.00	.0	.00	13362.	5612.	.00
16.0	1269.6	159.5	44416.	5000.0	89.8	80.6	.133	8.12	1.3015	.1332	2.00	.00	.0	.00	13255.	5615.	.00
17.0	1425.3	161.0	44415.	5000.0	94.6	84.8	.140	7.95	1.3017	.1332	2.00	.00	.0	.00	13149.	5618.	.00
18.0	1589.0	162.6	44413.	5000.0	99.3	89.0	.147	7.78	1.3019	.1332	2.00	.00	.0	.00	13046.	5621.	.00
19.0	1760.5	164.2	44412.	5000.0	103.8	93.1	.154	7.61	1.3022	.1332	2.00	.00	.0	.00	12945.	5624.	.00
20.0	1939.7	165.7	44410.	5000.0	108.3	97.2	.161	7.44	1.3024	.1333	2.00	.00	.0	.00	12847.	5628.	.00
21.0	2126.3	167.3	44409.	5000.0	112.7	101.1	.167	7.27	1.3027	.1333	2.00	.00	.0	.00	12750.	5631.	.00
22.0	2320.2	168.9	44407.	5000.0	117.0	104.9	.174	7.10	1.3029	.1333	2.00	.00	.0	.00	12656.	5635.	.00
23.0	2521.3	170.4	44406.	5000.0	121.1	108.7	.180	6.93	1.3032	.1333	2.00	.00	.0	.00	12564.	5638.	.00
24.0	2729.3	172.0	44404.	5000.0	125.2	112.3	.186	6.76	1.3035	.1334	2.00	.00	.0	.00	12474.	5642.	.00
25.0	2944.2	173.6	44402.	5000.0	129.2	115.9	.192	6.59	1.3037	.1334	2.00	.00	.0	.00	12386.	5645.	.00
26.0	3165.6	175.1	44401.	5000.0	133.0	119.4	.198	6.42	1.3040	.1334	2.00	.00	.0	.00	12300.	5649.	.00
27.0	3393.5	176.7	44399.	5000.0	136.8	122.7	.203	6.26	1.3043	.1335	2.00	.00	.0	.00	12229.	5653.	.00

0 ROTATION (TIME= 26.9 AND TAS= 136.3 EAS= 122.2)
28.0 3627.7 178.3 44398. 5000.0 140.4 126.0 .208 5.89 1.4255 .1480 3.42 .00 .0 .85 12170. 5656. 1.42
29.0 3867.8 179.8 44396. 5000.0 143.8 129.0 .213 5.42 1.5532 .1663 4.95 .00 .0 .97 12115. 5659. 2.95

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS ²)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
LIFT OFF (TIME= 29.0 DIST= 3867.8 TAS= 143.8 EAS= 129.0)																	
30.0	4113.3	181.4	44395.	5000.3	146.9	131.7	.218	4.78	1.6527	.1816	6.16	.26	68.6	1.09	12066.	5663.	4.42
31.0	4363.6	183.0	44393.	5003.0	149.6	134.2	.222	4.35	1.6096	.1749	5.56	.98	258.4	1.10	12021.	5665.	4.54
32.0	4618.3	184.6	44391.	5008.9	152.0	136.4	.226	3.96	1.5611	.1677	4.96	1.68	450.9	1.10	11979.	5667.	4.64
33.0	4876.8	186.1	44390.	5018.1	154.3	138.4	.229	3.60	1.5149	.1609	4.46	2.36	643.6	1.09	11941.	5668.	4.82
34.0	5138.9	187.7	44388.	5030.4	156.3	140.2	.232	3.22	1.4770	.1555	4.06	3.04	840.4	1.09	11905.	5669.	5.10
DISTANCE TO 35 FT = 5221.6 TAS= 156.9 EAS= 140.7 V35/V50= 1.2535																	
35.0	5404.0	189.3	44387.	5046.1	158.1	141.8	.235	2.84	1.4493	.1516	3.76	3.71	1036.1	1.10	11873.	5669.	5.47
GEAR RETRACTION STARTED AT 35.2 SEC, COMPLETE AT 42.2 SEC																	
36.0	5671.8	190.9	44385.	5065.0	159.7	143.2	.237	2.53	1.4228	.1450	3.46	4.37	1232.3	1.10	11843.	5668.	5.83
37.0	5941.9	192.4	44384.	5087.2	161.2	144.4	.239	2.27	1.3969	.1378	3.16	5.02	1428.9	1.10	11814.	5667.	6.18
38.0	6214.1	194.0	44382.	5112.6	162.5	145.5	.241	2.01	1.3710	.1307	2.86	5.67	1626.7	1.09	11788.	5665.	6.53
39.0	6488.0	195.6	44380.	5141.4	163.6	146.4	.243	1.74	1.3539	.1250	2.66	6.30	1820.6	1.10	11764.	5663.	6.96
40.0	6763.2	197.2	44378.	5173.3	164.6	147.2	.244	1.48	1.3367	.1194	2.46	6.95	2017.3	1.09	11742.	5660.	7.41
41.0	7039.6	198.7	44377.	5208.6	165.4	147.9	.246	1.21	1.3281	.1148	2.36	7.58	2211.6	1.10	11721.	5656.	7.84
42.0	7316.9	200.3	44376.	5247.0	166.0	148.4	.247	.97	1.3109	.1092	2.16	8.21	2403.4	1.09	11703.	5652.	8.37
43.0	7594.6	201.9	44374.	5288.7	166.5	148.7	.248	.65	1.3022	.1075	2.06	8.84	2592.5	1.09	11686.	5648.	8.90
44.0	7872.6	203.4	44373.	5333.4	166.8	148.9	.248	.29	1.3023	.1075	2.06	9.45	2776.5	1.10	11672.	5642.	9.51
45.0	8150.3	205.0	44371.	5381.2	166.9	148.8	.248	.01	1.2762	.1048	1.76	10.08	2960.0	1.08	11661.	5636.	9.84
FLAP RETRACTION STARTED AT 45.4 SEC, COMPLETE AT 49.9 SEC																	
46.0	8427.7	206.6	44369.	5431.3	166.9	148.7	.248	.00	1.1531	.1011	1.91	10.27	3014.2	.97	11651.	5630.	10.18
47.0	8705.2	208.1	44368.	5480.7	166.9	148.6	.248	.00	1.0734	.1096	3.51	9.85	2894.0	.91	11640.	5624.	11.36

OVSTLKT= 112.2 KTS EAS VRAT= 1.100 CLTO= 1.7514
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 203.1 KNOTS EAS
(TEMP.= 537. DEG. STD.+36.)
0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS ²)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	134.6	44441.	5000.0	.0	.0	.000	10.70	1.2994	.1329	2.00	.00	.0	.00	15682.	5585.	.00
1.0	5.3	136.2	44440.	5000.0	6.3	5.7	.009	10.57	1.2994	.1329	2.00	.00	.0	.00	15499.	5585.	.00
2.0	21.3	137.7	44438.	5000.0	12.5	11.3	.019	10.43	1.2995	.1329	2.00	.00	.0	.00	15319.	5585.	.00
3.0	47.7	139.3	44437.	5000.0	18.7	16.8	.028	10.28	1.2995	.1330	2.00	.00	.0	.00	15142.	5586.	.00
4.0	84.4	140.8	44435.	5000.0	24.7	22.2	.037	10.13	1.2996	.1330	2.00	.00	.0	.00	14968.	5587.	.00
5.0	131.2	142.4	44434.	5000.0	30.7	27.6	.046	9.97	1.2996	.1330	2.00	.00	.0	.00	14797.	5589.	.00
6.0	188.1	143.9	44432.	5000.0	36.6	32.8	.054	9.81	1.2997	.1330	2.00	.00	.0	.00	14630.	5591.	.00
7.0	254.7	145.5	44431.	5000.0	42.4	38.0	.063	9.64	1.2999	.1330	2.00	.00	.0	.00	14465.	5592.	.00
8.0	331.1	147.0	44429.	5000.0	48.0	43.1	.071	9.47	1.3000	.1330	2.00	.00	.0	.00	14302.	5594.	.00
9.0	417.0	148.6	44427.	5000.0	53.6	48.1	.080	9.30	1.3001	.1330	2.00	.00	.0	.00	14143.	5596.	.00
10.0	512.2	150.1	44426.	5000.0	59.1	53.0	.088	9.12	1.3003	.1330	2.00	.00	.0	.00	13986.	5598.	.00
11.0	616.5	151.7	44424.	5000.0	64.5	57.8	.096	8.94	1.3005	.1331	2.00	.00	.0	.00	13833.	5601.	.00
12.0	729.9	153.3	44423.	5000.0	69.7	62.5	.104	8.77	1.3006	.1331	2.00	.00	.0	.00	13698.	5603.	.00
13.0	852.0	154.8	44421.	5000.0	74.9	67.2	.111	8.61	1.3008	.1331	2.00	.00	.0	.00	13584.	5606.	.00
14.0	982.8	156.4	44420.	5000.0	80.0	71.7	.119	8.45	1.3010	.1331	2.00	.00	.0	.00	13472.	5609.	.00
15.0	1122.0	157.9	44418.	5000.0	84.9	76.2	.126	8.28	1.3012	.1331	2.00	.00	.0	.00	13362.	5612.	.00
16.0	1269.6	159.5	44416.	5000.0	89.8	80.6	.133	8.12	1.30								

ENGINE FAILURE (TIME= 25.4 AND TAS= 130.7 EAS= 117.2)
 26.0 3165.1 174.7 44401. 5000.0 131.7 118.1 .196 1.89 1.3039 .1407 2.00 .00 .0 .00 6165. 2824. .00
 27.0 3388.4 175.4 44401. 5000.0 132.8 119.1 .197 1.86 1.3040 .1405 2.00 .00 .0 .00 6153. 2824. .00
 28.0 3613.6 176.2 44400. 5000.0 133.9 120.1 .199 1.82 1.3041 .1404 2.00 .00 .0 .00 6141. 2825. .00
 29.0 3840.7 177.0 44399. 5000.0 135.0 121.1 .200 1.78 1.3042 .1402 2.00 .00 .0 .00 6130. 2825. .00
 30.0 4069.5 177.8 44398. 5000.0 136.0 122.0 .202 1.74 1.3043 .1401 2.00 .00 .0 .00 6121. 2826. .00

0 ROTATION (TIME= 30.2 AND TAS= 136.3 EAS= 122.2)
 31.0 4300.1 178.6 44397. 5000.0 137.0 122.9 .203 1.59 1.3756 .1478 2.83 .00 .0 .78 6113. 2826. .83
 32.0 4532.2 179.4 44397. 5000.0 137.9 123.7 .205 1.28 1.5033 .1653 4.35 .00 .0 .87 6106. 2827. 2.35
 33.0 4765.7 180.2 44396. 5000.0 138.5 124.3 .206 .94 1.6311 .1844 5.91 .00 .0 .95 6100. 2827. 3.91

LIPTOFF (TIME= 33.4 DIST= 4859.4 TAS= 138.7 EAS= 124.5)
 34.0 5000.1 180.9 44395. 5000.0 139.0 124.7 .206 .56 1.7473 .2032 7.37 .06 14.2 1.03 6097. 2827. 5.43
 35.0 5235.1 181.7 44394. 5000.8 139.3 124.9 .207 .37 1.7514 .2039 7.38 .33 82.0 1.04 6094. 2827. 5.71
 36.0 5470.4 182.5 44394. 5002.8 139.4 125.1 .207 .19 1.7514 .2040 7.29 .64 156.6 1.04 6093. 2827. 5.92
 37.0 5706.0 183.3 44393. 5006.1 139.5 125.1 .207 .01 1.7514 .2041 7.22 .95 234.6 1.04 6092. 2827. 6.17
 38.0 5941.5 184.1 44392. 5010.5 139.5 125.1 .207 .02 1.7090 .1971 6.71 1.17 287.6 1.01 6092. 2827. 5.87
 39.0 6177.1 184.9 44391. 5015.5 139.5 125.1 .207 .00 1.6990 .1955 6.61 1.25 308.7 1.01 6091. 2827. 5.86
 40.0 6412.6 185.7 44390. 5020.7 139.5 125.1 .207 .02 1.6885 .1938 6.51 1.28 317.0 1.00 6090. 2826. 5.79
 41.0 6648.2 186.4 44390. 5026.0 139.5 125.1 .207 .01 1.6868 .1936 6.51 1.30 320.2 1.00 6090. 2826. 5.80
 42.0 6883.8 187.2 44389. 5031.4 139.5 125.1 .207 .01 1.6856 .1934 6.51 1.30 321.8 1.00 6089. 2826. 5.81
 DISTANCE TO 35 FT.= 7043.1 TAS= 139.5 EAS= 125.1 V35/V5= 1.1147
 43.0 7119.4 188.0 44388. 5036.7 139.5 125.1 .207 .01 1.6847 .1933 6.51 1.31 322.1 1.00 6088. 2825. 5.81
 44.0 7355.0 188.8 44387. 5042.1 139.6 125.1 .207 .02 1.6841 .1932 6.51 1.30 321.5 1.00 6088. 2825. 5.81
 45.0 7590.7 189.6 44386. 5047.5 139.6 125.1 .207 .02 1.6836 .1931 6.51 1.30 320.4 1.00 6087. 2825. 5.81

ACCELERATE - STOP DISTANCE = 6584.9 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 7043.1 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 5221.6 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 6004.9 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 5463.2 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .180 HRS FUEL USED= 209. LBS WEIGHT= 44367. LBS ALT.= 5500. FT.

ACCELERATE TO MACH NO. = .412

0 TIME RANGE FUEL USED WEIGHT ALT. TAS EAS MACH MACH THRUST FUEL FLOW
 (HRS) (NM) (LBS) (LBS) (FT) (KTS) (KTS) NO. DIV (LBS) (LB/HR)
 .180 .00 208.8 44367. 5500. 161. 149. .248 .726 11905. 5541.
 .189 2.00 259.9 44316. 5500. 268. 247. .412 .809 10154. 5696.

END OF ACCELERATION SEGMENT
 0 TIME= .189 HRS FUEL USED= 259.9 LBS WEIGHT= 44316. LBS RANGE= 2. NM
 0 CLIMB TO 35000. FT. AT MAXIMUM RATE OF CLIMB

0 TIME RANGE FUEL USED WEIGHT ALT. TAS EAS MACH MACH CL CD ALPHA GAMMA FUS. R/C THRUST FUEL FLOW
 (HRS) (NM) (LBS) (LBS) (FT) (KTS) (KTS) NO. DIV (DEG) (DEG) (DEG) (PPM) (LBS) (LB/HR)
 .189 2. 260. 44316. 5500. 245. 226. .378 .801 .5156 .0376 4.15 7.59 9.74 3285. 9057. 5008.
 .191 3. 273. 44303. 6000. 246. 225. .380 .801 .5195 .0378 4.19 7.17 9.36 3119. 8977. 4960.
 .196 4. 299. 44277. 7000. 249. 225. .386 .800 .5233 .0380 4.22 6.83 9.05 3004. 8794. 4861.
 .202 5. 326. 44250. 8000. 251. 223. .390 .799 .5309 .0384 4.29 6.77 9.06 3002. 8623. 4761.
 .208 7. 353. 44223. 9000. 261. 228. .407 .802 .5094 .0372 4.02 5.46 7.48 2515. 8350. 4662.
 .214 8. 383. 44193. 10000. 263. 227. .412 .801 .5143 .0375 4.07 6.10 8.17 2836. 8182. 4559.
 .220 10. 410. 44166. 11000. 266. 225. .418 .801 .5199 .0378 4.12 6.27 8.38 2942. 8015. 4457.
 .226 11. 435. 44140. 12000. 269. 224. .424 .800 .5264 .0382 4.18 5.71 7.88 2707. 7849. 4359.
 .232 13. 462. 44114. 13000. 271. 223. .429 .799 .5327 .0385 4.23 5.51 7.75 2641. 7684. 4262.
 .238 15. 489. 44087. 14000. 274. 221. .435 .798 .5391 .0389 4.29 5.32 7.61 2574. 7520. 4168.
 .245 17. 516. 44060. 15000. 277. 220. .442 .798 .5453 .0392 4.34 5.11 7.46 2500. 7356. 4076.
 .251 18. 543. 44033. 16000. 283. 221. .453 .798 .5401 .0389 4.26 4.52 6.79 2260. 7150. 3981.
 .259 20. 573. 44003. 17000. 286. 219. .459 .797 .5469 .0393 4.32 4.65 6.98 2348. 6973. 3880.
 .266 23. 600. 43976. 18000. 288. 218. .465 .797 .5540 .0397 4.38 4.45 6.83 2266. 6799. 3782.
 .273 25. 628. 43948. 19000. 291. 217. .472 .796 .5613 .0401 4.45 4.24 6.69 2184. 6627. 3685.
 .281 27. 656. 43920. 20000. 294. 215. .479 .795 .5686 .0405 4.51 4.04 6.55 2102. 6459. 3590.
 .289 29. 685. 43891. 21000. 297. 214. .485 .794 .5759 .0410 4.57 3.84 6.41 2018. 6292. 3498.
 .297 32. 714. 43862. 22000. 300. 212. .493 .793 .5835 .0414 4.63 3.65 6.28 1938. 6129. 3407.
 .306 34. 743. 43833. 23000. 304. 211. .500 .792 .5902 .0418 4.68 3.44 6.12 1846. 5967. 3318.
 .315 37. 773. 43803. 24000. 311. 212. .514 .793 .5829 .0414 4.56 2.92 5.48 1603. 5778. 3241.
 .325 40. 807. 43769. 25000. 314. 211. .521 .792 .5915 .0419 4.63 3.04 5.67 1686. 5610. 3161.
 .335 43. 838. 43738. 26000. 319. 210. .531 .791 .5953 .0421 4.64 2.73 5.37 1537. 5438. 3084.
 .346 47. 871. 43705. 27000. 323. 209. .540 .791 .6008 .0425 4.67 2.56 5.23 1464. 5272. 3008.
 .357 50. 905. 43671. 28000. 327. 208. .549 .790 .6073 .0429 4.71 2.39 5.10 1379. 5111. 2932.
 .369 54. 941. 43635. 29000. 332. 207. .560 .790 .6107 .0431 4.71 2.15 4.85 1259. 4950. 2859.
 .382 59. 979. 43597. 30000. 335. 205. .568 .788 .6206 .0438 4.78 2.07 4.85 1226. 4800. 2785.
 .396 63. 1017. 43559. 31000. 359. 216. .612 .796 .5588 .0400 4.00 1.07 3.06 678. 4559. 2726.
 .421 72. 1084. 43492. 32000. 362. 214. .619 .795 .5704 .0407 4.09 1.58 3.67 1015. 4404. 2632.
 .437 78. 1127. 43449. 33000. 365. 212. .627 .793 .5825 .0414 4.18 1.41 3.59 911. 4252. 2541.
 .455 85. 1173. 43403. 34000. 369. 210. .637 .792 .5896 .0418 4.20 1.18 3.39 772. 4103. 2455.
 .477 93. 1226. 43350. 35000. 376. 210. .651 .792 .5913 .0419 4.17 .97 3.13 643. 3957. 2374.

0 END OF CLIMB TO 35000. FT
 TIME= .477 HRS FUEL USED= 1226. LBS WEIGHT= 43350. LBS RANGE= 93. NM

0 ALTITUDE= 35000. FT TAS= 457.18 KTS MACH NO= .7922

ACCELERATE TO MACH NO. = .800

0 TIME RANGE FUEL USED WEIGHT ALT. TAS EAS MACH MACH THRUST FUEL FLOW
 (HRS) (NM) (LBS) (LBS) (FT) (KTS) (KTS) NO. DIV (LBS) (LB/HR)
 .477 92.75 1226.4 43350. 35000. 376. 210. .651 .791 4226. 2700.
 .530 116.02 1378.3 43198. 35000. 461. 258. .800 .816 4319. 2822.

END OF ACCELERATION SEGMENT
 TIME= .530 HRS FUEL USED= 1378.3 LBS WEIGHT= 43198. LBS RANGE= 116. NM
 SPECIFIED MACH NUMBER CONDITION CAN NOT BE PERFORMED AT NORMAL RATED POWER CONDITION

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
 - GASP solution (continued)

ACCELERATE TO MACH NO. = .792

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.477	92.75	1226.4	43350.	35000.	376.	210.	.651	.791	4226.	2700.
.527	114.68	1370.2	43206.	35000.	457.	255.	.792	.815	4313.	2816.

END OF ACCELERATION SEGMENT

TIME= .527 HRS FUEL USED= 1370.2 LBS WEIGHT= 43206. LBS RANGE= 115. NM

ACCELERATE TO MACH NO. = .810

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.477	92.75	1226.4	43350.	35000.	376.	210.	.651	.791	4226.	2700.
.533	117.66	1388.3	43188.	35000.	467.	261.	.810	.817	4326.	2829.

END OF ACCELERATION SEGMENT

TIME= .533 HRS FUEL USED= 1388.3 LBS WEIGHT= 43188. LBS RANGE= 118. NM

DESIGN CASE
CRUISE PERFORMANCE SUMMARY
FOR
***** DESIGN PAYLOAD *****
***** MAXIMUM PAYLOAD *****
***** MAXIMUM FUEL *****
FUEL AVAILABLE= 8340.

	AT		AT		AT		
	SPECIFIED	SPEED	NORMAL	POWER	BEST SPEC.	RANGE	
	START	END	START	END	START	END	
	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	
TIME	HRS.	.000	.000	.527	2.646	.533	2.850
RANGE	N.MI	0.	0.	115.	1084.	118.	1200.
FUEL USED	LBS.	0.	0.	1370.	5996.	1388.	6609.
WEIGHT	LBS.	0.	0.	43206.	38580.	43188.	37967.
ALTITUDE	FT.	0.	0.	35000.	35000.	35000.	35000.
TAS	KTS.	.0	.0	457.2	457.2	467.2	467.2
EAS	KTS.	.0	.0	254.8	254.8	260.4	260.4
MACH NO.		.0000	.0000	.7922	.7922	.8095	.8095
DIV. MACH		.0000	.0000	.8154	.8220	.8175	.8232
ANGLE ATTACK	DEG.	.000	.000	1.832	1.369	1.616	1.228
FUSE. ANGLE	DEG.	.000	.000	-.168	-.631	-.384	-.772
CL		.0000	.0000	.4012	.3470	.3840	.3376
L/D		.000	.000	12.495	11.538	12.261	11.390
FUEL FLOW	LB/HR	.0	.0	2242.3	2126.9	2308.5	2202.5
BREG. FACTOR	N.MI.	0.	0.	8815.	8298.	8746.	8059.
SPEC. RANGE	NM/LB	.00000	.00000	.20389	.21495	.20238	.21212

0 DESCENT FROM CRUISE AT NORMAL POWER CONDITION
(U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MMO OR VMO)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ANGLE (DEG)	R/S (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
2.659	1089.	6015.	38561.	35000.	457.	255.	.792	.821	.3546	.0302	1.43	-1.66	-2.22	1339.	2174.	1514. R
2.671	1095.	6035.	38341.	34000.	459.	261.	.792	.823	.3381	.0297	1.29	-1.61	-2.31	1306.	2299.	1604. R
2.685	1101.	6057.	38519.	33000.	461.	268.	.792	.825	.3226	.0291	1.16	-1.56	-2.40	1271.	2432.	1698. R
2.698	1107.	6082.	38494.	32000.	463.	274.	.792	.827	.3078	.0287	1.03	-1.51	-2.48	1241.	2568.	1797. R
2.712	1114.	6108.	38468.	31000.	465.	280.	.792	.829	.2939	.0282	.91	-1.47	-2.55	1209.	2711.	1900. R
2.726	1120.	6136.	38440.	30000.	467.	287.	.792	.830	.2807	.0279	.80	-1.43	-2.63	1180.	2858.	2007. R
2.740	1127.	6167.	38409.	29000.	469.	293.	.792	.832	.2681	.0275	.69	-1.39	-2.69	1153.	3010.	2118. R
2.755	1134.	6200.	38376.	28000.	471.	300.	.792	.833	.2562	.0272	.59	-1.35	-2.76	1127.	3167.	2233. R
2.770	1141.	6235.	38341.	27000.	473.	306.	.792	.835	.2449	.0269	.50	-1.31	-2.82	1100.	3332.	2355. R
2.786	1149.	6274.	38302.	26000.	475.	313.	.792	.836	.2342	.0266	.40	-1.28	-2.88	1077.	3516.	2487. R
2.802	1156.	6315.	38261.	25000.	477.	320.	.792	.837	.2240	.0264	.32	-1.25	-2.93	1053.	3691.	2618. R
2.818	1164.	6360.	38216.	24000.	479.	327.	.792	.838	.2143	.0262	.23	-1.22	-2.98	1032.	3871.	2753. R
2.834	1172.	6407.	38168.	23000.	481.	334.	.792	.840	.2051	.0260	.15	-1.19	-3.03	1011.	4058.	2894. R
2.851	1180.	6459.	38117.	22000.	483.	341.	.792	.841	.1963	.0258	.08	-1.16	-3.08	992.	4250.	3040. R
2.868	1188.	6512.	38064.	21000.	482.	346.	.786	.841	.1908	.0257	.04	-1.14	-3.10	972.	4374.	3142. R
2.873	1190.	6516.	38060.	20000.	414.	302.	.673	.834	.2487	.0270	.79	-4.79	-6.00	3500.	941.	677. A
2.878	1192.	6519.	38057.	19000.	409.	304.	.663	.834	.2460	.0269	.78	-4.78	-6.00	3455.	981.	709. A
2.883	1194.	6523.	38053.	18000.	404.	306.	.653	.835	.2433	.0269	.77	-4.77	-6.00	3410.	1023.	742. A
2.888	1196.	6527.	38049.	17000.	400.	307.	.643	.835	.2406	.0268	.76	-4.76	-6.00	3366.	1065.	776. A
2.893	1198.	6531.	38045.	16000.	396.	309.	.634	.835	.2379	.0267	.75	-4.75	-6.00	3322.	1110.	811. A
2.898	1200.	6535.	38041.	15000.	392.	311.	.624	.836	.2352	.0267	.74	-4.74	-6.00	3278.	1155.	848. A
2.903	1202.	6540.	38036.	14000.	387.	313.	.616	.836	.2326	.0266	.72	-4.72	-6.00	3235.	1203.	886. A
2.908	1204.	6544.	38032.	13000.	383.	314.	.607	.836	.2299	.0265	.71	-4.71	-6.00	3192.	1251.	925. A
2.913	1206.	6549.	38026.	12000.	380.	316.	.598	.837	.2272	.0265	.69	-4.69	-6.00	3150.	1302.	966. A
2.919	1208.	6555.	38021.	11000.	376.	318.	.590	.837	.2246	.0264	.68	-4.68	-6.00	3108.	1354.	1009. A
2.929	1211.	6563.	38013.	10000.	291.	250.	.455	.820	.3640	.0306	2.35	-3.18	-2.84	1637.	1073.	771. S
2.939	1214.	6571.	38005.	9000.	286.	250.	.446	.820	.3640	.0306	2.36	-3.13	-2.77	1584.	1109.	800. S
2.950	1217.	6580.	37996.	8000.	282.	250.	.438	.820	.3639	.0306	2.37	-3.07	-2.70	1532.	1146.	830. S
2.962	1220.	6590.	37986.	7000.	277.	250.	.430	.820	.3638	.0306	2.38	-3.01	-2.63	1480.	1185.	860. S
2.973	1224.	6600.	37976.	6000.	273.	250.	.422	.820	.3637	.0306	2.39	-2.95	-2.56	1428.	1225.	892. S
2.985	1227.	6611.	37964.	5000.	269.	250.	.414	.820	.3636	.0306	2.40	-2.89	-2.49	1377.	1266.	924. S
2.998	1230.	6624.	37952.	4000.	265.	250.	.406	.820	.3635	.0306	2.41	-2.83	-2.41	1327.	1309.	958. S
3.011	1234.	6636.	37939.	3000.	261.	250.	.399	.820	.3634	.0305	2.42	-2.76	-2.34	1277.	1353.	993. S
3.025	1237.	6650.	37926.	2000.	257.	250.	.391	.820	.3633	.0305	2.43	-2.69	-2.26	1227.	1398.	1030. S
3.031	1239.	6658.	37918.	1500.	255.	250.	.388	.820	.3631	.0305	2.43	-2.66	-2.23	1202.	1421.	1048. S

0 END OF DESCNT TO 1500. FT
TIME= 3.031 HRS FUEL USED= 6658. LBS WEIGHT= 37918. LBS RANGE= 1239. NM

0 RESERVE FUEL(LBS) 0. 1682. 1731.
(45.0 MIN.)

0 RANGE = 1239. BLOCK TIME= 3.031 USED FOR DESIGN RANGE AND COST

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
- GASP solution (continued)

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0 *****
0 TEMP.= 537. DEG:STD.+36.
  LANDING ELEVATION= 5000. FT.
  LANDING WING LOADING= 85.34 PSF.
  LANDING WEIGHT = 41901. LBS.

  LANDING DISTANCE FROM 50. FT.= 2947. FT.

  F.A.R. FACTORED FIELD LENGTH = 4912. FT.
0 APPROACH TRANSITION DELAY ROLL
0 DIST= 697. DIST= 203. DIST= 206. DIST= 1841.
  R/S= 1000. XLFMX= 1.200 TDELAY= 1.00 MUB= .4000
  VAPAS= 123.60 SINKTD= 3.000 TIDLE= 579. TR/TIDLE= .0000
  VAPTAS= 137.92 VSTEAS= 95.08 VTDIAS= 122.00 ABAR(G)= .3587
  THETA= 4.10 CLMX= 2.7832
  THRUST= 3016. HPLAR= 20.9
0 *****
0 *****
0 RANGE OR ENDURANCE ITERATION SUMMARY
  GROSS RANGE(NMI) OR
  ITERATION WEIGHT(LB) ENDURANCE(HR)
  0 44050.00 1178.872
  1 44575.99 1238.908
  REQUIRED RG. OR END. = 1250.000
0
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
  ANGLE OF ATTACK(DEGREES)= 1.927 LIFT= 43238.7 L/D= 12.729 ALTITUDE= 35000.0 MACH= .8000
0 GROSS WEIGHT = 44576. PASSENGERS = 50. PLUS CREW
0 FUSELAGE LENGTH (ELF) 79.25 FT
  WIDTH (SWF) 9.25 FT
  WETTED AREA (SF) 1910. SQFT
  DELTA P (DELP) 8.20 PSI
0 WING ASPECT RATIO (AR) 8.84
  AREA (SW) 419.1 SQFT
  SPAN (S) 60.9 FT
  GEOM. MEAN CHORD (CBARM) 7.98 FT
  QUARTER CHORD SWEEP (DLMC4) 16.1 DEG
  TAPER RATIO (SLM) .183
  ROOT THICKNESS (TCR) .130
  TIP THICKNESS (TCT) .100
  WING LOADING (WGS) 90.8 PSF
  WING FUEL VOLUME (VFW) 974.7 GAL
0 CANARD ASPECT RATIO (ARcan) 6.01
  AREA (SWc) 71.9 SQFT
  SPAN (Bcan) 20.8 FT
  GEOM. MEAN CHORD (CBARc) 3.59 FT
  QUARTER CHORD SWEEP (DwpqCa) 18.2 DEG
  TAPER RATIO (SLMcan) .496
  THICKNESS/CHORD (TCcan) .100
  MOMENT ARM (ELcan) 33.1 FT
  VOLUME COEFF. (VBARc) .711
  CANARD LOADING (WGS) 90.8 PSF
0 HOR. TAIL ASPECT RATIO (ARHT) 3.98
  AREA (SHT) 94.4 SQFT
  SPAN (BHT) 19.39 FT
  MEAN CHORD (CBARHT) 5.01 FT
  THICKNESS/CHORD (TCHT) .100
  MOMENT ARM (ELTH) 41.8 FT
  VOLUME COEFF. (VBARH) 1.179
0 VERT. TAIL ASPECT RATIO (ARVT) 1.14
  AREA (SVT) 90.4 SQFT
  SPAN (BVT) 10.16 FT
  MEAN CHORD (CBARVT) 8.99 FT
  THICKNESS/CHORD (TCVT) .120
  MOMENT ARM (ELTV) 34.3 FT
  VOLUME COEFF. (VBARV) .121
0 ENG. NACELLES LENGTH (ELN) 11.30 FT
  MEAN DIAMETER (DBARN) 3.77 FT
  NUMBER ENGINES (ENP) 2.0
  WETTED AREA (SN) 267.08 SQFT
  LOCATION ON FUSELAGE
0 VDIVE = 715. KTS VMO = 596. KTS MMO = .900
  ULT. LF = 5.33 MAN. LF = 2.50 GUST LF = 3.55
0 PROPULSION GROUP
  PRIMARY ENGINES (WEP) 2829.
  PRIMARY ENGINE INSTL. (WPEI) 382.
  FUEL SYSTEM (WFPSS) 167.
  TOTAL PROP.GROUP WT. (WP) 3378.
0 STRUCTURES GROUP
  WING (WW) 4415.
  CANARD (WWc) 424.
  HOR. TAIL (WHT) 468.
  VERT. TAIL (WVT) 398.
  FUSELAGE (WB) 5991. (INCL. .0 LBS A.T.W.)
  LANDING GEAR (WLG) 1694.
  PRIMARY ENG. SECTION (WPES) 948.
  GROUP WEIGHT INC. (DELWST) 0.
  TOTAL STRUC.GROUP WT. (WST) 14338.
0 FLIGHT CONTROLS GROUP
  COCKPIT CONTROLS (WCC) 95.
  FIXED WING CONTROLS (WCFW) 809.
  SAS (WSAS) 0.
  GROUP WEIGHT INC. (DELWFC) 0.
  TOTAL CONTROL WT. (WPC) 904.
0 WT. OF FIXED EQUIPMENT (WFE) 6550.

```

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
- GASP solution (continued)


```

WEIGHT EMPTY (WE) 25170.
FIXED USEFUL LOAD (WFUL) 1066. (INC. CREW )
OPERATING WEIGHT EMPTY (OME) 26236.
0 PAYLOAD (WPL) 10000. (PAI.VOL.= 50. DESIGN PAI= 50.)
FUEL (WFA) 8340. (WFW= 6518.) (WFTF= 0.)
GROSS WEIGHT (WG) 44576.
0 FIXED EQUIP GROUP FIXED USEFUL LOAD
0 WAPU 372.27 WCREW ( 2.) 340.00
WINSTR 232.85 WSTU ( 1.) 130.00
WHYD 361.40 WCBAG 110.00
WELEC 970.00 WUF 122.83
WAV 500.00 WOIL 119.49
WFOR 3410.00 WSRV 116.00
WAC 477.91 WH2O 53.00
WAI 205.11 WEMER 40.00
WAUXG 20.00 WCATER 35.00
WFE 6549.54 WFUL 1066.32

```

```

0 DESIGN MACH = .800 DESIGN ALTITUDE = 35000. DESIGN Q (PSF) =224.03
0 DESIGN RE.NUM. PER FT. = 1.922E+06 FLATPLATE CP AT RE=10EX7 IS .00274

```

```

0 AERODYNAMIC DATA
0 DRAG BREAKDOWN FLATPLATE WETTED
0 WING AREA(SQFT) CDO AREA(SQFT)
CANARD .5226 .00106 67.83
FUSELAGE 5.4592 .01112 1910.38
VERT. TAIL .5744 .00117 180.76
HOR. TAIL .6310 .00129 188.83
ENGINE NAC. 1.1474 .00234 267.08
TIP TANKS .0000 .00000 .00
INCREMENTAL .7365 .00150 .00
0 TOTAL 11.8719 .02418 3251.06
MEAN SKIN FRICTION COEF.= .003652

```

```

0 AERODYNAMIC COEFF. AIRCRAFT WING CANARD
(except Wing and Canard)
A1 .8048 .8384
A2 -.1232 -.1236
A3 .0375 .0273
A4=.75X(T/C) .0907 .0750
A5=CDO-- .0149
A6 2.4391 2.6524
A7=1/(PI.SEE.AR) .0457 .0632
3-D LIFT SLOPE AT CRUISE MACH (CLALPH) 6.7596 PER RAD. (CLALPc) 5.7419 PER RAD.
OSWALD FACTOR (SEE) .7875 (SEECAN) .8390

```

```

0 CRUISE CD = .0240 + .0483 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
0 RETRACTABLE LANDING GEAR CD INC.= .02999

```

```

0 CRUISE DRAG
OCL= .2000
MACH CD L/D CLALPH ALPHA
.50000 .02592 7.7147 5.3851 .5279
.55000 .02592 7.7147 5.5192 .4762
.60000 .02592 7.7147 5.6792 .4177
.65000 .02592 7.7147 5.8716 .3516
.70000 .02592 7.7147 6.1055 .2769
.75000 .02592 7.7147 6.3944 .1921
.80000 .02592 7.7147 6.7596 .0952
.85000 .02595 7.7073 7.2371 -.0166
OCL= .3000
MACH CD L/D CLALPH ALPHA
.50000 .02848 10.5348 5.3851 1.5919
.55000 .02848 10.5348 5.5192 1.5144
.60000 .02848 10.5348 5.6792 1.4266
.65000 .02848 10.5348 5.8716 1.3274
.70000 .02848 10.5348 6.1055 1.2153
.75000 .02848 10.5348 6.3944 1.0881
.80000 .02848 10.5348 6.7596 .9428
.85000 .02876 10.4305 7.2371 .7751
OCL= .4000
MACH CD L/D CLALPH ALPHA
.50000 .03200 12.5019 5.3851 2.6558
.55000 .03200 12.5019 5.5192 2.5525
.60000 .03200 12.5019 5.6792 2.4355
.65000 .03200 12.5019 5.8716 2.3032
.70000 .03200 12.5019 6.1055 2.1537
.75000 .03200 12.5019 6.3944 1.9841
.80000 .03200 12.5019 6.7596 1.7905
.85000 .03307 12.0966 7.2371 1.5668
OCL= .5000
MACH CD L/D CLALPH ALPHA
.50000 .03665 13.6421 5.3851 3.7198
.55000 .03665 13.6421 5.5192 3.5906
.60000 .03665 13.6421 5.6792 3.4443
.65000 .03665 13.6421 5.8716 3.2790
.70000 .03665 13.6421 6.1055 3.0922
.75000 .03665 13.6421 6.3944 2.8802
.80000 .03665 13.6421 6.7596 2.6381
.85000 .03933 12.7125 7.2371 2.3585

```

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
 - GASP solution (continued)

OCL= .6000

MACH	CD	L/D	CLALPH	ALPHA
.50000	.04227	14.1935	5.3851	4.7838
.55000	.04227	14.1935	5.5192	4.6287
.60000	.04227	14.1935	5.6792	4.4532
.65000	.04227	14.1935	5.8716	4.2548
.70000	.04227	14.1935	6.1055	4.0306
.75000	.04227	14.1935	6.3944	3.7762
.80000	.04229	14.1868	6.7596	3.4857
.85000	.04768	12.5851	7.2371	3.1502

0 LOW SPEED LIFT/DRAG-GR.UP(IF R)O.G.E.

FLAPS UP				TAKEOFF				LANDING			
ALPHA	CL	CD	L/D	CL	CD	L/D	CL	CD	L/D	CL	L/D
-2.00000	-.03425	.02412	-1.41986	.95011	.07801	12.17970	1.62688	.21281	7.64476		
.00000	.13699	.02488	5.50656	1.12135	.09032	12.41566	1.79812	.22868	7.86316		
2.00000	.30823	.02873	10.72856	1.29259	.10648	12.13919	1.96936	.24896	7.91030		
4.00000	.47948	.03562	13.46205	1.46383	.12769	11.46379	2.14060	.27572	7.76370		
6.00000	.65072	.04567	14.24829	1.63507	.15326	10.66895	2.31184	.30579	7.56027		
8.00000	.82196	.05913	13.89993	1.80632	.18171	9.94076	2.48308	.33917	7.32108		
10.00000	.99320	.07652	12.98036	1.97756	.21305	9.28214	2.65433	.37586	7.06199		
11.50561	1.12430	.09411	11.94631	2.10865	.23900	8.82296	2.78324	.40567	6.86088		
11.50561	1.12430	.09411	11.94631	2.10865	.23900	8.82296	2.78324	.40567	6.86088		
11.50561	1.12430	.09411	11.94631	2.10865	.23900	8.82296	2.78324	.40567	6.86088		

0 DFLAP= .00 DFLAP= 15.00 DFLAP= 40.00
 0 CLMAX= 1.12430 CLMAX= 2.11925 CLMAX= 2.78324

0 LOW SPEED AERO FOR OTHER FLAP DEPLECTIONS

FLAP DEFL.	CLMAX	CL	CD	L/D
10.000	1.81051	.65415	.05871	11.14144
		.82539	.06843	12.06232
		.99663	.08150	12.22905
		1.16787	.09867	11.83605
		1.33911	.12144	11.02722
		1.51035	.14760	10.23242
		1.68159	.17663	9.52031
		1.81051	.20037	9.03576
		1.81051	.20037	9.03576
		1.81051	.20037	9.03576
20.000	2.31932	1.16296	.10068	11.55109
		1.33420	.11431	11.67153
		1.50544	.13201	11.40379
		1.67668	.15561	10.77475
		1.84792	.18242	10.12982
		2.01917	.21216	9.51741
		2.19041	.24480	8.94757
		2.31932	.27131	8.54862
		2.31932	.27131	8.54862
		2.31932	.27131	8.54862
30.000	2.61862	1.46226	.14838	9.85464
		1.63350	.16353	9.98925
		1.80474	.18305	9.85937
		1.97598	.20837	9.48326
		2.14723	.23671	9.07110
		2.31847	.26808	8.64829
		2.48971	.30249	8.23085
		2.61862	.33038	7.92608
		2.61862	.33038	7.92608
		2.61862	.33038	7.92608

0 ALTITUDE= 35000. FT TAS= 462.24 KTS MACH NO= .8010

0 RDT&E AND AIRFRAME PRODUCTION COSTS

(1993. DOLLARS)

TOTAL RDT&E COSTS 1009.2150 MILLION

AIRFRAME PRODUCTION COSTS (INCLUDING 10% PROFIT)

500. AIRCRAFT

	WEIGHT (LB)	COST (\$)	COST (\$/LB)
STRUCTURE(4109540.\$)			
WING	4415.	1104832.	250.26
CANARD	424.	183527.	433.06
EMPENNAGE	867.	333989.	385.36
FUSELAGE	5991.	1662262.	277.45
LANDING GEAR	1694.	302217.	178.42
NACELLES	948.	522713.	551.56
PROPULSION INSTAL(162710.\$)			
ENGINE INSTALLAT.	382.	139067.	364.08
FUEL SYSTEM	167.	23642.	141.74
SYSTEMS(2548004.\$)			
FLIGHT CONTROLS	904.	424255.	469.41
HYDRAULIC	361.	45018.	124.57
ELECTRICAL	970.	464214.	478.57
AIR CONDITIONING	478.	256070.	535.82
ANTI-ICING	205.	108021.	526.66
AUX. POWER UNIT	372.	207143.	556.42
FURNISHINGS	3410.	796443.	233.56
INSTRUMENTS	233.	193137.	829.44
AVIONICS INSTALL.	250.	49032.	196.13
AUX. ITEMS	20.	4671.	233.56
INTEGRATION(1705064.\$)			
AIRFRAME TOTALS	22090.	8525318.	385.93
ENGINES		2615686.	
PROPELLER		0.	
AVIONICS		4000000.	
A/C COST(NO RD)		15141004.	
R&D PER A/C		2018430.	
TOTAL A/C COST		17159434.	

0 ENGINES NUMBER = 2. TYPE = 7

0 EMPTY WEIGHT= 25170. AIRFRAME WEIGHT= 22340. WEIGHT OF 1 ENGINE= 1415. CRUISE SPEED= 462. KTS

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
 - GASP solution (continued)

0 THRUST/ENGINE= 8842. AIRFRAME COST= 14543748. COST OF 1 ENGINE= 1307843. COST OF 1 PROP.= 0.
 0 TOTAL AIRCRAFT COST= 17159434.

```

0          --- COST DATA ---
0          GASP SHORThAUL METHOD
0          DESIGN MISSION
0          OPERATING COST FOR NOR.RATED POWER AND 35000. ALTITUDE
0          *****
0          RANGE= 1239. N.M.      BLOCK FUEL= 6658. LBS      BLOCK TIME= 3.0315 HRS.
0          UTILIZATION      3200.
0          FLYING OPERATIONS
0          FLIGHT CREW      378.932
0          FUEL,OIL,AND TAXES( .850$/G)      884.361
0          INSURANCE      81.278
0          DIRECT MAINTENANCE
0          AIRFRAME      170.286
0          ENGINE      286.822
0          MAINTENANCE BURD.      373.355
0          DEPRECIATION      1092.378
0
0          TOTAL DOC ($/TRIP)      3267.413
0          ($/B.HR.)      1077.837
0          ($/N.MI.)      2.637
  
```

Fig E15 - Three-Lifting Surface Configuration optimised for minimum M.T.O.W.
 - GASP solution (concluded)

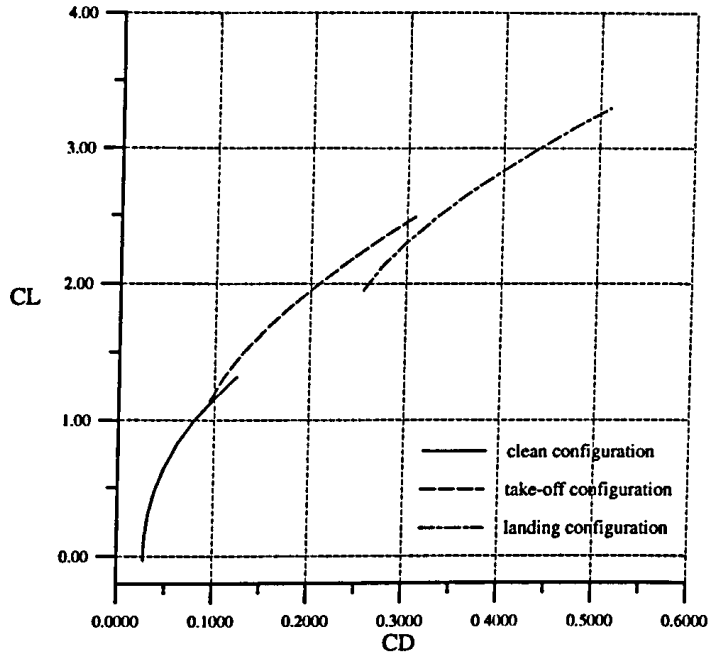


Fig E16.1 - Minimum D.O.C. Conventional concept low speed drag polars

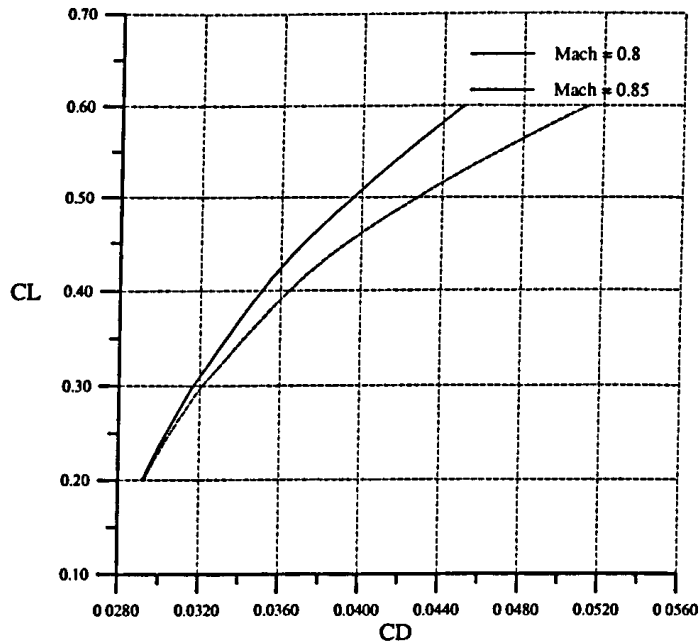


Fig E16.2 - Minimum D.O.C. Conventional concept Cruise drag polar

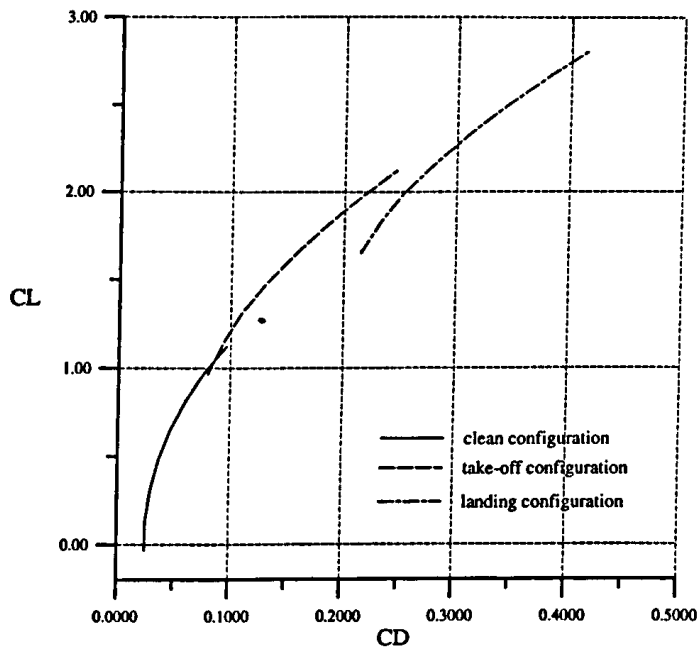


Fig E17.1 - Minimum D.O.C. Three-lifting Surface concept low speed drag polars

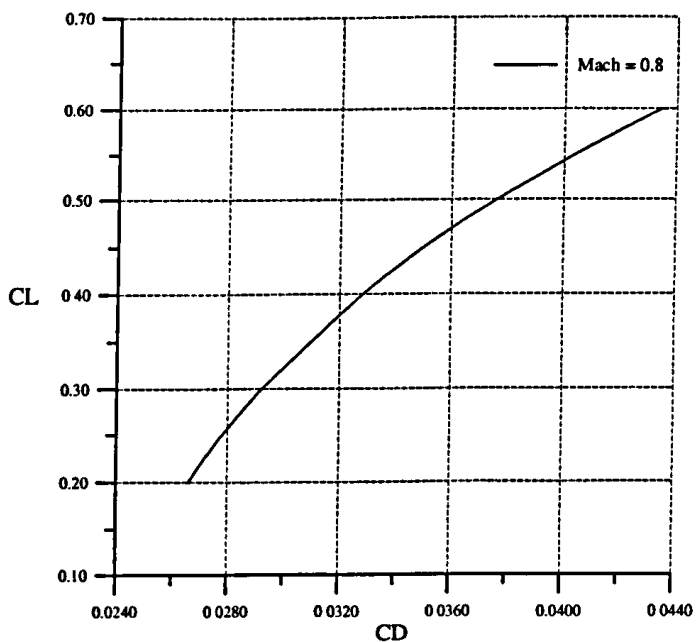


Fig E17.2 - Minimum D.O.C. Three-lifting Surface concept Cruise drag polar

APPENDIX F

Optimisation Convergence Histories

Introduction

Design optimisation was performed using the RAE Recursive Quadratic Programming Minimization (RQPMIN) numerical technique. This Appendix illustrates the convergence histories of the problem functions and design variables for the direct operating costs optimisation cases (first solutions) performed on both configurations. The behaviour of RQPMIN-GASP is represented in figures F1 and F2, respectively for the conventional and the three-surface optimum designs. An analysis of these historical diagrams was done in section 5.4 where some explanation on the reasons leading to its peculiar behaviour was given, as well as suggestions for improvement.

In complement to the discussion given in section 5.4, an additional comment is herein given. It is seen on fig F1 a very sharp jump at about iteration number 82. This reflects the very irregular nature of the multidimensional design surface topology. This jump means that a preferential feasible path to minimize the objective function was located at a particular design point (corresponding to this iteration). As shown, this path effectively headed the search on the right direction, toward the local minimum convergence point obtained at the end.

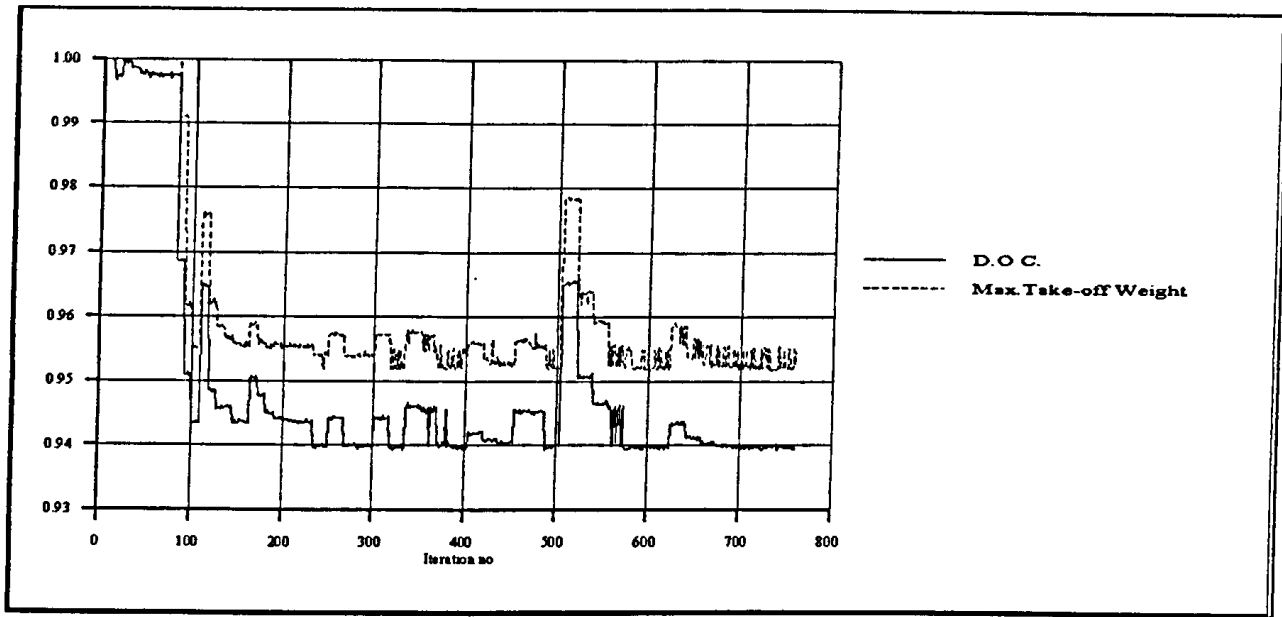


Fig F1.1 - History of the Objective Function (D.O.C) and Maximum Take-off Weight

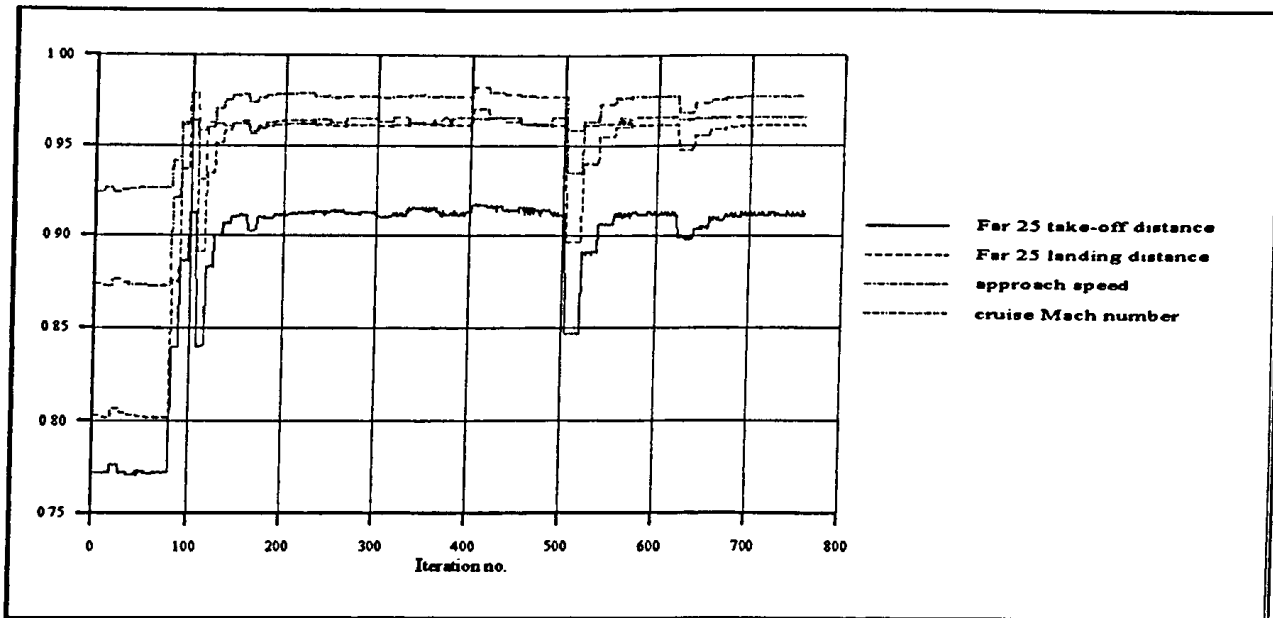


Fig F1.2 - History of the Constraint Functions

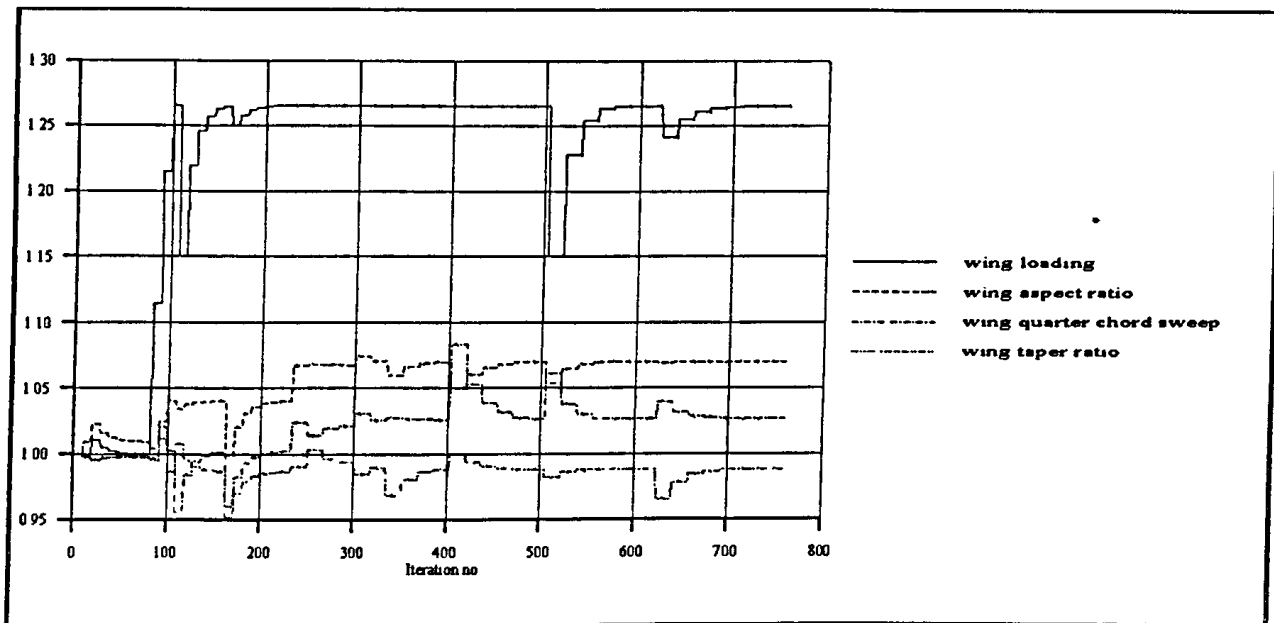


Fig F1.3 - History of the Wing design variables

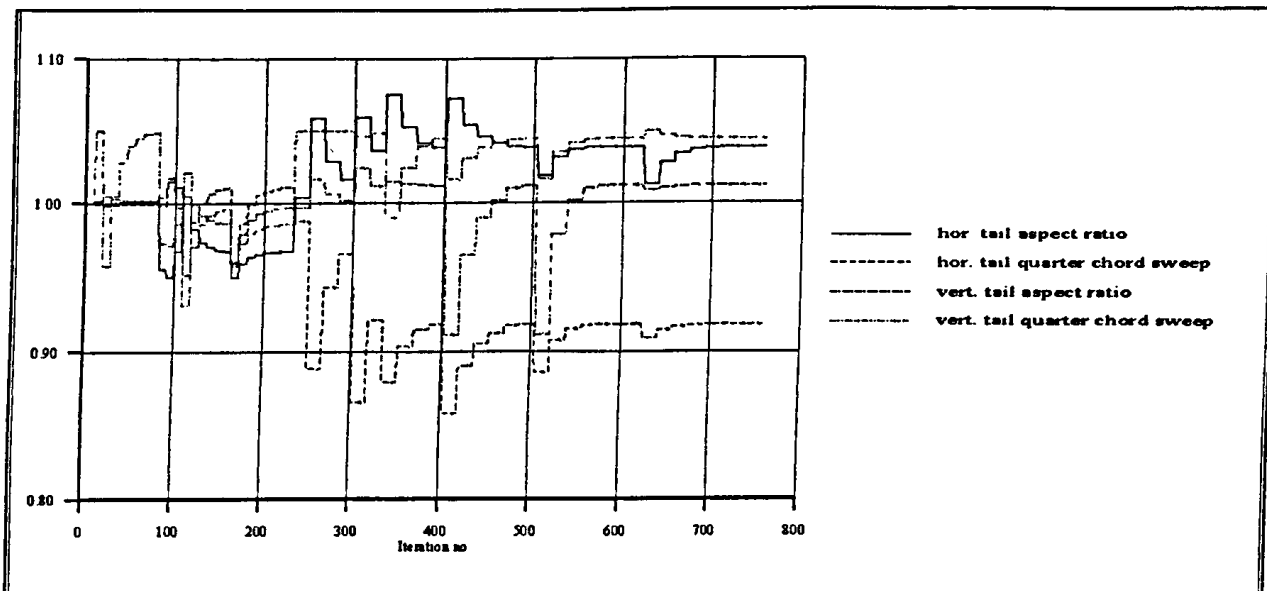


Fig F1.4 - History of the tail design variables

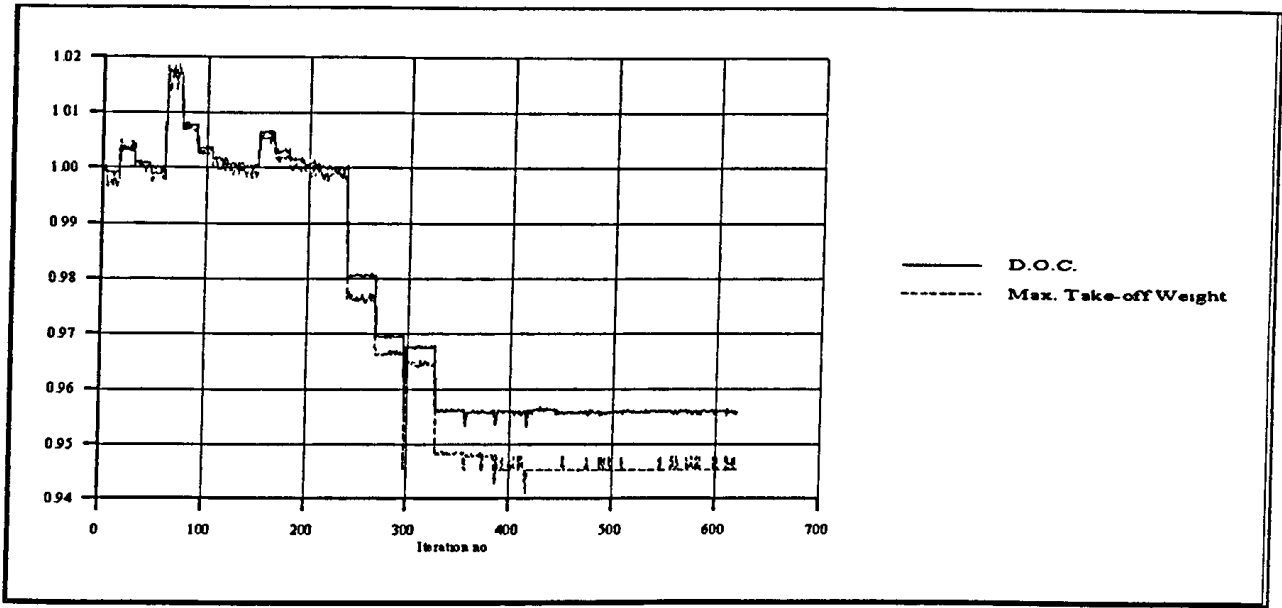


Fig F2.1 - History of the Objective Function (D.O.C.) and Maximum Take-off Weight

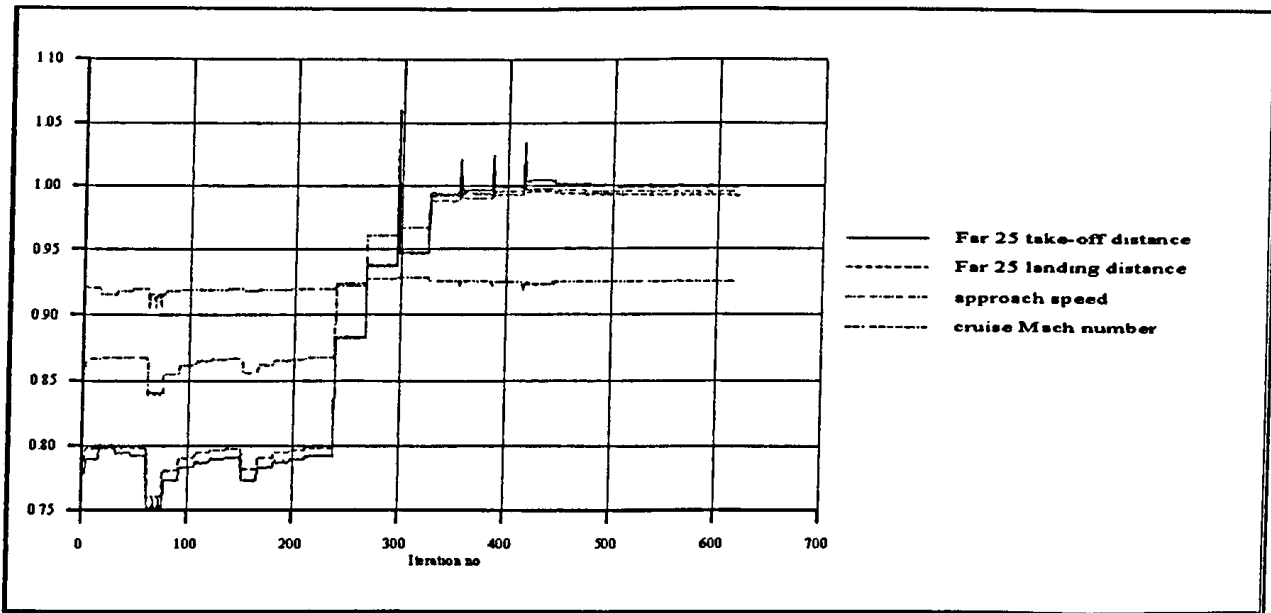


Fig F2.2 - History of the Constraint Functions

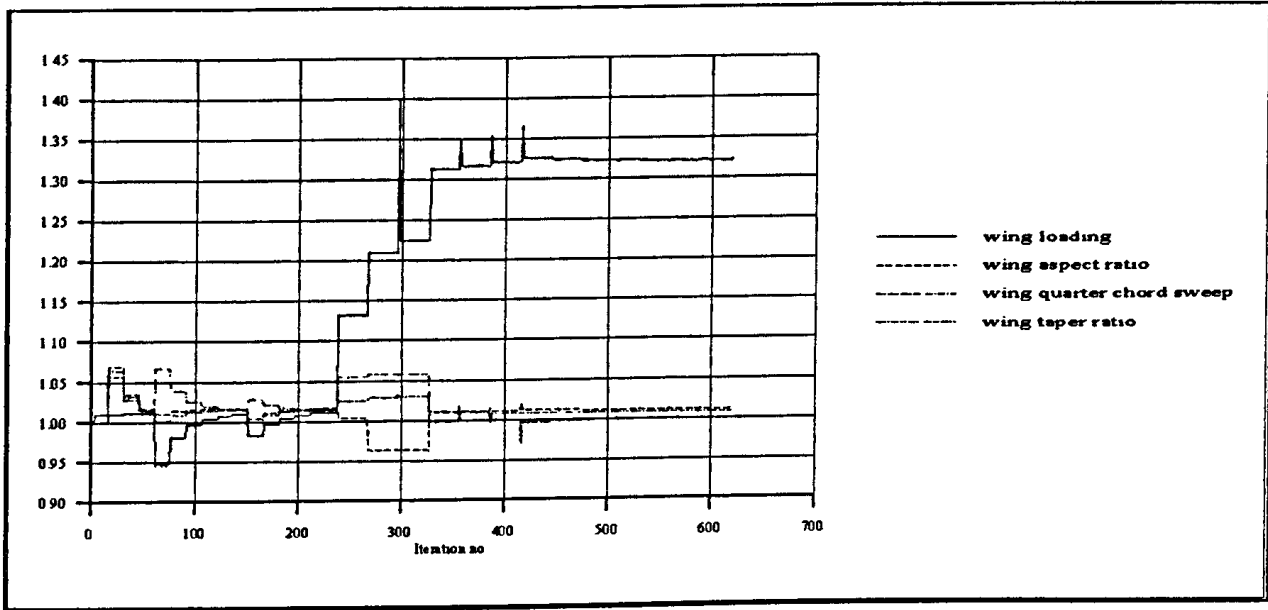


Fig F2.3 - History of the Wing design variables

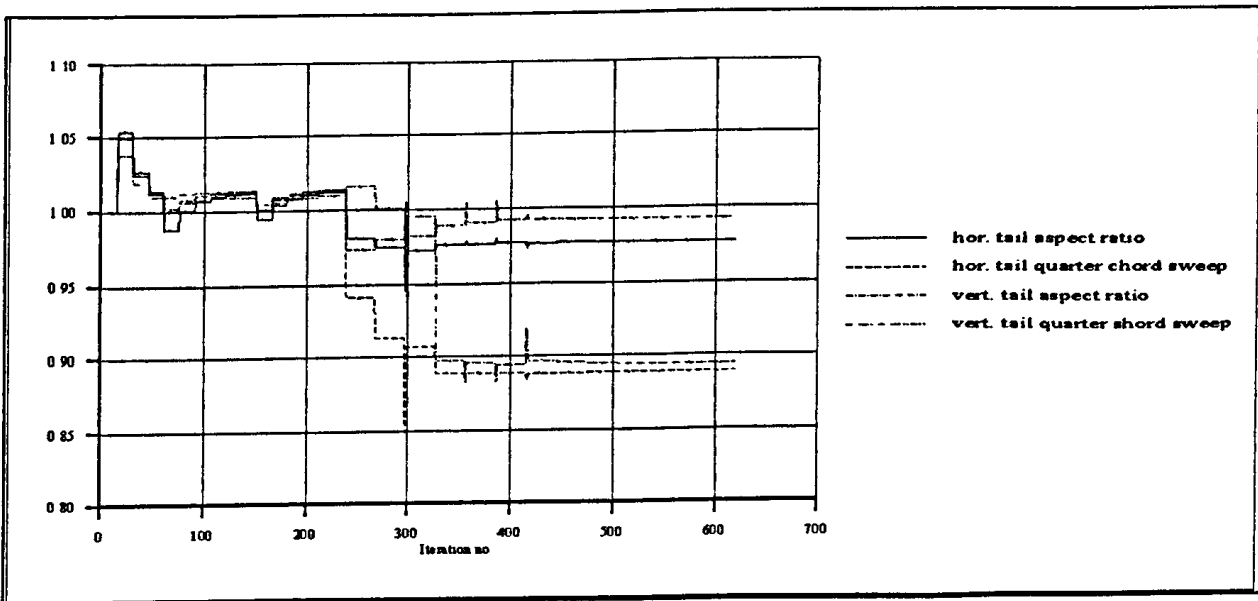


Fig F2.4 - History of the Tail design variables

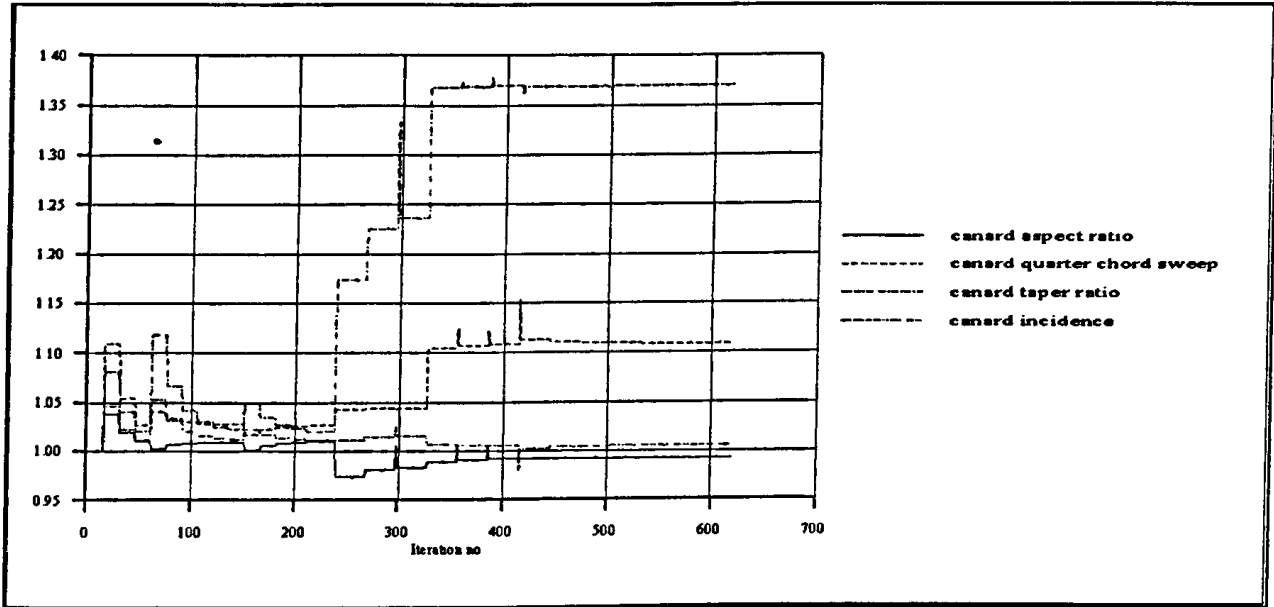


Fig F2.5 - History of the Canard design variables

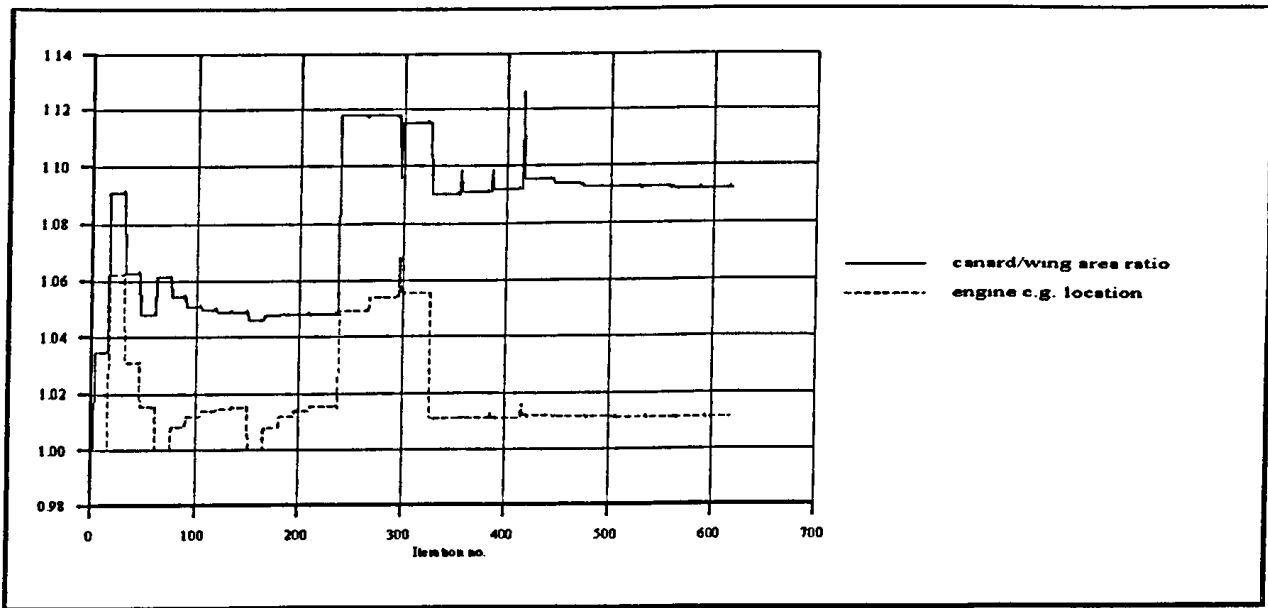


Fig F2.6 - History of the Miscellaneous design variables

APPENDIX G

Conventional Concept Drag and Handling Qualities Evaluation

Introduction

In this Appendix, the low speed and high speed drag polars for the baseline and the minimum DOC conventional aircraft configurations, as obtained by GASP aerodynamic module, are compared with those obtained using the DELTADD program. Analysis of the dynamic stability and control of these conventional designs is also performed using the revised MITCHELL program.

G.1 Conventional-Concept Drag Estimation

Aerodynamic drag estimates were performed on the baseline and D.O.C. optimum aft-tail designs using the CoA DELTADD program to check the drag polar predictions computed by the GASP aerodynamic module during the design synthesis runs. As referred to in Chapter 3, the former program is based on the Lockheed Delta empirical drag build-up technique^{G1} and is claimed to give good results within sufficient accuracy for the initial processes of preliminary design.

The original Delta method was most applicable near the cruise flight conditions and was not appropriate for performance analysis near maximum lift coefficients. However, this restriction was overcome by Professor Howe in the College of Aeronautics who included the effects of high lift devices and undercarriage in the later version of the program allowing for the prediction of the low speed aerodynamic characteristics.

Figures G1 and G2 present the DELTADD results for both designs, including cruise flight and flight at low speeds for clean wing, take-off and landing configurations.

Assuming an additional correction of about 33 drag counts on the zero-lift drag coefficient, DELTADD estimates a drag polar that almost overlaps that obtained by GASP for the useful range of cruise lift coefficients of the baseline concept, as shown on fig G3. Regarding the D.O.C. optimum solution, GASP seems to overestimate the drag coefficient in about 20 drag counts. Figures G4 and G5 show the GASP obtained low speed drag polars together with DELTADD point performance estimates which remarkably lie very closely on the curves. Additional work could be done on the DELTADD flap input details in order to increase the take-off and landing lift coefficients required by the designs.

Concluding Remarks

For the initial preliminary design purposes and with limited knowledge of the aircraft geometric parameters and design details, the agreement obtained on these curves can be considered fairly good. Therefore, GASP aerodynamic results are assumed correct within the degree of accuracy usually expected during this initial design phase.

G.2 Conventional-Concept Handling Qualities Evaluation

GASP program is able to select the tail surface areas and volume coefficients to comply with a given set of important static trim and stability conditions as reported in Chapter 3. This capability will ensure satisfactory handling on most conventional designs but minor configuration changes or the use of some kind of stability augmentation system may be required. The prediction of the dynamic stability of the aircraft and the responses to control inputs is usually done on a later stage in the design process because it requires considerable effort and specialised knowledge and experience. However, an early assessment of the aircraft handling qualities is wellcome in providing greater confidence to the designer.

This will be illustrated in the present appendix by using MITCHELL program^{G2,G3}, already introduced in Chapter 3. Using information available early in the design process such as aircraft geometry, weight, propulsion and flight conditions the program predicts the aerodynamic stability and control derivatives, estimates the aircraft moments of inertia, calculates the characteristics of the longitudinal and lateral stick-fixed modes, predicts the responses to certain disturbances at the specified flight condition and calculates the limiting speeds for low-speed flight at sea level assuming the aircraft as a rigid body.

Time shortage didn't allow appropriate changes to be included in the program in order to simulate the stability and control characteristics of a three-lifting surface aircraft, thus only the results obtained for the conventional designs are shown (both for the baseline and D.O.C. optimised solutions, figures G6 and G7 respectively). These results were produced with respect to the initial cruise flight condition using GASP geometry, weight and performance data as input, together with a slight adjustment on the aircraft C.G. location to maintain the desired cruise stability static margin of 10% MAC. In spite of the aircraft model simplifications, the program gives reasonably accurate answers^{G2}, so due credibility is given to the predictions made.

A brief analysis of the longitudinal and lateral-directional stick-fixed modes is performed based on the results obtained for the conventional baseline concept which is compared to the military analytical specifications set out in the MIL-F-8785 C^{G4}. This reflects current practice since the civil airworthiness regulations do not generally provide any analytical performance criteria for the dynamic behaviour of piloted aircraft.

The military specification defines aircraft classes, flight phases and flying quality levels, specifying different modes so that different combinations can be assessed. The flying quality levels are related to the Cooper-Harper^{G5} pilot opinion rating scale. The transport under study can be classified as a Class II aircraft and the particular flight condition analysed corresponds to flight phase Category B.

Longitudinal modes

Phugoid

MIL specification^{G4} dictates that for level 1 flying qualities the damping ratio of the phugoid mode shall be at least $\zeta_p=0.04$. Figure G6 states for the conventional baseline concept a phugoid oscillation damping ratio of $\zeta_p=0.061$ which meets the desired level.

Short-Period

Ref G4 sets limits on the short-period equivalent undamped natural frequency, ω_n and on the equivalent damping ratio, ζ_{sp} , respectively on Figure B2 and Table IV. For the particular flight condition (Cat. B), fig G6 gives $\omega_n = 1.821 \text{ rad sec}^{-1}$, $\zeta_{sp} = 0.722$ and the load-factor response to angle of attack, $n/\alpha = 0.378 \text{ g deg}^{-1}$.

For level 1 flying qualities Fig B2 (MIL) requires $\omega_n^2/(n/\alpha) \in [0.085, 3.6]$. Computing for the specific aircraft, this parameter reads $\omega_n^2/(n/\alpha) = 0.153 \text{ rad}^3\text{sec}^{-2}\text{g}^{-1}$ which satisfies the specification. The same conclusion is found for the equivalent damping ratio, ζ_{sp} which falls within Table IV (MIL) requirements, where $\zeta_{sp} \in [0.30, 2.00]$, for the same flying qualities level.

Lateral-directional modes

Dutch Roll

Ref G4 states that the undamped frequency, ω_{nd} and the damping ratio, ζ_d of the Dutch roll mode following a yaw disturbance shall exceed the minimum values of Table VI. For level 1 and Cat B phase, these figures are respectively $\omega_{nd} = 0.4 \text{ rad sec}^{-1}$ and $\zeta_d = 0.08$, while the results for the tail-aft baseline aircraft as shown in figure G6 reads respectively $\omega_{nd} = 1.721 \text{ rad sec}^{-1}$ and $\zeta_d = 0.068$. The latter suggests that the oscillation is very poorly damped which would make landing in gusty wind difficult to the pilot and a very uncomfortable flight in turbulence for passengers sitting near the tail. The addition of a convenient stability augmentation system or simply a yaw-damper, as is usually done on jet-transport aircraft, would improve this lateral-directional oscillation mode.

Roll Subsidence

Table VII (MIL) establishes maximum roll mode time constant values. For flight Cat B and level 1, this value is $T_r = 1.4 \text{ sec}$ which is well above the time constant shown in fig G6 for the study aircraft, $T_r = 0.393 \text{ sec}$. This value also suggests a fast roll response.

Spiral Stability

The spiral mode is allowed to be unstable, so limits are placed on the minimum time for the bank angle to double, following a disturbance in bank of up to 20 degrees from trimmed, wings-level, zero-yaw-rate flight with cockpit controls free. These limits are shown on Table VIII (MIL) and to satisfy level 1 handling it shall be $T_{2s} = 20 \text{ sec}$. MITCHELL results for the case aircraft, fig G6, unveils a stable exponential spiral mode with a very long time constant of $T_s = 185.5 \text{ sec}$ which will be in favour.

Concluding Remarks

MITCHELL results for the conventional baseline concept, fig G6, show two stable longitudinal oscillatory modes, the phugoid and the short-period modes, that satisfy reasonably well the military analytical specifications of the MIL-F-8785 C^{G4}. Regarding the lateral-directional modes, both the roll and the spiral modes are adequate stable subsidences, while the Dutch roll oscillation indicates some deficiency in damping ratio which can be corrected with the addition of a convenient yaw-damper. Analysis of the results regarding the stability and control dynamics of the D.O.C. optimised conventional design, as presented in fig G7, would qualitatively lead to similar conclusions, but in this particular case, the dutch roll mode would require more yaw-damping compensation.

References:

- G1. Feagin,R.C.;Morrison,W.D.,Jr.
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Final Report, Lockheed-California Co., Burbank, Dec 1978
- G2. Mitchell,C.G.B.
A Computer Program to Predict the Stability and Control Characteristics of Subsonic Aircraft
RAE TR no. 73079, Sept 1973
- G3. Theophilou,M.K.
Development of Computer Programs for Initial Project Design of Combat Aircraft
M.Sc. Thesis, CIT, Sept 1983
- G4. Anon.
MIL-F-8785C- U. S. DoD Military Specification: Flying Qualities of Piloted Airplanes
Nov. 1980
- G5. Cooper,G.E.;Harper,R.P.,Jr.
The Use of Pilot Rating in the Evaluation of Aircraft Handling Qualities
NASA, TN D-5153, Washington, D.C.,1969

** DELTADD DRAG ESTIMATE - VERSION 4.42 **

- INPUT DATA -

TITLE : conv_bl

DATA VERSION : 3.32

GENERAL :

INPUT DATA UNITS [0=imperial 1=metric]	0
OUTPUT TYPE [1=report 2=detailed]	1
TEMP DIFF FROM ISA CONDITIONS [C]	20.0
ADDITIONAL ZERO LIFT DRAG COEFFICIENT	-1.000

WING :

AEROFOIL TYPE [1=conventional 2=advanced]	2
SPAN [m or ft]	69.190
AREA [m2 or ft2]	576.783
WETTED AREA [m2 or ft2]	910.280
MEAN AERO. CHORD [m or ft]	9.571
ASPECT RATIO	8.300
C/4 SWEEP	14.5
LE SWEEP	18.7
TAPER RATIO	.200
t/c [ratio]	.115
CAMBER [100{z(u)-z(1)}/2c @ 70% semi-span]	.000

FUSELAGE :

LENGTH [m or ft]	79.250
HEIGHT [m or ft]	9.250
WIDTH [m or ft]	9.250
BASE AREA [m2 or ft2]	.795
MAX XSECT AREA EXCLUDING INLETS [m2 or ft2]	67.200
WETTED AREA [m2 or ft2]	1910.380

TAILPLANE :

MAC [m or ft]	8.247
WETTED AREA [m2 or ft2]	540.590
t/c [ratio]	.100

FIN :

MAC [m or ft]	11.156
WETTED AREA [m2 or ft2]	243.810
t/c [ratio]	.120

NACELLES AND PYLONS :

NUMBER	2
LENGTH [m or ft]	11.960
WETTED AREA - SINGLE NACELLE [m2 or ft2]	149.920
- SINGLE PYLON [m2 or ft2]	36.000

Fig. G1 - Conventional Baseline Concept Drag Estimate
Deltadd Output file

EXTRA DRAG DATA :

flap type [0=split 1=slotted or fowler]	1
flap chord/wing chord ratio - 1	.060
..... - 2	.240
..... - 3	.000
flap outer end semi-span (ratio)	.884
flap inner end semi-span (ratio)	.134
number of piston engines	0
max design all-up mass	47873.0
max design diving speed [Mach no.]	.900
max lift coefficient - CLMAX	1.200
miscellaneous additional coefficient	.003

**Fig. G1 - Conventional Baseline Concept Drag Estimate
Deltadd Output file (continued)**

CASE DATA :

CASE No.	MACH No.	ALTITUDE m or ft			AIRCRAFT MASS Kg or lb
1	.80	35000.0			46442.0
2	.25	5000.0			47648.0
3	.20	5000.0			47680.0
4	.17	5000.0			45001.0

CASE No.	UNDERCARRIAGE		FLAP DEFLNS deg			FLAP EXTN ratio
	0=up	1=down	-1-	-2-	-3-	
1	0.		.0	.0	.0	1.00
2	0.		.0	.0	.0	1.00
3	0.		7.5	15.0	.0	1.29
4	0.		20.0	40.0	.0	1.24

Fig. G1 - Conventional Baseline Concept Drag Estimate
Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_bl

CASE 1 OF 4

FREE STREAM MACH No. = .80
 ALTITUDE = 10668.0 m
 AIRCRAFT MASS = 21076.8 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = .0 deg
 -2- = .0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.00
 TRUE AIRSPEED = 250.5 m/s
 AIR TEMPERATURE = 243.9 K
 AIR DENSITY = .384 Kg/m3
 UNIT REYNOLDS NO. = 6.138E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 CDF = .0190 Landing gear CDADDL = .0000
 CDC = .0015 Flaps zero lift . CDADDF = .0000
 CDADD = .0033 Engine cooling .. CDADDC = .0000
 CDMIN = .0237 Stores CDADDS = .0000
 Misc. extra..... CDADDX = .0033

OVERALL DRAG POLAR : CD = .0237 + .0500 CL²

CL	CD
.1240	.0251
.2240	.0259
.3240	.0285
.4240	.0322
.4740	.0344
.5240	.0375
.5740	.0409
.6240	.0447
.7240	.0549
.8240	.0680

Flap lift coefficient increment = .0000
 FLAP PRESSURE DRAG COEFFICIENT = .0000 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .0284
 CASE CL = .3199
 BUFFET ONSET CL = .6326
 DESIGN CL = .5240
 DRAG RISE MACH No. = .8166
 CASE DRAG FORCE = 18.5 KN

Fig. G1 - Conventional Baseline Concept Drag Estimate
 Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_bl

CASE 2 OF 4

FREE STREAM MACH No. = .25
 ALTITUDE = 1524.0 m
 AIRCRAFT MASS = 21624.2 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = .0 deg
 -2- = .0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.00
 TRUE AIRSPEED = 86.7 m/s
 AIR TEMPERATURE = 298.9 K
 AIR DENSITY = .995 Kg/m3
 UNIT REYNOLDS NO. = 4.684E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 Landing gear CDADDL = .0000
 Flaps zero lift . CDADDF = .0000
 Engine cooling .. CDADDC = .0000
 Stores CDADDS = .0000
 Misc. extra CDADDX = .0033
 CDF = .0206
 CDC = .0015
 CDADD = .0033
 CDMIN = .0253

OVERALL DRAG POLAR : $CD = .0253 + .0480 CL^2$

CL	CD
.1240	.0264
.2240	.0274
.3240	.0299
.4240	.0336
.4740	.0356
.5240	.0385
.5740	.0423
.6240	.0456
.7240	.0551
.8240	.0689

Flap lift coefficient increment = .0000
 FLAP PRESSURE DRAG COEFFICIENT = .0000 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .0858
 CASE CL = 1.0584
 BUFFET ONSET CL = 1.1812
 DESIGN CL = .5240
 DRAG RISE MACH No. = .8166
 CASE DRAG FORCE = 17.3 KN

Fig. G1 - Conventional Baseline Concept Drag Estimate
 Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_bl

CASE 3 OF 4

FREE STREAM MACH No. = .20
 ALTITUDE = 1524.0 m
 AIRCRAFT MASS = 21638.7 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = 7.5 deg
 -2- = 15.0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.29
 TRUE AIRSPEED = 69.3 m/s
 AIR TEMPERATURE = 298.9 K
 AIR DENSITY = .995 Kg/m3
 UNIT REYNOLDS NO. = 3.747E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 Landing gear CDADDL = .0000
 CDF = .0214 Flaps zero lift . CDADDF = .0028
 CDC = .0015 Engine cooling .. CDADDC = .0000
 CDADD = .0060 Stores CDADDS = .0000
 CDMIN = .0289 Misc. extra CDADDX = .0033

OVERALL DRAG POLAR : CD = .0289 + .0000 CL²

CL	CD
.1240	.0300
.2240	.0310
.3240	.0335
.4240	.0371
.4740	.0392
.5240	.0421
.5740	.0459
.6240	.0491
.7240	.0586
.8240	.0724

Flap lift coefficient increment = .9240
 FLAP PRESSURE DRAG COEFFICIENT = .0111 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .1625
 CASE CL = 1.6549
 BUFFET ONSET CL = 1.1927
 DESIGN CL = .5240
 DRAG RISE MACH No. = .8166
 CASE DRAG FORCE = 21.0 KN

Fig. G1 - Conventional Baseline Concept Drag Estimate
 Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_bl

CASE 4 OF 4

FREE STREAM MACH No. = .17
 ALTITUDE = 1524.0 m
 AIRCRAFT MASS = 20422.9 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = 20.0 deg
 -2- = 40.0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.24
 TRUE AIRSPEED = 57.6 m/s
 AIR TEMPERATURE = 298.9 K
 AIR DENSITY = .995 Kg/m3
 UNIT REYNOLDS NO. = 3.110E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 CDF = .0221 Landing gear CDADDL = .0000
 CDC = .0015 Flaps zero lift . CDADDF = .0178
 CDADD = .0210 Engine cooling .. CDADDC = .0000
 CDMIN = .0446 Stores CDADDS = .0000
 Misc. extra CDADDX = .0033

OVERALL DRAG POLAR : CD = .0446 + .0000 CL2

CL	CD
.1240	.0457
.2240	.0467
.3240	.0491
.4240	.0528
.4740	.0548
.5240	.0578
.5740	.0616
.6240	.0648
.7240	.0743
.8240	.0881

Flap lift coefficient increment =1.3352

FLAP PRESSURE DRAG COEFFICIENT = .0232 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .2824
 CASE CL = 2.2672
 BUFFET ONSET CL = 1.1927
 DESIGN CL = .5240
 DRAG RISE MACH No. = .8166
 CASE DRAG FORCE = 25.1 KN

Fig. G1 - Conventional Baseline Concept Drag Estimate
 Deltadd Output file (concluded)

- INPUT DATA -

TITLE :	conv_doc	DATA VERSION :	3.32
GENERAL :			
INPUT DATA UNITS [0=imperial 1=metric]			0
OUTPUT TYPE [1=report 2=detailed]			1
TEMP DIFF FROM ISA CONDITIONS [C]			20.0
ADDITIONAL ZERO LIFT DRAG COEFFICIENT			-1.000
WING :			
AEROFOIL TYPE [1=conventional 2=advanced]			2
SPAN [m or ft]			62.171
AREA [m2 or ft2]			435.303
WETTED AREA [m2 or ft2]			667.210
MEAN AERO. CHORD [m or ft]			8.049
ASPECT RATIO			8.879
C/4 SWEEP			14.9
LE SWEEP			18.8
TAPER RATIO			.198
t/c [ratio]			.115
CAMBER [100{z(u)-z(1)}/2c @ 70% semi-span]			.000
FUSELAGE :			
LENGTH [m or ft]			79.250
HEIGHT [m or ft]			9.250
WIDTH [m or ft]			9.250
BASE AREA [m2 or ft2]			.795
MAX XSECT AREA EXCLUDING INLETS [m2 or ft2]			67.200
WETTED AREA [m2 or ft2]			1910.380
TAILPLANE :			
MAC [m or ft]			6.312
WETTED AREA [m2 or ft2]			330.120
t/c [ratio]			.100
FIN :			
MAC [m or ft]			10.034
WETTED AREA [m2 or ft2]			199.550
t/c [ratio]			.120
NACELLES AND PYLONS :			
NUMBER			2
LENGTH [m or ft]			11.860
WETTED AREA - SINGLE NACELLE [m2 or ft2]			147.105
- SINGLE PYLON [m2 or ft2]			36.000

Fig. G2 - Conventional D.O.C. optimised Concept Drag Estimate
Deltadd Output file

EXTRA DRAG DATA :

flap type [0=split 1=slotted or fowler]	1
flap chord/wing chord ratio - 1	.060
..... - 2	.240
..... - 3	.000
flap outer end semi-span (ratio)	.899
flap inner end semi-span (ratio)	.149
number of piston engines	0
max design all-up mass	45707.0
max design diving speed [Mach no.]	.900
max lift coefficient - CLMAX	1.200
miscellaneous additional coefficient	.003

Fig. G2 - Conventional D.O.C. Optimised Concept Drag Estimate
Deltadd Output file (continued)

CASE DATA :

CASE No.	MACH No.	ALTITUDE			AIRCRAFT MASS
		m or ft			Kg or lb
1	.80	35000.0			44315.0
2	.27	5000.0			45482.0
3	.22	5000.0			45512.0
4	.19	5000.0			42964.0

CASE No.	UNDERCARRIAGE		FLAP DEFLNS deg			FLAP EXTN ratio
	0=up	1=down	-1-	-2-	-3-	
1	0.		.0	.0	.0	1.00
2	0.		.0	.0	.0	1.00
3	0.		7.5	15.0	.0	1.29
4	0.		20.0	40.0	.0	1.24

Fig. G2 - Conventional D.O.C. Optimised Concept Drag Estimate
Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_doc

CASE 1 OF 4

FREE STREAM MACH No. = .80
 ALTITUDE = 10668.0 m
 AIRCRAFT MASS = 20111.5 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = .0 deg
 -2- = .0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.00
 TRUE AIRSPEED = 250.5 m/s
 AIR TEMPERATURE = 243.9 K
 AIR DENSITY = .384 Kg/m3
 UNIT REYNOLDS NO. = 6.138E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 Landing gear CDADDL = .0000
 Flaps zero lift . CDADDF = .0000
 Engine cooling .. CDADDC = .0000
 Stores CDADDS = .0000
 Misc. extra CDADDX = .0033
 CDF = .0213
 CDC = .0016
 CDADD = .0033
 CDMIN = .0261

OVERALL DRAG POLAR : CD = .0261 + .0461 CL²

CL	CD
.1403	.0275
.2403	.0283
.3403	.0310
.4403	.0345
.4903	.0366
.5403	.0395
.5903	.0429
.6403	.0466
.7403	.0566
.8403	.0697

Flap lift coefficient increment = .0000
 FLAP PRESSURE DRAG COEFFICIENT = .0000 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .0332
 CASE CL = .4045
 BUFFET ONSET CL = .6550
 DESIGN CL = .5403
 DRAG RISE MACH No. = .8149
 CASE DRAG FORCE = 16.3 KN

Fig. G2 - Conventional D.O.C. Optimised Concept Drag Estimate
 Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_doc

CASE 2 OF 4

FREE STREAM MACH No. = .27
 ALTITUDE = 1524.0 m
 AIRCRAFT MASS = 20641.2 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = .0 deg
 -2- = .0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.00
 TRUE AIRSPEED = 93.6 m/s
 AIR TEMPERATURE = 298.9 K
 AIR DENSITY = .995 Kg/m3
 UNIT REYNOLDS NO. = 5.059E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 Landing gear CDADDL = .0000
 CDF = .0228 Flaps zero lift . CDADDF = .0000
 CDC = .0015 Engine cooling .. CDADDC = .0000
 CDADD = .0033 Stores CDADDS = .0000
 CDMIN = .0276 Misc. extra CDADDX = .0033

OVERALL DRAG POLAR : CD = .0276 + .0446 CL²

CL	CD
.1403	.0288
.2403	.0298
.3403	.0322
.4403	.0358
.4903	.0378
.5403	.0406
.5903	.0442
.6403	.0473
.7403	.0562
.8403	.0704

Flap lift coefficient increment = .0000
 FLAP PRESSURE DRAG COEFFICIENT = .0000 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .0923
 CASE CL = 1.1477
 BUFFET ONSET CL = 1.2366
 DESIGN CL = .5403
 DRAG RISE MACH No. = .8149
 CASE DRAG FORCE = 16.4 KN

Fig. G2 - Conventional D.O.C. Optimised Concept Drag Estimate
 Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_doc

CASE 3 OF 4

FREE STREAM MACH No. = .22
 ALTITUDE = 1524.0 m
 AIRCRAFT MASS = 20654.8 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = 7.5 deg
 -2- = 15.0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.29
 TRUE AIRSPEED = 76.3 m/s
 AIR TEMPERATURE = 298.9 K
 AIR DENSITY = .995 Kg/m3
 UNIT REYNOLDS NO. = 4.122E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 CDF = .0236 Landing gear CDADDL = .0000
 CDC = .0015 Flaps zero lift . CDADDF = .0028
 CDADD = .0060 Engine cooling .. CDADDC = .0000
 CDMIN = .0311 Stores CDADDS = .0000
 Misc. extra CDADDX = .0033

OVERALL DRAG POLAR : $CD = .0311 + .0000 CL^2$

CL	CD
.1403	.0323
.2403	.0333
.3403	.0357
.4403	.0393
.4903	.0413
.5403	.0441
.5903	.0477
.6403	.0508
.7403	.0597
.8403	.0739

Flap lift coefficient increment = .9479

FLAP PRESSURE DRAG COEFFICIENT = .0123 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .1681
 CASE CL = 1.7298
 BUFFET ONSET CL = 1.2550
 DESIGN CL = .5403
 DRAG RISE MACH No. = .8149
 CASE DRAG FORCE = 19.8 KN

Fig. G2 - Conventional D.O.C. Optimised Concept Drag Estimate
 Deltadd Output file (continued)

DELTADD DRAG ESTIMATE : conv_doc

CASE 4 OF 4

FREE STREAM MACH No. = .19
 ALTITUDE = 1524.0 m
 AIRCRAFT MASS = 19498.4 Kg
 UNDERCARRIAGE (0=up) = 0
 FLAP DEFLECTION -1- = 20.0 deg
 -2- = 40.0 deg
 -3- = .0 deg
 FLAP EXTENSION RATIO = 1.24
 TRUE AIRSPEED = 64.5 m/s
 AIR TEMPERATURE = 298.9 K
 AIR DENSITY = .995 Kg/m3
 UNIT REYNOLDS NO. = 3.485E+06 per m

ZERO LIFT DRAG COEFFICIENT : * Additional drag function called *
 CDF = .0243 Landing gear CDADDL = .0000
 CDC = .0015 Flaps zero lift . CDADDF = .0175
 CDADD = .0208 Engine cooling .. CDADDC = .0000
 CDMIN = .0465 Stores CDADDS = .0000
 Misc. extra CDADDX = .0033

OVERALL DRAG POLAR : CD = .0465 + .0000 CL2

CL	CD
.1403	.0478
.2403	.0488
.3403	.0512
.4403	.0548
.4903	.0567
.5403	.0596
.5903	.0632
.6403	.0663
.7403	.0752
.8403	.0894

Flap lift coefficient increment = 1.3525

FLAP PRESSURE DRAG COEFFICIENT = .0250 [NOT included in above CD values]

SPECIFIC CASE OUTPUT :

CASE CD = .2761
 CASE CL = 2.2845
 BUFFET ONSET CL = 1.2569
 DESIGN CL = .5403
 DRAG RISE MACH No. = .8149
 CASE DRAG FORCE = 23.3 KN

Fig. G2 - Conventional D.O.C. Optimised Concept Drag Estimate
 Deltadd Output file (concluded)

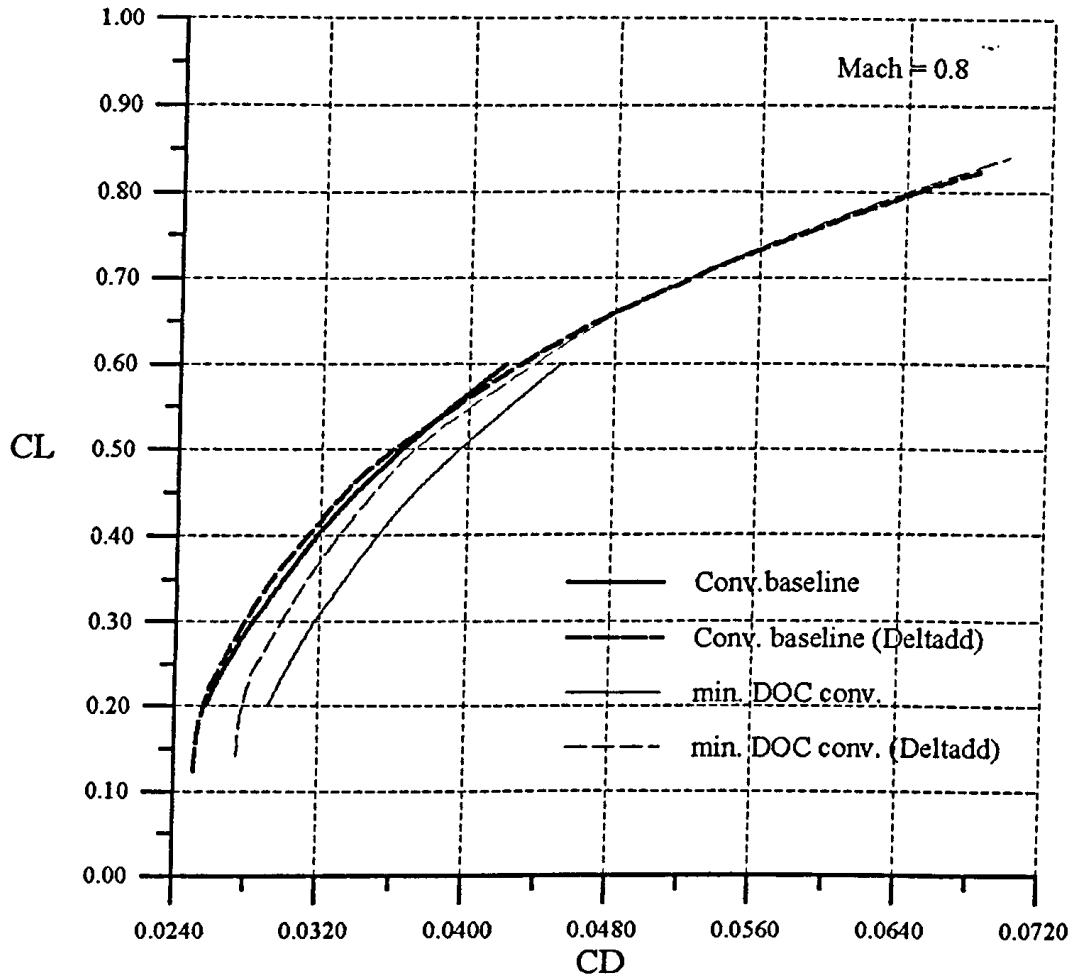


Fig. G3 - Conventional concepts cruise drag polars
(comparison with Deltadd results)

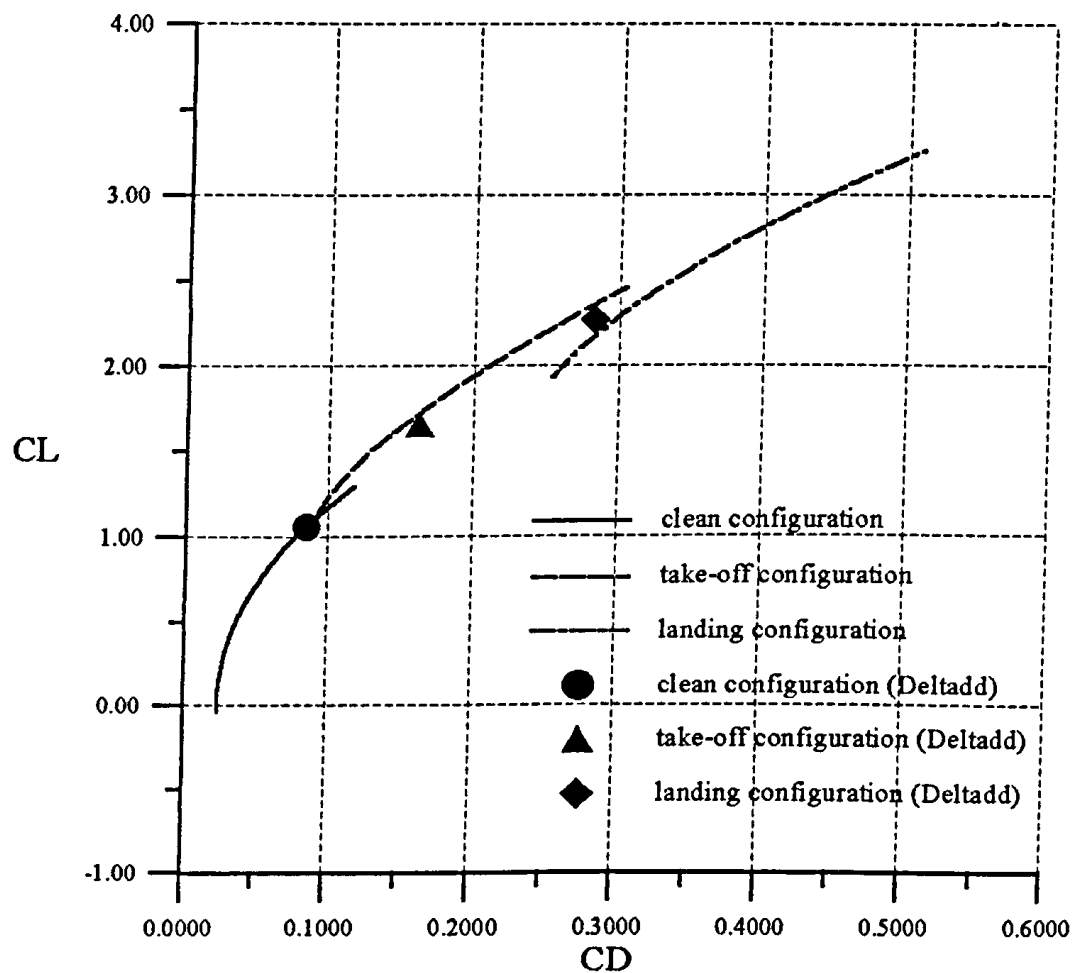


Fig. G4 - Conventional baseline concept low speed drag polars
(comparison with Deltadd case results)

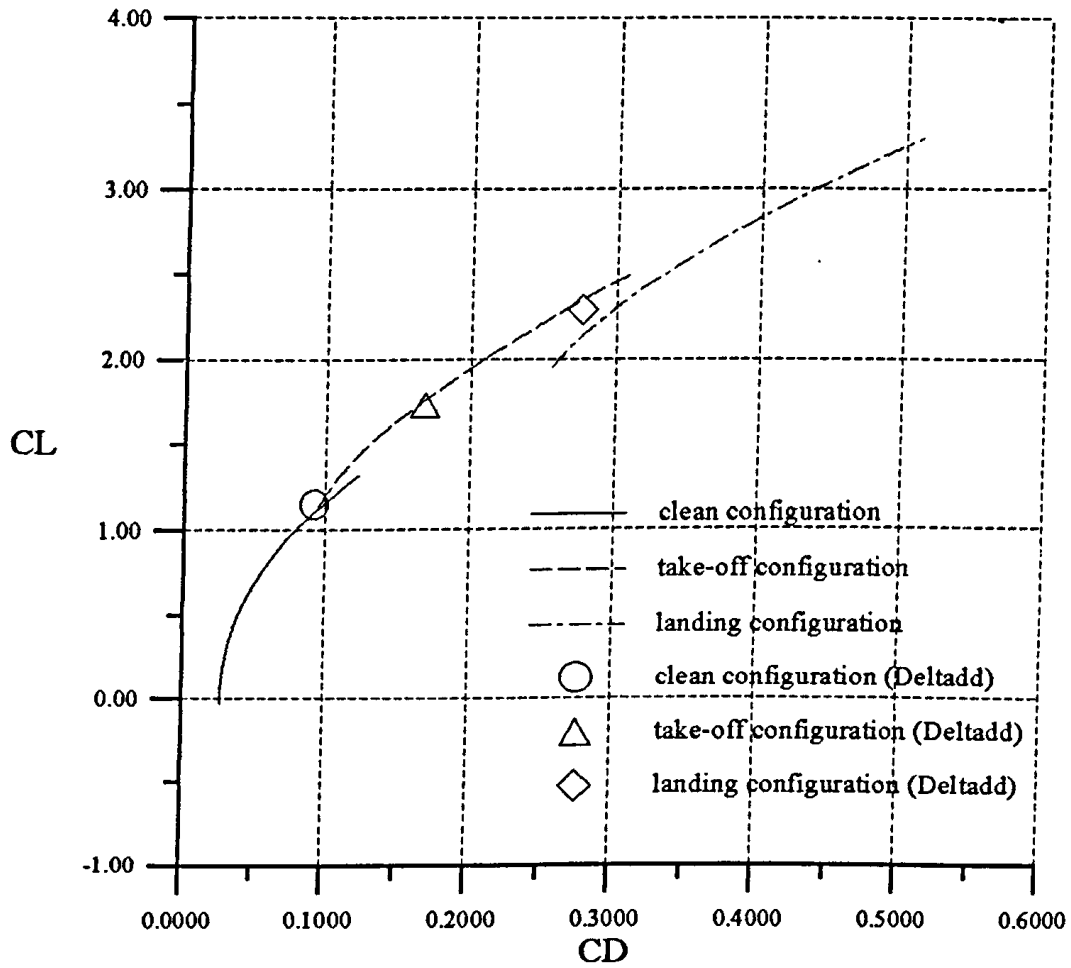


Fig. G5 - Minimum D.O.C. Conventional concept low speed drag polars
(comparison with Deltadd case results)

6

'50 Pax Turbofan Conventional Airliner (Baseline)'

4.368851 5.278069 13.390931 10.764469 2.8194 2.8194 .762 2.907082 .0
 4.234891 .8470392 18.723 10.544556 .115 2. 2.333 .846978 .169408
 9.530156 10.444556 -25. 15. .0 .0 .0 .0 .0
 7.597141 4.456842 2.771546 52.459 4.774997 4.774997 .12 1.4097 1.337053
 .831464 1.4859 4.4196 25.
 13.831248 2.751125 2.259787 28.593 5.011064 .962894 .790926 .231648
 4.8768 .1 .0 -25. 15. -7. 7.
 2.234794 7.349795 -.8001 44126.80 -98.060 .16343 -5.134196 1.216152
 .0 .0 .0 .0 .0 .0 .0 .0
 -1.6 .0238 -.021 1.2 .0
 .0 .0 .0 .0
 8169.1986 2439.4198 246.7542 430.9128 408.5733 3609.6881 4535.9237 .8
 1
 10668.0 .8 21065.737 3.486 .0 .0

Fig. G6.1 - Conventional Baseline Concept Stability and Control Evaluation
Mitchell Program Input file

1STABILITY WITH CONTROLS FIXED AND RESPONSE TO CONTROLS FOR A RIGID AIRCRAFT (METRIC UNITS)

DESCRIPTION : '50 Pax Turbofan Conventional Airliner (Baseline)'

OCASE 1 OF 1

0PRINCIPAL GEOMETRIC PARAMETERS

OWING SPAN = 21.1 OVERALL LENGTH = 29.6 FUSELAGE LENGTH = 24.2

OWING

OAREA = 53.6 ASPECT RATIO = 8.30 TAPER RATIO = .200 1/4C SWEEP = 14.5

OSMC = 2.54 MAC = 2.92 LE OF MAC FROM APEX DATUM = 1.39

OTAILPLANE

OAREA = 25.1 ASPECT RATIO = 4.00 TAPER RATIO = .321 1/4C SWEEP = 27.5

OARM = 12.3 HEIGHT = 4.84 VOLUME = 2.267

OFIN

OAREA(GROSS) = 16.3 AREA(NET) = 11.3 ASPECT RATIO (GROSS) = 1.494 1/4C SWEEP = 50.5

OARM = 8.9 HEIGHT TO CP = 3.1 VOLUME = .128

0CONFIGURATION DATA INSERTED

OWING AND FLAPS

0ALPHA 0(3-D) = -1.6 DEGREES DCL-FLAP (2-D) = .000 CLMAX (3-D) = 1.200 CM0 = -.0210

0CDO A/C = .0238 TAILPLANE SETTING = .0 DEGREES

0FLIGHT CONDITIONS

OMASS = 21065.7 HEIGHT = 10668.0 SPEED = 237.2 MACH NO = .800

0CG FROM DATUM = 3.49 CG POSITION = 82.49% SMC CG ABOVE DATUM = .00

0INCIDENCE (ALPHA) = 1.3 CL = .361

0LONGITUDINAL STABILITY

OWING CL = .330 TAIL CL = .066 TAIL LOAD UP = 17786.0N ELEVATOR ANGLE TO TRIM = 3.9

OWING AC FROM DATUM = 2.17 (= 30.55% SMC) WING A1 = 6.533 A/C A1 = 7.791

0NEUTRAL POINT (TAIL OFF) = 1.41 (= .88% SMC) (TAIL ON) = 3.78 (= 94.08% SMC) STATIC MARGIN = 11.58% SMC

0DOWNWASH GRADIENT DE/DA = .377 Q/QO AT TAILPLANE = 1.000 TAIL A1 = 4.311 ELEVATOR A2 = 2.946

0LONGITUDINAL STABILITY DERIVATIVES

0 XU = -.0284 XW = .0896 XQ = 0.0000

0 ZU = -.3609 ZW = -3.9097 ZQ = -1.0101

0 MU = 0.0000 MW = -.0932 MQ = -1.0404 MDW = -.3809

0LATERAL STABILITY DERIVATIVES

0 LV = -.1236 NV = .1551 YV = -.4728 NV (TAIL OFF) = -.1169

0 LR = .1085 NR = -.2304

0 LP = -.5127 NP = -.0232

0LATERAL CONTROL DERIVATIVES

0FIN A1 = 2.131 RUDDER A2 = .789

0AILERON LXI = -.0305 NXI = .0014

0SPOILER L = .0000 N = .0000

0RUDDER LZETA = .0353 NZETA = -.1007

1MOMENTS OF INERTIA (M.KG.UNITS)

0IX = 110284. IY = 596303. IZ = 696728. IXZ = 0.

0NON-DIMENSIONAL QUANTITIES

AERO T = 4.365 MU1 = 84.247 MU2 = 98.213

IX = .04712 IZ = .29742 IXZ = -.00309

IY = .18733

Fig. G6.2 - Conventional Baseline Concept Stability and Control Evaluation
Mitchell Program Output file

0LONGITUDINAL MODES, STICK FIXED

ROOTS OF	REAL PART	IMAG. PART
MODE 1	-1.3144	1.2599
MODE 2	-1.3144	-1.2599
MODE 3	-.0029	.0475
MODE 4	-.0029	-.0475

VECTORS REAL PART IMAG.PART AMPLITUDE PHASE

MODE 2

U	-.0009	.0011	.0014	-130.11
W	-.0526	.1583	.1668	-108.37
Q	.9783	.0000	.9783	.00
THETA	-.0889	.0852	.1231	-136.22

MODE 4

U	-.0574	-.6440	.6466	95.10
W	.0018	.0205	.0205	-84.93
Q	-.0095	-.1549	.1552	93.52
THETA	.7466	.0000	.7466	.00

0STABILITY PARAMETERS

0MODE 2 IS OSCILLATORY

0 FREQUENCY= .2005HZ (= 1.260RAD/S) PERIOD= 4.987SEC.
 UNDAMPED FREQ.= 1.821RAD/S
 0 DAMPING-- ANGLE=46.22DEG. RATIO(ZETA)= .722
 TIME TO HALF-AMP= .527SEC. CYCLES TO HALF-AMP= .106
 LOG.DEC.= 6.555

0MODE 4 IS OSCILLATORY

0 FREQUENCY= .0076HZ (= .048RAD/S) PERIOD=132.159SEC.
 UNDAMPED FREQ.= .048RAD/S
 0 DAMPING-- ANGLE= 3.51DEG. RATIO(ZETA)= .061
 TIME TO HALF-AMP=237.671SEC. CYCLES TO HALF-AMP= 1.798
 LOG.DEC.= .385

0NORMAL ACCELERATION NZ/ALPHA = .378 G/DEGREE

Fig. G6.2 - Conventional Baseline Concept Stability and Control Evaluation
 Mitchell Program Output file (continued)

ILATERAL MODES, STICK FIXED

ROOTS OF	REAL PART	IMAG. PART
MODE 1	-.1167	1.7170
MODE 2	-.1167	-1.7170
MODE 3	-2.5453	.0000
MODE 4	-.0054	.0000
MODE 5	.0000	.0000

VECTORS	REAL PART	IMAG.PART	AMPLITUDE	PHASE
---------	-----------	-----------	-----------	-------

MODE 2

V	-.0388	.0244	.0459	-147.83
P	.9350	.0000	.9350	.00
R	-.1860	-.2676	.3259	124.81
PHI	-.0084	.1242	.1245	-93.90
PSI	.0372	-.0223	.0434	30.92

MODE 3

V	.0008			
P	.9959			
R	-.0076			
PHI	-.0896			
PSI	.0007			

MODE 4

V	-.0003			
P	.0031			
R	-.0233			
PHI	-.1301			
PSI	.9912			

MODE 5 HAS ONLY CONSTANT TERMS

0STABILITY PARAMETERS

0MODE 2 IS OSCILLATORY

0 FREQUENCY= .2733HZ (= 1.717RAD/S) PERIOD= 3.659SEC.
 UNDAMPED FREQ.= 1.721RAD/S
 0 DAMPING-- ANGLE= 3.89DEG. RATIO(ZETA)= .068
 TIME TO HALF-AMP= 5.937SEC. CYCLES TO HALF-AMP= 1.622
 LOG.DEC.= .427

0MODE 3 IS EXPONENTIAL TIME CONSTANT= .393SEC.

0MODE 4 IS EXPONENTIAL TIME CONSTANT=185.507SEC.

0MODE 5 IS NEUTRALLY STABLE

0SINGLE DEGREE OF FREEDOM ROLLING DUE TO AILERONS

0ROLL ACCELERATION = 1.164 RAD.SEC-2 STEADY ROLL RATE = .467 RAD/SEC TIME FROM +30 TO -30 BANK = 3.029 SEC

Fig. G6.2 - Conventional Baseline Concept Stability and Control Evaluation
 Mitchell Program Output file (continued)

IFULL RESPONSE TO A STEP APPLICATION OF FULL AILERON AND SPOILER

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	.000	.000	.000	.000	.000	.000
.218	-.001	-.645	-.195	-.023	.016	.004	.000
.437	-.002	-.346	-.306	-.079	.010	.007	.002
.655	-.005	-.170	-.365	-.153	.001	.008	.003
.873	-.008	-.071	-.391	-.236	-.008	.008	.005
1.091	-.012	-.002	-.399	-.323	-.018	.005	.007
1.310	-.016	.035	-.395	-.409	-.027	.000	.007
1.528	-.019	.048	-.386	-.495	-.034	-.007	.007
1.746	-.021	.044	-.375	-.578	-.039	-.015	.004
1.964	-.022	.029	-.366	-.658	-.039	-.023	.000
2.183	-.021	.007	-.361	-.738	-.037	-.032	-.006
2.401	-.020	-.014	-.361	-.816	-.031	-.039	-.013
2.619	-.018	-.032	-.365	-.896	-.025	-.046	-.023
2.838	-.016	-.048	-.373	-.976	-.016	-.050	-.033
3.056	-.013	-.055	-.384	-1.059	-.010	-.053	-.045
3.274	-.011	-.055	-.397	-1.144	-.003	-.055	-.057
3.492	-.009	-.046	-.408	-1.232	.001	-.055	-.069
3.711	-.009	-.032	-.417	-1.322	.003	-.055	-.081
3.929	-.009	-.013	-.423	-1.414	.001	-.054	-.093
4.147	-.010	.004	-.425	-1.506	-.002	-.054	-.104
4.365	-.012	.024	-.422	-1.599	-.008	-.055	-.116
4.584	-.014	.038	-.416	-1.690	-.014	-.057	-.129
4.802	-.017	.046	-.407	-1.780	-.019	-.061	-.141
5.020	-.019	.049	-.397	-1.868	-.024	-.065	-.155
5.238	-.021	.045	-.386	-1.953	-.029	-.071	-.170
5.457	-.022	.035	-.377	-2.037	-.031	-.078	-.186
5.675	-.023	.020	-.371	-2.118	-.031	-.084	-.204
5.893	-.022	.006	-.367	-2.199	-.029	-.091	-.223
6.112	-.022	-.009	-.367	-2.279	-.025	-.097	-.244
6.330	-.020	-.023	-.370	-2.359	-.020	-.102	-.265
6.548	-.019	-.030	-.376	-2.441	-.016	-.106	-.288

IFULL RESPONSE TO A STEP APPLICATION OF FULL RUDDER

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	-.030	.000	.000	-.016	.000	.000
.218	.023	.600	.262	.033	-.671	-.161	-.018
.437	.078	-.277	.305	.098	-.497	-.292	-.068
.655	.156	-1.022	.164	.153	-.264	-.377	-.142
.873	.244	-1.570	-.118	.160	.007	-.408	-.229
1.091	.331	-1.808	-.487	.095	.245	-.384	-.316
1.310	.405	-1.770	-.883	-.055	.429	-.314	-.393
1.528	.456	-1.495	-1.247	-.288	.542	-.208	-.450
1.746	.478	-.957	-1.530	-.593	.574	-.085	-.483
1.964	.470	-.413	-1.696	-.948	.523	.038	-.488
2.183	.434	.188	-1.728	-1.324	.404	.141	-.468
2.401	.377	.774	-1.627	-1.692	.222	.212	-.428
2.619	.307	1.232	-1.415	-2.026	.005	.242	-.378
2.838	.234	1.467	-1.124	-2.304	-.191	.227	-.326
3.056	.169	1.499	-.798	-2.514	-.348	.171	-.282
3.274	.119	1.330	-.483	-2.653	-.468	.083	-.254
3.492	.091	1.018	-.221	-2.729	-.519	-.026	-.247
3.711	.088	.543	-.046	-2.756	-.504	-.139	-.265
3.929	.108	.055	.025	-2.756	-.428	-.242	-.307
4.147	.147	-.473	-.015	-2.753	-.287	-.323	-.369
4.365	.200	-.853	-.153	-2.770	-.134	-.373	-.446
4.584	.258	-1.122	-.366	-2.825	.038	-.387	-.529
4.802	.313	-1.210	-.621	-2.933	.173	-.366	-.612
5.020	.358	-1.132	-.881	-3.097	.294	-.315	-.687
5.238	.387	-.933	-1.111	-3.315	.352	-.245	-.748
5.457	.397	-.599	-1.280	-3.577	.363	-.166	-.793
5.675	.387	-.140	-1.369	-3.868	.310	-.090	-.821
5.893	.360	.258	-1.369	-4.168	.217	-.029	-.834
6.112	.320	.564	-1.285	-4.459	.112	.009	-.835
6.330	.273	.849	-1.131	-4.724	-.035	.019	-.832
6.548	.226	.966	-.933	-4.950	-.148	.001	-.829

Fig. G6.2 - Conventional Baseline Concept Stability and Control Evaluation
Mitchell Program Output file (continued)

1FULL RESPONSE TO AN ENGINE FAILURE, CONTROLS FIXED

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	.966	.000	.000	-.148	.000	.000
.218	-.001	.011	.001	.000	.026	.006	.001
.437	-.003	.031	.005	.001	.019	.011	.003
.655	-.005	.048	.013	.002	.012	.015	.006
.873	-.009	.064	.025	.006	.002	.017	.009
1.091	-.012	.071	.040	.014	-.008	.016	.013
1.310	-.015	.069	.056	.024	-.014	.014	.016
1.528	-.017	.057	.070	.038	-.019	.010	.019
1.746	-.018	.038	.081	.054	-.021	.006	.020
1.964	-.017	.016	.088	.073	-.019	.001	.021
2.183	-.016	-.007	.090	.092	-.014	-.002	.021
2.401	-.014	-.027	.086	.112	-.008	-.005	.020
2.619	-.012	-.044	.079	.130	.000	-.006	.019
2.838	-.009	-.054	.068	.146	.007	-.005	.018
3.056	-.006	-.057	.056	.159	.013	-.003	.017
3.274	-.004	-.050	.044	.170	.019	.000	.016
3.492	-.003	-.039	.034	.178	.020	.005	.017
3.711	-.003	-.020	.027	.185	.020	.009	.018
3.929	-.004	.000	.024	.190	.017	.013	.021
4.147	-.005	.017	.025	.195	.012	.016	.024
4.365	-.007	.031	.030	.201	.007	.019	.028
4.584	-.009	.041	.037	.209	.000	.020	.032
4.802	-.011	.045	.047	.218	-.005	.019	.036
5.020	-.013	.043	.056	.229	-.010	.018	.040
5.238	-.014	.034	.065	.242	-.012	.015	.044
5.457	-.014	.022	.072	.257	-.013	.012	.047
5.675	-.014	.006	.075	.273	-.011	.010	.049
5.893	-.013	-.010	.076	.290	-.007	.008	.051
6.112	-.012	-.022	.073	.306	-.003	.006	.053
6.330	-.010	-.031	.067	.322	.002	.006	.054
6.548	-.008	-.036	.060	.335	.006	.007	.056

1FULL RESPONSE TO A 10 M/S SIDE GUST, CONTROLS FIXED

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	-.036	.000	.000	.006	.000	.000
.218	-.004	-.261	-.092	-.011	.101	.025	.003
.437	-.012	-.040	-.129	-.036	.071	.044	.010
.655	-.025	.110	-.124	-.065	.035	.057	.022
.873	-.038	.208	-.090	-.088	-.002	.061	.035
1.091	-.052	.264	-.038	-.102	-.041	.056	.047
1.310	-.064	.266	.021	-.104	-.072	.044	.059
1.528	-.072	.230	.076	-.093	-.089	.027	.066
1.746	-.076	.160	.120	-.072	-.095	.007	.070
1.964	-.075	.063	.146	-.042	-.087	-.014	.069
2.183	-.069	-.027	.151	-.009	-.069	-.031	.064
2.401	-.060	-.116	.136	.022	-.041	-.043	.056
2.619	-.049	-.189	.103	.049	-.008	-.049	.046
2.838	-.038	-.228	.058	.066	.024	-.048	.035
3.056	-.028	-.233	.007	.073	.051	-.040	.025
3.274	-.020	-.210	-.042	.070	.067	-.028	.018
3.492	-.016	-.152	-.083	.056	.076	-.012	.013
3.711	-.015	-.089	-.111	.034	.074	.005	.013
3.929	-.018	.002	-.122	.009	.060	.020	.015
4.147	-.025	.071	-.116	-.018	.041	.031	.021
4.365	-.033	.132	-.095	-.041	.017	.038	.029
4.584	-.042	.176	-.061	-.058	-.011	.039	.037
4.802	-.051	.190	-.021	-.067	-.032	.035	.045
5.020	-.058	.177	.019	-.067	-.051	.026	.052
5.238	-.062	.143	.056	-.059	-.060	.014	.057
5.457	-.064	.086	.082	-.044	-.061	.001	.058
5.675	-.063	.024	.097	-.024	-.053	-.012	.057
5.893	-.059	-.039	.097	-.003	-.039	-.023	.053
6.112	-.052	-.088	.084	.017	-.022	-.030	.048
6.330	-.045	-.128	.061	.033	-.002	-.032	.041
6.548	-.038	-.150	.030	.043	.018	-.031	.034

Fig. G6.2 - Conventional Baseline Concept Stability and Control Evaluation
Mitchell Program Output file (continued)

LOW SPEED HANDLING AT SEA LEVEL

STALL SPEED = 134.0KN INCIDENCE = 13.2

TAILPLANE SETTING = -7.0 ELEVATOR ANGLE = 7.8 TAIL CL = .266 TAIL INCIDENCE = -.9

NOSEWHEEL LIFTED BY THRUST

MINIMUM CONTROL SPEED = 104.6 KNOTS

STEADY SIDESLIP AT SPEED 174.2 KNOTS

AILERON LIMITED (AILERONS AND SPOILERS AT 0.8 OF MAXIMUM DEFLECTIONS)

SLIP ANGLE = .043 RADS CROSSWIND SPEED = 7.4 KNOTS RUDDER ANGLE = 3.6 DEG.

0

Fig. G6.2 - Conventional Baseline Concept Stability and Control Evaluation
Mitchell Program Output file (concluded)

6

'50 Pax Turbofan Conventional Airliner (DOC optimised)'

3.473348 6.173572 12.495428 11.659972 2.8194 2.8194 .762 2.399093 .0
 3.798418 .6269736 16.859 9.115958 .115 2. 2.333 .7596835 .1253947
 8.246669 8.9916 -25. 15. .0 .0 .0 .0 .0
 7.519788 3.569822 2.199742 52.435 4.522013 4.522013 .12 1.4097 .942838
 .659922 1.4859 4.2672 25.
 13.575951 2.022958 2.022958 20.951 3.96682 .708035 .708035 .231648
 3.9624 .1 .0 -25. 15. -7. 7.
 2.227722 6.454292 -.8001 43960.88 -97.691 .16282 -4.324694 1.213104
 .0 .0 .0 .0 .0 .0 .0 .0
 -1.6 .0273 -.025 1.2 .0
 .0 .0 .0 .0
 7941.9488 1989.4561 205.0238 337.0191 401.7694 3524.4127 4535.9237 .8
 1
 10668. .8 20048.783 2.62207 .0 .0

**Fig. G7.1 - Conventional D.O.C. optimised Concept Stability and Control Evaluation
Mitchell Program Input file**

1STABILITY WITH CONTROLS FIXED AND RESPONSE TO CONTROLS FOR A RIGID AIRCRAFT (METRIC UNITS)

DESCRIPTION : '50 Pax Turbofan Conventional Airliner (DOC optimised)'

OCASE 1 OF 1

0PRINCIPAL GEOMETRIC PARAMETERS

OWING SPAN = 18.2 OVERALL LENGTH = 28.8 FUSELAGE LENGTH = 24.2

OWING

OAREA = 40.3 ASPECT RATIO = 8.24 TAPER RATIO = .165 1/4C SWEEP = 12.2

OSMC = 2.21 MAC = 2.59 LE OF MAC FROM APEX DATUM = 1.05

0TAILPLANE

OAREA = 16.0 ASPECT RATIO = 3.92 TAPER RATIO = 1.000 1/4C SWEEP = 21.0

OARM = 12.2 HEIGHT = 4.59 VOLUME = 2.197

0FIN

OAREA(GROSS) = 12.2 AREA(NET) = 8.3 ASPECT RATIO (GROSS) = 1.592 1/4C SWEEP = 50.8

OARM = 9.3 HEIGHT TO CP = 2.9 VOLUME = .155

0CONFIGURATION DATA INSERTED

OWING AND FLAPS

OALPHA 0(3-D) = -1.6 DEGREES DCL-FLAP (2-D) = .000 CLMAX (3-D) = 1.200 CM0 = -.0250

OCDO A/C = .0273 TAILPLANE SETTING = .0 DEGREES

0FLIGHT CONDITIONS

OMASS = 20048.8 HEIGHT = 10668.0 SPEED = 237.2 MACH NO = .800

OCG FROM DATUM = 2.62 CG POSITION = 70.99% SMC CG ABOVE DATUM = .00

OINCIDENCE (ALPHA) = 2.1 CL = .456

0LONGITUDINAL STABILITY

OWING CL = .430 TAIL CL = .067 TAIL LOAD UP = 11469.5N ELEVATOR ANGLE TO TRIM = 3.1

OWING AC FROM DATUM = 1.74 (= 30.96% SMC) WING A1 = 6.572 A/C A1 = 7.685

ONEUTRAL POINT (TAIL OFF) = .82 (= -10.63% SMC) (TAIL ON) = 2.89 (= 82.89% SMC) STATIC MARGIN = 11.90%

SMC

0DOWNWASH GRADIENT DE/DA = .365 Q/QO AT TAILPLANE = 1.000 TAIL A1 = 4.405 ELEVATOR A2 = 2.980

0LONGITUDINAL STABILITY DERIVATIVES

0 XU = -.0351 XW = .1082 XQ = 0.0000

0 ZU = -.4563 ZW = -3.8600 ZQ = -.8762

0 MU = 0.0000 MW = -.0828 MQ = -.8914 MDW = -.3197

0LATERAL STABILITY DERIVATIVES

0 LV = -.1313 NV = .1715 YV = -.5427 NV (TAIL OFF) = -.1824

0 LR = .1445 NR = -.3634

0 LP = -.5117 NP = -.0294

0LATERAL CONTROL DERIVATIVES

0FIN A1 = 2.289 RUDDER A2 = .869

0AILERON LXI = -.0276 NXI = .9016

0SPOILER L = .0000 N = .0000

0RUDDER LZETA = .0411 NZETA = -.1343

1MOMENTS OF INERTIA (M.KG.UNITS)

0IX = 73823. IY = 562709. IZ = 627646. IXZ = 0.

0NON-DIMENSIONAL QUANTITIES

AERO T = 5.519 MU1 = 107.146 MU2 = 143.618

IX = .04431 IZ = .37672 IXZ = .00085

IY = .18798

Fig. G7.2 - Conventional D.O.C. optimised Concept Stability and Control Evaluation
Mitchell Program Output file

0LONGITUDINAL MODES, STICK FIXED

ROOTS OF	REAL PART	IMAG. PART
MODE 1	-.9327	1.1266
MODE 2	-.9327	-1.1266
MODE 3	-.0027	.0497
MODE 4	-.0027	-.0497

VECTORS	REAL PART	IMAG.PART	AMPLITUDE	PHASE
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MODE 2

U	-.0006	.0018	.0019	-109.80
W	-.0309	.1501	.1532	-101.66
Q	.9807	.0000	.9807	.00
THETA	-.0775	.0936	.1215	-129.63

MODE 4

U	-.0544	-.6217	.6241	95.00
W	.0021	.0207	.0208	-84.17
Q	-.0111	-.2065	.2068	93.09
THETA	.7532	.0000	.7532	.00

0STABILITY PARAMETERS

0MODE 2 IS OSCILLATORY

0 FREQUENCY= .1793HZ (= 1.127RAD/S) PERIOD= 5.577SEC.
 UNDAMPED FREQ.= 1.463RAD/S
 0 DAMPING-- ANGLE=39.62DEG. RATIO(ZETA)= .638
 TIME TO HALF-AMP= .743SEC. CYCLES TO HALF-AMP= .133
 LOG.DEC.= 5.202

0MODE 4 IS OSCILLATORY

0 FREQUENCY= .0079HZ (= .050RAD/S) PERIOD=126.452SEC.
 UNDAMPED FREQ.= .050RAD/S
 0 DAMPING-- ANGLE= 3.08DEG. RATIO(ZETA)= .054
 TIME TO HALF-AMP=259.178SEC. CYCLES TO HALF-AMP= 2.050
 LOG.DEC.= .338

0NORMAL ACCELERATION NZ/ALPHA = .295 G/DEGREE

Fig. G7.2 - Conventional D.O.C. optimised Concept Stability and Control Evaluation
 Mitchell Program Output file (continued)

ILATERAL MODES, STICK FIXED

ROOTS OF	REAL PART	IMAG. PART
MODE 1	-.0697	1.5418
MODE 2	-.0697	-1.5418
MODE 3	-2.2158	.0000
MODE 4	-.0092	.0000
MODE 5	.0000	.0000

VECTORS	REAL PART	IMAG.PART	AMPLITUDE	PHASE
---------	-----------	-----------	-----------	-------

MODE 2

V	-.0264	.0177	.0318	-146.14
P	.9606	.0000	.9606	.00
R	-.1478	-.2018	.2501	126.23
PHI	-.0051	.1127	.1128	-92.60
PSI	.0245	-.0163	.0294	33.63

MODE 3

V	.0016
P	.9967
R	.0001
PHI	-.0815
PSI	.0000

MODE 4

V	-.0007
P	.0111
R	-.0495
PHI	-.2182
PSI	.9746

MODE 5 HAS ONLY CONSTANT TERMS

0STABILITY PARAMETERS

0MODE 2 IS OSCILLATORY

0 FREQUENCY= .2454HZ (= 1.542RAD/S) PERIOD= 4.075SEC.
 UNDAMPED FREQ.= 1.543RAD/S
 0 DAMPING-- ANGLE= 2.59DEG. RATIO(ZETA)= .045
 TIME TO HALF-AMP= 9.940SEC. CYCLES TO HALF-AMP= 2.439
 LOG.DEC.= .284

0MODE 3 IS EXPONENTIAL TIME CONSTANT= .451SEC.

0MODE 4 IS EXPONENTIAL TIME CONSTANT=108.754SEC.

0MODE 5 IS NEUTRALLY STABLE

0SINGLE DEGREE OF FREEDOM ROLLING DUE TO AILERONS

0ROLL ACCELERATION = 1.025 RAD.SEC-2 STEADY ROLL RATE = .490 RAD/SEC TIME FROM +30 TO -30 BANK = 3.055 SEC

Fig. G7.2 - Conventional D.O.C. optimised Concept Stability and Control Evaluation Mitchell Program Output file (continued)

IFULL RESPONSE TO A STEP APPLICATION OF FULL AILERON AND SPOILER

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	.000	.000	.000	.000	.000	.000
.276	.000	-.569	-.214	-.032	.008	.002	.000
.552	-.002	-.291	-.332	-.109	.006	.004	.001
.828	-.005	-.137	-.391	-.210	.001	.005	.002
1.104	-.009	-.024	-.413	-.322	-.008	.004	.004
1.380	-.014	.037	-.412	-.436	-.018	.001	.004
1.656	-.018	.064	-.399	-.548	-.026	-.005	.004
1.932	-.022	.072	-.380	-.656	-.033	-.013	.001
2.207	-.025	.059	-.361	-.758	-.037	-.023	-.004
2.483	-.025	.031	-.347	-.855	-.036	-.033	-.011
2.759	-.025	.002	-.341	-.950	-.033	-.043	-.022
3.035	-.022	-.030	-.344	-1.044	-.026	-.051	-.035
3.311	-.019	-.053	-.355	-1.140	-.018	-.058	-.050
3.587	-.016	-.068	-.371	-1.240	-.010	-.062	-.067
3.863	-.013	-.069	-.390	-1.345	-.004	-.064	-.084
4.139	-.011	-.058	-.408	-1.456	.001	-.064	-.102
4.415	-.010	-.037	-.422	-1.570	.002	-.063	-.119
4.691	-.011	-.005	-.429	-1.688	.000	-.063	-.137
4.967	-.013	.023	-.428	-1.806	-.005	-.063	-.154
5.243	-.016	.044	-.420	-1.924	-.011	-.065	-.172
5.519	-.020	.060	-.405	-2.038	-.018	-.069	-.190
5.795	-.023	.067	-.388	-2.147	-.025	-.075	-.210
6.071	-.026	.062	-.370	-2.252	-.029	-.082	-.232
6.347	-.028	.044	-.354	-2.351	-.031	-.091	-.256
6.622	-.028	.024	-.344	-2.447	-.031	-.099	-.282
6.898	-.027	-.001	-.340	-2.542	-.027	-.108	-.311
7.174	-.025	-.024	-.343	-2.636	-.022	-.115	-.341
7.450	-.023	-.042	-.352	-2.731	-.015	-.120	-.374
7.726	-.020	-.051	-.365	-2.830	-.009	-.123	-.407
8.002	-.018	-.050	-.379	-2.933	-.005	-.126	-.442
8.278	-.017	-.041	-.392	-3.039	-.002	-.126	-.476

IFULL RESPONSE TO A STEP APPLICATION OF FULL RUDDER

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	-.041	.000	.000	-.002	.000	.000
.276	.033	.542	.345	.056	-.626	-.191	-.027
.552	.112	-.715	.344	.158	-.412	-.341	-.101
.828	.223	-1.601	.042	.218	-.167	-.427	-.209
1.104	.345	-2.168	-.480	.161	.088	-.441	-.331
1.380	.456	-2.347	-1.113	-.057	.328	-.383	-.446
1.656	.536	-2.062	-1.736	-.452	.494	-.270	-.537
1.932	.573	-1.478	-2.238	-1.004	.548	-.125	-.591
2.207	.562	-.524	-2.532	-1.668	.493	.023	-.605
2.483	.506	.318	-2.575	-2.378	.365	.145	-.581
2.759	.417	1.225	-2.366	-3.065	.142	.218	-.530
3.035	.311	1.790	-1.952	-3.665	-.077	.230	-.466
3.311	.207	2.077	-1.412	-4.131	-.316	.178	-.409
3.587	.124	1.980	-.845	-4.442	-.464	.072	-.373
3.863	.074	1.488	-.351	-4.604	-.557	-.070	-.372
4.139	.066	.792	-.012	-4.650	-.545	-.224	-.413
4.415	.099	-.028	.117	-4.630	-.445	-.366	-.495
4.691	.165	-.767	.023	-4.606	-.288	-.471	-.611
4.967	.251	-1.405	-.269	-4.636	-.079	-.527	-.750
5.243	.342	-1.736	-.699	-4.767	.117	-.527	-.897
5.519	.421	-1.752	-1.187	-5.027	.281	-.475	-1.036
5.795	.475	-1.457	-1.645	-5.420	.380	-.385	-1.156
6.071	.494	-.924	-1.992	-5.925	.400	-.277	-1.247
6.347	.477	-.233	-2.172	-6.503	.342	-.171	-1.309
6.622	.428	.405	-2.159	-7.105	.231	-.089	-1.344
6.898	.357	1.043	-1.962	-7.678	.058	-.047	-1.362
7.174	.276	1.421	-1.622	-8.175	-.108	-.052	-1.374
7.450	.200	1.568	-1.203	-8.565	-.269	-.104	-1.395
7.726	.142	1.426	-.782	-8.839	-.384	-.194	-1.435
8.002	.112	.998	-.432	-9.004	-.433	-.308	-1.504
8.278	.112	.519	-.210	-9.089	-.414	-.426	-1.605

Fig. G7.2 - Conventional D.O.C. optimised Concept Stability and Control Evaluation
Mitchell Program Output file (continued)

1FULL RESPONSE TO AN ENGINE FAILURE, CONTROLS FIXED

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	.519	.000	.000	-.414	.000	.000
.276	-.001	.022	.002	.000	.028	.009	.001
.552	-.005	.051	.011	.002	.020	.016	.005
.828	-.009	.080	.029	.007	.009	.020	.010
1.104	-.014	.101	.054	.019	-.003	.021	.015
1.380	-.019	.104	.083	.037	-.013	.019	.021
1.656	-.023	.091	.110	.064	-.020	.014	.025
1.932	-.024	.061	.132	.098	-.022	.008	.028
2.207	-.024	.020	.145	.136	-.019	.002	.030
2.483	-.021	-.020	.147	.177	-.013	-.002	.030
2.759	-.017	-.051	.138	.217	-.005	-.005	.029
3.035	-.013	-.079	.120	.252	.005	-.005	.027
3.311	-.008	-.090	.097	.282	.015	-.003	.026
3.587	-.005	-.084	.073	.306	.022	.002	.026
3.863	-.002	-.066	.051	.323	.025	.009	.027
4.139	-.002	-.036	.036	.335	.025	.016	.031
4.415	-.003	-.002	.031	.344	.021	.022	.036
4.691	-.006	.031	.035	.353	.014	.027	.043
4.967	-.010	.061	.047	.364	.005	.030	.051
5.243	-.014	.074	.066	.379	-.003	.031	.060
5.519	-.017	.075	.086	.400	-.011	.029	.068
5.795	-.019	.064	.106	.427	-.015	.025	.075
6.071	-.020	.042	.121	.458	-.016	.021	.082
6.347	-.020	.008	.129	.493	-.013	.017	.087
6.622	-.017	-.022	.128	.528	-.007	.014	.091
6.898	-.014	-.045	.120	.563	-.001	.012	.095
7.174	-.011	-.061	.105	.594	.006	.013	.098
7.450	-.007	-.068	.087	.620	.013	.016	.102
7.726	-.005	-.062	.068	.642	.018	.020	.107
8.002	-.004	-.046	.053	.658	.020	.025	.113
8.278	-.004	-.023	.044	.672	.019	.031	.121

1FULL RESPONSE TO A 10 M/S SIDE GUST, CONTROLS FIXED

0 TIME	SLIP	DP/DT	P	PHI	DR/DT	R	PSI
.000	.000	-.023	.000	.000	.019	.000	.000
.276	-.004	-.268	-.116	-.018	.078	.023	.003
.552	-.015	-.012	-.155	-.057	.051	.042	.012
.828	-.030	.158	-.138	-.099	.017	.052	.026
1.104	-.046	.253	-.082	-.130	-.016	.053	.040
1.380	-.060	.293	-.006	-.142	-.047	.044	.054
1.656	-.071	.265	.074	-.133	-.070	.028	.064
1.932	-.077	.198	.139	-.103	-.078	.008	.069
2.207	-.076	.072	.179	-.058	-.071	-.013	.068
2.483	-.069	-.043	.187	-.007	-.053	-.031	.062
2.759	-.058	-.149	.163	.042	-.028	-.043	.051
3.035	-.044	-.229	.110	.081	.002	-.047	.039
3.311	-.031	-.269	.041	.102	.033	-.043	.026
3.587	-.020	-.259	-.033	.103	.053	-.031	.016
3.863	-.013	-.198	-.098	.084	.066	-.014	.009
4.139	-.012	-.114	-.144	.050	.066	.004	.008
4.415	-.016	.003	-.162	.008	.052	.021	.012
4.691	-.024	.096	-.152	-.036	.033	.034	.019
4.967	-.036	.180	-.115	-.074	.006	.040	.030
5.243	-.048	.226	-.060	-.098	-.019	.039	.041
5.519	-.058	.232	.004	-.106	-.040	.031	.050
5.795	-.066	.200	.065	-.096	-.054	.018	.057
6.071	-.069	.129	.112	-.071	-.058	.002	.060
6.347	-.067	.048	.138	-.036	-.053	-.014	.058
6.622	-.061	-.044	.138	.002	-.038	-.026	.053
6.898	-.052	-.133	.115	.038	-.014	-.034	.044
7.174	-.041	-.182	.072	.064	.007	-.035	.034
7.450	-.032	-.203	.018	.076	.028	-.031	.025
7.726	-.024	-.189	-.037	.074	.043	-.021	.018
8.002	-.020	-.139	-.083	.057	.050	-.008	.014
8.278	-.020	-.072	-.113	.029	.049	.006	.014

Fig. G7.2 - Conventional D.O.C. optimised Concept Stability and Control Evaluation Mitchell Program Output file (continued)

LOW SPEED HANDLING AT SEA LEVEL

0STALL SPEED = 153.1KN INCIDENCE = 13.1

0TAILPLANE SETTING = -7.0 ELEVATOR ANGLE = 6.2 TAIL CL = .207 TAIL INCIDENCE = -.7

0NOSEWHEEL LIFT SPEED = 25.7KNOTS WITH TAILPLANE SET TO -1.2DEGREES

0MINIMUM CONTROL SPEED = 111.4 KNOTS

0STEADY SIDESLIP AT SPEED 199.1 KNOTS

0AILERON LIMITED (AILERONS AND SPOILERS AT 0.8 OF MAXIMUM DEFLECTIONS)

0SLIP ANGLE = .041 RADS CROSSWIND SPEED = 8.1 KNOTS RUDDER ANGLE = 2.9 DEG.

0

Fig. G7.2 - Conventional D.O.C. optimised Concept Stability and Control Evaluation
Mitchell Program Output file (concluded)

APPENDIX H

List of GASP Input Variable Names

Introduction

This Appendix includes a complete list of GASP input variable names. These are grouped by disciplinary areas. Parameters related to the modifications done in GASP are shown in italics as well as their respective control options. The values included correspond to those proposed and used for the initial trial baseline configurations, both conventional and unconventional. These values also correspond to the starting point, or the initial estimate of the optimum solutions.

List of GASP Input Variable Names

Geometry

General data

IENG SZ	Engine cycle indicator - General Electric CF 34	5
<i>Kanard</i>	<i>Conventional (0) or Three-Lifting Surface concept (1) (option)</i>	
WG	take-off gross weight (initial guess) [lb]	44050
WGS	take-off wing loading (initial guess) [lb/sqft]	83
PAX	number of passengers	50
EMCRU	design cruise Mach number	0.8
HNCRU	design cruise altitude [ft]	35000
ENP	number of engines	2
KWRITE	selected summary statements are printed (option)	2
IGEAR	retractable landing gear (option)	0
KCONFIG	conventional fuselage tail cone (option)	0
KTIPX	no tip tanks (option)	0
NTYE	turbofan engine (option)	7
KPLOT	plots aerodynamic data (option)	1

Fuselage data

SAB	seats abreast in fuselage	4
WS	seat width [in]	20
AS	number of aisles	1
WAS	aisle width [in]	19
PS	seat pitch [in]	31
ELPC	length of flight deck plus passenger door allowance [ft]	11.22
HCK	mean fuselage diameter minus nose cone max. diameter [ft] (\approx windscreen height)	2.47
ELODN	fuselage nose cone fineness ratio	1
ELODT	fuselage tail cone fineness ratio (assuming allowances for galley, toilet and rear passenger door)	3.2

Nacelle

KNAC	nacelle drag assumed as part of aircraft drag (option)	1
ELRW	length of pylon attachment for fuselage mounted engines [ft]	10
ELN	nacelle length [ft] (computed by program)	0
DBARN	nacelle mean diameter [ft] (computed by program)	0

Wing

AR	wing aspect ratio	8.3
TCT	wing tip thickness to chord ratio	0.10
TCR	wing root thickness to chord ratio	0.13

SLM	wing taper ratio	0.20
DLMC4	sweep of wing 1/4 chord [degrees]	14.5
EYEW	wing incidence to fuselage horizontal datum line [degrees]	2

Canard

<i>ARcan</i>	<i>canard aspect ratio</i>	5.5
<i>TCcan</i>	<i>canard thickness to chord ratio</i>	0.10
<i>SLMcan</i>	<i>canard taper ratio</i>	0.50
<i>DwpqCa</i>	<i>sweep of canard 1/4 chord [degrees]</i>	15
<i>EYEcan</i>	<i>canard incidence to fuselage horizontal datum line [degrees]</i>	2
<i>SWcOSW</i>	<i>canard to wing area ratio</i>	0.145

Horizontal tail

SAH	location of tailplane on vertical fin as a fraction of fin span	1
ARHT	tailplane aspect ratio	4
TCHT	tailplane thickness to chord ratio	0.10
SLMH	tailplane taper ratio (initial value)	0.55
DWPQCH	sweep of tailplane 1/4 chord [degrees]	27.5

Vertical tail

ARVT	fin aspect ratio	1
TCVT	fin thickness to chord ratio	0.12
SLMV	fin taper ratio	0.70
DWPQCV	sweep of fin 1/4 chord [degrees]	50.5

Aerodynamics

KWCD	number of points in wing/canard profile drag table	12
ACLS	values of C_L in wing/canard profile drag table: -1.0, -0.6, -0.4, -0.2, 0, 0.1, 0.2, 0.4, 0.6, 0.8, 1, 1.2	
ACDCDR	normalized wing/canard profile drag values in wing/canard profile drag table: 2.400, 1.466, 1.221, 1.066, 1.005, 1.000, 1.005, 1.046, 1.138, 1.333, 1.743, 2.718	
DELCD	increment in overall drag coefficient	0.0015
DELFE	increment in equivalent flat plate area of fuselage [sqft]	0.2
SCFAC	shift in drag divergence Mach number due to supercritical aerofoil design	0.75
DLSWSW	increment in wetted area/wing area	0
ALPHLO	wing zero lift angle of attack [degrees]	-1.6
DCDSE	program computes increment in drag coefficient due to engine out (option)	-1.0
RCLMAX	maximum clean basic wing lift coefficient at reference conditions	1.2
ALTFLP	altitude for Reynolds number calculation (field conditions) [ft]	5000
<i>cmacw</i>	<i>wing pitching moment coefficient</i>	-0.06
<i>alzerc</i>	<i>canard zero lift angle of attack [degrees]</i>	-1.0
<i>CKWc</i>	<i>canard aerodynamic form factor (computed by program)</i>	-1.0

CKW	wing aerodynamic form factor (computed by program)	-1.0
CKHT	tailplane aerodynamic form factor (computed by program)	-1.0
CKVT	fin aerodynamic form factor (computed by program)	-1.0
CKF	fuselage aerodynamic form factor (computed by program)	-1.0
CKN	nacelle aerodynamic form factor (computed by program)	-1.0

Flaps

FLAPN	number of flap segments per wing panel	1
BENGOB	fraction of wing span without flaps due to wing mounted engine	0
JFLTYP	double slotted Fowler flaps (selection)	7
DFLPTO	take-off flap deflection [degrees]	15
DFLPLD	landing flap deflection [degrees]	40
CFOC	flap chord to wing chord ratio	0.30
BTEOB	flap span to wing span ratio	0.75
WCFLAP	flap weight trend coefficient (default function of flap type)	-1.0

Propulsion

JENGSZ	engines sized for cruise, take-off and climb (option)	2
IPART	FAR Part 25 turbine propulsion sizing requirements (option)	1
KODETO	engine power setting during take-off, maximum power (option)	5
KODECL	engine power setting during climb, maximum climb power (option)	7
KODEAC	engine power setting during acceleration, maximum power (option)	5
HPORT	take-off field altitude [ft]	5000
TDELTO	increment in take-off ambient temperature above ISA standard day [degree F]	36
RCCRU	required rate of climb at cruise conditions [fpm]	50
XTORQ	required take-off distance to 35 ft (not constrained)	99999
SM1D engine	face sea level static Mach number	0.5
HBTP	engine face hub/tip ratio	0.437
RWCRTX	ratio of cruise weight to maximum take-off gross weight (for engine sizing)	0.97
HSCREQ	engine out service ceiling required [ft]	0
THIN	input maximum static thrust for one engine (if engine known) [lb]	0
PR	inlet pressure recovery factor	1

Weights

SKPEI	weight trend coefficient of engine installation, fraction of dry engine	0.135
SKLG	weight trend coefficient of landing gear, fraction of gross weight	0.038
SKMG	main gear weight fraction of landing gear weight	0.8
SKPES	weight trend coefficient of engine nacelle, fraction of dry engine	0.338
UWPAX	weight per passenger including luggage [lb]	200

STRUT	wing/canard strut attachment point, fraction of semi-span (for cantilever wing/canard = 0)	0
DELWFC	incremental control group weight [lb]	0
SKY	weight trend coefficient of horizontal tail	0.18
SKZ	weight trend coefficient of vertical tail	0.22
SKWW	weight trend coefficient of wing and canard, excluding high lift devices	133.4
YMG	location of main gear on wing, fraction of wing semi-span	0.25
RELP	engine c.g. fraction of fuselage length (for fuselage mounted engines)	0.75
RELR	c.g. of fuselage and contents, fraction of fuselage length	0.45
CATD	transport design structural category, FAR Part 25 (used to determine allowable load factors and design speeds)	3
VMLFSL	maximum operating design flight speed, structural [mph]	685
SKB	weight trend coefficient of fuselage	107
SKCC	weight trend coefficient of cockpit controls	20
SKFW	weight trend coefficient of fixed wing controls	0.43
SKSAS	weight of stability augmentation system [lb]	0
EGMRGN	engine c.g. in relation to the leading edge of the wing mean aerodynamic chord (mac), as a fraction of mac, for wing mounted engines, positive aft	0
CPMRGN	wing/canard c.g. with respect to mac quarter chord point, fraction of mac	0.2
STMRGN	aircraft c.g. with respect to mac quarter chord point, fraction of mac	0
DELP	fuselage pressure differential in order to maintain an 8000 ft cabin at 40000 ft altitude [psi]	8.2
YP	location of engines on wing (on fuselage = 0)	0
SKFS	weight trend coefficient for fuel system	0.02
SKWF	fraction of total theoretical wing volume used for wing fuel	0.43
LCWING	program computes fwd and aft c.g. limits and sizes canard and, or horizontal and vertical tail for stability and control	2
DELWST	incremental structural weight [lb]	0
WPLX	design payload [lb] (default function of passenger number)	0
WFEX	fixed equipment weight [lb] (computed by program)	0
WFUL	fixed useful load weight [lb] (computed by program)	0
WENG	dry weight of one engine, function of engine size [lb]	0
SWSLS	engine specific weight [lb/lb _{Thrust}]	0.16
WNAC	weight of one nacelle, function of engine size [lb]	0
UWNAC	nacelle weight to nacelle surface area ratio [lb/sqft]	2.287
WPYLON	weight of one pylon, function of engine size [lb]	0
FPYL	factor for turbofan engine pylon weight	0.7
XLQDE	nacelle length to diameter ratio	3

Stability and Control (Canard and/or Tail Sizing)

<i>K</i> Fixd	<i>controls free (0) or controls locked (1) (option)</i>	<i>1</i>
CMPLD	pitching moment coefficient about centre of gravity due to all engines during landing (direct thrust effect only)	0

STATIC	aircraft static margin, fraction of mac	0.1
RH	elevator chord to horizontal tail chord ratio	0.35
DEMAX	maximum up elevator deflection, negative for trailing edge up (degrees)	-25
EYET	tailplane incidence angle relative to fuselage horizontal datum line (degrees)	0
TP	vertical position of thrust line relative to c.g., positive for thrust below c.g.	0
CXA	distance of main wheel contact point aft of mac leading edge, fraction of mac	0.52
HWING	low wing position on fuselage	0
CNPAC	required directional stability of aircraft, function of take-off gross weight and wing span [degree ⁻¹]	0.002
RV	rudder chord to vertical tail chord	0.30
RVMCS	ratio of minimum control speed to stall speed in take-off configuration	0.99
DRMAX	maximum rudder deflection [degrees]	25
<i>rc</i>	<i>canardvator chord to canard chord ratio</i>	0.35
<i>dcmcpj</i>	<i>jet-flow inclination contribution to the aircraft longitudinal static stability</i>	0.03
CMFLPL	wing pitching moment coefficient about c.g., landing flaps (function of flap deflection, computed by program)	999
CMFLPT	wing pitching moment coefficient about c.g., take-off flaps (function of flap deflection, computed by program)	999
CHALF	two dimensional variation of elevator hinge moment coefficient with angle of attack (computed by program)	999
CHDEL	two dimensional variation of elevator hinge moment coefficient with elevator deflection (computed by program)	999
TAUH	elevator effectiveness (computed by program)	999
TAUV	rudder effectiveness (computed by program)	999
ZCG	height above runway of c.g. at nose wheel lift off [ft] (computed by program)	999
DCMCLP	direct thrust engine stability term (computed by program)	9999
ARVTE	vertical tail effective aspect ratio (computed by program)	-1.0
Performance		
Taxi		
DELTT	time spent taxiing before take-off and after landing [hr]	0.1666
Take-off		
IFLY	program computes full mission (option)	1
NFAIL	program computes engine-out and acceleration/stop distance (option)	0
THEMAX	maximum allowable fuselage floor angle [degrees]	15
H00	altitude at start of mission [ft]	5000
XLFMAX	maximum load factor during take-off rotation	1.1

DELTVR	estimate of time required to rotate aircraft during take-off [sec]	3.5
DV1	increment of engine failure decision speed above stall [kt]	5
DVR	increment of take-off rotation speed above engine failure decision speed [kt]	5
VRAT	ratio of allowable lift-off speed to stall speed	1.1
UM	coefficient of rolling friction	0.02
MUB	coefficient of braking friction	0.4
TDELTX	increment in take-off ambient temperature above ISA standard day [degree F]	36
HTMAX	terminal altitude for take-off segment [ft]	500
 Climb		
ICLM	climb at maximum rate of climb (option)	1
DELH	altitude increment during climb [ft]	1000
 Cruise		
ICRUS	cruise flown at speed at normal rated cruise power, for cost and range calculation (option)	1
ISWING	hold wing loading fixed during range balance (option)	0
FRESF	required fuel reserve, fraction of 45 min	1
RCRRQ	required design range [NM]	1250
OFALT	off-design mission altitude [ft]	25000
OFEM	off-design specified Mach number	0.5
FACW1	maximum take-off gross weight scale factor for range balance iterations (default function of gross weight and range)	0.80
 Landing		
IWLD	landing weight as a fraction of gross weight (option)	2
TDELLD	increment in landing ambient temperature above ISA standard day (degree F)	36
TDELAY	time delay for brake and reverse thrust application during landing (sec)	1
HTG	wing height above ground during ground run (ft)	5.5
XLDGRQ	required landing distance (not constrained)	99999
ALTLND	altitude of landing field (ft)	5000
WLPCT	ratio of landing weight to maximum take-off gross weight	0.94
VRATT	ratio of approach speed to stall speed	1.3
RSMX	maximum allowable rate of sink during approach [ft/min]	1000
TROTID	ratio of reverse thrust to idle thrust during landing	0
VTDRAT	ratio of touchdown speed to stall speed	1.15
HAPP	obstacle height (ft)	50
SINKTD	landing touchdown sink rate (ft/sec)	3
XLFMX	landing flare load factor	1.2

Costs

NCADE	additional equipment cost as a function of base cost (option)	1
CLIAB	year of cost calculation	1993
HRI	cost of avionic equipment (US\$)	4.E06
TBO	aircraft utilization per year (hr/annum)	3200
FCSF	fuel cost (US\$/US gallon)	0.85
HIR	insurance as a fraction of flyaway price per annum	0.005
TR	maintenance burden factor	2
PRV	aircraft residual value as a fraction of initial value	0.10
DYR	aircraft depreciation period [years]	15
OHR	production quantity	500
CRWOH	maintenance labour cost (US\$/man-hour)	23
CINP	annual average inflation rate	0.08

Note: The GASP Input Data templates show some variables that are not employed in the present computations. They consist of parameters with default values that relate to program or configuration options not used in the present work. So, they are not reproduced in the variable list.

APPENDIX I

Validation of the Design Model

Introduction

In this Appendix, validation of the GASP design model is demonstrated for two conventional aircraft configurations.

For the purpose, two actual aircraft were chosen, a similar size aircraft as represented by the Canadair Regional Jet 100, and the Fokker 100. The latter one would require additional tabulation of the Rolls-Royce Tay engine performance data, since this powerplant is not considered in the GASP Propulsion module. This module, however, incorporates other powerplant performance data which include the Garrett TFE 731-2 turbo-fan. This engine powers the Learjet 35A business aircraft, thus making GASP readily suitable for the design synthesis of the corporate aircraft. As a result, this one was used in place of the Fokker aeroplane.

Figures I1 and I2 show the detailed output results for both aircraft, RJ 100 and Learjet 35A, as were modelled by the GASP program. Tables I1 and I2 present a summary of the main characteristics together with the actual values, compiled from "Jane's All The World Aircraft", and show the model accuracy. Figures I3 and I4 illustrate the aircraft geometries corresponding to the present results.

Note that the computed Maximum Take-off Weights are within 7% of those of the actual aircraft using similar requirements, geometric parameters and wing loadings. Although the overall results show slightly over-powered designs, with slightly increased tail areas, when compared with the real aircraft, GASP model accuracy may be considered good for initial conceptual design work.

For the purposes of the present research work where different concepts are compared, using the same assumptions, design criteria and analysis methods, relative trade-offs and trends are more important issues than the absolute precision of a given performance index. These relative differences are usually much more accurate and meaningful, providing sufficient detail is embodied in the methods and that they are used within their range of validity. Only then, will the changes correctly reflect in the results. This is especially true of GASP where the analysis modules are considerably detailed, thus producing reasonably good answers to comparative performance and economic assessments, trade-off and sensitivity studies of conventional configurations¹¹.

References:

- I1. Galloway, T.L.; Hague, D.S. and al
GASP - General Aviation Synthesis Program
NASA CR-152303, Jan 1978

	GASP Results	Actual Values (*)	Accuracy [%]
Fuselage Length	80.0	80.0	0
Wing Area	547.2	587.1	-6.8
Wing Aspect Ratio	8.85	8.85	0
Tailplane Area	132.4	101.6	30.3
Fin Area	118.3	98.8	19.7
Engine Max. St. T/O Thrust	9241.9	9220.0	0.2
M.T.O.W.	44222	47450	-6.8
O.E.W.	27245	30100	-9.5
E.W.	26157	29180	-10.4
Fuel Weight	6976		
Wing Fuel Volume	1439.4	1400.0	2.8
Maximum Fuel Weight	9625	9380	2.6
T/O Wing Loading	80.82	80.82	0
T/O Thrust to Weight Ratio	0.418	0.389	7.5
Cruise Mach No.	0.81	0.74	9.5
Cruise Speed (TAS)	465.9	424.0	9.5
Cruise Height	37000	37000	0
Approach Speed (TAS)	133.83	137.0	-2.3
T/O Flap (angle/CLmax)	15/2.093	15/	
Landing Flap (angle/CLmax)	45/2.537	45/	
FAR 25 T/O Field Length	5198	5265 (S/L,ISA)	
FAR 25 Land. Field Length	4714	4725 (S/L,ISA)	
Mission Range	983.09	980.0	0.3

(*) source: Jane's All The World Aircraft

Table II - GASP Validation for Canadair Regional Jet 100

		GASP Results	Actual Values (*)	Accuracy [%]
Fuselage Length	ft	43.7	45.8	-4.6
Wing Area	sqft	241.8	253.3	-4.6
Wing Aspect Ratio		5.74	5.74	0
Tailplane Area	sqft	71.3	54.0	32.0
Fin Area	sqft	51.3	37.37	37.3
Engine Max. St. T/O Thrust	lb	3968.2	3500.0	13.4
M.T.O.W.	lb	17457	18300	-4.6
O.E.W.	lb	10411		
E.W.	lb	9850	10119	-2.7
Fuel Weight	lb	5447		
T/O Wing Loading	lb/sq ft	72.2	72.2	0
T/O Thrust to Weight Ratio		0.455	0.383	18.8
Cruise Mach No.		0.81	0.73	10.7
Cruise Speed (TAS)	kt	463.3	418.0	10.7
Cruise Height	ft	45000	45000	0
Landing Stall Speed (TAS)	kt	105.5	96.0	9.9
T/O Flap (angle/CLmax)		20/1.447	20/	
Landing Flap (angle/CLmax)		40/1.599	40/	
FAR 25 Balanced Field Length	ft	6765.9	4972 (S/LISA)	
FAR 25 Land. Field Length	ft	5978.0	3075 (S/LISA)	
Mission Range	nm	1913	2196 (with 4 pax)	

1 50 PAX TURBOPAN AIRLINER USING SCALED GE CF-34 - CANADAIR RJ 100
 0 ENGINE CYCLE IS G. E. CF-34

INPUT DATA FOLLOW

```

0
0 CONFIG WG = 44050.          *****GEOMETRY*****
      WGS = 80.820          KWRITE = 2          FUSEL SAB = 4.          ELODN = 1.000
      PAX = 50.             IGEAR = 0          WS = 19.000          ELODT = 3.200
      ENCRU = 0.740        KCONFG = 0          AS = 1.             BMLOD = 14.500
      HNCRU = 37000.       KTIPI = 0          WAS = 18.000        NACELLE KNAC = 1
      Kanard = 0           ENP = 2.           PS = 31.0           ELN = 0.000
      KRELOT = 1          NTYE = 7          HPC = 13.720        DBARN = 0.000
      KWRITE = 2          KRELOT = 1          HCK = 2.470         ELRW = 10.000

0 WING TCT = 0.100          HORIZ VBARHX = 0.0000    VERT VBARVZ = 0.0000    Canard TCcan = 0.100
      TCR = 0.132          TAIL TCHT = 0.100      TAIL TCVT = 0.120     ARcan = 5.500
      AR = 8.850           ARMT = 4.069         ARVT = 1.050         SLMcan = 0.500
      SLM = 0.250          SLMH = 0.530         SLMV = 0.679         DwpqCa = 15.000
      DLNCA = 24.750       DMPCCH = 30.000      DMPCCV = 43.000     EYEcan = 2.000
      EYEW = 2.000        COELTH = 0.000      BOELTV = 0.000      SWCOSW = 0.145
      SAH = 1.000

0
0 CKW = -1.000          ***AERODYNAMICS***          GRPE = 0.000          DCDSE = -1.0000
      CFP = -1.000        CKHT = -1.000          SCFAC = 0.750         CKMc = -1.0000
      CKN = -1.000        CKPT = -1.000          DLSWSW = 0.300        cmawc = -0.060
      CFVT = -1.000       DELCD = 0.00150       ALPHLO = -1.600      alzero = -1.000
      DELFE = 0.200

0
0 KWCD = 12
      ACLS = -1.000       -0.600 -0.400 -0.200 0.000 0.100 0.200 0.400 0.600 0.800 1.000 1.200
      ACCDDR = 2.400     1.466 1.221 1.066 1.005 1.000 1.005 1.046 1.138 1.333 1.743 2.718

0
0 RCLMAX = 1.200          *HIGH LIFT DEVICES*          LED CLEOC = 0.000
      AITFLP = 5000.       FLAPS JFLTYP = 7          DELEED = 0.000
      FLAPW = 2.           DFLETO = 15.000         DCLMLE = 0.830
      WCFLAP = -1.000     DFPLD = 45.000         DELLEO = 45.000
      BENG09 = 0.000      CFOC = 0.300           BTEOB = 0.560
      DCLMTE = 0.000      DCDOYE = 0.000         DELTEO = 0.000

0
0 JENGSZ = 2             ***PROPULSION***          ACCRU = 200.000        RWCRIZ = 0.970
      IPART = 1            HPORT = 5000.          ITCRQ = 99999.        HSCREQ = 0.
      KODETO = 5           KODECL = 7             SMLD = 0.500          THIN = 0.
      KODETR = 5           KODEAC = 5             HBTFF = 0.437        PR = 1.000

0
0 SKPEI = 0.1350         *****WEIGHTS*****          SKB = 107.000         SKFS = 0.0200
      SKLG = 0.0380        SKZ = 0.2200           SKCC = 20.000         SKWF = 0.4300
      SKMG = 0.8000        SKTL = 1.0000         SKFW = 0.4300         SKFT = 0.8790
      SKPES = 0.3380       SKWV = 133.400        SKSAS = 0.000         SKMTP = 1.8900
      WPLX = 0.0           YMG = 0.1500          EGMGRN = 0.0000      LCWING = 2
      WPEI = 0.0           RELP = 0.7350         CFNRGN = 0.2000      LDCRFX = 8.000
      WPUL = 0.0           RELR = 0.4500         STNRGN = 0.0000     ATWIOC = 3.160
      UWPAX = 200.0        CATD = 3.             DELP = 8.300         DELWST = 0.0
      STRUT = 0.0000       VMLFSL = 685.0        YP = 0.0000
      DELWFC = 0.0         WNAC = 0.0            WFLON = 0.0          XLQDE = 3.000
      WENG = 0.0           UWNAC = 2.287         FFXL = 0.700
      SWSLS = 0.160

0
0 KSFIXD = 1             *STABILITY AND CONTROL*          ZCG = 999.000         CNPAC = 0.0020
      CMFLPL = 999.000     CHALF = 999.000        TP = 0.0             ARVTE = -1.000
      CMFLPT = 999.000     CHDEL = 999.000       CXA = 0.700          RV = 0.300
      CMPLD = 0.000        RH = 1.000            DCMCLP = 9999.000    TAUV = 999.000
      DEMAX = -25.0        EYET = 0.0           HWING = 0.           RWMS = 0.990
      EYET = 0.0          TAUH = 999.000       dcmcpi = 0.030      DRMAX = 25.0
      rc = 0.350

0,
0 TAXI DELTT = 0.167     ***PERFORMANCE***          DVR = 5.000           TDELTX = 36.000
      TO IFLY = 1         ILFMAX = 1.100         UM = 0.020           HTMAX = 500.000
      THEMAY = 15.000     DELTVR = 3.500        MUB = 0.400          HFAIL = 0
      H00 = 5000.         DVI = 5.000           WTHISN = 0.
      VRAT = 1.10

0 CLIMB ICLM = 1         CRUISE CRMACH = 0.000     PRESF = 1.000         FACW1 = 0.800
      DELH = 1000.        CREALT = 0.           RCRAQ = 980.0        ISWING = 0
      VCLMB = 0.0         ICRUS = 1             OFALT = 25000.       OFEN = 0.500
0 LAND IWLD = 2          XLDGRQ = 99999.        VRATT = 1.300        HAPP = 50.
      TDELLD = 36.0       ALTLDN = 5000.        RSMX = 1000.         SINKTD = 3.0
      TDELAY = 1.0        WLPCT = 0.9062       TROTID = 0.000      ILPMX = 1.200
      HTG = 5.5          TIDLE = 0.0          VTRAT = 1.1

0
0 NCADE = 1             *****COST*****          RI = 0.300            CMV = 0.800
      CLZAB = 1993.0       TR = 2.000            CHR = 500.000         CCRW = 0.
      HRI = 4000000.       PRV = 0.100           CRWOM = 23.000        UCSENG = 0.000
      CMP = 0.2            DFR = 15.0            CINP = 0.             UCSFP = 0.000
      TBO = 3200.0        SRPM = 0.0            CP = 0.               ALR = 3.400
      PCSF = 0.850
    
```

1
 0++++ H.TAIL C.L. CHORD MUST = 7.827 TO BE LOCATED AT SPECIFIED POSITION ON VERTICAL++++
 +++++ H.TAIL TAPER CHANGED TO 0.9262

Fig 11 - Canadair Regional Jet 100 GASP result

```

*****
ITERATION TO BALANCE RANGE
RANGE ERROR, RANGE ERROR MINUS 1 1.2560 -0.0199
GROSS WGT, GROSS WGT MINUS1 44221.6 55062.5

0 *****
0 FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
      CLMAX      VSTALL,KTS  FLAP ANGLE  LE ANGLE  DELTA CL  DELTA CD
FLAPS UP      1.3235      144.8      0.0      0.0      0.0000  0.0000
T.O. CONFIG   2.0934      115.1     15.0     0.0     0.7700  0.0336
LDG. CONFIG   2.5369      104.6     45.0     0.0     1.2189  0.1790

0 DOUBLE SLOTTED POWLER FLAPS
      DEFL AT OPT  DELCL AT OPT  DELCD AT OPT  AREA(FT2)  WEIGHT(LB)
FLAPS      30.0      2.2500      0.1500      89.7      424.5
0 *****
0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK(DEGREES)= 2.805  LIFT= 42894.9  L/D= 14.152  ALTITUDE= 37000.0  MACH= 0.7400

1 ENGINE SIZING DATA FOLLOW
*****
0VSTLKT= 106.7 KTS EAS VRAT= 1.100 CLTO= 1.7301
VEND = 234.2 KNOTS EAS
0
ROTATION (TIME= 24.4 AND TAS= 130.1 EAS= 116.7)
LIFTOFF (TIME= 26.6 DIST= 3372.3 TAS= 139.1 EAS= 124.8)
DISTANCE TO 35 FT.= 4682.3 TAS= 154.4 EAS= 138.4 V35/V3= 1.2969
GEAR RETRACTION STARTED AT 32.8 SEC, COMPLETE AT 39.8 SEC
FLAP RETRACTION STARTED AT 42.9 SEC, COMPLETE AT 47.4 SEC
0VSTLKT= 106.7 KTS EAS VRAT= 1.100 CLTO= 1.7301
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 199.2 KNOTS EAS
ENGINE FAILURE (TIME= 23.1 AND TAS= 124.5 EAS= 111.7)
0
ROTATION (TIME= 26.3 AND TAS= 130.1 EAS= 116.7)
LIFTOFF (TIME= 29.4 DIST= 3973.8 TAS= 134.1 EAS= 120.3)
DISTANCE TO 35 FT.= 5379.4 TAS= 136.0 EAS= 121.9 V35/V3= 1.1427

ACCELFRATE - STOP DISTANCE = 5668.9 FEET.
0 ENGINE OUT DISTANCE TO 35 FT. = 5379.4 FEET
OALL ENGINE DISTANCE TO 35 FT. (L) = 4682.3 FEET
PAR 25 T.O. DISTANCE (1.15XL) = 5384.7 FEET
ALL ENGINE DISTANCE TO 50 FT. = 4919.5 FEET
0 AT END OF TAKEOFF PHASE
TIME= 0.012 HRS FUEL USED= 71. LBS WEIGHT= 44151. LBS ALT.= 5500. FT.
STAKE OFF RATE OF CLIMB REQUIREMENTS - PAR PART 25
AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION      ALT (FT)      VS KEAS      V/V3      V KTAS      GRAD (PCT)      R/C (FPM)      REQ. R/C (FPM)      CL      L/D
1ST SEG:T.O. FLAPS+LD GEAR EXT - ONE ENG OUT 5000. 106.8 1.1310 134.7 2.660 362.71 1.00 1.643 8.828
2ND SEG: T.O. FLAPS - ONE ENGINE OUT 5250. 106.8 1.2000 143.5 4.557 661.69 348.51 1.460 10.859
FINAL T.O. CRUISE CONFIG - ONE ENG OUT 6500. 134.4 1.2500 191.7 5.505 1067.80 232.74 0.951 14.111
APPROACH FLAPS -ONE ENG OUT 5000. 106.6 1.3997 166.4 5.011 844.02 353.68 1.077 11.919
LANDING FLAPS - ALL ENGINES 5000. 97.1 1.3000 140.7 10.855 1545.27 455.54 1.507 5.915

APPROACH FLAP SETTING = 15.5 DEG.

+++ ENGINE-OUT SERVICE CEILING = 25080.3 FT.
BEST RATE OF CLIMB SPEED = 265.5 KTAS
ENGINE-OUT RATE OF CLIMB = 49.8 FPM
WEIGHT AT ALTITUDE = 42452.7 LBS

0 *****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES*****

0PROPULSION SYSTEM WEIGHTS
ENGINE WEIGHT/ENGINE 1426.7
NACELLE WEIGHT/ENGINE 320.9
FYLON WEIGHT/ENGINE 170.4
PROP OR QFAN 0.0
GEARBOX 0.0
SHROUD 0.0

ENGINE POD DIMENSIONS
ENGINE FACE DIAMETER(FT) 3.86
NACELLE LENGTH(FT) 11.58

0VSTLKT= 106.7 KTS EAS VRAT= 1.100 CLTO= 1.7301
VEND = 234.2 KNOTS EAS
0
ROTATION (TIME= 23.4 AND TAS= 130.1 EAS= 116.7)
LIFTOFF (TIME= 25.8 DIST= 3294.3 TAS= 140.1 EAS= 125.6)
DISTANCE TO 35 FT.= 4534.7 TAS= 155.0 EAS= 139.0 V35/V3= 1.3028
GEAR RETRACTION STARTED AT 31.7 SEC, COMPLETE AT 38.7 SEC
FLAP RETRACTION STARTED AT 41.7 SEC, COMPLETE AT 46.2 SEC
0VSTLKT= 106.7 KTS EAS VRAT= 1.100 CLTO= 1.7301
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 197.1 KNOTS EAS
ENGINE FAILURE (TIME= 22.2 AND TAS= 124.5 EAS= 111.7)
0
ROTATION (TIME= 25.4 AND TAS= 130.1 EAS= 116.7)
LIFTOFF (TIME= 28.4 DIST= 3848.5 TAS= 134.4 EAS= 120.6)
DISTANCE TO 35 FT.= 5188.1 TAS= 136.6 EAS= 122.4 V35/V3= 1.1474

ACCELERATE - STOP DISTANCE = 5571.7 FEET.
0 ENGINE OUT DISTANCE TO 35 FT. = 5188.1 FEET
OALL ENGINE DISTANCE TO 35 FT. (L) = 4534.7 FEET
PAR 25 T.O. DISTANCE (1.15XL) = 5215.0 FEET
ALL ENGINE DISTANCE TO 50 FT. = 4771.2 FEET
0 AT END OF TAKEOFF PHASE
TIME= 0.012 HRS FUEL USED= 71. LBS WEIGHT= 44150. LBS ALT.= 5500. FT.

```

Fig II - Canadair Regional Jet 100 GASP result (continued)

OTAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	VS KEAS	V/VS	V KTAS	GRAD (PCT)	R/C (PPM)	REQ. R/C (PPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	106.8	1.1310	134.7	2.924	398.62	1.00	1.643	8.640
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	106.8	1.2000	143.5	4.800	696.97	348.51	1.460	10.563
FINAL T.O. CRUISE COMFIG - ONE ENG OUT	6500.	134.4	1.2500	181.7	5.595	1085.23	232.74	0.851	13.413
APPROACH FLAPS -ONE ENG OUT	5000.	106.6	1.3997	166.4	5.189	873.93	353.68	1.077	11.493
LANDING FLAPS - ALL ENGINES	5000.	97.1	1.3000	140.7	11.782	1677.22	453.34	1.307	5.886

APPROACH FLAP SETTING = 15.5 DEG.

+++ ENGINE-OUT SERVICE CEILING = 25443.8 FT.
 BEST RATE OF CLIMB SPEED = 263.4 KTAS
 ENGINE-OUT RATE OF CLIMB = 49.9 PPM
 WEIGHT AT ALTITUDE = 42452.7 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 362.43

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R;ALT= 5000.) SLS AIRFLOW= 362.43

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 9241.9 LBS

PROPULSION SYSTEM WEIGHTS

ENGINE WEIGHT/ENGINE	1478.7
NACELLE WEIGHT/ENGINE	320.9
PYLON WEIGHT/ENGINE	174.1
PROP OR QPAN	0.0
GEARBOX	0.0
SHROUD	0.0

ENGINE POD DIMENSIONS

ENGINE FACE DIAMETER(FT)	3.86
NACELLE LENGTH(FT)	11.58

.....0.....

Fig 11 - Canadair Regional Jet 100 GASP result (continued)

---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---

	MOST FWD LOAD		MOST APT LOAD		DESIGN LOAD	
	WT	CG	WT	CG	WT	CG
A/C OWE	27245.11	45.16	27245.11	45.16	27245.11	45.16
PAX	6120.00		2040.00		8500.00	
BAGGAGE	0.00	58.67	1500.00	58.67	1500.00	58.67
WING FUEL	1395.30	49.20	9625.40	49.20	6976.49	49.20
TIP FUEL	0.00	0.00	0.00	0.00	0.00	0.00
FUS FUEL	0.00	49.20	0.00	49.20	0.00	49.20
TOTAL	34760.41	43.03	40410.51	46.88	44221.59	45.03

0 ---TAIL SIZING SUMMARY---

Static Longitudinal Stability, Stick-fixed, considered

CONDITION	ALPHA	WING		CANARD		TAIL		DOWN WASH	FLAP CM
		CL	CLA	Cmac	ALPHA	CLA	CLA		
CRUISE	2.9416	0.4643	0.1023-0.0600	0.0000	0.0000	0.0729	1.0000		
LIPTOFF	2.0000	1.0856	0.0671-0.0600	0.0000	0.0000	0.0631	1.0000	0.3248-0.1031	
LANDING	14.5325	2.5369	0.0817-0.0600	0.0000	0.0000	0.0631	1.0000	2.3601-0.2081	

CONDITION	--FUSELAGE--		---NACELLE---		-----POWER-----				L.GEAR ROT.POWER		
	DCM	CM	DCM	CM	DCMth	DCMfine	CMth	CMfine	CT	CM	CM
CRUISE	0.4475		0.0907		0.0000	0.0300			0.0000		
LIPTOFF	0.6822	0.0000	0.0907	0.0000			0.0000	0.0326	0.0000-1.4763	4.3412	
LANDING	0.5604	0.5737	0.0907	0.0929			0.0000	0.0761			

0 ELEVATOR PARAMETERS
 CMDELTA(CONTROL POWER) = -0.06820 WING DE/DALPHA = 0.32481
 TAUM(EFFECTIVENESS) = 1.00000
 DEMAX(MAX.ELEVATOR DEFLEC.) = -25.00000

	FRACTION	STATION (DATUM NOSE)	HORIZONTAL TAIL SIZES	
			MAC	
NEUTRAL POINT	0.2016	47.430	STATIC STABILITY AND LANDING TRIM	132.3745
STATIC MARGIN	0.1000		STATIC STABILITY AND LIPTOFF ROT.	88.6605
AFT CG LIMIT(STABILITY)	0.1016	46.549		
CG RANGE(LOADING)	0.4372		REQUIRED TAIL SIZE	132.3745
FWD CG LIMIT(CONTROL)	-0.3357	42.775	TAIL ARM(ELTN)	38.0349

0 VERTICAL TAIL AREA = 118.2915 FOR DIRECTIONAL STABILITY OF 0.00200
 0 RUDDER POWER AT MAX.DEFL.= 0.0184 PER DEG. RUDDER CL AT MAX.DEFL.= 0.4590
 0 VERTICAL TAIL AREA= 98.3197 FOR MINIMUM CONTROL SPEED = 105.63 KTS
 0 REQUIRED VERTICAL TAIL AREA = 118.2915 TAIL ARM(ELTV) = 27.2696

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
 ANGLE OF ATTACK(DEGREES)= 2.805 LIPT= 42894.9 L/D= 13.638 ALTITUDE= 37000.0 MACN= 0.7400

0 WING LOCATION INFO.					
FUSELAGE LENGTH =	80.00	H-TAIL VOL. ARM =	38.03	C.G.LOCATION OF PROPULSION=	60.40
WING 1/4C LOC.ON C.L.=	41.69	H-TAIL C.G.LOCATION =	86.60	C.G.OF REMAINING WEIGHT =	36.00
MAC 1/4C LOCATION =	48.11	H-TAIL MAC FROM C.L. =	5.73		
MAC DIST.FROM C.L. =	13.92	H-TAIL LOCAT ON VERT.=	1.00		
WING C.G.LOCATION =	49.87	V-TAIL VOL. ARM =	27.27		
TIP TANKS C.G.LOCATE =	0.00	V-TAIL C.G.LOCATION =	76.24	DIST.L.E.VERT. TO L.E.HORZ.=	2.66

	WING	H-TAIL	V-TAIL
AREA	547.161	132.374	118.291
SPAN	69.587	23.208	11.145
ASPECT RATIO	8.850	4.069	1.050
TAPER RATIO	0.230	0.926	0.679
1/4C. SWEEP	24.750	30.000	43.000
L.E. SWEEP	27.870	30.402	45.666
C.L. CHORD	12.581	5.922	12.643
MEAN CHORD	8.807	5.707	10.743
TIP CHORD	3.145	5.485	8.585

Fig 11 - Canadair Regional Jet 100 GASP result (continued)

MISSION PERFORMANCE DATA FOLLOWS

0 TAXI AT IDLE THRUST

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	FUEL FLOW (LB/HR)
0.000	0.	0.	44222.	5000.	845.
0.167	0.	141.	44081.	5000.	845.

OVSTLKT= 106.5 KTS EAS VRAT= 1.100 CLTO= 1.7301
 VEND = 234.1 KNOTS EAS
 (TEMP.= 537. DEG:STD.+36.)
 0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
0.0	0.0	140.7	44081.	5000.0	0.0	0.0	0.000	11.32	1.0836	0.0951	2.00	0.00	0.0	0.00	16391.	5837.	0.00
1.0	5.6	142.3	44079.	5000.0	6.7	6.0	0.010	11.16	1.0836	0.0951	2.00	0.00	0.0	0.00	16189.	5837.	0.00
2.0	22.5	143.9	44078.	5000.0	13.3	11.9	0.020	11.01	1.0837	0.0951	2.00	0.00	0.0	0.00	15991.	5838.	0.00
3.0	50.3	145.6	44076.	5000.0	19.7	17.7	0.029	10.85	1.0837	0.0951	2.00	0.00	0.0	0.00	15796.	5839.	0.00
4.0	89.1	147.2	44074.	5000.0	26.1	23.4	0.039	10.69	1.0838	0.0951	2.00	0.00	0.0	0.00	15604.	5840.	0.00
5.0	138.6	148.8	44073.	5000.0	32.4	29.1	0.048	10.52	1.0839	0.0951	2.00	0.00	0.0	0.00	15416.	5842.	0.00
6.0	198.6	150.4	44071.	5000.0	38.6	34.7	0.057	10.35	1.0840	0.0951	2.00	0.00	0.0	0.00	15231.	5844.	0.00
7.0	269.0	152.1	44070.	5000.0	44.7	40.1	0.066	10.18	1.0841	0.0952	2.00	0.00	0.0	0.00	15048.	5846.	0.00
8.0	349.7	153.7	44068.	5000.0	50.7	45.5	0.075	10.00	1.0842	0.0952	2.00	0.00	0.0	0.00	14869.	5848.	0.00
9.0	440.3	155.3	44066.	5000.0	56.6	50.8	0.084	9.82	1.0843	0.0952	2.00	0.00	0.0	0.00	14693.	5851.	0.00
10.0	540.9	156.9	44065.	5000.0	62.4	56.0	0.093	9.64	1.0845	0.0952	2.00	0.00	0.0	0.00	14520.	5853.	0.00
11.0	651.1	158.6	44063.	5000.0	68.1	61.1	0.101	9.46	1.0847	0.0952	2.00	0.00	0.0	0.00	14355.	5856.	0.00
12.0	770.8	160.2	44061.	5000.0	73.7	66.1	0.109	9.31	1.0849	0.0952	2.00	0.00	0.0	0.00	14227.	5859.	0.00
13.0	899.8	161.8	44060.	5000.0	79.1	71.0	0.117	9.15	1.0851	0.0952	2.00	0.00	0.0	0.00	14100.	5862.	0.00
14.0	1038.0	163.4	44058.	5000.0	84.5	75.8	0.125	8.99	1.0853	0.0952	2.00	0.00	0.0	0.00	13976.	5865.	0.00
15.0	1185.3	165.1	44057.	5000.0	89.8	80.6	0.133	8.82	1.0855	0.0952	2.00	0.00	0.0	0.00	13854.	5869.	0.00
16.0	1341.4	166.7	44055.	5000.0	95.0	85.2	0.141	8.66	1.0857	0.0952	2.00	0.00	0.0	0.00	13734.	5872.	0.00
17.0	1506.2	168.3	44053.	5000.0	100.1	89.8	0.149	8.49	1.0859	0.0952	2.00	0.00	0.0	0.00	13617.	5876.	0.00
18.0	1679.5	170.0	44052.	5000.0	105.1	94.3	0.156	8.33	1.0862	0.0952	2.00	0.00	0.0	0.00	13502.	5880.	0.00
19.0	1861.2	171.6	44050.	5000.0	110.0	98.7	0.163	8.16	1.0864	0.0952	2.00	0.00	0.0	0.00	13389.	5884.	0.00
20.0	2051.0	173.2	44048.	5000.0	114.8	103.0	0.170	7.99	1.0867	0.0953	2.00	0.00	0.0	0.00	13278.	5888.	0.00
21.0	2248.9	174.9	44047.	5000.0	119.5	107.2	0.177	7.83	1.0869	0.0953	2.00	0.00	0.0	0.00	13169.	5892.	0.00
22.0	2454.7	176.5	44045.	5000.0	124.1	111.4	0.184	7.66	1.0872	0.0953	2.00	0.00	0.0	0.00	13063.	5896.	0.00
23.0	2668.2	178.2	44043.	5000.0	128.6	115.4	0.191	7.49	1.0875	0.0953	2.00	0.00	0.0	0.00	12959.	5900.	0.00

ROTATION (TIME= 23.3 AND TAS= 129.9 EAS= 116.5)

24.0	2889.1	179.8	44042.	5000.0	133.0	119.3	0.197	7.28	1.1814	0.0999	3.11	0.00	0.0	0.71	12857.	5905.	1.11
25.0	3117.4	181.4	44040.	5000.0	137.3	123.1	0.204	6.95	1.3650	0.1113	5.33	0.00	0.0	0.88	12775.	5909.	3.33

LIFTOFF (TIME= 25.6 DIST= 3257.8 TAS= 139.7 EAS= 125.3)

26.0	3352.7	183.1	44039.	5000.1	141.3	126.7	0.210	6.47	1.5353	0.1251	7.48	0.08	20.8	1.05	12706.	5913.	5.56
27.0	3594.4	184.7	44037.	5001.7	144.9	130.0	0.215	5.87	1.5144	0.1269	7.18	0.75	192.1	1.09	12644.	5917.	5.92
28.0	3842.0	186.4	44035.	5006.5	148.2	133.0	0.220	5.21	1.4508	0.1301	6.38	1.47	384.7	1.09	12587.	5919.	5.84
29.0	4094.8	188.0	44034.	5014.6	151.2	135.6	0.224	4.56	1.4037	0.1339	5.88	2.18	581.4	1.10	12535.	5922.	6.05
30.0	4352.1	189.7	44032.	5025.9	153.7	137.9	0.228	4.02	1.3550	0.1341	5.38	2.88	781.6	1.10	12489.	5923.	6.23

DISTANCE TO 35 FT.= 4519.9 TAS= 155.2 EAS= 139.2 V05/V30= 1.3063

31.0	4613.2	191.3	44030.	5040.6	156.0	139.9	0.232	3.54	1.3172	0.1327	4.98	3.55	980.0	1.10	12447.	5924.	6.53
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GEAR RETRACTION STARTED AT 31.5 SEC. COMPLETE AT 38.5 SEC

32.0	4877.8	192.9	44029.	5058.6	158.0	141.6	0.235	3.17	1.2819	0.1285	4.58	4.22	1179.4	1.09	12409.	5924.	6.80
33.0	5145.4	194.6	44027.	5079.9	159.8	143.2	0.237	2.84	1.2564	0.1231	4.28	4.88	1378.8	1.10	12374.	5923.	7.16
34.0	5415.5	196.2	44025.	5104.5	161.4	144.6	0.240	2.55	1.2315	0.1175	3.98	5.53	1577.1	1.10	12341.	5921.	7.51
35.0	5688.0	197.9	44024.	5132.5	162.9	145.8	0.242	2.28	1.2068	0.1118	3.68	6.17	1774.7	1.09	12310.	5919.	7.85
36.0	5962.4	199.5	44022.	5163.7	164.2	146.9	0.244	1.99	1.1904	0.1069	3.48	6.81	1973.7	1.09	12282.	5917.	8.29
37.0	6238.5	201.2	44020.	5198.2	165.3	147.8	0.246	1.73	1.1740	0.1020	3.28	7.44	2170.2	1.09	12255.	5914.	8.72
38.0	6516.0	202.8	44019.	5236.0	166.3	148.6	0.247	1.45	1.1659	0.0980	3.18	8.08	2366.7	1.10	12231.	5910.	9.25
39.0	6794.5	204.4	44017.	5277.1	167.1	149.2	0.248	1.17	1.1494	0.0946	2.98	8.69	2559.0	1.09	12208.	5905.	9.67
40.0	7073.7	206.1	44016.	5321.3	167.7	149.7	0.249	0.82	1.1412	0.0938	2.88	9.31	2747.6	1.10	12188.	5900.	10.18
41.0	7353.3	207.7	44014.	5368.7	168.1	149.9	0.250	0.48	1.1330	0.0931	2.78	9.92	2934.3	1.09	12171.	5894.	10.70

FLAP RETRACTION STARTED AT 41.6 SEC. COMPLETE AT 46.1 SEC

42.0	7632.8	209.4	44012.	5419.1	168.3	150.0	0.250	0.18	1.0859	0.0918	2.98	10.50	3108.3	1.05	12157.	5888.	11.48
43.0	7912.3	211.0	44011.	5471.2	168.4	150.0	0.250	0.13	0.9978	0.0925	3.98	10.55	3125.6	0.97	12144.	5881.	12.53

OVSTLKT= 106.5 KTS EAS VRAT= 1.100 CLTO= 1.7301

0 ENGINE OUT PERFORMANCE FOLLOWS
 VEND = 196.9 KNOTS EAS
 (TEMP.= 537. DEG:STD.+36.)
 0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
0.0	0.0	140.7	44081.	5000.0	0.0	0.0	0.000	11.32	1.0836	0.0951	2.00	0.00	0.0	0.00	16391.	5837.	0.00
1.0	5.6	142.3	44079.	5000.0	6.7	6.0	0.010	11.16	1.0836	0.0951	2.00	0.00	0.0	0.00	16189.	5837.	0.00
2.0	22.5	143.9	44078.	5000.0	13.3	11.9	0.020	11.01	1.0837	0.0951	2.00	0.00	0.0	0.00	15991.	5838.	0.00
3.0	50.3	145.6	44076.	5000.0	19.7	17.7	0.029	10.85	1.0837	0.0951	2.00	0.00	0.0	0.00	15796.	5839.	0.00
4.0	89.1	147.2	44074.	5000.0	26.1	23.4	0.039	10.69	1.0838	0.0951	2.00	0.00	0.0	0.00	15604.	5840.	0.00
5.0	138.6	148.8	44073.	5000.0	32.4	29.1	0.048	10.52	1.0839	0.0951	2.00	0.00	0.0	0.00	15416.	5842.	0.00
6.0	198.6	150.4	44071.	5000.0	38.6	34.7	0.057	10.35	1.0840	0.0951	2.00	0.00	0.0	0.00	15231.	5844.	0.00
7.0	269.0	152.1	44070.	5000.0	44.7	40.1	0.066	10.18	1.0841	0.0952	2.00	0.00	0.0	0.00	15048.	5846.	0.00
8.0	349.7	153.7	44068.	5000.0	50.7	45.5	0.075	10.00	1.0842	0.0952	2.00	0.00	0.0	0.00	14869.	5848.	0.00
9.0	440.3	155.3	44066.	5000.0	56.6	50.8	0.084	9.82	1.0843	0.0952	2.00	0.00	0.0	0.00	14693.	5851.	0.00
10.0	540.9	156.9	44065.	5000.0	62.4	56.0	0.093	9.64	1.0845	0.0952	2.00	0.00	0.0	0.00	14520.	5853.	0.00
11.0	651.1	158.6	44063.	5000.0	68.1	61.1	0.101	9.46	1.0847	0.0952	2.00	0.00	0.0	0.00	14355.	5856.	0.00
12.0	770.8	160.2	44061.	5000.0	73.7	66.1	0.109	9.31	1.0849	0.0952	2.00	0.00	0.0	0.00	14227.	5859.	0.00
13.0	899.8	161.8	44060.	5000.0	79.1	71.0	0.117	9.15	1.0851	0.0952	2.00	0.00	0.0	0.00	14100.	5862.	0.00
14.0	1038.0	163.4	44058.	5000.0	84.5	75.8	0.125	8.99	1.0853	0.0952	2.00	0.00	0.0	0.00	13976.	5865.	0.00
15.0	1185.3	165.1	44057.	5000.0	89.8	80.6	0.133	8.82	1.0855	0.0952	2.00	0.00	0.0	0.00	13854.	5869.	0.00
16.0	1341.4	166.7	44055.	5000.0	95.0	85.2	0.141	8.66	1.0857	0.0952	2.00	0.00	0.0	0.00	13734.	5872.	0.00
17.0	1506.2	168.3	44053.	5000.0	100.1	89.8	0.1										

33.0	4914.1	185.7	44036.	5024.6	136.3	122.2	0.202	0.01	1.5497	0.1633	7.75	2.29	552.9	0.99	6393.	2952.	8.04
34.0	5144.1	186.5	44035.	5032.6	136.3	122.2	0.202	0.00	1.5453	0.1683	7.75	2.20	530.3	0.99	6392.	2952.	7.95
DISTANCE TO 35 FT. = 5179.8 TAS = 136.3 EAS = 122.2 VS/VS = 1.1470																	
35.0	5374.1	187.3	44034.	5042.3	136.3	122.2	0.202	0.00	1.5510	0.1711	7.85	2.10	505.7	0.99	6391.	2951.	7.95
36.0	5604.2	188.2	44033.	5050.5	136.3	122.2	0.202	-0.01	1.5577	0.1733	7.95	2.03	488.2	1.00	6390.	2951.	7.97

ACCELERATE - STOP DISTANCE = 5556.7 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT. = 5179.8 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 4519.9 FEET
 PAR 25 T.O. DISTANCE (1.15XL) = 5197.9 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 4757.1 FEET
 0 AT END OF TAKEOFF PHASE
 TIME = 0.179 HRS FUEL USED = 212. LBS WEIGHT = 44010. LBS ALT. = 5500. FT.

ACCELERATE TO MACH NO. = 0.391

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
0.179	0.00	211.9	44010.	5500.	163.	150.	0.251	0.750	12418.	5793.
0.185	1.46	252.3	43969.	5500.	234.	234.	0.391	0.827	10860.	5933.

END OF ACCELERATION SEGMENT
 TIME = 0.185 HRS FUEL USED = 252.3 LBS WEIGHT = 43969. LBS RANGE = 1. NM

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ANGLE (DEG)	N/C (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
0.185	1.	252.	43969.	5500.	242.	223.	0.372	0.824	0.4718	0.0338	3.94	8.39	10.33	3577.	9529.	5230.
0.188	2.	264.	43957.	6000.	243.	222.	0.375	0.823	0.4731	0.0339	3.97	7.91	9.88	3387.	9443.	5180.
0.193	3.	290.	43932.	7000.	246.	221.	0.380	0.823	0.4794	0.0341	4.01	7.62	9.63	3298.	9253.	5076.
0.198	4.	316.	43906.	8000.	247.	219.	0.384	0.822	0.4872	0.0343	4.10	7.56	9.66	3298.	9077.	4970.
0.203	6.	341.	43881.	9000.	249.	218.	0.388	0.821	0.4954	0.0349	4.19	7.36	9.55	3234.	8900.	4865.
0.208	7.	366.	43856.	10000.	252.	217.	0.395	0.821	0.4986	0.0350	4.21	6.91	9.12	3073.	8701.	4763.
0.213	8.	392.	43830.	11000.	262.	222.	0.411	0.823	0.4769	0.0340	3.93	6.98	8.91	3226.	8427.	4660.
0.218	10.	416.	43806.	12000.	264.	220.	0.417	0.822	0.4832	0.0343	4.00	6.39	8.39	2984.	8253.	4555.
0.224	11.	441.	43781.	13000.	267.	219.	0.423	0.822	0.4893	0.0346	4.06	6.19	8.25	2917.	8080.	4453.
0.230	13.	467.	43755.	14000.	270.	218.	0.428	0.821	0.4955	0.0349	4.12	5.99	8.10	2850.	7908.	4354.
0.236	14.	492.	43730.	15000.	272.	217.	0.436	0.821	0.4977	0.0350	4.13	5.61	7.74	2708.	7725.	4259.
0.242	16.	518.	43703.	16000.	278.	217.	0.445	0.821	0.4970	0.0349	4.10	5.25	7.35	2377.	7517.	4154.
0.248	18.	545.	43677.	17000.	281.	216.	0.451	0.820	0.5037	0.0353	4.17	5.29	7.45	2620.	7331.	4048.
0.255	19.	571.	43651.	18000.	283.	214.	0.457	0.819	0.5106	0.0356	4.23	5.07	7.30	2537.	7148.	3944.
0.261	21.	597.	43625.	19000.	286.	213.	0.463	0.818	0.5177	0.0360	4.30	4.86	7.16	2454.	6968.	3843.
0.268	23.	623.	43599.	20000.	289.	211.	0.470	0.817	0.5249	0.0363	4.37	4.64	7.01	2371.	6791.	3743.
0.275	25.	649.	43572.	21000.	292.	210.	0.476	0.816	0.5322	0.0367	4.44	4.44	6.88	2288.	6617.	3646.
0.282	27.	676.	43546.	22000.	295.	208.	0.483	0.815	0.5397	0.0371	4.51	4.23	6.74	2205.	6446.	3550.
0.290	30.	703.	43519.	23000.	298.	207.	0.491	0.814	0.5463	0.0374	4.56	4.01	6.57	2109.	6275.	3457.
0.298	32.	730.	43492.	24000.	305.	208.	0.503	0.815	0.5415	0.0372	4.48	3.47	5.95	1867.	6076.	3377.
0.307	35.	760.	43466.	25000.	307.	206.	0.510	0.814	0.5508	0.0377	4.57	3.61	6.18	1961.	5900.	3293.
0.315	37.	788.	43434.	26000.	310.	204.	0.516	0.813	0.5605	0.0382	4.66	3.41	6.07	1867.	5728.	3209.
0.324	40.	817.	43405.	27000.	313.	202.	0.523	0.811	0.5702	0.0387	4.75	3.21	5.96	1773.	5560.	3127.
0.334	43.	846.	43376.	28000.	315.	201.	0.530	0.810	0.5801	0.0393	4.84	3.01	5.85	1680.	5394.	3046.
0.343	46.	876.	43345.	29000.	319.	199.	0.539	0.809	0.5868	0.0397	4.89	2.75	5.63	1551.	5229.	2968.
0.354	50.	908.	43313.	30000.	323.	198.	0.547	0.808	0.5950	0.0401	4.95	2.58	5.54	1474.	5068.	2890.
0.365	53.	941.	43281.	31000.	327.	197.	0.557	0.808	0.6010	0.0405	4.99	2.31	5.30	1338.	4874.	2793.
0.378	57.	976.	43246.	32000.	334.	198.	0.572	0.808	0.5963	0.0402	4.89	1.91	4.80	1131.	4672.	2705.
0.393	62.	1015.	43206.	33000.	355.	206.	0.609	0.814	0.5498	0.0376	4.27	1.21	3.48	758.	4449.	2638.
0.415	70.	1074.	43149.	34000.	363.	206.	0.626	0.815	0.5457	0.0374	4.17	1.42	3.59	909.	4292.	2554.
0.433	77.	1120.	43101.	35000.	371.	207.	0.643	0.815	0.5417	0.0372	4.07	1.23	3.31	809.	4135.	2474.
0.454	84.	1171.	43050.	36000.	376.	206.	0.655	0.814	0.5463	0.0374	4.08	1.16	3.24	773.	3980.	2394.
0.475	92.	1223.	42999.	37000.	380.	204.	0.662	0.813	0.5394	0.0381	4.19	1.05	3.23	706.	3827.	2322.

END OF CLIMB TO 37000. FT
 TIME = 0.475 HRS FUEL USED = 1223. LBS WEIGHT = 42999. LBS RANGE = 92. NM
 ALTITUDE = 37000. FT TAS = 465.92 KTS MACH NO = 0.8116

ACCELERATE TO MACH NO. = 0.740

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
0.475	92.44	1223.0	42999.	37000.	380.	203.	0.662	0.812	4059.	2609.
0.501	103.54	1296.2	42925.	37000.	425.	227.	0.740	0.826	4122.	2703.

END OF ACCELERATION SEGMENT
 TIME = 0.501 HRS FUEL USED = 1296.2 LBS WEIGHT = 42925. LBS RANGE = 104. NM

ACCELERATE TO MACH NO. = 0.812

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
0.475	92.44	1223.0	42999.	37000.	380.	203.	0.662	0.812	4059.	2609.
0.528	116.06	1372.3	42849.	37000.	466.	249.	0.812	0.835	4173.	2763.

END OF ACCELERATION SEGMENT
 TIME = 0.528 HRS FUEL USED = 1372.3 LBS WEIGHT = 42849. LBS RANGE = 116. NM

ACCELERATE TO MACH NO. = 0.752

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
0.475	92.44	1223.0	42999.	37000.	380.	203.	0.662	0.812	4059.	2609.
0.506	105.43	1308.0	42914.	37000.	432.	231.	0.752	0.828	4129.	2713.

TIME = 0.506 HRS FUEL USED = 1308.0 LBS WEIGHT = 42914. LBS RANGE = 105. NM

Fig II - Canadair Regional Jet 100 GASP result (continued)

DESIGN CASE
CRUISE PERFORMANCE SUMMARY
FOR
***** MAXIMUM FUEL *****
FUEL AVAILABLE= 9625.

		AT		AT		AT	
		SPECIFIED	SPEED	NORMAL	POWER	BEST SPEC.	RANGE
		START	END	START	END	START	END
		CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE
TIME	HRS.	0.501	4.092	0.528	3.301	0.506	4.010
RANGE	N.MI	104.	1629.	116.	1408.	103.	1619.
FUEL USED	LBS.	1296.	8136.	1372.	7284.	1308.	8112.
WEIGHT	LBS.	42925.	36086.	42849.	36938.	42914.	36110.
ALTITUDE	FT.	37000.	37000.	37000.	37000.	37000.	37000.
TAS	KTS.	424.8	424.8	465.9	465.9	431.9	431.9
EAS	KTS.	226.9	226.9	248.8	248.8	230.7	230.7
MACH NO.		0.7400	0.7400	0.8116	0.8116	0.7523	0.7523
DIV. MACH		0.8265	0.8355	0.8362	0.8441	0.8293	0.8371
ANGLE ATTACK DEG.		2.808	2.106	1.825	1.250	2.620	1.951
FUSE. ANGLE DEG.		0.808	0.106	-0.175	-0.750	0.620	-0.049
CL		0.4509	0.3791	0.3742	0.3114	0.4361	0.3670
L/D		13.642	12.579	12.679	11.339	13.492	12.387
FUEL FLOW	LB/HR	1986.3	1828.8	2194.6	2074.5	2018.2	1870.3
BREG. FACTOR	N.MI.	9187.	8388.	9103.	8301.	9190.	8344.
SPEC. RANGE	NM/LB	0.21389	0.23230	0.21231	0.22459	0.21401	0.23093

0 DESCENT FROM CRUISE AT NORMAL POWER CONDITION
(U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MMO OR VMO)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ANGLE (DEG)	R/S (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
3.312	1413.	7301.	36921.	37000.	466.	249.	0.812	0.843	0.3193	0.0281	1.32	-1.75	-2.42	1439.	2123.	1478.
3.324	1419.	7320.	36902.	36000.	466.	235.	0.812	0.845	0.3043	0.0276	1.19	-1.68	-2.50	1388.	2266.	1570.
3.337	1423.	7340.	36881.	35000.	468.	262.	0.812	0.847	0.2901	0.0272	1.05	-1.63	-2.57	1349.	2411.	1670.
3.349	1431.	7363.	36859.	34000.	470.	268.	0.812	0.848	0.2766	0.0268	0.93	-1.58	-2.63	1315.	2559.	1773.
3.362	1437.	7387.	36834.	33000.	473.	274.	0.812	0.850	0.2639	0.0265	0.81	-1.53	-2.72	1280.	2715.	1882.
3.376	1443.	7414.	36808.	32000.	475.	280.	0.812	0.852	0.2518	0.0262	0.70	-1.48	-2.78	1247.	2877.	1995.
3.390	1450.	7443.	36779.	31000.	477.	287.	0.812	0.853	0.2403	0.0259	0.60	-1.44	-2.84	1217.	3042.	2112.
3.404	1456.	7474.	36747.	30000.	479.	294.	0.812	0.854	0.2295	0.0257	0.50	-1.40	-2.90	1188.	3213.	2234.
3.418	1463.	7508.	36713.	29000.	481.	300.	0.812	0.856	0.2192	0.0255	0.41	-1.36	-2.96	1160.	3389.	2361.
3.433	1470.	7545.	36677.	28000.	483.	307.	0.812	0.857	0.2095	0.0253	0.32	-1.33	-3.01	1134.	3573.	2493.
3.448	1478.	7585.	36637.	27000.	485.	314.	0.812	0.858	0.2002	0.0251	0.23	-1.29	-3.06	1106.	3781.	2639.
3.463	1485.	7627.	36594.	26000.	487.	321.	0.812	0.859	0.1914	0.0249	0.15	-1.26	-3.11	1083.	3975.	2781.
3.479	1493.	7674.	36548.	25000.	489.	328.	0.812	0.860	0.1831	0.0248	0.08	-1.22	-3.15	1059.	4179.	2930.
3.495	1501.	7723.	36499.	24000.	491.	335.	0.812	0.861	0.1751	0.0246	0.00	-1.19	-3.19	1038.	4388.	3084.
3.511	1509.	7775.	36447.	23000.	488.	339.	0.802	0.862	0.1714	0.0246	-0.02	-1.18	-3.20	1017.	4601.	3241.
3.528	1517.	7829.	36393.	22000.	482.	341.	0.790	0.862	0.1691	0.0245	-0.02	-1.17	-3.19	997.	4822.	3401.
3.533	1519.	7832.	36390.	21000.	403.	290.	0.658	0.854	0.2326	0.0258	0.81	-4.81	-6.00	3428.	962.	691.
3.538	1521.	7836.	36386.	20000.	398.	291.	0.648	0.854	0.2301	0.0257	0.80	-4.80	-6.00	3381.	1003.	724.
3.543	1523.	7839.	36382.	19000.	394.	293.	0.638	0.855	0.2276	0.0256	0.79	-4.79	-6.00	3335.	1046.	758.
3.548	1525.	7844.	36378.	18000.	389.	294.	0.628	0.855	0.2251	0.0256	0.78	-4.78	-6.00	3289.	1090.	793.
3.553	1527.	7848.	36374.	17000.	385.	296.	0.619	0.855	0.2226	0.0255	0.76	-4.76	-6.00	3243.	1135.	829.
3.558	1529.	7852.	36369.	16000.	381.	298.	0.610	0.856	0.2201	0.0255	0.75	-4.75	-6.00	3199.	1182.	867.
3.563	1531.	7857.	36365.	15000.	377.	299.	0.601	0.856	0.2176	0.0254	0.73	-4.73	-6.00	3154.	1231.	906.
3.569	1533.	7862.	36360.	14000.	373.	301.	0.593	0.856	0.2151	0.0254	0.72	-4.72	-6.00	3111.	1281.	947.
3.574	1535.	7868.	36354.	13000.	369.	303.	0.584	0.857	0.2126	0.0253	0.70	-4.70	-6.00	3068.	1333.	989.
3.580	1537.	7873.	36348.	12000.	366.	305.	0.576	0.857	0.2101	0.0253	0.68	-4.68	-6.00	3026.	1387.	1033.
3.585	1539.	7879.	36342.	11000.	362.	306.	0.569	0.857	0.2076	0.0252	0.66	-4.66	-6.00	2984.	1443.	1078.
3.595	1542.	7887.	36335.	10000.	291.	250.	0.455	0.844	0.3122	0.0278	1.97	-3.33	-3.36	1712.	1121.	806.
3.605	1544.	7895.	36326.	9000.	286.	250.	0.446	0.844	0.3122	0.0278	1.98	-3.27	-3.29	1656.	1159.	836.
3.616	1547.	7905.	36317.	8000.	282.	250.	0.438	0.844	0.3121	0.0278	1.99	-3.21	-3.22	1599.	1198.	867.
3.626	1550.	7914.	36307.	7000.	277.	250.	0.430	0.844	0.3120	0.0278	2.00	-3.15	-3.15	1544.	1239.	899.
3.638	1553.	7925.	36297.	6000.	273.	250.	0.422	0.844	0.3119	0.0278	2.01	-3.08	-3.07	1489.	1281.	932.
3.649	1557.	7936.	36286.	5000.	269.	250.	0.414	0.844	0.3119	0.0278	2.01	-3.01	-3.00	1434.	1324.	966.
3.661	1560.	7948.	36274.	4000.	265.	250.	0.406	0.844	0.3118	0.0278	2.02	-2.94	-2.92	1380.	1368.	1002.
3.674	1563.	7961.	36261.	3000.	261.	250.	0.399	0.844	0.3117	0.0278	2.03	-2.87	-2.84	1327.	1414.	1038.
3.687	1566.	7975.	36247.	2000.	257.	250.	0.391	0.844	0.3116	0.0278	2.04	-2.80	-2.76	1273.	1461.	1076.
3.694	1568.	7982.	36239.	1500.	255.	250.	0.388	0.844	0.3114	0.0278	2.04	-2.76	-2.72	1247.	1486.	1096.

0 END OF DESCENT TO 1500. FT
TIME= 3.694 HRS FUEL USED= 7982. LBS WEIGHT= 36239. LBS RANGE= 1568. NM

0 RESERVE FUEL(LBS) 1490. 1646. 1514.
(45.0 MIN.)

ACCELERATE TO MACH NO. =0.740

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
0.475	92.44	1223.0	42999.	37000.	380.	203.	0.662	0.812	4059.	2609.
0.501	103.54	1296.2	42925.	37000.	425.	227.	0.740	0.826	4122.	2703.

END OF ACCELERATION SEGMENT
TIME= 0.501 HRS FUEL USED= 1296.2 LBS WEIGHT= 42925. LBS RANGE= 104. NM

ACCELERATE TO MACH NO. =0.812

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
0.475	92.44	1223.0	42999.	37000.	380.	203.	0.662	0.812	4059.	2609.
0.528	116.06	1372.3	42849.	37000.	466.	249.	0.812	0.833	4173.	2763.

END OF ACCELERATION SEGMENT
TIME= 0.528 HRS FUEL USED= 1372.3 LBS WEIGHT= 42849. LBS RANGE= 116. NM

ACCELERATE TO MACH NO. =0.752

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
0.475	92.44	1223.0	42999.	37000.	380.	203.	0.662	0.812	4059.	2609.
0.506	105.43	1308.0	42914.	37000.	432.	231.	0.752	0.828	4129.	2713.

END OF ACCELERATION SEGMENT
TIME= 0.506 HRS FUEL USED= 1308.0 LBS WEIGHT= 42914. LBS RANGE= 105. NM

Fig II - Canadair Regional Jet 100 GASP result (continued)

DESIGN CASE
CRUISE PERFORMANCE SUMMARY
FOR
***** DESIGN PAYLOAD *****
**** MAXIMUM PAYLOAD ****
FUEL AVAILABLE= 6976.

		AT		AT		AT	
		SPECIFIED	NORMAL	BEST SPEC.	RANGE		
		START	END	START	END	START	END
		CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE
TIME	HRS.	0.501	2.662	0.528	2.042	0.506	2.609
RANGE	N.MI	104.	1021.	116.	822.	105.	1014.
FUEL USED	LBS.	1296.	5487.	1372.	4634.	1308.	5463.
WEIGHT	LBS.	42925.	38735.	42849.	39588.	42914.	38759.
ALTITUDE	FT.	37000.	37000.	37000.	37000.	37000.	37000.
TAS	KTS.	424.8	424.8	465.9	465.9	431.9	431.9
EAS	KTS.	226.9	226.9	248.8	248.8	230.7	230.7
MACH NO.		0.7400	0.7400	0.8116	0.8116	0.7523	0.7523
DIV. MACH		0.8265	0.8320	0.8362	0.8412	0.8283	0.8337
ANGLE ATTACK	DEG.	2.808	2.378	1.825	1.462	2.620	2.212
FUSE. ANGLE	DEG.	0.808	0.378	-0.175	-0.538	0.620	0.212
CL		0.4509	0.4069	0.3742	0.3346	0.4361	0.3939
L/D		13.642	13.047	12.679	11.872	13.492	12.872
FUEL FLOW	LB/HR	1986.3	1896.7	2194.6	2116.2	2018.2	1935.5
BREG. FACTOR	N.MI.	9187.	8682.	9103.	8722.	9190.	8655.
SPEC. RANGE	NM/LB	0.21389	0.22399	0.21231	0.22017	0.21401	0.22316

DESCENT FROM CRUISE AT NORMAL POWER CONDITION
(U=NO CONSTRAINT; R= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=HMD OR VMD)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	FUS. ANGLE (DEG)	R/S (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
2.054	827.	4651.	39571.	37000.	466.	249.	0.812	0.840	0.3422	0.0288	1.53	-1.75	-2.21	1439.	2126.	1480. R
2.066	833.	4670.	39552.	36000.	466.	255.	0.812	0.842	0.3261	0.0283	1.38	-1.68	-2.30	1388.	2268.	1571. R
2.078	838.	4690.	39531.	35000.	468.	262.	0.812	0.844	0.3108	0.0278	1.25	-1.63	-2.38	1349.	2412.	1670. R
2.091	844.	4713.	39509.	34000.	470.	268.	0.812	0.846	0.2964	0.0274	1.11	-1.58	-2.47	1315.	2559.	1773. R
2.104	851.	4737.	39484.	33000.	473.	274.	0.812	0.848	0.2828	0.0270	0.99	-1.53	-2.54	1280.	2714.	1882. R
2.117	857.	4761.	39458.	32000.	475.	280.	0.812	0.849	0.2698	0.0267	0.87	-1.48	-2.61	1247.	2875.	1993. R
2.131	863.	4793.	39429.	31000.	477.	287.	0.812	0.851	0.2576	0.0263	0.76	-1.44	-2.68	1217.	3039.	2111. R
2.145	870.	4824.	39397.	30000.	479.	294.	0.812	0.852	0.2460	0.0261	0.65	-1.40	-2.75	1188.	3209.	2233. R
2.160	877.	4858.	39363.	29000.	481.	300.	0.812	0.854	0.2350	0.0258	0.55	-1.36	-2.81	1160.	3385.	2359. R
2.174	884.	4895.	39327.	28000.	483.	307.	0.812	0.855	0.2245	0.0256	0.46	-1.33	-2.87	1134.	3568.	2491. R
2.189	892.	4935.	39287.	27000.	485.	314.	0.812	0.856	0.2146	0.0254	0.36	-1.29	-2.92	1106.	3775.	2636. R
2.205	899.	4977.	39244.	26000.	487.	321.	0.812	0.857	0.2052	0.0252	0.28	-1.26	-2.98	1083.	3967.	2777. R
2.220	907.	5023.	39198.	25000.	489.	328.	0.812	0.859	0.1963	0.0250	0.20	-1.22	-3.03	1059.	4169.	2924. R
2.237	915.	5073.	39149.	24000.	491.	335.	0.812	0.860	0.1878	0.0248	0.12	-1.19	-3.08	1038.	4378.	3079. R
2.253	923.	5125.	39097.	23000.	488.	339.	0.803	0.860	0.1834	0.0248	0.09	-1.18	-3.08	1017.	4479.	3164. R
2.270	931.	5178.	39043.	22000.	482.	341.	0.791	0.861	0.1811	0.0247	0.09	-1.17	-3.08	997.	4539.	3222. R
2.274	933.	5191.	39030.	21000.	497.	357.	0.812	0.863	0.1643	0.0245	-0.10	-1.90	-6.00	3432.	3155.	2661. A
2.279	935.	5195.	39027.	20000.	409.	299.	0.665	0.854	0.2342	0.0258	0.82	-4.82	-6.00	3483.	1003.	724. A
2.284	937.	5199.	39023.	19000.	404.	301.	0.655	0.854	0.2317	0.0257	0.81	-4.81	-6.00	3436.	1046.	758. A
2.289	939.	5202.	39019.	18000.	400.	302.	0.645	0.854	0.2293	0.0257	0.80	-4.80	-6.00	3389.	1090.	793. A
2.294	941.	5207.	39015.	17000.	395.	304.	0.635	0.855	0.2268	0.0256	0.79	-4.79	-6.00	3343.	1135.	829. A
2.299	943.	5211.	39011.	16000.	391.	305.	0.626	0.855	0.2244	0.0256	0.77	-4.77	-6.00	3298.	1182.	867. A
2.304	945.	5216.	39006.	15000.	387.	307.	0.617	0.855	0.2219	0.0255	0.76	-4.76	-6.00	3253.	1231.	906. A
2.309	947.	5220.	39001.	14000.	383.	309.	0.608	0.856	0.2195	0.0255	0.74	-4.74	-6.00	3208.	1281.	947. A
2.315	949.	5226.	38996.	13000.	379.	310.	0.599	0.856	0.2170	0.0254	0.73	-4.73	-6.00	3163.	1333.	989. A
2.320	951.	5231.	38990.	12000.	375.	312.	0.591	0.856	0.2146	0.0254	0.71	-4.71	-6.00	3122.	1387.	1033. A
2.325	953.	5237.	38985.	11000.	371.	314.	0.583	0.857	0.2121	0.0253	0.70	-4.70	-6.00	3079.	1443.	1078. A
2.335	956.	5245.	38976.	10000.	291.	250.	0.455	0.841	0.3349	0.0286	2.23	-3.22	-3.00	1658.	1121.	806. S
2.346	959.	5254.	38968.	9000.	286.	250.	0.446	0.841	0.3349	0.0286	2.24	-3.17	-2.93	1604.	1159.	836. S
2.357	962.	5263.	38958.	8000.	282.	250.	0.438	0.841	0.3348	0.0285	2.25	-3.11	-2.86	1551.	1198.	867. S
2.368	965.	5273.	38948.	7000.	277.	250.	0.430	0.841	0.3347	0.0285	2.26	-3.05	-2.79	1498.	1239.	899. S
2.379	968.	5284.	38938.	6000.	273.	250.	0.422	0.841	0.3346	0.0285	2.27	-2.99	-2.72	1446.	1281.	932. S
2.391	971.	5295.	38926.	5000.	269.	250.	0.414	0.841	0.3346	0.0285	2.28	-2.93	-2.65	1394.	1324.	966. S
2.404	975.	5308.	38914.	4000.	265.	250.	0.406	0.841	0.3345	0.0285	2.29	-2.86	-2.58	1343.	1368.	1002. S
2.417	978.	5321.	38900.	3000.	261.	250.	0.399	0.841	0.3344	0.0285	2.29	-2.80	-2.50	1292.	1414.	1038. S
2.430	981.	5336.	38886.	2000.	257.	250.	0.391	0.841	0.3342	0.0285	2.30	-2.73	-2.43	1242.	1461.	1076. S
2.437	983.	5343.	38878.	1500.	255.	250.	0.388	0.841	0.3341	0.0285	2.30	-2.69	-2.39	1217.	1486.	1096. S

END OF DSCNT TO 1500. FT
TIME= 2.437 HRS FUEL USED= 5343. LBS WEIGHT= 38878. LBS RANGE= 983. NM

RESERVE FUEL(LBS) 1490. 1646. 1514.
(45.0 MIN.)

RANGE = 983. BLOCK TIME= 2.437 USED FOR DESIGN RANGE AND COST

TEMP.= 537. DEG:STD.+36.
LANDING ELEVATION= 5000. FT.
LANDING WING LOADING= 73.24 PSP.
LANDING WEIGHT = 40074. LBS.

LANDING DISTANCE FROM 50. FT.= 2829. FT.

F.A.R. FACTORED FIELD LENGTH = 4714. FT.

APPROACH	TRANSITION	DELAY	ROLL
DIST= 676.	DIST= 197.	DIST= 200.	DIST= 1755.
R/S= 1000.	XLFMX= 1.200	TDELAY= 1.00	MUB= 0.4000
VAPAS= 119.93	SINKTD= 3.000	TIDLE= 604.	TR/TIDLE= 0.0000
VAPTAS= 133.83	VSTEAS= 92.26	VTDTAS= 118.38	ABAR(G)= 0.3541
THETA= 4.23	CLMX= 2.5369		
THRUST= 3857.	HFLAR= 20.9		

Fig 11 - Canadair Regional Jet 100 GASP result (continued)

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.....
0 RANGE OR ENDURANCE ITERATION SUMMARY

      GROSS      RANGE (NMI) OR
ITERATION WEIGHT (LB) ENDURANCE (HR)
      0      44050.00      960.518
      1      55062.50      2210.849
      2      44221.59      983.085
      REQUIRED RG. OR END. = 980.000

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK (DEGREES) = 2.805 LIFT = 42894.9 L/D = 13.638 ALTITUDE = 37000.0 MACH = 0.7400

0 GROSS WEIGHT = 44222. PASSENGERS = 50. PLUS CREW

0 FUSELAGE LENGTH (ELF) 80.00 FT
          WIDTH (SWF) 8.83 FT
          WETTED AREA (SFA) 1846. SQFT
          DELTA P (DELP) 8.30 PSI

0 WING ASPECT RATIO (AR) 8.85
      AREA (SW) 547.2 SQFT
      SPAN (S) 69.6 FT
      GEOM. MEAN CHORD (CBARM) 8.81 FT
      QUARTER CHORD SWEEP (DLQMC4) 24.8 DEG
      TAPER RATIO (SLM) 0.250
      ROOT THICKNESS (TCR) 0.132
      TIP THICKNESS (TCT) 0.100
      WING LOADING (WGS) 80.8 PSF
      WING FUEL VOLUME (VFW) 1439.4 GAL

0 HOR. TAIL ASPECT RATIO (ARHT) 4.07
          AREA (SHT) 132.4 SQFT
          SPAN (BHT) 23.21 FT
          MEAN CHORD (CBARHT) 5.71 FT
          THICKNESS/CHORD (TCHT) 0.100
          MOMENT ARM (ELTH) 38.0 FT
          VOLUME COEFF. (VBARH) 1.045

      VERT. TAIL ASPECT RATIO (ARVT) 1.05
          AREA (SVT) 118.3 SQFT
          SPAN (BVT) 11.14 FT
          MEAN CHORD (CBARVT) 10.74 FT
          THICKNESS/CHORD (TCVT) 0.120
          MOMENT ARM (ELTV) 27.3 FT
          VOLUME COEFF. (VBARV) 0.085

0 ENG. NACELLES LENGTH (ELN) 11.58 FT
          MEAN DIAMETER (DBARN) 3.86 FT
          NUMBER ENGINES (ENP) 2.0
          WETTED AREA (SN) 280.59 SQFT

      LOCATION ON FUSELAGE

0 VOIVE = 715. KTS VMO = 596. KTS MMO = 0.900
  ULT. LP = 5.92 MAN. LP = 2.50 GUST LP = 3.94

0 PROPULSION GROUP
  PRIMARY ENGINES (WEP) 2957.
  PRIMARY ENGINE INSTL. (WPEI) 399.
  FUEL SYSTEM (WFSS) 140.
  TOTAL PROP. GROUP WT. (WP) 3496.

0 STRUCTURES GROUP
  WING (WW) 5384.
  HOR. TAIL (WHT) 698.
  VERT. TAIL (WVT) 519.
  FUSELAGE (WB) 5773. (INCL. 0.0 LBS A.T.W.)
  LANDING GEAR (WLG) 1680.
  PRIMARY ENG. SECTION (WPES) 990.
  GROUP WEIGHT INC. (DELMST) 0.
  TOTAL STRUC. GROUP WT. (WST) 15045.

0 FLIGHT CONTROLS GROUP
  COCKPIT CONTROLS (WCC) 95.
  FIXED WING CONTROLS (WCFW) 939.
  SAS (WSAS) 0.
  GROUP WEIGHT INC. (DELMWFC) 0.
  TOTAL CONTROL WT. (WFC) 1034.

0 WT. OF FIXED EQUIPMENT (WFE) 6582.

  WEIGHT EMPTY (WE) 26157.

  FIXED USEFUL LOAD (WFUL) 1088. (INC. CREW )

  OPERATING WEIGHT EMPTY (OWE) 27245.
0 PAYLOAD (WPL) 10000. (PAX.VOL. = 50. DESIGN PAX = 50.)

  FUEL (WFA) 6976. (WFM = 6976.) (WFTP = 0.)

  GROSS WEIGHT (WG) 44222.

0 FIXED EQUIP GROUP FIXED USEFUL LOAD
0 WAPU 372.27 WCREW ( 2. ) 340.00
  WINSTR 254.92 WSTU ( 1. ) 130.00
  WHYD 372.24 WCBAG 110.00
  WELEC 870.00 WUF 140.35
  WAV 500.00 WOIL 123.81
  WPU 3374.86 WSRV 116.00
  WAC 463.26 WH2O 53.00
  WAI 254.82 WEMER 40.00
  WAUXG 20.00 WCATER 35.00

  WFE 6582.37 WFUL 1088.16

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Fig 11 - Canadair Regional Jet 100 GASP result (continued)

0 DESIGN MACH = 0.740 DESIGN ALTITUDE = 37000. DESIGN Q (PSF) =174.22
 0 DESIGN RE.NUM. PER FT. = 1.638E+06 FLATPLATE CF AT RE=10EX7 IS 0.00276

0 AERODYNAMIC DATA

	FLATPLATE AREA(SQFT)	CDO	WETTED AREA(SQFT)
0 DRAG BREAKDOWN			
WING	3.7255	0.00681	882.64
FUSELAGE	5.3604	0.00980	1845.60
VERT. TAIL	0.7548	0.00138	236.58
HOR. TAIL	0.8949	0.00164	264.75
ENGINE NAC.	1.1723	0.00214	280.59
TIP TANKS	0.0000	0.00000	0.00
INCREMENTAL	0.8207	0.00150	0.00
0 TOTAL	12.7286	0.02326	3510.17

MEAN SKIN FRICTION COEF. = 0.003626

0 AERODYNAMIC COEFF.

A1		0.8234
A2		-0.1262
A3		0.0323
A4 = .75X(T/C)		0.0914
A5 = CDO--		0.0143
A6		2.4681
A7 = 1/(PI. SEE. AR)		0.0458
3-D LIFT SLOPE AT CRUISE MACH	(CLALPH)	5.8606 PER RADIAN
OSWALD FACTOR	(SEE)	0.7858

0 CRUISE CD = 0.0233 + 0.0458 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
 0 RETRACTABLE LANDING GEAR CD INC. = 0.02674

0 CRUISE DRAG

OCL= 0.2000

MACH	CD	L/D	CLALPH	ALPHA
0.30000	0.02513	7.9593	5.0970	0.6482
0.35000	0.02513	7.9593	5.2087	0.6000
0.60000	0.02513	7.9593	5.3405	0.5437
0.65000	0.02513	7.9593	5.4969	0.4847
0.70000	0.02513	7.9593	5.6837	0.4161
0.75000	0.02513	7.9593	5.9094	0.3391
0.80000	0.02513	7.9593	6.1866	0.2523
0.85000	0.02513	7.9593	6.5347	0.1536

OCL= 0.3000

MACH	CD	L/D	CLALPH	ALPHA
0.50000	0.02756	10.8868	5.0970	1.7723
0.55000	0.02756	10.8868	5.2087	1.7000
0.60000	0.02756	10.8868	5.3405	1.6186
0.65000	0.02756	10.8868	5.4969	1.5270
0.70000	0.02756	10.8868	5.6837	1.4242
0.75000	0.02756	10.8868	5.9094	1.3087
0.80000	0.02756	10.8868	6.1866	1.1784
0.85000	0.02756	10.8859	6.5347	1.0304

OCL= 0.4000

MACH	CD	L/D	CLALPH	ALPHA
0.50000	0.03090	12.9450	5.0970	2.8964
0.55000	0.03090	12.9450	5.2087	2.8000
0.60000	0.03090	12.9450	5.3405	2.6914
0.65000	0.03090	12.9450	5.4969	2.5693
0.70000	0.03090	12.9450	5.6837	2.4323
0.75000	0.03090	12.9450	5.9094	2.2783
0.80000	0.03090	12.9450	6.1866	2.1045
0.85000	0.03103	12.8905	6.5347	1.9072

OCL= 0.5000

MACH	CD	L/D	CLALPH	ALPHA
0.50000	0.03533	14.1511	5.0970	4.0205
0.55000	0.03533	14.1511	5.2087	3.9000
0.60000	0.03533	14.1511	5.3405	3.7643
0.65000	0.03533	14.1511	5.4969	3.6117
0.70000	0.03533	14.1511	5.6837	3.4404
0.75000	0.03533	14.1511	5.9094	3.2478
0.80000	0.03533	14.1511	6.1866	3.0306
0.85000	0.03602	13.8815	6.5347	2.7840

OCL= 0.6000

MACH	CD	L/D	CLALPH	ALPHA
0.50000	0.04068	14.7488	5.0970	5.1446
0.55000	0.04068	14.7488	5.2087	5.0001
0.60000	0.04068	14.7488	5.3405	4.8371
0.65000	0.04068	14.7488	5.4969	4.6540
0.70000	0.04068	14.7488	5.6837	4.4485
0.75000	0.04068	14.7488	5.9094	4.2174
0.80000	0.04068	14.7488	6.1866	3.9568
0.85000	0.04267	14.0627	6.5347	3.6608

0 LOW SPEED LIFT/DRAG-GR. UP (IF R) O.G.E.

FLAPS UP				TAKEOFF				LANDING				
ALPHA	CL	CD	L/D	CL	CD	L/D	CL	CD	L/D	CL	CD	L/D
-2.00000	-0.03274	0.02341	-1.39811	0.73729	0.06674	11.04784	1.18620	0.21457	5.52836			
0.00000	0.13094	0.02406	5.44266	0.80096	0.07540	11.94900	1.34987	0.22532	5.99099			
2.00000	0.29462	0.02740	10.75160	1.06464	0.08710	12.22328	1.51355	0.23972	6.31374			
4.00000	0.45829	0.03337	13.73255	1.22832	0.10232	12.00441	1.67723	0.25830	6.49338			
6.00000	0.62197	0.04206	14.78909	1.39199	0.12221	11.39020	1.84090	0.28219	6.52357			
8.00000	0.78565	0.05369	14.63337	1.55567	0.14576	10.67263	2.00458	0.31024	6.45935			
10.00000	0.94932	0.06887	13.78489	1.71935	0.17182	10.00679	2.16826	0.34161	6.34710			
12.00000	1.11300	0.08878	12.53712	1.88302	0.20038	9.39744	2.33193	0.37602	6.20161			
14.00000	1.27667	0.11211	11.38740	2.04670	0.23144	8.84345	2.49561	0.41356	6.03447			
14.50408	1.32348	0.11924	11.09953	2.09337	0.24075	8.69514	2.53686	0.42351	5.99004			

0 DFLAP= 0.00 DFLAP= 15.00 DFLAP= 45.00
 0 CLMAX= 1.32348 CLMAX= 2.09337 CLMAX= 2.53686

Fig 11 - Canadair Regional Jet 100 GASP result (continued)

0 LOW SPEED AERO FOR OTHER FLAP DEFLECTIONS

FLAP DEF.	CIMAX	CL	CD	L/D
10.000	1.86055			
		0.50989	0.05145	9.90973
		0.67356	0.05850	11.51320
		0.83724	0.06840	12.24059
		1.00092	0.08139	12.29716
		1.16459	0.09792	11.89361
		1.32827	0.11988	11.08043
		1.49194	0.14431	10.33845
		1.65562	0.17122	9.66940
		1.81930	0.20061	9.06871
		1.86055	0.20841	8.92732
20.000	2.26162			
		0.91095	0.08628	10.55842
		1.07463	0.09601	11.19289
		1.23831	0.10682	11.37902
		1.40198	0.12516	11.20151
		1.56566	0.14701	10.65006
		1.72934	0.17155	10.08058
		1.89301	0.19862	9.53076
		2.05669	0.22822	9.01188
		2.22036	0.26035	8.52849
		2.26162	0.26884	8.41241
30.000	2.49754			
		1.14688	0.12877	8.90653
		1.31055	0.13948	9.39582
		1.47423	0.15350	9.60419
		1.63791	0.17136	9.55818
		1.80158	0.19452	9.26144
		1.96526	0.22031	8.92037
		2.12893	0.24872	8.55954
		2.29261	0.27975	8.19512
		2.45629	0.31341	7.83733
		2.49754	0.32231	7.74899
40.000	2.62730			
		1.27663	0.18785	6.79607
		1.44031	0.19914	7.23252
		1.60399	0.21392	7.49795
		1.76766	0.23260	7.59953
		1.93134	0.25714	7.51089
		2.09502	0.28454	7.36271
		2.25869	0.31482	7.17460
		2.42237	0.34796	6.96162
		2.58604	0.38397	6.73499
		2.62730	0.39350	6.67674

0 ALTITUDE= 37000. FT TAS= 470.12 KTS MACH NO= 0.8189

0 RDT&E AND AIRFRAME PRODUCTION COSTS
 0 (1993. DOLLARS)
 0 TOTAL RDT&E COSTS 1071.7244 MILLION
 0 AIRFRAME PRODUCTION COSTS(INCLUDING 10% PROFIT)
 0 500. AIRCRAFT

	WEIGHT(LB)	COST(\$)	COST(\$/LB)
STRUCTURE(4175819.\$)			
WING	5384.	1286296.	238.90
EMPNENAGE	1217.	433284.	355.90
FUSELAGE	5773.	1615574.	279.87
LANDING GEAR	1680.	300178.	178.63
NACELLES	990.	540488.	545.96
PROPULSION INSTAL(165136.\$)			
ENGINE INSTALLAT.	399.	145359.	364.08
FUEL SYSTEM	140.	19777.	141.74
SYSTEMS(2638784.\$)			
FLIGHT CONTROLS	1034.	483255.	469.41
HYDRAULIC	372.	46369.	124.57
ELECTRICAL	970.	464214.	478.57
AIR CONDITIONING	463.	248223.	535.82
ANTI-ICING	255.	134201.	526.66
AUX. POWER UNIT	372.	207143.	556.42
FURNISHINGS	3375.	788235.	233.56
INSTRUMENTS	255.	211440.	829.44
AVIONICS INSTALL.	250.	49032.	196.13
AUX. ITEMS	20.	4671.	233.56
INTEGRATION(1744935.\$)			
AIRFRAME TOTALS	22950.	8724673.	380.17
ENGINES		2742208.	
PROPELLER		0.	
AVIONICS		4000000.	
A/C COST(NO RD)		15466880.	
R&D PER A/C		2143449.	
TOTAL A/C COST		17610328.	

0 ENGINES NUMBER = 2. TYPE= 7

0 EMPTY WEIGHT= 26157. AIRFRAME WEIGHT= 23200. WEIGHT OF 1 ENGINE= 1479. CRUISE SPEED= 470. KTS
 0 THRUST/ENGINE= 9242.
 0 TOTAL AIRCRAFT COST= 17610328. AIRFRAME COST= 14868122. COST OF 1 ENGINE= 1371104. COST OF 1 PROP.= 0.

0 --- COST DATA ---
 0 GASP SHORThAUL METHOD

0 DESIGN MISSION
 0 OPERATING COST FOR NOR.RATED POWER AND 37000. ALTITUDE
 0

0 RANGE= 983. N.M. BLOCK FUEL= 5343. LBS BLOCK TIME= 2.4368 HRS.

0 UTILIZATION 3200.

0 FLYING OPERATIONS

FLIGHT CREW	304.598
FUEL,OIL,AND TAXES(0.850\$/G)	709.752
INSURANCE	67.051
DIRECT MAINTENANCE	
AIRFRAME	147.362
ENGINE	240.401
MAINTENANCE BURD.	314.806
DEPRECIATION	901.162

0 TOTAL DOC (\$/TRIP) 2685.132
 (\$/B.MR.) 1101.918
 (\$/N.MI.) 2.731

Fig II - Canadair Regional Jet 100 GASP result (concluded)

1
0

BUSINESS JET USING SCALED GARRETT TPE 731-2 - LEARJET 35A
ENGINE CYCLE IS GARRETT TPE731-2

INPUT DATA FOLLOW

```

0
0 CONFIG WG = 19000.          *****GEOMETRY*****
      WGS = 72.200          FUSEL SAB = 2.          ELODM = 2.000
      PAX = 8.              WS = 18.000          ELODT = 3.300
      ENCRU = .730         AS = 1.              EML0D = 14.500
      HNCRU = 45000.       WAS = 18.000          MACELLE KNAC = 1
      Kanard = 0           PS = 51.5          ELN = .000
                                ELPC = 4.440          DBARN = .000
                                HCK = 2.470          ELMW = 9.000

0 WING TCT = .090          HORIZ VBARHX = .0000    VERT VBARVX = .0000    Canard TCCan = .100
      TCR = .090          TAIL TCMT = .080      TAIL TCVT = .100      ARcan = 3.300
      AR = 3.740         ARHT = 3.984         ARVT = .879          SLMcan = .500
      SLM = .550         SLMH = .500         SLMV = .537          DupqCa = 13.000
      DIMC4 = 12.500     DWPOCH = 24.000     DWPOCV = 38.000     FYScan = 2.000
      EYEW = 1.000      COELTH = .000      BOELTV = .000      SWCOSW = .145

0
0      CFM = -1.000      ***AERODYNAMICS***      GRPE = .000          LCDSE = -1.0000
      CKF = -1.000      CKHT = -1.000          SCFAC = .000         CMWc = -1.000
      CKN = -1.000      CKTP = -1.000          DLSW = .000          cmacv = -.020
      CKVT = -1.000     DELCD = .00000        ALPHLO = -1.000     alterc = -1.000

0      RWCD = 12          ACLS = -1.000          ACDCDR = 2.400      1.466 1.221 1.066 1.005 1.100 1.200 1.400 1.600 1.800 1.000 1.003 1.046 1.138 1.333 1.743 2.719

0
0      RCLMAX = 1.200    FLAPS JFLTYP = 3          LED CLROC = .000
      ALTFLE = 5000.     DFLPTO = 20.000         DELLED = .000
      FLAPN = 1.         DFLPLD = 40.000        DCLMLE = .930
      WCFLAP = -1.000    CFPC = .280           DELLEO = 45.000
      BENGOR = .000     BTEOB = .560
                                DCLNTE = .000
                                DCDDTE = .000
                                DELTEO = .000

0
0      JENGSZ = 2        HPORT = 5000.          RCCRU = 100.000      RMCRTX = .970
      IPART = 1         TDELTO = 36.          ITCORQ = 99999.     HSCREQ = 0.
      KODETO = 5        KODECL = 7           SMID = .500         THIN = 0.
      KODETR = 5        KODEAC = 5           HBTF = .498         PA = 1.000

0
0      SKPEI = .1350     SKY = .1800           SKB = 136.000        SKFS = .0200
      SKLG = .0318      SKZ = .2200           SRCC = 11.000        SKMF = .4300
      SFMG = .8000      SKTL = 1.0000        SKFW = .4040         SKPT = .9790
      SKPES = .3380     SKMW = 133.400       SKSAS = .000         SKGTP = 1.8900
      WPLX = .0         YMG = .2286          EGMRGN = .0000      ZCWMG = 2
      WPEX = .0         RELP = .6530         CFMRGN = .2000
      WPUL = .0         RELR = .4500         STMGRN = .0000      LOCKMX = 8.000
      WMPAX = 200.0     CATD = 3.           DELP = 9.400        ATMKOC = 3.160
      STRUT = .0000     VMLFSL = 616.5      YP = .0000          DELWST = .0
0 ENGINE DELWFC = .0      WNAC = .0            WPYLON = .0         EL0DK = 3.120
      WENG = .0         UWNAC = 2.287        PPYL = .700
      SWSLS = .203

0
0      KSPAXd = 0        STATIC = .100         ZCG = 999.000        CNPAC = .0020
      CMPLFL = 999.000   CHALF = 999.000      TP = .0             ARVTE = -1.000
      CMPLPT = 999.000   CHDEL = 999.000     CIA = .350          RV = .250
      CMPLD = .000      RH = .333           PCMCLP = 9999.000   TAUV = 999.000
                                DEMAX = -25.0        HMING = 0.          RVNCS = .990
                                EYET = .0           dcmcp1 = .030      DRMAX = 25.0
                                TAUH = 999.000    rc = .350

0
0 TAXI DELTT = .167     XLFMAX = 1.100        DVR = 5.000          TDELTX = 36.000
      TO IFLY = 1       DELTVR = 3.500        UM = .020           HTHAX = 500.000
      THEMAY = 15.000   DVL = 5.000          MUB = .400          NFAIL = 0
      H00 = 5000.       VRAT = 1.10         WTMISN = 0.

0 CLIMB ICLM = 1        CRUISE CRMACH = .000   PRESF = 1.000        FACW1 = .830
      DELH = 1000.     CRALT = 0.           ACRARQ = 1900.0     ISWING = 0
      VCLMB = .0       ICRUS = 1           OFALT = 25000.      OFEM = .500
0 LAND IWLID = 2       ILDGRQ = 99999.     VRATT = 1.300        HAFP = 50.
      TDELLO = 36.0    ALTLD = 5000.       RSMX = 1000.        SINKTD = 3.0
      TDELAY = 1.0     WLEPCT = .8360     TROTID = .000      XLFN2 = 1.200
      NTG = 3.2        TIDLE = .0         VTDRAT = 1.1

0
0      NCADE = 1         HIR = .005           RI = .300           CNV = .800
      CILAB = 1993.0    TRV = 2.000          CHR = 700.000        CCRW = 0.
      HPI = 1000000.   PRV = .100          CRMOW = 23.000       UCSENG = .000
      CHF = .2         DYR = 15.0          CINP = 0.           UCSPP = .000
      TBO = 800.0      SRPM = .0           CP = 0.             ALR = 3.400
      FCSF = .850

```

1
0***** H.TAIL C.L. CHORD MUST = 4.743 TO BE LOCATED AT SPECIFIED POSITION ON VERTICAL*****
***** H.TAIL TAPER CHANGED TO .6892

Fig I2 - Learjet 35A GASP result

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.....
ITERATION TO BALANCE RANGE
RANGE ERROR, RANGE ERROR MINUS 1 .0439 -.2002
GROSS WGT, GROSS WGT MINUS1 17437.1 17827.2
.....
0 *****
0 FLAP PERFORMANCE SUMMARY (OUT OF GROUND EFFECT)
CINAX VSTALL,KTS FLAP ANGLE LE ANGLE DELTA CL DELTA CD
FLAPS UP 1.0593 152.9 .0 .0 .0000 .0000
T.O. CONFIG 1.4469 130.9 20.0 .0 .3903 .0247
LDG. CONFIG 1.5993 124.5 40.0 .0 .5472 .0667
0
0 SINGLE SLOTTED FLAPS
OPT ANGLE DELCL AT OPT DELCD AT OPT AREA(FT2) WEIGHT(LB)
FLAPS 40.0 1.1800 .1300 33.2 121.7
0 *****
0
SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK(DEGREES)= 5.345 LIFT= 16933.4 L/D= 13.630 ALTITUDE= 45000.0 MACH= .7300
1
ENGINE SIZING DATA FOLLOW
*****
OVSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958
VEND = 250.0 KNOTS EAS
0
ROTATION (TIME= 29.4 AND TAS= 146.4 EAS= 131.3)
LIFTOFF (TIME= 32.2 DIST= 4619.7 TAS= 156.9 EAS= 140.7)
DISTANCE TO 35 FT.= 6011.4 TAS= 169.4 EAS= 151.9 V35/V5= 1.2517
GEAR RETRACTION STARTED AT 38.1 SEC, COMPLETE AT 45.1 SEC
FLAP RETRACTION STARTED AT 48.4 SEC, COMPLETE AT 54.4 SEC
OVSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 213.1 KNOTS EAS
ENGINE FAILURE (TIME= 27.9 AND TAS= 140.8 EAS= 126.3)
0
ROTATION (TIME= 32.1 AND TAS= 146.4 EAS= 131.3)
LIFTOFF (TIME= 35.4 DIST= 5384.8 TAS= 150.0 EAS= 134.6)
DISTANCE TO 35 FT.= 7708.7 TAS= 151.7 EAS= 136.0 V35/V5= 1.1211
ACCELERATE - STOP DISTANCE = 7008.5 FEET.
0 ENGINE OUT DISTANCE TO 35 FT.= 7708.7 FEET
OALL ENGINE DISTANCE TO 35 FT. (L) = 6011.4 FEET
FAR 25 T.O. DISTANCE (1.15XL) = 6913.2 FEET
ALL ENGINE DISTANCE TO 50 FT. = 6273.8 FEET
0 AT END OF TAKEOFF PHASE
TIME= .014 HRS FUEL USED= 41. LBS WEIGHT= 17416. LBS ALT.= 5500. FT.
STAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F
CONFIGURATION ALT (FT) VS KEAS V/V5 V GRAD (PCT) R/C (FPM) REQ. R/C (FPM) CL L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT 5000. 121.5 1.1153 151.0 1.277 185.17 1.00 1.168 8.117
2ND SEG: T.O. FLAPS - ONE ENGINE OUT 5250. 121.5 1.2000 163.1 3.757 620.23 396.21 1.009 10.354
FINAL T.O. CRUISE CONFIG - ONE ENG OUT 6300. 142.1 1.2500 202.7 5.042 1034.43 246.18 .679 12.788
APPROACH FLAPS - ONE ENG OUT 5000. 126.8 1.3210 186.8 3.957 747.90 396.91 .764 11.116
LANDING FLAPS - ALL ENGINES 5000. 115.5 1.3000 167.5 12.144 2057.85 542.27 .950 6.913
APPROACH FLAP SETTING = 12.9 DEG.
+++ ENGINE-OUT SERVICE CEILING = 31585.4 FT.
BEST RATE OF CLIMB SPEED = 317.6 KTAS
ENGINE-OUT RATE OF CLIMB = 49.9 FPM
WEIGHT AT ALTITUDE = 16758.8 LBS
0
****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES****
0 PROPULSION SYSTEM WEIGHTS
ENGINE WEIGHT/ENGINE 764.1
NACELLE WEIGHT/ENGINE 124.8
PYLON WEIGHT/ENGINE 103.6
PROP OR OFAN .0
GEARBOX .0
SHROUD .0
0 ENGINE POD DIMENSIONS
ENGINE FACE DIAMETER(FT) 2.36
NACELLE LENGTH(FT) 7.36
OVSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958
VEND = 250.0 KNOTS EAS
0
ROTATION (TIME= 28.5 AND TAS= 146.4 EAS= 131.3)
LIFTOFF (TIME= 31.4 DIST= 4515.8 TAS= 157.3 EAS= 141.1)
DISTANCE TO 35 FT.= 5889.9 TAS= 170.0 EAS= 152.5 V35/V5= 1.2567
GEAR RETRACTION STARTED AT 37.3 SEC, COMPLETE AT 44.3 SEC
FLAP RETRACTION STARTED AT 47.5 SEC, COMPLETE AT 53.5 SEC
OVSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 205.2 KNOTS EAS
ENGINE FAILURE (TIME= 27.2 AND TAS= 140.8 EAS= 126.3)
0
ROTATION (TIME= 31.1 AND TAS= 146.4 EAS= 131.3)
LIFTOFF (TIME= 34.4 DIST= 5231.7 TAS= 150.3 EAS= 134.8)
DISTANCE TO 35 FT.= 7297.2 TAS= 152.0 EAS= 136.3 V35/V5= 1.1237
ACCELERATE - STOP DISTANCE = 6907.4 FEET.
0 ENGINE OUT DISTANCE TO 35 FT.= 7297.2 FEET
OALL ENGINE DISTANCE TO 35 FT. (L) = 5889.9 FEET
FAR 25 T.O. DISTANCE (1.15XL) = 6773.4 FEET
ALL ENGINE DISTANCE TO 50 FT. = 6133.1 FEET
0 AT END OF TAKEOFF PHASE
TIME= .014 HRS FUEL USED= 42. LBS WEIGHT= 17415. LBS ALT.= 5500. FT.

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Fig I2 - Learjet 35A GASP result (continued)

TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	V5 KEAS	V/V5	V KTAS	GRAD (PCT)	R/C (PPM)	REQ.R/C (PPM)	CL	L/D
1ST SEG:T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	121.5	1.1153	151.0	1.408	215.26	1.00	1.168	7.972
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	121.5	1.2000	163.1	3.871	639.01	396.21	1.009	10.106
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	142.1	1.2500	202.7	5.078	1041.84	246.18	.679	12.313
APPROACH FLAPS -ONE ENG OUT	5000.	126.8	1.3210	186.8	4.019	759.70	396.91	.764	10.784
LANDING FLAPS - ALL ENGINES	5000.	115.5	1.3000	167.5	12.710	2153.88	542.27	.950	6.852

APPROACH FLAP SETTING = 12.9 DEG.

+++ ENGINE-OUT SERVICE CEILING = 31544.6 FT.
 BEST RATE OF CLIMB SPEED = 314.2 KTAS
 ENGINE-OUT RATE OF CLIMB = 49.8 PPM
 WEIGHT AT ALTITUDE = 16758.8 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 124.76

ENGINE SIZED TO MATCH T.O. DISTANCE OF 99999. FT (STD DAY+ 36. DEG R/ALT= 5000.) SLS AIRFLOW= 124.76

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 3864.3 LBS

OPROPULSION SYSTEM WEIGHTS

ENGINE WEIGHT/ENGINE	784.1
NACELLE WEIGHT/ENGINE	124.8
PYLON WEIGHT/ENGINE	105.3
PROP OR QFAN	.0
GEARBOX	.0
SHROUD	.0

ENGINE POD DIMENSIONS

ENGINE FACE DIAMETER(FT)	2.36
NACELLE LENGTH(FT)	7.36

0 *****RESIZE ENGINES TO ACCOUNT FOR TIP TANKS*****

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE

ANGLE OF ATTACK(DEGREES)= 5.345 LIFT= 16933.4 L/D= 13.275 ALTITUDE= 45000.0 MACH= .7300

1 ENGINE SIZING DATA FOLLOW

0VSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958
 VEND = 250.0 KNOTS EAS

0 ROTATION (TIME= 27.8 AND TAS= 146.4 EAS= 131.3)
 LIFTOFF (TIME= 30.6 DIST= 4402.7 TAS= 157.4 EAS= 141.2)
 DISTANCE TO 35 FT.= 5791.0 TAS= 170.8 EAS= 153.2 V35/V5= 1.2624
 GEAR RETRACTION STARTED AT 36.5 SEC, COMPLETE AT 43.5 SEC
 FLAP RETRACTION STARTED AT 46.7 SEC, COMPLETE AT 52.7 SEC

0VSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958

0 ENGINE OUT PERFORMANCE FOLLOWS

VEND = 203.6 KNOTS EAS
 ENGINE FAILURE (TIME= 26.3 AND TAS= 140.8 EAS= 126.3)

0 ROTATION (TIME= 30.1 AND TAS= 146.4 EAS= 131.3)
 LIFTOFF (TIME= 33.4 DIST= 5070.3 TAS= 150.2 EAS= 134.7)
 DISTANCE TO 35 FT.= 7152.1 TAS= 152.1 EAS= 136.3 V35/V5= 1.1239

ACCELERATE - STOP DISTANCE = 6814.4 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 7152.1 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 5791.0 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 6659.7 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 6055.7 FEET

0 AT END OF TAKEOFF PHASE
 TIME= .014 HRS FUEL USED= 42. LBS WEIGHT= 17415. LBS ALT.= 5500. FT.

TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	V5 KEAS	V/V5	V KTAS	GRAD (PCT)	R/C (PPM)	REQ.R/C (PPM)	CL	L/D
1ST SEG:T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	121.5	1.1153	151.0	1.693	258.73	1.00	1.168	7.934
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	121.5	1.2000	163.1	4.116	679.53	396.21	1.009	10.009
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	142.1	1.2500	202.7	5.236	1074.15	246.18	.679	12.063
APPROACH FLAPS -ONE ENG OUT	5000.	126.8	1.3000	183.8	4.233	787.67	390.61	.789	10.590
LANDING FLAPS - ALL ENGINES	5000.	115.5	1.3000	167.5	13.271	2248.93	542.27	.950	6.798

APPROACH FLAP SETTING = 12.9 DEG.

+++ ENGINE-OUT SERVICE CEILING = 31524.8 FT.
 BEST RATE OF CLIMB SPEED = 310.1 KTAS
 ENGINE-OUT RATE OF CLIMB = 49.6 PPM
 WEIGHT AT ALTITUDE = 16758.6 LBS

0 *****RESIZE ENGINES AT CRUISE TO ACCOUNT FOR RESIZED NACELLES*****

OPROPULSION SYSTEM WEIGHTS

ENGINE WEIGHT/ENGINE	803.5
NACELLE WEIGHT/ENGINE	131.2
PYLON WEIGHT/ENGINE	107.5
PROP OR QFAN	.0
GEARBOX	.0
SHROUD	.0

ENGINE POD DIMENSIONS

ENGINE FACE DIAMETER(FT)	2.42
NACELLE LENGTH(FT)	7.55

Fig I2 - Learjet 35A GASP result (continued)

OVSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958
 VEND = 250.0 KNOTS EAS
 0
 ROTATION (TIME= 27.7 AND TAS= 146.4 EAS= 131.3)
 LIPTOFF (TIME= 30.4 DIST= 4357.9 TAS= 156.9 EAS= 140.8)
 DISTANCE TO 35 FT.= 5813.2 TAS= 171.2 EAS= 153.5 V35/V5= 1.2656
 GEAR RETRACTION STARTED AT 36.5 SEC, COMPLETE AT 43.5 SEC
 FLAP RETRACTION STARTED AT 46.7 SEC, COMPLETE AT 52.7 SEC
 OVSTLKT= 121.3 KTS EAS VRAT= 1.100 CLTO= 1.1958
 0 ENGINE OUT PERFORMANCE FOLLOWS
 VEND = 198.3 KNOTS EAS
 ENGINE FAILURE (TIME= 26.4 AND TAS= 140.8 EAS= 126.3)
 0
 ROTATION (TIME= 30.2 AND TAS= 146.4 EAS= 131.3)
 LIPTOFF (TIME= 33.6 DIST= 5126.0 TAS= 150.4 EAS= 134.9)
 DISTANCE TO 35 FT.= 7077.4 TAS= 152.2 EAS= 136.5 V35/V5= 1.1249

ACCELERATE - STOP DISTANCE = 6806.6 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT.= 7077.4 FEET
 GALL ENGINE DISTANCE TO 35 FT. (L) = 5813.2 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 6685.2 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 6079.1 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .014 HRS FUEL USED= 42. LBS WEIGHT= 17415. LBS ALT.= 5500. FT.
 0 TAKE OFF RATE OF CLIMB REQUIREMENTS - FAR PART 25
 AIRPORT ALTITUDE= 5000. FT; AMBIENT TEMP ABOVE STD. DAY= 36.0 DEG F

CONFIGURATION	ALT (FT)	VS KEAS	V/V5	V KTAS	GRAD (PCT)	R/C (FPM)	REQ. R/C (FPM)	CL	L/D
1ST SEG: T.O. FLAPS+LD GEAR EXT - ONE ENG OUT	5000.	121.5	1.1153	151.0	1.704	260.38	1.00	1.168	7.922
2ND SEG: T.O. FLAPS - ONE ENGINE OUT	5250.	121.5	1.2000	163.1	4.125	681.06	396.21	1.009	9.989
FINAL T.O. CRUISE CONFIG - ONE ENG OUT	6500.	142.1	1.2500	202.7	5.239	1074.71	246.18	.679	12.027
APPROACH FLAPS -ONE ENG OUT	5000.	126.8	1.3000	183.8	4.240	788.70	390.61	.789	10.564
LANDING FLAPS - ALL ENGINES	5000.	115.5	1.3000	167.5	13.318	2256.90	542.27	.950	6.793

APPROACH FLAP SETTING = 12.9 DEG.

+++ ENGINE-OUT SERVICE CEILING = 31522.8 FT.
 BEST RATE OF CLIMB SPEED = 309.8 KTAS
 ENGINE-OUT RATE OF CLIMB = 49.6 FPM
 WEIGHT AT ALTITUDE = 16758.8 LBS

ENGINE SIZED TO MATCH CRUISE DRAG - SLS AIRFLOW= 128.11

ENGINE SIZED TO MATCH T.O. DISTANCE OF 9999. FT (STD DAY+ 36. DEG R;ALT= 5000.) SLS AIRFLOW= 128.11

ENGINE SIZE MEETS ALL RATE OF CLIMB REQUIREMENTS

RATED SEA LEVEL STATIC THRUST PER ENGINE= 3968.2 LBS

0 PROPULSION SYSTEM WEIGHTS
 ENGINE WEIGHT/ENGINE 805.1
 NACELLE WEIGHT/ENGINE 131.2
 PYLON WEIGHT/ENGINE 107.7
 PROP OR OPAN .0
 GEARBOX .0
 SHROUD .0

0 ENGINE POD DIMENSIONS
 ENGINE FACE DIAMETER(PT) 2.42
 NACELLE LENGTH(PT) 7.55

0.....

Fig I2 - Learjet 35A GASP result (continued)

---AIRCRAFT C.G. SUMMARY (DATUM=NOSE)---

	MOST FWD LOAD		MOST AFT LOAD		DESIGN LOAD	
	WT	CG	WT	CG	WT	CG
A/C OWE	10410.50	23.52	10410.50	23.52	10410.50	23.52
PAY	680.00		340.00		1360.00	
BAGGAGE	.00	28.93	240.00	28.93	240.00	28.93
WING FUEL	.00	24.01	2360.34	24.01	2360.34	24.01
TIP FUEL	472.07	23.01	2467.89	23.01	2467.89	23.01
FUS FUEL	.00	24.01	.00	24.01	618.36	24.01
TOTAL	11562.57	23.02	15818.72	23.65	17457.08	23.31

0

---TAIL SIZING SUMMARY---

Static Longitudinal Stability, Stick-free, considered

0

CONDITION	ALPHA	WING		Cmac	CANARD		TAIL	DOWN	FLAP
		CL	CLA		ALPHA	CLA			
CRUISE	5.5417	.6255	.0956	-.0200	.0000	.0000	.0751	1.0000	
LIFTOFF	1.0000	.5711	.0656	-.0200	.0000	.0000	.0646	1.0000	.2229 - .1300
LANDING	12.6061	1.5993	.0773	-.0200	.0000	.0000	.0647	1.0000	2.8103 - .2000

0

CONDITION	--FUSELAGE--		---NACELLE---		-----POWER-----			L. GEAR	ROT. POWER		
	DCM	CM	DCM	CM	DCM _{th}	DCM _{fine}	CM _{th}			CM _{fine}	CT
CRUISE	.2748		-.0024		.0000	.0300			.0000		
LIFTOFF	.4007	.0000	-.0024	.0000			.0000	.0171	.0000	-.3409	1.1795
LANDING	.3398	.3049	-.0024	-.0021			.0000	.0480			

0

ELEVATOR PARAMETERS

CN _{ALPHA} (FLOATING TENDENCY)	=	-.00460	WING DE/DALPHA	=	.44586
CN _{DELTA} (RESTORING TENDENCY)	=	-.01181			
CN _{DELTA} (CONTROL POWER)	=	-.02648			
TAUH (EFFECTIVENESS)	=	.46285			
DEMAX (MAX. ELEVATOR DEFLEC.)	=	-25.00000			

0

	FRACTION	STATION (DATUM NOSE)	HORIZONTAL TAIL SIZES	
NEUTRAL POINT	.2627	23.231	STATIC STABILITY AND LANDING TRIM	71.2921
STATIC MARGIN	.1000		STATIC STABILITY AND LIFTOFF ROT.	35.2682
AFT CG LIMIT (STABILITY)	.1627	22.564		
CG RANGE (LOADING)	.0939		REQUIRED TAIL SIZE	71.2921
FWD CG LIMIT (CONTROL)	.0689	21.861	TAIL ARM (ELTH)	19.4081

0

VERTICAL TAIL AREA =	47.7328	FOR DIRECTIONAL STABILITY OF	.00200
RUDDER POWER AT MAX. DEFL. =	.0143	PER DEG. RUDDER CL AT MAX. DEFL. =	.3585
VERTICAL TAIL AREA =	51.3112	FOR MINIMUM CONTROL SPEED =	120.08 KTS
REQUIRED VERTICAL TAIL AREA =	51.3112	TAIL ARM (ELTV) =	14.5560

0

SUMMARY OF CRUISE LIFT-WEIGHT BALANCE

ANGLE OF ATTACK (DEGREES) = 5.345 LIFT = 16933.4 L/D = 12.523 ALTITUDE = 45000.0 MACH = .7300

0 WING LOCATION INFO.

FUSELAGE LENGTH	=	43.66	H-TAIL VOL. ARM	=	19.41	C.G. LOCATION OF PROPULSION =	28.51
WING 1/4C LOC. ON C.L.	=	22.14	H-TAIL C.G. LOCATION	=	43.76	C.G. OF REMAINING WEIGHT =	19.63
MAC 1/4C LOCATION	=	24.01	H-TAIL MAC FROM C.L.	=	4.02		
MAC DIST. FROM C.L.	=	8.41	H-TAIL LOCAT ON VERT.	=	1.00		
WING C.G. LOCATION	=	25.34	V-TAIL VOL. ARM	=	14.56		
TIP TANKS C.G. LOCATE	=	24.01	V-TAIL C.G. LOCATION	=	39.19	DIST. L.E. VERT. TO L.E. HORIZ. =	.32

0

	WING	H-TAIL	V-TAIL
AREA	241.788	71.292	51.311
SPAN	37.254	16.852	6.718
ASPECT RATIO	5.740	3.984	.879
TAPER RATIO	.550	.757	.537
1/4C SWEEP	12.500	24.000	38.000
L.E. SWEEP	15.231	25.638	43.607
C.L. CHORD	8.375	4.816	9.939
MEAN CHORD	6.673	4.237	7.869
TIP CHORD	4.606	3.645	5.337

Fig I2 - Learjet 35A GASP result (continued)

MISSION PERFORMANCE DATA FOLLOWS

0 TAXI AT IDLE THRUST

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	FUEL FLOW (LB/HR)
.000	0.	0.	17457.	5000.	574.
.167	0.	96.	17361.	5000.	574.

OVSTLKT= 121.0 KTS EAS VRAT= 1.100 CLTO= 1.1958
VEND = 249.9 KNOTS EAS
(TEMP.= 537. DEG:STD.+36.)
0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	95.6	17361.	5000.0	.0	.0	.000	10.80	.5696	.0774	1.00	.00	.0	.00	6178.	3104.	.00
1.0	5.4	96.5	17361.	5000.0	6.4	5.7	.009	10.69	.5696	.0774	1.00	.00	.0	.00	6119.	3104.	.00
2.0	21.5	97.4	17360.	5000.0	12.7	11.4	.019	10.57	.5696	.0774	1.00	.00	.0	.00	6060.	3104.	.00
3.0	48.2	98.2	17359.	5000.0	18.9	17.0	.028	10.45	.5696	.0774	1.00	.00	.0	.00	6002.	3104.	.00
4.0	85.3	99.1	17358.	5000.0	25.1	22.5	.037	10.32	.5697	.0774	1.00	.00	.0	.00	5944.	3103.	.00
5.0	132.8	100.0	17357.	5000.0	31.2	28.0	.046	10.19	.5697	.0774	1.00	.00	.0	.00	5887.	3103.	.00
6.0	190.6	100.8	17356.	5000.0	37.2	33.3	.055	10.05	.5698	.0774	1.00	.00	.0	.00	5831.	3106.	.00
7.0	258.4	101.7	17355.	5000.0	43.1	38.7	.064	9.91	.5698	.0774	1.00	.00	.0	.00	5776.	3106.	.00
8.0	336.1	102.5	17355.	5000.0	48.9	43.9	.073	9.77	.5699	.0774	1.00	.00	.0	.00	5721.	3107.	.00
9.0	423.6	103.4	17354.	5000.0	54.7	49.1	.081	9.62	.5700	.0774	1.00	.00	.0	.00	5668.	3107.	.00
10.0	520.8	104.3	17353.	5000.0	60.4	54.2	.090	9.47	.5701	.0774	1.00	.00	.0	.00	5615.	3108.	.00
11.0	627.5	105.1	17352.	5000.0	65.9	59.2	.098	9.32	.5702	.0774	1.00	.00	.0	.00	5563.	3108.	.00
12.0	743.5	106.0	17351.	5000.0	71.4	64.1	.106	9.18	.5703	.0774	1.00	.00	.0	.00	5523.	3109.	.00
13.0	868.7	106.9	17350.	5000.0	76.8	68.9	.114	9.05	.5704	.0774	1.00	.00	.0	.00	5488.	3110.	.00
14.0	1003.0	107.7	17349.	5000.0	82.2	73.7	.122	8.92	.5705	.0774	1.00	.00	.0	.00	5453.	3110.	.00
15.0	1146.3	108.6	17348.	5000.0	87.4	78.4	.130	8.78	.5706	.0774	1.00	.00	.0	.00	5418.	3111.	.00
16.0	1298.4	109.5	17348.	5000.0	92.6	83.1	.137	8.65	.5707	.0774	1.00	.00	.0	.00	5385.	3112.	.00
17.0	1459.1	110.3	17347.	5000.0	97.7	87.7	.145	8.51	.5709	.0774	1.00	.00	.0	.00	5351.	3113.	.00
18.0	1628.4	111.2	17346.	5000.0	102.7	92.2	.153	8.37	.5710	.0774	1.00	.00	.0	.00	5318.	3114.	.00
19.0	1806.0	112.0	17345.	5000.0	107.7	96.6	.160	8.22	.5711	.0774	1.00	.00	.0	.00	5286.	3115.	.00
20.0	1992.0	112.9	17344.	5000.0	112.5	100.9	.167	8.08	.5713	.0774	1.00	.00	.0	.00	5254.	3116.	.00
21.0	2186.0	113.8	17343.	5000.0	117.3	105.2	.174	7.93	.5714	.0774	1.00	.00	.0	.00	5223.	3116.	.00
22.0	2388.0	114.6	17342.	5000.0	121.9	109.4	.181	7.79	.5716	.0774	1.00	.00	.0	.00	5193.	3117.	.00
23.0	2597.8	115.5	17342.	5000.0	126.5	113.5	.188	7.64	.5717	.0774	1.00	.00	.0	.00	5162.	3118.	.00
24.0	2815.2	116.4	17341.	5000.0	131.0	117.5	.194	7.49	.5719	.0774	1.00	.00	.0	.00	5133.	3119.	.00
25.0	3040.2	117.2	17340.	5000.0	135.4	121.5	.201	7.34	.5721	.0774	1.00	.00	.0	.00	5104.	3120.	.00
26.0	3272.6	118.1	17339.	5000.0	139.7	125.4	.207	7.19	.5722	.0774	1.00	.00	.0	.00	5075.	3121.	.00
27.0	3512.2	119.0	17338.	5000.0	144.0	129.2	.214	7.05	.5724	.0775	1.00	.00	.0	.00	5047.	3122.	.00

0 ROTATION (TIME= 27.5 AND TAS= 146.0 EAS= 131.0)

28.0	3758.9	119.8	17337.	5000.0	148.1	132.9	.220	6.89	.6276	.0790	1.62	.00	.0	.52	5020.	3123.	.62
29.0	4012.4	120.7	17336.	5000.0	152.1	136.5	.226	6.65	.8057	.0856	3.67	.00	.0	.72	4993.	3124.	2.67
30.0	4272.7	121.6	17335.	5000.0	156.0	139.9	.232	6.32	.9838	.0947	5.81	.00	.0	.93	4968.	3125.	4.81

0 LIFTOFF (TIME= 30.2 DIST= 4325.5 TAS= 156.8 EAS= 140.6)

31.0	4539.2	122.4	17335.	5000.3	159.6	143.2	.237	5.76	1.1087	.1036	7.40	.25	69.5	1.10	4944.	3125.	6.64
32.0	4811.6	123.3	17334.	5003.0	162.8	146.1	.242	5.07	1.0660	.1083	7.10	.90	258.0	1.10	4923.	3126.	6.99
33.0	5089.0	124.2	17333.	5008.9	165.7	148.6	.246	4.35	1.0306	.1146	6.90	1.53	447.9	1.10	4904.	3127.	7.43
34.0	5370.7	125.1	17332.	5018.0	168.1	150.7	.250	3.77	1.0012	.1172	6.70	2.15	638.9	1.10	4889.	3128.	7.83
35.0	5656.2	125.9	17331.	5030.2	170.2	152.6	.253	3.33	.9715	.1161	6.40	2.77	832.8	1.09	4875.	3129.	8.16

0 DISTANCE TO 35 FT.= 5751.1
TAS= 170.8 EAS= 153.2 V35/V30= 1.2660

36.0	5944.8	126.8	17330.	5045.7	172.1	154.2	.255	2.93	.9341	.1150	6.20	3.37	1024.7	1.10	4864.	3129.	8.57
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0 GEAR RETRACTION STARTED AT 36.2 SEC, COMPLETE AT 43.2 SEC

37.0	6236.2	127.7	17329.	5064.4	173.7	155.7	.258	2.65	.9383	.1109	6.00	3.96	1216.8	1.10	4853.	3130.	8.96
38.0	6530.1	128.5	17329.	5086.3	175.2	157.0	.260	2.42	.9229	.1059	5.80	4.56	1411.9	1.10	4844.	3131.	9.36
39.0	6826.2	129.4	17328.	5111.4	176.6	158.2	.262	2.21	.9075	.1009	5.60	5.15	1606.0	1.10	4836.	3132.	9.74
40.0	7124.3	130.3	17327.	5139.8	177.9	159.3	.264	2.01	.8921	.0959	5.40	5.73	1798.6	1.09	4829.	3133.	10.12
41.0	7424.1	131.1	17326.	5171.4	179.1	160.2	.266	1.80	.8844	.0917	5.30	6.30	1992.0	1.10	4823.	3133.	10.60
42.0	7725.4	132.0	17325.	5206.2	180.1	161.0	.268	1.62	.8689	.0867	5.10	6.88	2186.3	1.09	4818.	3134.	10.98
43.0	8027.9	132.9	17324.	5244.3	181.0	161.8	.269	1.44	.8612	.0826	5.00	7.43	2377.2	1.09	4814.	3135.	11.44
44.0	8331.5	133.8	17323.	5285.5	181.8	162.4	.270	1.15	.8535	.0810	4.90	8.01	2568.3	1.09	4811.	3136.	11.91
45.0	8635.9	134.6	17322.	5329.9	182.4	162.8	.271	.85	.8457	.0802	4.80	8.58	2758.9	1.09	4809.	3137.	12.38
46.0	8940.7	135.5	17322.	5377.4	182.8	163.1	.272	.53	.8458	.0802	4.80	9.13	2940.6	1.10	4808.	3138.	12.93

0 FLAP RETRACTION STARTED AT 46.5 SEC, COMPLETE AT 52.5 SEC

47.0	9245.5	136.4	17321.	5427.9	183.1	163.1	.272	.19	.8418	.0811	5.20	9.69	3121.5	1.10	4809.	3139.	13.88
48.0	9550.0	137.2	17320.	5481.3	183.1	163.0	.272	.00	.8004	.0794	5.50	10.17	3275.7	1.05	4811.	3140.	14.67

0 OVSTLKT= 121.0 KTS EAS VRAT= 1.100 CLTO= 1.1958
0 ENGINE OUT PERFORMANCE FOLLOWS
VEND = 202.1 KNOTS EAS
(TEMP.= 537. DEG:STD.+36.)
0 TAKEOFF (ELEVATION= 5000. FT)

TIME (SEC)	DIST. (FEET)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	ACCEL (FPS2)	CL	CD	ALPHA (DEG)	GAMMA (DEG)	ROC (FPM)	LOAD FACT	THRUST (LBS)	FUEL FLOW (LB/HR)	FUS. ANGLE (DEG)
.0	.0	95.6	17361.	5000.0	.0	.0	.000	10.80	.5696	.0774	1.00	.00	.0	.00	6178.	3104.	.00
1.0	5.4	96.5	17361.	5000.0	6.4	5.7	.009	10.69	.5696	.0774	1.00	.00	.0	.00	6119.	3104.	.00
2.0	21.5	97.4	17360.	5000.0	12.7	11.4	.019	10.57	.5696	.0774	1.00	.00	.0	.00	6060.	3104.	.00
3.0	48.2	98.2	17359.	5000.0	18.9	17.0	.028	10.45	.5696	.0774	1.00	.00	.0	.00	6002.	3104.	.00
4.0	85.3	99.1	17358.	5000.0	25.1	22.5	.037	10.32	.5697	.0774	1.00	.00	.0	.00	5944.	3103.	.00
5.0	132.8	100.0	17357.	5000.0	31.2	28.0	.046	10.19	.5697	.0774	1.00	.00	.0	.00	5887.	3103.	.00
6.0	190.6	100.8	17356.	5000.0	37.2	33.3	.055	10.05	.5698	.0774	1.00	.00	.0	.00	5831.	3106.	.00
7.0	258.4	101.7	17355.	5000.0	43.1	38.7	.064	9.91	.5698	.0774	1.00	.00	.0	.00	5776.	3106.	.00
8.0	336.1	102.5	17355.	5000.0	48.9	43.9	.073	9.77	.5699	.0774	1.00	.00	.0	.00	5721.	3107.	.00
9.0	423.6	103.4	17354.	5000.0	54.7	49.1	.081	9.62	.5700	.0774	1.00	.00	.0	.00	5668.	3107.	.00
10.0	520.8	104.3	17353.	5000.0	60.4	54.2	.090	9.47	.5701	.0774	1.00	.00	.0	.00	5615.	3108.	.00
11.0	627.5	105.1	17352.	5000.0	65.9	59.2	.098	9.32	.5702	.0774	1.00	.00	.0	.00	5563.	3108.	.00
12.0	743.5	106.0	17351.	5000.0	71.4	64.1	.106	9.18	.5703	.0774	1.00	.00	.0	.00	5523.	3109.	.00
13.0	868.7	106.9	17350.	5000.0	76.8	68.9	.114	9.05	.5704	.0774	1.00	.00	.0	.00	5488.	3110.	.00
14.0	1003.0	107.7	17349.	5000.0	82.2	73.7	.122	8.92	.5705	.0774	1.00	.00	.0	.00	5453.	3111.	.00
15.0	1146.3	108.6	17348.	5000.0	87.4	78.4	.130	8.78	.5706	.0774	1.00	.00	.0	.00	5418.	3111.	.00
16.0	1298.4	109.5	17348.	5000.0	92.6	83.1	.137	8.65	.5707	.0774	1.00	.00	.0	.00	5385.	3112.	.00
17.0	1459.1	110.3	17347.	5000.0	97												

ROTATION (TIME= 30.1 AND TAS= 146.0 EAS= 131.0)

31.0	4488.0	120.4	17337.	5000.0	147.2	132.1	.219	2.09	.7037	.0867	2.49	.00	.0	.58	2513.	1561.	1.49
32.0	4737.6	120.8	17336.	5000.0	148.4	133.1	.220	1.95	.8918	.0942	4.58	.00	.0	.75	2509.	1561.	3.58
33.0	4989.2	121.2	17336.	5000.0	149.5	134.1	.222	1.71	1.0599	.1043	6.77	.00	.0	.91	2503.	1562.	5.77

LIFTOFF (TIME= 33.4 DIST= 5090.3 TAS= 149.9 EAS= 134.5)

34.0	5242.5	121.7	17335.	5000.1	150.4	134.9	.223	1.36	1.1958	.1150	8.52	.11	30.2	1.03	2502.	1562.	7.64
35.0	5497.2	122.1	17335.	5001.4	151.1	135.6	.224	.97	1.1958	.1202	8.67	.49	130.3	1.06	2500.	1562.	8.13
36.0	5752.8	122.5	17335.	5004.3	151.5	135.9	.225	.42	1.1958	.1304	8.85	.92	247.8	1.06	2499.	1562.	8.78
37.0	6008.7	123.0	17334.	5009.7	151.6	136.0	.225	.02	1.1614	.1355	8.61	1.36	265.3	1.04	2499.	1562.	8.97
38.0	6264.7	123.4	17334.	5016.0	151.6	136.0	.225	.02	1.1110	.1347	8.11	1.41	378.6	.99	2499.	1562.	8.52
39.0	6520.8	123.8	17333.	5022.1	151.6	136.0	.225	.02	1.1055	.1364	8.11	1.32	353.8	.98	2499.	1562.	8.43
40.0	6776.8	124.3	17333.	5027.8	151.6	136.0	.225	.02	1.1106	.1383	8.21	1.24	331.7	.99	2499.	1562.	8.45
41.0	7032.9	124.7	17332.	5033.2	151.7	136.0	.225	.01	1.1170	.1398	8.31	1.18	316.0	1.00	2499.	1562.	8.49

DISTANCE TO 35 FT.= 7120.1 TAS= 151.7 EAS= 136.0 V35/V50= 1.1239

42.0	7289.0	125.1	17332.	5038.4	151.7	136.0	.225	.02	1.1163	.1401	8.31	1.14	306.4	.99	2499.	1562.	8.45
43.0	7545.1	125.6	17332.	5043.4	151.7	136.0	.225	.00	1.1237	.1414	8.41	1.11	297.8	1.00	2499.	1562.	8.52
44.0	7801.2	126.0	17331.	5048.4	151.7	136.0	.225	.00	1.1235	.1415	8.41	1.10	295.9	1.00	2499.	1562.	8.51

ACCELERATE - STOP DISTANCE = 6765.9 FEET.
 0 ENGINE OUT DISTANCE TO 35 FT. = 7120.1 FEET
 0 ALL ENGINE DISTANCE TO 35 FT. (L) = 5751.1 FEET
 FAR 25 T.O. DISTANCE (1.15XL) = 6613.8 FEET
 ALL ENGINE DISTANCE TO 50 FT. = 6013.9 FEET
 0 AT END OF TAKEOFF PHASE
 TIME= .180 HRS FUEL USED= 138. LBS WEIGHT= 17320. LBS ALT.= 5500. FT.

ACCELERATE TO MACH NO. = .418

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.180	.00	137.5	17320.	5500.	177.	163.	.272	.736	6046.	3831.
.185	1.24	158.6	17299.	5500.	271.	250.	.418	.791	5626.	3916.

END OF ACCELERATION SEGMENT
 0 TIME= .185 HRS FUEL USED= 158.6 LBS WEIGHT= 17299. LBS RANGE= 1. NM
 0 CLIMB TO 45000. FT. AT MAXIMUM RATE OF CLIMB

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	PUS. ANGLE (DEG)	R/C (FPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
.185	1.	159.	17299.	5500.	271.	230.	.418	.793	.3296	.0291	3.03	12.64	14.69	6015.	5277.	3665.
.187	2.	164.	17293.	6000.	273.	250.	.421	.793	.3311	.0291	3.06	11.32	13.38	5434.	5224.	3633.
.190	2.	175.	17282.	7000.	277.	250.	.429	.793	.3313	.0291	3.03	10.94	12.99	5336.	5110.	3563.
.193	3.	186.	17271.	8000.	282.	250.	.438	.793	.3315	.0291	3.04	10.56	12.61	5233.	4997.	3499.
.196	4.	197.	17260.	9000.	286.	250.	.446	.793	.3317	.0291	3.04	10.18	12.22	5126.	4884.	3432.
.199	5.	208.	17249.	10000.	291.	250.	.455	.793	.3319	.0291	3.03	9.80	11.83	5014.	4770.	3366.
.203	6.	219.	17238.	11000.	309.	261.	.485	.796	.3320	.0280	2.63	10.14	11.77	5507.	4602.	3315.
.206	7.	229.	17228.	12000.	311.	259.	.491	.795	.3321	.0282	2.69	9.23	10.92	5057.	4499.	3248.
.209	8.	240.	17217.	13000.	314.	257.	.496	.795	.3322	.0284	2.75	8.94	10.49	4941.	4396.	3181.
.212	9.	251.	17206.	14000.	316.	255.	.502	.794	.3323	.0286	2.80	8.67	10.46	4826.	4297.	3114.
.216	10.	262.	17195.	15000.	319.	253.	.508	.794	.3324	.0288	2.85	8.39	10.24	4708.	4198.	3047.
.219	11.	272.	17185.	16000.	321.	251.	.514	.793	.3325	.0291	2.91	8.11	10.02	4590.	4099.	2981.
.223	12.	283.	17174.	17000.	324.	249.	.520	.792	.3326	.0293	2.97	7.84	9.80	4472.	4002.	2916.
.227	14.	294.	17163.	18000.	326.	247.	.526	.791	.3327	.0296	3.02	7.56	9.59	4353.	3904.	2851.
.231	13.	305.	17152.	19000.	329.	245.	.533	.791	.3328	.0300	3.09	7.30	9.38	4233.	3811.	2786.
.234	16.	316.	17141.	20000.	332.	242.	.539	.790	.3330	.0301	3.14	7.03	9.17	4114.	3717.	2722.
.239	17.	327.	17130.	21000.	334.	240.	.546	.789	.3331	.0304	3.20	6.77	8.97	3994.	3624.	2659.
.243	19.	338.	17119.	22000.	338.	239.	.553	.789	.3332	.0307	3.25	6.45	8.70	3870.	3532.	2597.
.247	20.	349.	17108.	23000.	349.	242.	.574	.790	.3333	.0308	3.09	4.91	7.01	3025.	3417.	2545.
.253	22.	363.	17094.	24000.	371.	254.	.614	.794	.3334	.0298	2.66	3.40	5.06	2231.	3294.	2512.
.260	25.	382.	17075.	25000.	375.	251.	.622	.793	.3335	.0290	2.69	5.12	6.81	3389.	3203.	2451.
.265	27.	394.	17063.	26000.	378.	249.	.630	.792	.3336	.0293	2.74	4.97	6.71	3317.	3114.	2390.
.270	29.	406.	17051.	27000.	381.	247.	.638	.791	.3337	.0296	2.80	4.73	6.53	3186.	3027.	2329.
.275	31.	418.	17039.	28000.	384.	244.	.646	.791	.3338	.0299	2.85	4.50	6.36	3056.	2942.	2270.
.281	33.	431.	17026.	29000.	387.	242.	.654	.790	.3339	.0302	2.91	4.28	6.18	2927.	2859.	2212.
.286	35.	443.	17014.	30000.	391.	240.	.662	.789	.3340	.0305	2.96	4.05	6.02	2799.	2776.	2155.
.292	37.	456.	17001.	31000.	394.	237.	.671	.788	.3341	.0308	3.01	3.84	5.85	2671.	2696.	2098.
.299	40.	469.	16988.	32000.	398.	235.	.680	.787	.3342	.0312	3.06	3.62	5.69	2545.	2617.	2043.
.305	42.	483.	16974.	33000.	401.	233.	.689	.787	.3343	.0315	3.11	3.41	5.53	2419.	2540.	1989.
.312	45.	496.	16961.	34000.	405.	231.	.699	.786	.3344	.0319	3.16	3.20	5.36	2299.	2464.	1935.
.319	48.	511.	16947.	35000.	409.	229.	.709	.785	.3345	.0322	3.20	2.98	5.18	2154.	2390.	1884.
.327	51.	525.	16932.	36000.	415.	227.	.722	.784	.3346	.0324	3.21	2.68	4.89	1962.	2318.	1834.
.336	55.	541.	16916.	37000.	419.	224.	.730	.783	.3347	.0330	3.29	2.49	4.77	1842.	2216.	1760.
.345	59.	557.	16901.	38000.	419.	219.	.730	.781	.3348	.0341	3.49	2.62	5.11	1940.	2112.	1677.
.353	62.	571.	16886.	39000.	419.	214.	.730	.778	.3349	.0353	3.71	2.34	5.05	1735.	2013.	1599.
.363	66.	586.	16871.	40000.	419.	209.	.730	.776	.3350	.0366	3.94	2.07	5.01	1536.	1919.	1524.
.374	71.	603.	16854.	41000.	419.	204.	.730	.773	.3351	.0381	4.17	1.81	4.98	1340.	1829.	1453.
.386	76.	621.	16836.	42000.	419.	199.	.730	.770	.3352	.0397	4.42	1.53	4.97	1148.	1744.	1383.
.401	82.	641.	16816.	43000.	419.	194.	.730	.767	.3353	.0414	4.68	1.29	4.97	959.	1662.	1320.
.418	89.	664.	16793.	44000.	419.	190.	.730	.764	.3354	.0433	4.95	1.04	4.99	773.	1583.	1259.
.440	98.	691.	16766.	45000.	419.	185.	.730	.761	.3355	.0454	5.23	.80	5.03	590.	1511.	1200.

0 END OF CLIMB TO 45000. FT
 TIME= .440 HRS FUEL USED= 691. LBS WEIGHT= 16766. LBS RANGE= 98. NM
 0 ALTITUDE= 45000. FT TAS= 463.31 KTS MACH NO= .8070

ACCELERATE TO MACH NO. = .807

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.440	98.32	691.2	16766.	45000.	419.	185.	.730	.760	1566.	1256.
.482	118.27	749.0	16708.	45000.	463.	205.	.807	.773	1578.	1307.

END OF ACCELERATION SEGMENT
 TIME= .482 HRS FUEL USED= 749.0 LBS WEIGHT= 16708. LBS RANGE= 118. NM

ACCELERATE TO MACH NO. = .790

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	THRUST (LBS)	FUEL FLOW (LB/HR)
.440	98.32	691.2	16766.	45000.	419.	185.	.730	.760	1566.	1256.
.473	113.58	735.7	16721.	45000.	453.	200.	.790	.770	1578.	1296.

END OF ACCELERATION SEGMENT
 TIME= .473 HRS FUEL USED= 735.7 LBS WEIGHT= 16721. LBS RANGE= 114. NM

Fig I2 - Learjet 35A GASP result (continued)

DESIGN CASE
CRUISE PERFORMANCE SUMMARY
FOR
***** DESIGN PAYLOAD *****
***** MAXIMUM PAYLOAD *****
***** MAXIMUM FUEL *****
FUEL AVAILABLE= 5447.

		AT		AT		AT	
		SPECIFIED	NORMAL	BEST SPEC.	RANGE	START	END
TIME	HRS.	START	END	START	END	START	END
RANGE	N.MI	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE	CRUISE
		.440	4.743	.482	3.986	.473	4.483
FUEL USED	LBS.	98.	1902.	118.	1741.	114.	1931.
WEIGHT	LBS.	16766.	12790.	16708.	13196.	16721.	12815.
ALTITUDE	FT.	45000.	45000.	45000.	45000.	45000.	45000.
TAS	KTS.	419.1	419.1	463.3	463.3	453.3	453.3
EAS	KTS.	184.8	184.8	204.3	204.3	199.9	199.9
MACH NO.		.7300	.7300	.8070	.8070	.7896	.7896
DIV. MACH		.7601	.7773	.7735	.7880	.7708	.7852
ANGLE ATTACK	DEG.	5.283	3.793	3.775	2.604	4.081	2.894
FUSE. ANGLE	DEG.	4.283	2.793	2.775	1.604	3.081	1.894
CL		.6007	.4583	.4898	.3697	.5121	.3925
L/D		12.530	12.123	12.189	11.376	12.476	11.684
FUEL FLOW	LB/HR	1039.4	817.2	1111.7	901.0	1072.9	881.4
BREG. FACTOR	N.MI.	6764.	6563.	6968.	6790.	7070.	6595.
SPEC. RANGE	NM/LB	.40320	.51282	.41677	.51422	.42252	.51429

0 DESCENT FROM CRUISE AT NORMAL POWER CONDITION
(U=NO CONSTRAINT; W= 500. FPM CABIN; A= -6.00 FUS. ANGLE; S=MD OR VMD)

TIME (HRS)	RANGE (NM)	FUEL USED (LBS)	WEIGHT (LBS)	ALT. (FT)	TAS (KTS)	EAS (KTS)	MACH NO.	MACH DIV	CL	CD	ALPHA (DEG)	GAMMA (DEG)	FUS. ANGLE (DEG)	R/S (PPM)	THRUST (LBS)	FUEL FLOW (LB/HR)
3.996	1746.	4265.	13192.	45000.	463.	205.	.807	.786	.3821	.0333	2.73	-2.00	-2.27	1636.	687.	394. U
4.006	1751.	4269.	13188.	44000.	463.	210.	.807	.789	.3642	.0323	2.55	-2.01	-4.46	1650.	705.	406. U
4.016	1755.	4273.	13184.	43000.	463.	215.	.807	.791	.3471	.0315	2.38	-2.04	-6.66	1673.	724.	419. U
4.026	1760.	4277.	13180.	42000.	463.	220.	.807	.793	.3309	.0307	2.23	-2.08	-8.86	1706.	742.	432. U
4.035	1764.	4282.	13175.	41000.	463.	225.	.807	.795	.3154	.0300	2.07	-2.13	-11.06	1748.	762.	445. U
4.045	1769.	4288.	13169.	40000.	463.	231.	.807	.796	.3006	.0294	1.93	-2.13	-12.20	1742.	798.	490. R
4.055	1773.	4296.	13162.	39000.	463.	236.	.807	.798	.2864	.0288	1.79	-2.04	-12.25	1676.	853.	733. R
4.065	1778.	4304.	13154.	38000.	463.	242.	.807	.800	.2729	.0283	1.66	-1.96	-12.30	1611.	911.	780. R
4.076	1783.	4312.	13145.	37000.	463.	248.	.807	.801	.2600	.0279	1.53	-1.89	-12.36	1550.	972.	830. R
4.087	1788.	4322.	13135.	36000.	464.	254.	.807	.803	.2477	.0275	1.42	-1.82	-12.41	1494.	1035.	882. R
4.099	1794.	4333.	13124.	35000.	466.	260.	.807	.804	.2361	.0271	1.30	-1.76	-12.46	1452.	1098.	939. R
4.110	1799.	4345.	13112.	34000.	468.	266.	.807	.805	.2251	.0267	1.19	-1.71	-12.51	1413.	1164.	999. R
4.123	1805.	4358.	13099.	33000.	470.	273.	.807	.807	.2146	.0264	1.09	-1.65	-12.56	1375.	1232.	1060. R
4.135	1811.	4372.	13085.	32000.	472.	279.	.807	.808	.2047	.0261	1.00	-1.60	-12.61	1339.	1303.	1123. R
4.148	1817.	4387.	13070.	31000.	474.	285.	.807	.809	.1954	.0259	.90	-1.55	-12.65	1304.	1381.	1196. R
4.161	1823.	4404.	13054.	30000.	476.	292.	.807	.810	.1863	.0257	.82	-1.51	-12.69	1271.	1456.	1264. R
4.174	1830.	4422.	13036.	29000.	478.	299.	.807	.811	.1780	.0255	.74	-1.47	-12.73	1240.	1536.	1339. R
4.188	1836.	4441.	13016.	28000.	480.	305.	.807	.812	.1700	.0253	.66	-1.42	-12.77	1209.	1612.	1411. R
4.202	1843.	4462.	12995.	27000.	482.	312.	.807	.813	.1624	.0251	.58	-1.39	-12.80	1183.	1700.	1492. R
4.217	1850.	4485.	12972.	26000.	484.	319.	.807	.814	.1552	.0250	.51	-1.35	-12.83	1155.	1787.	1574. R
4.220	1852.	4487.	12970.	25000.	486.	326.	.807	.815	.1479	.0248	.44	-1.30	-12.86	1135.	1877.	1660. U
4.224	1854.	4490.	12967.	24000.	488.	333.	.807	.815	.1416	.0247	.38	-1.27	-12.89	1121.	1970.	1750. U
4.228	1855.	4492.	12965.	23000.	488.	335.	.793	.816	.1403	.0247	.33	-1.25	-12.91	1111.	2071.	1844. U
4.231	1857.	4495.	12962.	22000.	475.	336.	.779	.816	.1396	.0247	.30	-1.23	-12.92	1103.	2171.	1938. U
4.235	1859.	4497.	12960.	21000.	468.	337.	.765	.816	.1387	.0247	.27	-1.21	-12.93	1100.	2271.	2032. U
4.239	1861.	4500.	12957.	20000.	462.	338.	.751	.816	.1379	.0247	.24	-1.19	-12.94	1100.	2371.	2128. U
4.243	1862.	4503.	12954.	19000.	455.	338.	.737	.816	.1372	.0246	.22	-1.17	-12.95	1100.	2471.	2224. U
4.247	1864.	4505.	12952.	18000.	449.	339.	.724	.816	.1365	.0246	.20	-1.15	-12.96	1100.	2571.	2320. U
4.250	1866.	4508.	12949.	17000.	442.	340.	.711	.816	.1359	.0246	.18	-1.14	-12.97	1100.	2671.	2416. U
4.254	1868.	4511.	12946.	16000.	436.	341.	.698	.816	.1353	.0246	.16	-1.13	-12.98	1100.	2771.	2512. U
4.258	1869.	4514.	12943.	15000.	430.	341.	.685	.816	.1348	.0246	.14	-1.12	-12.99	1100.	2871.	2608. U
4.263	1871.	4517.	12940.	14000.	423.	342.	.673	.816	.1343	.0246	.12	-1.11	-13.00	1100.	2971.	2704. U
4.267	1873.	4521.	12936.	13000.	417.	342.	.660	.816	.1339	.0246	.11	-1.10	-13.01	1100.	3071.	2800. U
4.271	1874.	4524.	12933.	12000.	411.	343.	.648	.816	.1333	.0246	.10	-1.09	-13.02	1100.	3171.	2896. U
4.275	1876.	4527.	12930.	11000.	405.	343.	.636	.816	.1328	.0246	.09	-1.08	-13.03	1100.	3271.	2992. U
4.289	1880.	4536.	12921.	10000.	291.	250.	.455	.802	.2512	.0276	2.05	-2.33	-12.29	1201.	888.	624. S
4.303	1884.	4545.	12912.	9000.	286.	250.	.446	.802	.2511	.0276	2.05	-2.35	-12.30	1190.	884.	627. S
4.317	1888.	4554.	12904.	8000.	282.	250.	.438	.802	.2509	.0276	2.06	-2.37	-12.31	1181.	880.	629. S
4.331	1892.	4563.	12895.	7000.	277.	250.	.430	.802	.2507	.0276	2.07	-2.39	-12.32	1174.	875.	632. S
4.346	1896.	4572.	12886.	6000.	273.	250.	.422	.802	.2505	.0275	2.07	-2.42	-12.34	1169.	870.	633. S
4.360	1900.	4581.	12876.	5000.	269.	250.	.414	.802	.2504	.0275	2.08	-2.44	-12.36	1163.	864.	634. S
4.374	1904.	4590.	12867.	4000.	265.	250.	.406	.802	.2502	.0275	2.08	-2.47	-12.39	1158.	858.	634. S
4.389	1907.	4599.	12858.	3000.	261.	250.	.399	.802	.2500	.0275	2.09	-2.50	-12.41	1154.	852.	633. S
4.403	1911.	4608.	12849.	2000.	257.	250.	.391	.802	.2498	.0275	2.09	-2.53	-12.44	1152.	845.	631. S
4.410	1913.	4613.	12844.	1500.	255.	250.	.388	.802	.2496	.0275	2.09	-2.55	-12.46	1152.	841.	630. S

0 END OF DSCNT TO 1500. FT
TIME= 4.410 HRS FUEL USED= 4613. LBS WEIGHT= 12844. LBS RANGE= 1913. NM

0 RESERVE FUEL(LBS) 780. 834. 805.
(45.0 MIN.)
.....
0 RANGE = 1913. BLOCK TIME= 4.410 USED FOR DESIGN RANGE AND COST
.....

0 TEMP. = 537. DEG. STD. +36.
0 LANDING ELEVATION= 5000. FT.
0 LANDING WING LOADING= 60.36 PSP.
0 LANDING WEIGHT = 14594. LBS.
0 LANDING DISTANCE FROM 50. FT. = 1587. FT.

0 F.A.R. FACTORED FIELD LENGTH = 5978. FT.
0 APPROACH TRANSITION DELAY ROLL
0 DIST= 774. DIST= 225. DIST= 229. DIST= 2359.
0 R/S= 1000. ILMF= 1.200 TDELAY= 1.00 MUB= .4000
0 VAREAS= 137.13 SINKTD= 3.000 TIDLE= 349. TR/TIDLE= .0000
0 VAPTAS= 153.01 VSTEAS= 105.48 VTOTAS= 135.36 ABAR(G)= .3445
0 THETA= 3.70 CLMX= 1.5993
0 THRUST= 1215. HFLAR= 20.9
0

Fig I2 - Learjet 35A GASP result (continued)


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.....
0 RANGE OR ENDURANCE ITERATION SUMMARY

      GROSS RANGE (NMI) OR
ITERATION WEIGHT (LB) ENDURANCE (HR)
      0 19000.00 2116.848
      1 15770.00 1519.653
      2 17827.15 1983.431
      3 17457.08 1913.034
      REQUIRED RG. OR END. = 1900.000

0 SUMMARY OF CRUISE LIFT-WEIGHT BALANCE
ANGLE OF ATTACK (DEGREES) = 5.345 LIFT = 16933.4 L/D = 12.523 ALTITUDE = 45000.0 MACH = .7300

0 GROSS WEIGHT = 17457. PASSENGERS = 8. PLUS CREW

0 FUSELAGE LENGTH (ELF) 43.66 FT
          WIDTH (SWP) 5.50 FT
          WETTED AREA (SF) 613. SQFT
          DELTA P (DELP) 9.40 PSI

0 WING ASPECT RATIO (AR) 5.74
       AREA (SW) 241.8 SQFT
       SPAN (B) 37.3 FT
       GEOM. MEAN CHORD (CBARM) 6.67 FT
       QUARTER CHORD SWEEP (DLQCS) 12.5 DEG
       TAPER RATIO (SLM) .550
       ROOT THICKNESS (TCR) .090
       TIP THICKNESS (TCT) .090
       WING LOADING (WGS) 72.2 PSF
       WING FUEL VOLUME (VFW) 353.0 GAL

0 HOR. TAIL ASPECT RATIO (ARHT) 3.98
           AREA (SHT) 71.3 SQFT
           SPAN (BHT) 16.85 FT
           MEAN CHORD (CBARHT) 4.26 FT
           THICKNESS/CHORD (TCHT) .080
           MOMENT ARM (ELTH) 19.4 FT
           VOLUME COEFF. (VBARH) .858

0 VERT. TAIL ASPECT RATIO (ARVT) .88
           AREA (SVT) 51.3 SQFT
           SPAN (BVT) 6.72 FT
           MEAN CHORD (CBARVT) 7.67 FT
           THICKNESS/CHORD (TCVT) .100
           MOMENT ARM (ELTV) 14.6 FT
           VOLUME COEFF. (VBARV) .083

0 ENG. NACELLES LENGTH (ELN) 7.55 FT
              MEAN DIAMETER (DBARN) 2.42 FT
              NUMBER ENGINES (ENP) 2.0
              WETTED AREA (SN) 114.75 SQFT

0 TIP TANKS LOCATION ON FUSELAGE
            VOLUME (VFTP) 24.67 CUFT
            DIAMETER (BXIS) 1.82 FT
            LENGTH (AXIS) 14.55 FT
            WETTED AREA (STIP) 128.54 SQFT

0 VDIVE = 643. KTS VMO = 536. KTS MMO = .900
  ULT. LP = 6.21 MAN. LP = 2.50 GUST LP = 4.14

0 PROPULSION GROUP
  PRIMARY ENGINES (WEP) 1610.
  PRIMARY ENGINE INSTL. (WPEI) 217.
  FUEL SYSTEM (WFSS) 109.
  TOTAL PROP. GROUP WT. (WP) 1937.

0 STRUCTURES GROUP
  WING (WW) 1819.
  HOR. TAIL (WHT) 317.
  VERT. TAIL (WVT) 187.
  FUSELAGE (WB) 1963. (INCL. .0 LBS A.T.W.)
  LANDING GEAR (WLG) 555.
  PRIMARY ENG. SECTION (WPEP) 478.
  TIP TANKS (WTIP) 243.
  GROUP WEIGHT INC. (DEWST) 0.
  TOTAL STRUC. GROUP WT. (WST) 5562.

0 FLIGHT CONTROLS GROUP
  COCKPIT CONTROLS (WCC) 36.
  FIXED WING CONTROLS (WCFW) 373.
  SAS (WSAS) 0.
  GROUP WEIGHT INC. (DELWPC) 0.
  TOTAL CONTROL WT. (WPC) 409.

0 WT. OF FIXED EQUIPMENT (WFE) 1943.

WEIGHT EMPTY (WE) 9850.

FIXED USEFUL LOAD (WFUL) 560. (INC. CREW)

OPERATING WEIGHT EMPTY (OWE) 10411.
0 PAYLOAD (WPL) 1600. (PAX.VOL. = 8. DESIGN PAX = 8.)

FUEL (WFA) 5447. (WFW = 2360.) (WFTP = 2468.)

GROSS WEIGHT (WG) 17457.

0 FIXED EQUIP GROUP FIXED USEFUL LOAD
0 WAPU .00 WCREW ( 2. ) 340.00
  WINSTR 111.83 WSTU ( 0. ) .00
  WHYD 129.70 WCBAG 50.00
  WELEC 541.59 WUF 93.30
  WAV 340.00 WOLL 66.86
  WPAR 534.00 WSRV .00
  WAC 237.00 WHZO .00
  WAI 46.11 WEMER 10.00
  WAUXG 3.00 WCATER .00

WFE 1943.24 WFUL 560.16

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Fig I2 - Learjet 35A GASP result (continued)

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0 DESIGN MACH = .730          DESIGN ALTITUDE = 45000.          DESIGN Q (PSP) =115.60
0 DESIGN RE.NUM. PER FT. = 1.102E+06  FLATPLATE CF AT RE=10EX7 IS .00276

0 AERODYNAMIC DATA

0 DRAG BREAKDOWN          FLATPLATE          WETTED
0 MACH                    AREA(SQFT)      CDO          AREA(SQFT)
0 WING                    1.7180          .00711       394.52
0 FUSELAGE                2.2462          .00929       613.17
0 VERT.TAIL               .3515          .00145       102.62
0 HOR. TAIL               .5198          .00215       142.58
0 ENGINE MAC.            .5451          .00225       114.75
0 TIP TANKS              .3745          .00155       128.54
0 INCREMENTAL            .0000          .00000       .00
0 TOTAL                   5.7551          .02380       1496.17

MEAN SKIN FRICTION COEF.= .003847

0 AERODYNAMIC COEFF.
A1                      .8326
A2                     -.1207
A3                      .0249
A4=.75X(T/C)           .0675
A5=CDO--              .0144
A6                     2.5727
A7=1/(PI.SEE.AR)      .0641
3-D LIFT SLOPE AT CRUISE MACH (CLALPH) 5.4782 PER RADIAN
OSWALD FACTOR         (SEE) .8442

0 CRUISE CD = .0238 + .0641 CL2 (ASSUMES MINIMUM WING PROFILE DRAG)
0 RETRACTABLE LANDING GEAR CD INC.= .02918

0 CRUISE DRAG
OCL= .2000
MACH  CD  L/D  CLALPH  ALPHA
.50000 .02640 7.5750 4.8041 1.3853
.55000 .02640 7.5750 4.9083 1.3346
.60000 .02640 7.5750 5.0317 1.2774
.65000 .02640 7.5750 5.1785 1.2128
.70000 .02640 7.5750 5.3548 1.1400
.75000 .02640 7.5750 5.5692 1.0576
.80000 .02640 7.5750 5.8350 .9639
.85000 .02816 7.1025 6.1734 .8562
OCL= .3000
MACH  CD  L/D  CLALPH  ALPHA
.50000 .02975 10.0825 4.8041 2.5779
.55000 .02975 10.0825 4.9083 2.5020
.60000 .02975 10.0825 5.0317 2.4161
.65000 .02975 10.0825 5.1785 2.3192
.70000 .02975 10.0825 5.3548 2.2100
.75000 .02975 10.0825 5.5692 2.0864
.80000 .02976 10.0821 5.8350 1.9458
.85000 .03353 8.9476 6.1734 1.7843
OCL= .4000
MACH  CD  L/D  CLALPH  ALPHA
.50000 .03439 11.6317 4.8041 3.7705
.55000 .03439 11.6317 4.9083 3.6693
.60000 .03439 11.6317 5.0317 3.5548
.65000 .03439 11.6317 5.1785 3.4257
.70000 .03439 11.6317 5.3548 3.2800
.75000 .03439 11.6317 5.5692 3.1152
.80000 .03448 11.5998 5.8350 2.9277
.85000 .04133 9.6787 6.1734 2.7124
OCL= .5000
MACH  CD  L/D  CLALPH  ALPHA
.50000 .04049 12.3497 4.8041 4.9632
.55000 .04049 12.3497 4.9083 4.8366
.60000 .04049 12.3497 5.0317 4.6935
.65000 .04049 12.3497 5.1785 4.5321
.70000 .04049 12.3497 5.3548 4.3499
.75000 .04049 12.3497 5.5692 4.1439
.80000 .04101 12.1919 5.8350 3.9097
.85000 .05200 9.6163 6.1734 3.6405
OCL= .6000
MACH  CD  L/D  CLALPH  ALPHA
.50000 .04787 12.5346 4.8041 6.1558
.55000 .04787 12.5346 4.9083 6.0039
.60000 .04787 12.5346 5.0317 5.8322
.65000 .04787 12.5346 5.1785 5.6385
.70000 .04787 12.5346 5.3548 5.4199
.75000 .04787 12.5346 5.5692 5.1727
.80000 .04941 12.1423 5.8350 4.8916
.85000 .06561 9.1452 6.1734 4.5686

0 LOW SPEED LIFT/DRAG-GR.UP(IF R)O.G.E.
FLAPS UP          TAKEOFF          LANDING
ALPHA  CL  CD  L/D  CL  CD  L/D  CL  CD  L/D
-2.00000 -.07723 .02439 -3.16690 .31307 .04987 6.27781 .47002 .09231 5.09177
.00000 .07723 .02419 3.19240 .46753 .05454 8.57307 .62448 .09781 6.38489
2.00000 .23170 .02733 8.47897 .62200 .06251 9.94993 .77895 .10705 7.27662
4.00000 .38616 .03367 11.46869 .77647 .07386 10.51336 .93341 .12009 7.77232
6.00000 .54063 .04333 12.47679 .93093 .08889 10.47254 1.08788 .13723 7.92760
8.00000 .69510 .05642 12.31925 1.08540 .10797 10.05297 1.24234 .15889 7.81879
10.00000 .84956 .07317 11.61047 1.23986 .13190 9.39994 1.39681 .18596 7.51132
12.00000 1.00403 .09386 10.69678 1.39433 .16068 8.67752 1.55127 .21810 7.11232
12.62174 1.05929 .10309 10.27554 1.44694 .17121 8.45143 1.59929 .22883 6.98905
12.62174 1.05929 .10309 10.27554 1.44694 .17121 8.45143 1.59929 .22883 6.98905

0 DFLAP=.00          DFLAP= 20.00          DFLAP= 40.00
0 CLMAX= 1.05929    CLMAX= 1.44694        CLMAX= 1.59929

```

Fig I2 - Learjet 35A GASP result (continued)

0 LOW SPEED AERO FOR OTHER FLAP DEFLECTIONS

FLAP DEFL.	CLMAX	CL	CD	L/D
10.000	1.27642	.14714	.03627	4.05679
		.30160	.03956	7.62314
		.45607	.04609	9.99514
		.61054	.05597	10.90773
		.76500	.06933	11.03418
		.91947	.08640	10.64223
		1.07393	.10751	9.98888
		1.22840	.13462	9.12502
		1.27642	.14367	8.88407
		1.27642	.14367	8.88407
30.000	1.55004	.42076	.06900	6.09789
		.57523	.07425	7.74730
		.72969	.08294	8.79793
		.88416	.09515	9.29264
		1.03863	.11110	9.34866
		1.19309	.13135	9.08038
		1.34756	.15681	8.59383
		1.50202	.18686	8.03839
		1.55004	.19687	7.87362
		1.55004	.19687	7.87362

0 ALTITUDE= 45000. FT TAS= 465.73 KTS MACH NO= .8112

0 RDT&E AND AIRFRAME PRODUCTION COSTS
 0 (1993. DOLLARS)
 0 TOTAL RDT&E COSTS 435.6924 MILLION
 0 AIRFRAME PRODUCTION COSTS (INCLUDING 10% PROFIT)
 0 700. AIRCRAFT

	WEIGHT (LB)	COST (\$)	COST (\$/LB)
STRUCTURE(1833739.\$)			
WING	2062.	573065.	277.90
EMPENNAGE	503.	204737.	406.63
FUSELAGE	1963.	657176.	334.74
LANDING GEAR	555.	111313.	200.52
WACELLES	478.	287447.	601.65
PROPULSION INSTAL(91778.\$)			
ENGINE INSTALLAT.	217.	76797.	353.27
FUEL SYSTEM	109.	14981.	137.53
SYSTEMS(608136.\$)			
FLIGHT CONTROLS	409.	186171.	455.47
HYDRAULIC	130.	15676.	120.87
ELECTRICAL	542.	251494.	464.36
AIR CONDITIONING	237.	123219.	519.90
ANTI-ICING	46.	23562.	511.02
AUX. POWER UNIT	0.	0.	.00
FURNISHINGS	534.	88984.	166.64
INSTRUMENTS	112.	87191.	779.65
AVIONICS INSTALL.	170.	31340.	184.35
AUX. ITEMS	3.	500.	166.64
INTEGRATION(683414.\$)			
AIRFRAME TOTALS	8070.	3417068.	423.43
ENGINES		1105750.	
PROPELLER		0.	
AVIONICS		1000000.	
A/C COST (NO RD)		5522817.	
R&D PER A/C		622418.	
TOTAL A/C COST		6145235.	

0 ENGINES NUMBER = 2. TYPE= 7

0 EMPTY WEIGHT= 9850. AIRFRAME WEIGHT= 8240. WEIGHT OF 1 ENGINE= 805. CRUISE SPEED= 466. KTS
 0 THRUST/ENGINE= 3968.
 0 TOTAL AIRCRAFT COST= 6145235. AIRFRAME COST= 5039485. COST OF 1 ENGINE= 552875. COST OF 1 PROP.= 0.

0 --- COST DATA ---
 0 GASP SHORTHAIL METHOD

0 DESIGN MISSION
 0 OPERATING COST FOR NOR. RATED POWER AND 45000. ALTITUDE

0
 0 RANGE= 1913. N.M. BLOCK FUEL= 4613. LBS BLOCK TIME= 4.4104 HRS.
 0 UTILIZATION 800.

0 FLYING OPERATIONS

FLIGHT CREW	99.235
FUEL, OIL, AND TAXES (.850\$/G)	612.710
INSURANCE	169.395
DIRECT MAINTENANCE	
AIRFRAME	111.025
ENGINE	367.249
MAINTENANCE BURD.	384.490
DEPRECIATION	2154.708

0 TOTAL DOC (\$/TRIP) 3898.811
 0 (\$/B. HR.) 883.994
 0 (\$/N. MI.) 2.038

Fig I2 - Learjet 35A GASP result (concluded)

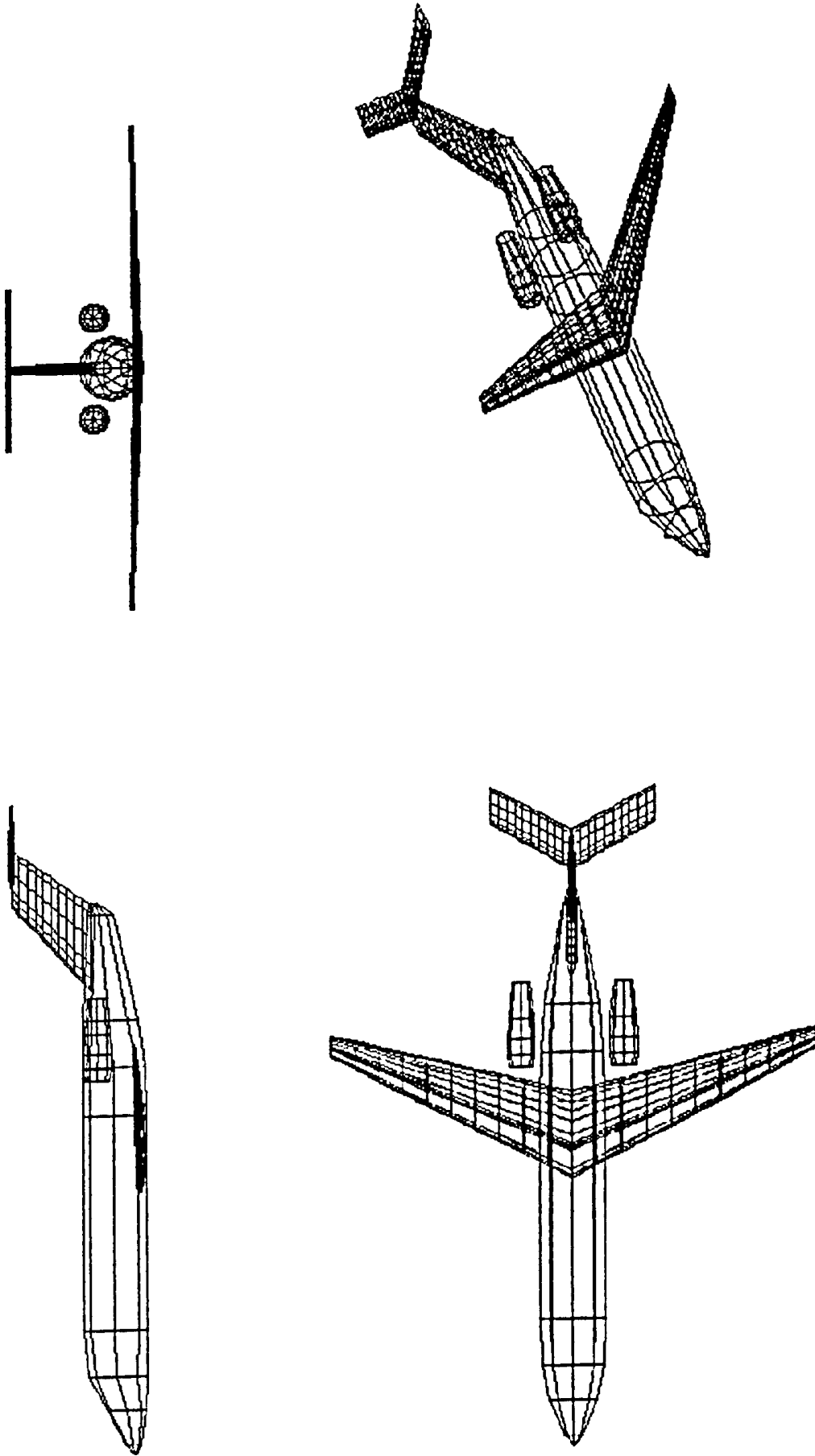


Fig 13 - Canadair Regional Jet 100 GASP model

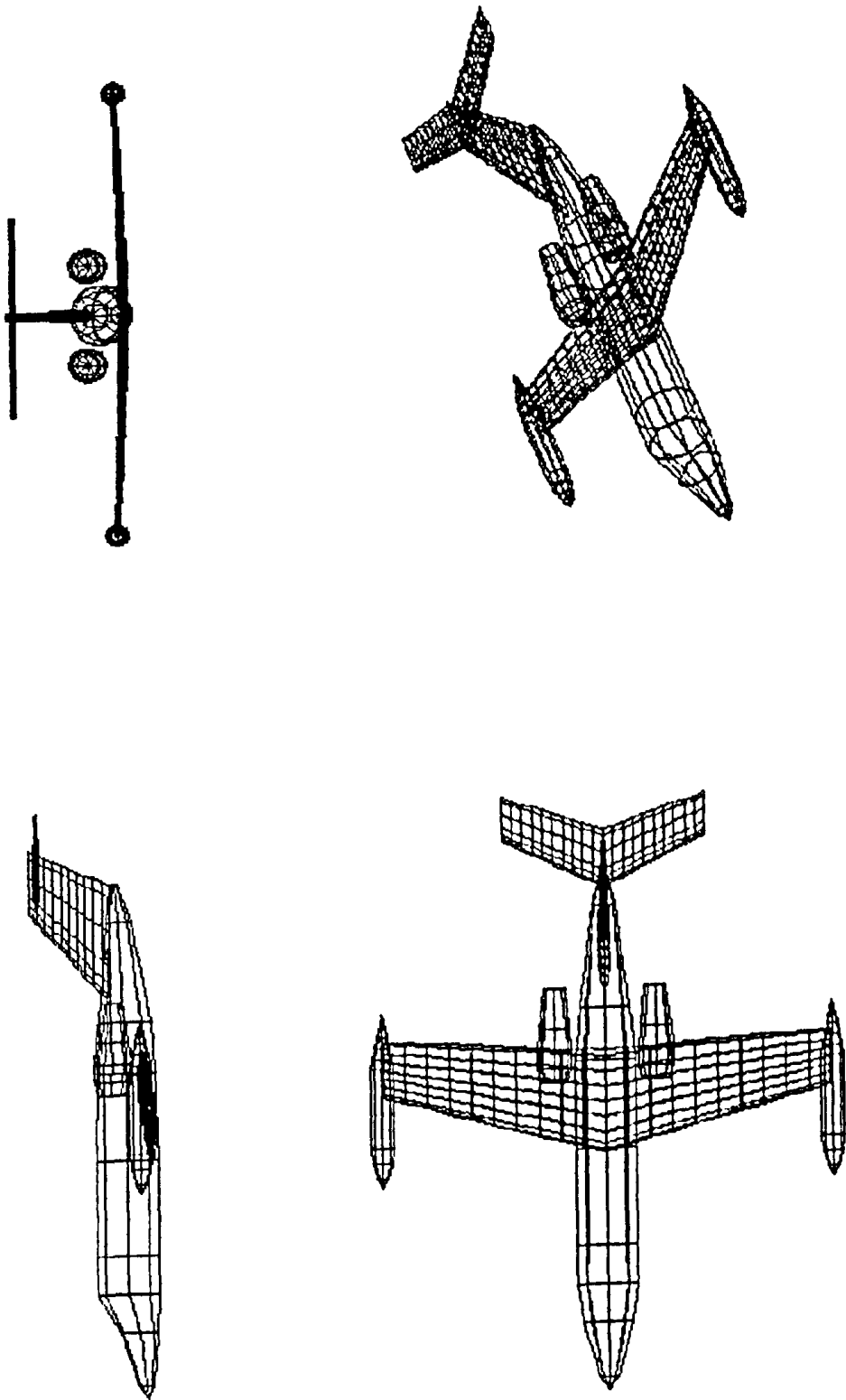


Fig 14 - Learjet 35A GASP model

APPENDIX J

Sensitivity Analysis

Introduction

This Appendix shows the results of the sensitivity analysis performed on the Min DOC conventional configuration to changes of fuselage mass and drag. All other parameters were kept as unchanged as possible and consistent with the GASP design synthesis procedure. GASP options for fixed engine, fixed wing area and tail volume coefficients were now used to simulate the same basic optimised configuration.

The final optimised answer, as obtained with these options, came up with some slight differences. These discrepancies are due to the small longitudinal shift experienced by the wing location on the fuselage, changing slightly the aircraft cg location. Since the differences are relatively small, they will not affect the validity of the final sensitivity analysis results. Thus, the solution just obtained is taken as the datum design, which the present investigation will be based on.

Incremental changes of -10% and +10% of the fuselage mass and drag were independently assumed. All the results reflect the effect of the changes on the final optimum design. Table J1 summarises the main results and shows the effect of the changes in terms of a percentage variation on the final performance and cost figures.

J.1 Fuselage Mass Sensitivity

By keeping the aircraft maximum Take-off Weight unchanged, Table J1 shows that a 10% fuselage structural weight reduction results in increases in both maximum fuel weight and design range amounting to 7.3% and 10.9% respectively, with a slight improvement in DOC figures. The reverse is true for a 10% increase of the fuselage structural weight. These results indicate a high sensitivity in performance due to fuselage weight changes experienced by this type of aircraft and considerable benefits may be achieved by keeping fuselage mass as low as possible. Operating on the design range or on shorter routes, providing adequate provision for cargo hold is incorporated in the design, means that fuel can be traded with freight improving the air carrier revenue potential. To fly the same distance, DOC values also decrease relatively.

As seen, for fuselage mass variations it appears that a critical trend exists in terms of exchanging mass between this component and fuel. It is worth noting that fuselage is the structural component which contributes more to the aircraft empty weight (about 23 to 24% of this weight) and it is roughly about the same order as the fuel weight. So, any means to reduce its structural mass are welcome, which may include the use of advanced technology features (materials, design and manufacturing methods) or even by adopting an unusual concept, changing radically the current design practice, or both.

On conventional aircraft, tail loads are generally very large which contribute heavily to bending the rearward fuselage. A critical combination of inertia loads, trimming load in the landing configuration with forward cg during the landing impact, especially on aircraft

with fuselage mounted engines, may determine the design loading condition. Critical loads may also arise from nose landing gear loads. If a three surface concept of the type developed in this research is sought, where half the pitching moment required to trim the aircraft is produced by the canard useful lift, a significant reduction on the above critical loads is expected, on the front fuselage, because the canard lift will damp the fuselage inertia loads. And on the rear fuselage, because the tail downward load will be significantly lower than in the equivalent conventional aircraft case, in addition to being a smaller and lighter tailplane (lower inertia). These effects will likely contribute to limit fuselage bending moments to lower levels in order to produce savings in structural weight, even without the consideration of advanced materials.

J.2 Drag Sensitivity

Table J1 also shows that a 10% decrease in overall drag results in a slight increase of both cruise Mach number and design range which amount respectively to 3% and 2.9%, with a slight improvement in the lift to drag ratio and DOC figures. For a 10% drag increase a slight degradation in these parameters is noticed. Very small changes in field length performance are also experienced. Although drag decrease offers scope for some improvement in the performance and cost parameters, the results indicate a very low sensitivity to drag variations.

It may be reasonable to assume that similar drag sensitivity holds for the three-surface configuration transport. This increases confidence in the computed performance and economics by minimising the impact of drag uncertainties in the final optimised solution, arising from the fuselage/canard interference. This concern was explained in section 6.2 of the main text.

Concluding Remarks

This sensitivity study shows that benefits arise from reducing both fuselage structural mass and drag. This is especially interesting of fuselage mass due to the large impact its changes have on range performance. Fuselage mass decrease also improves the aircraft economic worth by additionally increasing its cargo payload potential.

	Min DOC Conv		Fuselage Weight Sensitivity				Drag Sensitivity			
	Datum Design		(-)10% fus weight	% change	(+)10% fus weight	% change	(-)10% drag	% change	(+)10% drag	% change
Fuselage Weight	lb	6184	5665	-10.0	6802	10.0	6184	.0	6184	.0
Total Cruise Drag	counts	351	351	.0	351	.0	315.4	-10.1	385.7	9.9
Fuselage Length	ft	79.25	79.25	.0	79.25	.0	79.25	.0	79.25	.0
Wing Area	sqft	435.30	435.30	.0	435.30	.0	435.30	.0	435.30	.0
Wing Aspect Ratio		8.88	8.88	.0	8.88	.0	8.88	.0	8.88	.0
Tailplane Area	sqft	158.00	158.01	.0	157.99	.0	158.00	.0	158.00	.0
Fin Area	sqft	93.51	93.52	.0	93.50	.0	93.51	.0	93.51	.0
Engine Max. St. T/O Thrust	lb	9756	9756	.0	9756	.0	9756	.0	9756	.0
M.T.O.W.	lb	45707	45707	.0	45707	.0	45707	.0	45707	.0
O.E.W.	lb	27429	26823	-2.2	28035	2.2	27429	.0	27429	.0
E.W.	lb	26351	25744	-2.3	26957	2.3	26351	.0	26351	.0
Fuel Weight	lb	8278	8884	7.3	7671	-7.3	8278	.0	8278	.0
T/O Wing Loading	lb/sqft	105	105	.0	105	.0	105	.0	105	.0
T/O Thrust to Weight Ratio		0.427	0.427	.0	0.427	.0	0.427	.0	0.427	.0
Cruise Mach No.		0.83	0.83	.0	0.83	.0	0.86	3.0	0.80	-3.9
Cruise Speed (TAS)	kt	480.8	480.8	.0	480.8	.0	493.6	2.7	460.2	-4.3
Cruise Height	ft	35000	35000	.0	35000	.0	35000	.0	35000	.0
Cruise L/D		11.73	11.73	.0	11.73	.0	11.83	.8	11.63	-.9
Approach Speed (EAS)	kt	122.2	122.2	.0	122.2	.0	122.2	.0	122.2	.0
Approach Speed (TAS)	kt	136.3	136.3	.0	136.3	.0	136.3	.0	136.3	.0
T/O Stall Speed (TAS)	kt	120.0	120.0	.0	120.0	.0	120.0	.0	120.0	.0
Landing Stall Speed (TAS)	kt	104.7	104.7	.0	104.7	.0	104.7	.0	104.7	.0
T/O Flap (angle/CLmax)		15/2.503	15/2.503		15/2.503		15/2.503		15/2.503	
Landing Flap (angle/CLmax)		40/3.296	40/3.296		40/3.296		40/3.296		40/3.296	
FAR 25 T/O Field Length	ft	5478.4	5478.4	.0	5478.4	.0	5456.8	-.4	5489.5	.2
FAR 25 Land. Field Length	ft	4808.0	4808.0	.0	4808.0	.0	4812.0	.1	4804.0	-.1
Mission Range	nmi	1104	1224	10.9	982	-11.1	1186	2.9	1077	-2.4
Aircraft Price	US\$	1.78E+07	1.76E+07	-1.2	1.80E+07	1.2	1.79E+07	.4	1.77E+07	-.6
D.O.C./N Mile	US\$/nm	2.69	2.63	-2.2	2.76	2.6	2.62	-2.6	2.78	3.3

Table J1 - Analysis of Fuselage Weight and Drag Sensitivities on Min DOC Conventional Transport

APPENDIX K

Optimisation Jumps

Introduction

This Appendix describes the additional work done to identify reasons which could better explain the difficulties encountered during the optimisation process. GASP drag, mass and cost equations were reviewed and an additional analysis of the convergence history diagrams of figure F1, in Appendix F, was performed.

K.1 Review of GASP Equations

A detailed review of the equations employed in the synthesis program for drag, mass and cost predictions was undertaken.

Optimisation jumps, as shown in the objective function convergence histories of Appendix F, might result from possible discontinuities in the functions as described by these equations. Careful inspection of these relationships showed that, within the ranges for which they were used during the individual design synthesis runs (performed throughout the optimisation process), no discontinuities were present. These could occur whether the aircraft size was on the boundary of particular classes of aircraft, or if the optimisation process was allowed to change configurational features (such as conventional fuselage or twin boom, braced or cantilever wing, turbo-propeller or turbo-fan engines, fuselage mounted or wing podded engines, etc). The first situation could activate different or slightly different correlations for component/ system mass or cost estimating relationships producing comparatively different results for these items. The second one can not occur because the configuration is generally defined with the starting point and kept unchanged during the optimisation.

As an example, a list of the cost estimating relationships (CER) used, where discontinuities (step functions) could be found, is shown below. These CERs are weight based relationships^{K1}.

Cost Item	Item Weight [lb]	
	Discontinuity Point	Order used
Landing gear structure	10000	2000
Electrical System	5000	1000
Furnishings	3000 & 25000	3500

Since the item weights predicted during GASP runs are relatively apart from the discontinuity points, no "jumps" on the respective cost results would result so as to significantly affect the trends of the objective and constraint functions, from one design iteration to the next one.

K.2 Difficulties During the Optimisation

In this section, a particular region of the history diagrams of figure F1, related to the optimisation of the conventional transport for minimum DOC, is further analysed. As described in section 5.4.5, the numerical technique failed to satisfy the convergence criteria at iteration 487. At this point, the design corresponds to the optimised one as obtained at the end of the optimisation process (iteration 759). Following iteration 487, the designs tend to stabilise but sudden surges in the design variables and problem functions occur at iteration 504. Then, the process tries the convergence towards the minimum of the figure of merit and another excursion happens at iteration 623. Another subsidence takes place before finally meeting the convergence criteria.

Figures K1 through K4 represent similar history diagrams where the objective function (DOC), the MTOW and the design variables are, as before, normalised by the corresponding values of the initial design point. The constraint functions are normalised by their maximum constraint limit as defined in section 5.4.2. These graphs show the evolution of the problem functions and design variables between iterations 480 and 530.

Another set of history diagrams, figures K5 through K8, was devised where all the design parameters and functions are normalised by the respective values as obtained in the previous iteration. These diagrams show the magnitude of the large excursions both at iteration 504, in the wrong direction, and iteration 521, now in the right direction in its attempt to improve the cost function. They also allow for comparison with the usual small variations produced during most of the time.

A sample of intermediate design results, as obtained during the RQPMIN-GASP operation, is presented in table K1 for iterations 485 through 510. Tables K2 and K3 show the respective normalised values as employed in figures K1 through K4 and figures K5 through K8, respectively. This subset was selected to include iteration 487 and the large diversion of iteration 504.

Looking at figures K3/ K4 and K7/ K8, regarding the design variables evolution, as well as at the design variables related portion of table K3, a similar cyclic pattern is seen to repeat every 17 iterations with very slight changes in one or two of these variables. At the 17th iteration, a large excursion on all of them may occur which greatly explains the "jumps" on the cost figure and constraints (figures K1/ K2, K5/ K6 and tables). Iteration numbers 487, 504, 521, 623 as well as the final one, 759, pertain to this class of iteration.

It appears that RQPMIN collects data from 16 GASP successive iterations, corresponding to 16 very close design points, to determine the derivatives of the design surface functions with respect to the design variables at those points. Based on this information, RQPMIN will decide how to perturb the design variables in an attempt to effectively improve the figure of merit. However, the move at iteration 504 was in the wrong direction. An explanation for this occurrence may be as follows.

The convergence at iteration 487 was not satisfied probably because a very small

tolerance on the problem functions was imposed in combination with some difficulty experienced in improving the objective function. This latter difficulty can be related with the particular design surface topology. One way to overcome this problem consists of re-starting the optimisation process with a different starting point. With this in mind, RQPMIN may have possibly built in such a mechanism to solve this kind of difficulty. Thus, it may purposely generate a new starting design point to improve on when these difficulties arise.

Concluding Remarks

"Jumps" observed in the optimisation history diagrams are not induced by discontinuities of the disciplinary analysis equations. The reason being that these discontinuities are unlikely for the aircraft sizes studied.

The large excursions experienced during the optimisation process seem to result from:

- the proper operation of RQPMIN while improving the performance index, i.e. when effectively converging towards its optimum value, usually a local minimum, or
- difficulties encountered by the numerical technique to meet the convergence criteria (probably with very tight tolerances on the problem functions), when it finds unable to improve the objective function. Instead of stopping, the process suddenly diverges, possibly to re-initiate a new minimisation.

Note: the nomenclature in the tables follows the order by which the design variables (DV) and the constraint functions (CF) appear on the figures K3/ K4, and K2, respectively.

References:

- K1. Beltramo, M.N.; Trapp, D.L.; Kimoto, B.W.; Marsh, D.P.
Parametric Study of Transport Aircraft Systems Cost and Weight
NASA CR 151970, Apr 1977

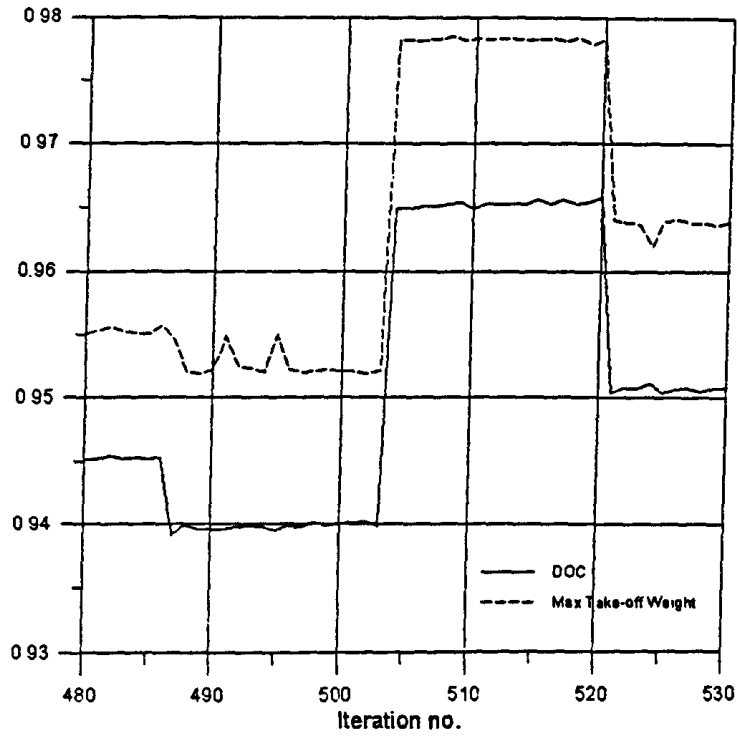


Fig K1 - History of the Objective Function (DOC) and MTOW

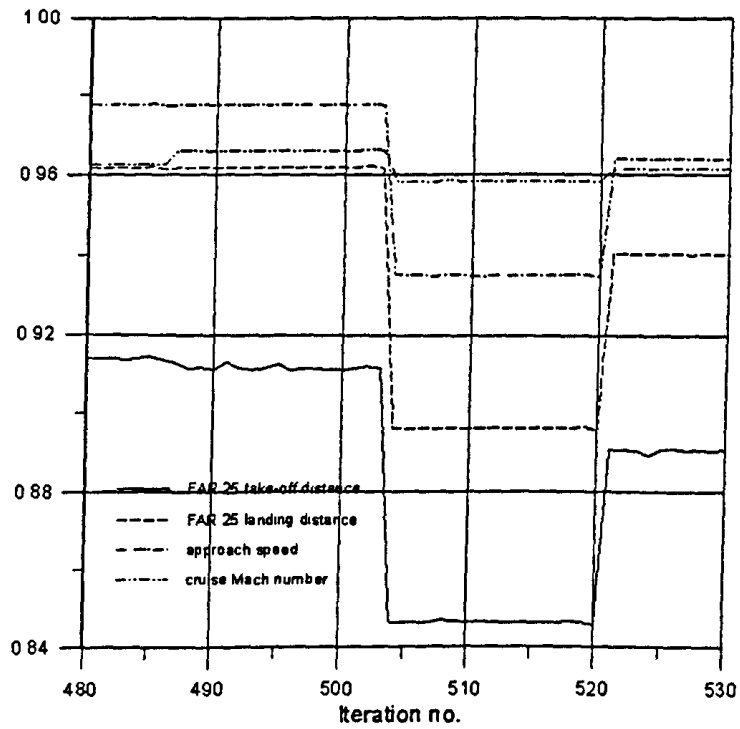


Fig K2 - History of the Constraint Functions

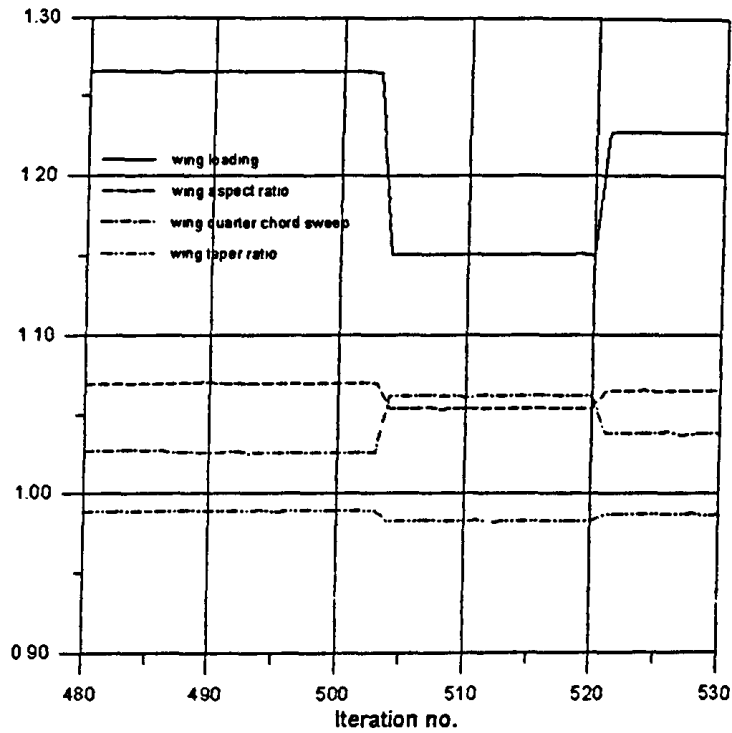


Fig K3 - History of the Wing Design Variables

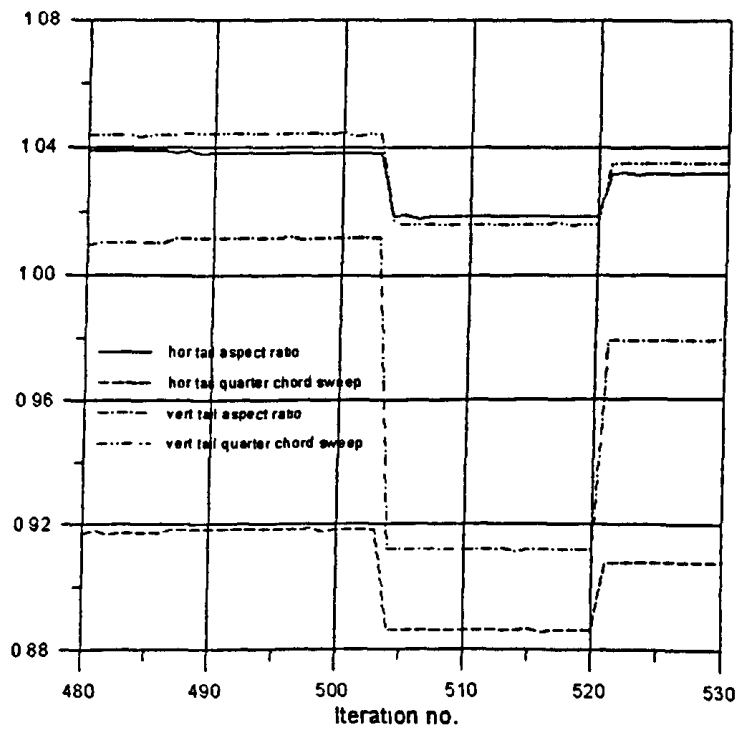


Fig K4 - History of the Tail Design Variables

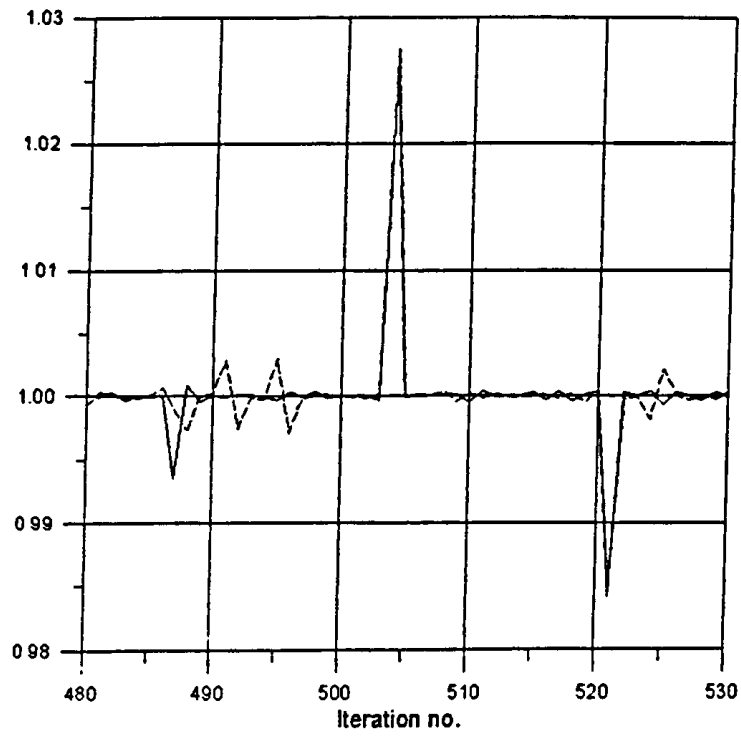


Fig K5 - History of the Objective Function (DOC) and MTOW (normalised by previous iteration data)

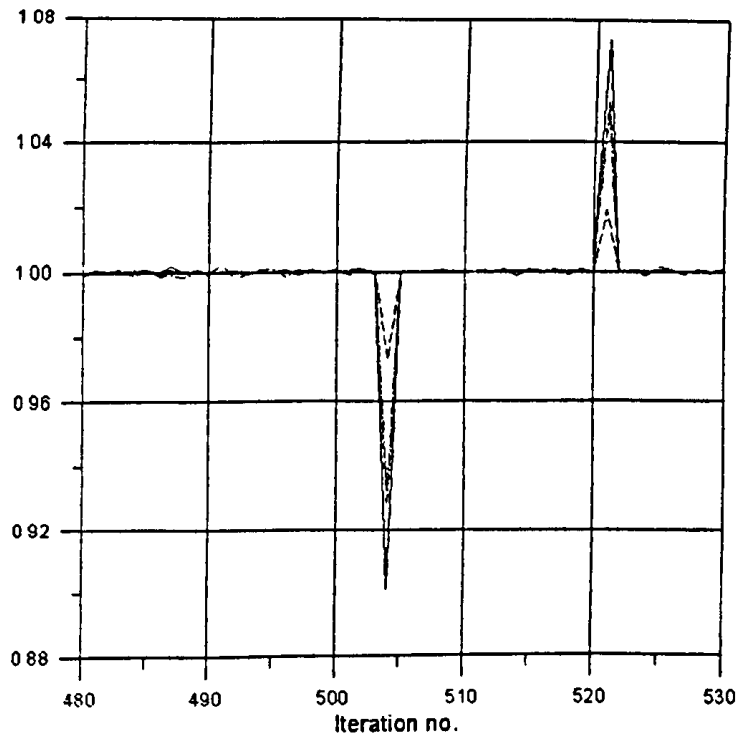


Fig K6 - History of the Constraint Functions (normalised by previous iteration data)

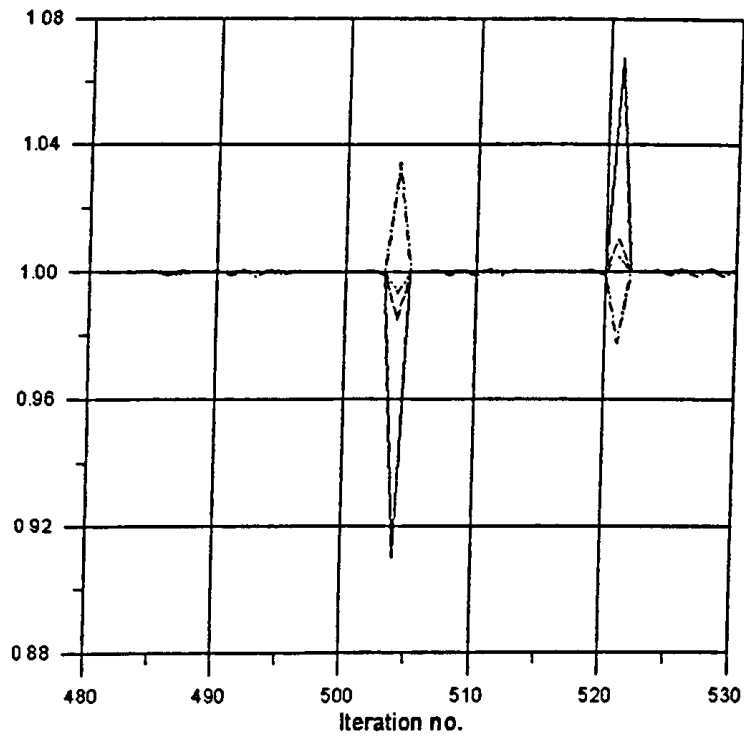


Fig K7 - History of the Wing Design Variables (normalised by previous iteration data)

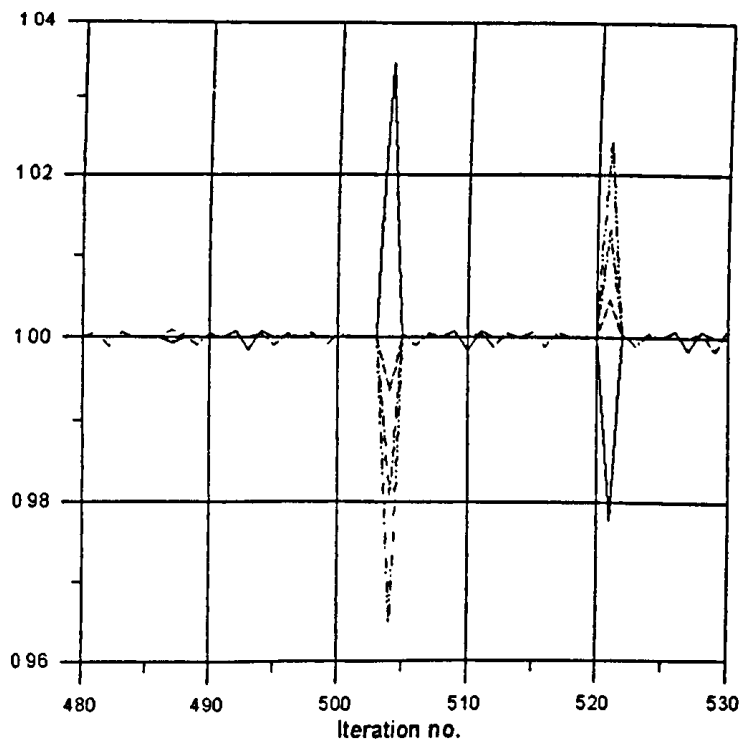


Fig K8 - History of the Tail Design Variables (normalised by previous iteration data)

Iter no.	Design Variables										Constraint Functions				Obj Function		MTOW
	DV1	DV2	DV3	DV4	DV5	DV6	DV7	DV8	CF1	CF2	CF3	CF4	DOC	DOC			
485	105.048	8.877	14.890	0.198	4.155	25.228	1.010	52.704	5486.85	4809.69	122.194	0.828	2.6376	2.6376	45729.4		
486	104.952	8.877	14.890	0.198	4.155	25.228	1.010	52.704	5480.54	4806.08	122.137	0.828	2.6377	2.6377	45757.9		
487	105.000	8.879	14.878	0.198	4.153	25.253	1.012	52.725	5475.67	4807.55	122.153	0.831	2.6205	2.6205	45706.8		
488	105.000	8.879	14.878	0.198	4.155	25.253	1.012	52.725	5467.37	4808.28	122.162	0.831	2.6228	2.6228	45580.7		
489	105.000	8.879	14.878	0.198	4.151	25.253	1.012	52.725	5469.44	4808.29	122.162	0.831	2.6217	2.6217	45578.4		
490	105.000	8.884	14.878	0.198	4.153	25.253	1.012	52.725	5465.12	4807.79	122.154	0.831	2.6219	2.6219	45589.0		
491	105.000	8.875	14.878	0.198	4.153	25.253	1.012	52.725	5478.47	4807.93	122.159	0.831	2.6218	2.6218	45718.5		
492	105.000	8.879	14.890	0.198	4.153	25.253	1.012	52.725	5470.13	4808.51	122.166	0.831	2.6222	2.6222	45602.8		
493	105.000	8.879	14.867	0.198	4.153	25.253	1.012	52.725	5466.13	4807.83	122.155	0.831	2.6225	2.6225	45596.0		
494	105.000	8.879	14.878	0.198	4.153	25.253	1.012	52.725	5468.61	4808.32	122.162	0.831	2.6224	2.6224	45584.1		
495	105.000	8.879	14.878	0.198	4.153	25.253	1.012	52.725	5474.44	4807.40	122.151	0.830	2.6216	2.6216	45722.0		
496	105.000	8.879	14.878	0.198	4.153	25.253	1.012	52.725	5465.58	4808.23	122.161	0.831	2.6225	2.6225	45589.3		
497	105.000	8.879	14.878	0.198	4.153	25.253	1.011	52.725	5468.18	4808.26	122.162	0.831	2.6224	2.6224	45582.8		
498	105.000	8.879	14.878	0.198	4.153	25.267	1.012	52.725	5466.78	4808.25	122.161	0.831	2.6233	2.6233	45585.6		
499	105.000	8.879	14.878	0.198	4.153	25.239	1.012	52.725	5465.79	4808.23	122.161	0.831	2.6229	2.6229	45589.6		
500	105.000	8.879	14.878	0.198	4.153	25.253	1.012	52.748	5465.04	4808.24	122.161	0.831	2.6231	2.6231	45587.2		
501	105.000	8.879	14.878	0.198	4.153	25.253	1.012	52.702	5466.94	4808.24	122.161	0.831	2.6233	2.6233	45586.0		
502	105.048	8.879	14.878	0.198	4.153	25.253	1.012	52.725	5471.10	4810.02	122.189	0.831	2.6235	2.6235	45579.2		
503	104.952	8.879	14.878	0.198	4.153	25.253	1.012	52.725	5467.65	4806.52	122.134	0.831	2.6226	2.6226	45586.2		
504	95.500	8.746	15.391	0.196	4.073	24.366	0.912	51.304	5078.65	4480.50	116.858	0.824	2.6925	2.6925	46838.3		
505	95.500	8.746	15.391	0.196	4.075	24.366	0.912	51.304	5078.11	4480.51	116.858	0.824	2.6924	2.6924	46836.7		
506	95.500	8.746	15.391	0.196	4.071	24.366	0.912	51.304	5078.76	4480.50	116.858	0.824	2.6928	2.6928	46838.2		
507	95.500	8.750	15.391	0.196	4.073	24.366	0.912	51.304	5077.65	4480.08	116.852	0.824	2.6929	2.6929	46839.3		
508	95.500	8.741	15.391	0.196	4.073	24.366	0.912	51.304	5080.96	4480.83	116.864	0.824	2.6933	2.6933	46855.0		
509	95.500	8.746	15.403	0.196	4.073	24.366	0.912	51.304	5079.20	4480.86	116.864	0.824	2.6937	2.6937	46834.7		
510	95.500	8.746	15.380	0.196	4.073	24.366	0.912	51.304	5078.77	4480.12	116.852	0.824	2.6924	2.6924	46844.8		

Table K1 - Min DOC Conv Aircraft Design Optimisation History (sample of intermediate results)

Iter no.	Design Variables								Constraint Functions				Obj Function	
	DV1	DV2	DV3	DV4	DV5	DV6	DV7	DV8	CF1	CF2	CF3	CF4	DOC	MTOW
0	83.000	8.300	14.500	0.200	4.000	27.500	1.000	50.500	6000.000	5000.000	125.000	0.860	2.7904	47880.4
485	1.26564	1.06951	1.02692	0.9885	1.03875	0.91739	1.0101	1.04364	0.91448	0.96194	0.97755	0.96244	0.94524	0.95508
486	1.26448	1.06951	1.02692	0.9885	1.03875	0.91739	1.0101	1.04364	0.91342	0.96122	0.97710	0.96244	0.94528	0.95567
487	1.26506	1.06980	1.02607	0.9885	1.03823	0.91828	1.0116	1.04406	0.91261	0.96151	0.97722	0.96570	0.93911	0.95460
488	1.26506	1.06980	1.02607	0.9885	1.03873	0.91828	1.0116	1.04406	0.91123	0.96166	0.97730	0.96570	0.93994	0.95197
489	1.26506	1.06980	1.02607	0.9885	1.03773	0.91828	1.0116	1.04406	0.91157	0.96166	0.97730	0.96570	0.93954	0.95192
490	1.26506	1.07034	1.02607	0.9885	1.03823	0.91828	1.0116	1.04406	0.91085	0.96156	0.97723	0.96570	0.93961	0.95214
491	1.26506	1.06925	1.02607	0.9885	1.03823	0.91828	1.0116	1.04406	0.91308	0.96159	0.97727	0.96570	0.93958	0.95485
492	1.26506	1.06980	1.02686	0.9885	1.03823	0.91828	1.0116	1.04406	0.91169	0.96170	0.97733	0.96570	0.93972	0.95243
493	1.26506	1.06980	1.02528	0.9885	1.03823	0.91828	1.0116	1.04406	0.91102	0.96157	0.97724	0.96570	0.93983	0.95229
494	1.26506	1.06980	1.02607	0.9890	1.03823	0.91828	1.0116	1.04406	0.91144	0.96166	0.97730	0.96570	0.93979	0.95204
495	1.26506	1.06980	1.02607	0.9880	1.03823	0.91828	1.0116	1.04406	0.91241	0.96148	0.97721	0.96558	0.93951	0.95492
496	1.26506	1.06980	1.02607	0.9885	1.03823	0.91828	1.0121	1.04406	0.91093	0.96165	0.97729	0.96570	0.93983	0.95215
497	1.26506	1.06980	1.02607	0.9885	1.03823	0.91828	1.0111	1.04406	0.91136	0.96165	0.97730	0.96570	0.93979	0.95201
498	1.26506	1.06980	1.02607	0.9885	1.03823	0.91879	1.0116	1.04406	0.91113	0.96165	0.97729	0.96570	0.94012	0.95207
499	1.26506	1.06980	1.02607	0.9885	1.03823	0.91779	1.0116	1.04406	0.91097	0.96165	0.97729	0.96570	0.93997	0.95216
500	1.26506	1.06980	1.02607	0.9885	1.03823	0.91828	1.0116	1.04452	0.91084	0.96165	0.97729	0.96570	0.94004	0.95211
501	1.26506	1.06980	1.02607	0.9885	1.03823	0.91828	1.0116	1.04360	0.91116	0.96165	0.97729	0.96570	0.94012	0.95208
502	1.26564	1.06980	1.02607	0.9885	1.03823	0.91828	1.0116	1.04406	0.91185	0.96200	0.97751	0.96581	0.94019	0.95194
503	1.26448	1.06980	1.02607	0.9885	1.03823	0.91828	1.0116	1.04406	0.91128	0.96130	0.97707	0.96570	0.93987	0.95208
504	1.15060	1.05372	1.06146	0.9820	1.01825	0.88603	0.9118	1.01592	0.84644	0.89610	0.93486	0.95826	0.96492	0.97824
505	1.15060	1.05372	1.06146	0.9820	1.01875	0.88603	0.9118	1.01592	0.84635	0.89610	0.93486	0.95826	0.96488	0.97820
506	1.15060	1.05372	1.06146	0.9820	1.01775	0.88603	0.9118	1.01592	0.84646	0.89610	0.93486	0.95826	0.96502	0.97823
507	1.15060	1.05427	1.06146	0.9820	1.01825	0.88603	0.9118	1.01592	0.84628	0.89602	0.93482	0.95826	0.96506	0.97826
508	1.15060	1.05318	1.06146	0.9820	1.01825	0.88603	0.9118	1.01592	0.84683	0.89617	0.93491	0.95837	0.96520	0.97858
509	1.15060	1.05372	1.06226	0.9820	1.01825	0.88603	0.9118	1.01592	0.84653	0.89617	0.93491	0.95826	0.96535	0.97816
510	1.15060	1.05372	1.06067	0.9820	1.01825	0.88603	0.9118	1.01592	0.84646	0.89602	0.93482	0.95826	0.96488	0.97837

Table K2 - Min DOC Conv Aircraft Design Optimisation History (sample of intermediate normalised results)

Iter no.	Design Variables										Constraint Functions				Obj Function		MTOW
	DV1	DV2	DV3	DV4	DV5	DV6	DV7	DV8	CF1	CF2	CF3	CF4	DOC	DOF			
485	1.00046	1.0	1.0	1.0	1.0	1.0	1.0	1.00044	1.00057	1.00042	1.00026	1.0	0.999962	1.000033			
486	0.99909	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0.99885	0.99925	0.99953	1.0	1.000038	1.000623			
487	1.00046	1.00027	0.99917	1.0	0.99949	1.00097	1.00149	1.0004	0.99911	1.00031	1.00013	1.00338	0.993479	0.998883			
488	1.0	1.0	1.0	1.0	1.00048	1.0	1.0	1.0	0.99848	1.00015	1.00007	1.0	1.000878	0.997241			
489	1.0	1.0	1.0	1.0	0.99904	1.0	1.0	1.0	1.00038	1.0	1.0	1.0	0.999581	0.999950			
490	1.0	1.00051	1.0	1.0	1.00048	1.0	1.0	1.0	0.99921	0.9999	0.99993	1.0	1.000076	1.000233			
491	1.0	0.99899	1.0	1.0	1.0	1.0	1.0	1.0	1.00244	1.00003	1.00004	1.0	0.999962	1.002841			
492	1.0	1.00051	1.00077	1.0	1.0	1.0	1.0	1.0	0.99848	1.00012	1.00006	1.0	1.000153	0.997469			
493	1.0	1.0	0.99846	1.0	1.0	1.0	1.0	1.0	0.99927	0.99986	0.99991	1.0	1.000114	0.999851			
494	1.0	1.0	1.00077	1.00051	1.0	1.0	1.0	1.0	1.00045	1.0001	1.00006	1.0	0.999962	0.999739			
495	1.0	1.0	1.0	0.99899	1.0	1.0	1.0	1.0	1.00107	0.99981	0.99991	0.99988	0.999695	1.003025			
496	1.0	1.0	1.0	1.00051	1.0	1.0	1.00049	1.0	0.99838	1.00017	1.00008	1.00012	1.000343	0.997098			
497	1.0	1.0	1.0	1.0	1.0	1.0	0.99901	1.0	1.00048	1.00001	1.00001	1.0	0.999962	0.999857			
498	1.0	1.0	1.0	1.0	1.0	1.00055	1.00049	1.0	0.99974	1.0	0.99999	1.0	1.000343	1.000061			
499	1.0	1.0	1.0	1.0	1.0	0.99891	1.0	1.0	0.99982	1.0	1.0	1.0	0.999848	1.000088			
500	1.0	1.0	1.0	1.0	1.0	1.00054	1.0	1.00044	0.99986	1.0	1.0	1.0	1.000076	0.999947			
501	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0.99912	1.00035	1.0	1.0	1.0	1.000076	0.999974			
502	1.00046	1.0	1.0	1.0	1.0	1.0	1.00044	1.00044	1.00076	1.00037	1.00023	1.00012	1.000076	0.999851			
503	0.99909	1.0	1.0	0.99342	0.98076	0.96487	0.90134	0.97305	0.99937	0.99927	0.99955	0.99988	0.999657	1.000154			
504	0.90994	0.98498	1.03449	0.99342	0.98076	0.96487	0.90134	0.97305	0.92885	0.93217	0.9568	0.99229	1.026653	1.027467			
505	1.0	1.0	1.0	1.0	1.00049	1.0	1.0	1.0	0.99989	1.0	1.0	1.0	0.999963	0.999966			
506	1.0	1.0	1.0	1.0	0.99902	1.0	1.0	1.0	1.00013	1.0	1.0	1.0	1.000149	1.000032			
507	1.0	1.00051	1.0	1.0	1.00049	1.0	1.0	1.0	0.99978	0.99991	0.99995	1.0	1.000037	1.000023			
508	1.0	0.99897	1.0	1.0	1.0	1.0	1.0	1.0	1.00065	1.00017	1.0001	1.00012	1.000149	1.000335			
509	1.0	1.00051	1.00075	1.0	1.0	1.0	1.0	1.0	0.99965	1.00001	1.0	0.99988	1.000149	0.999567			
510	1.0	1.0	0.99851	1.0	1.0	1.0	1.0	1.0	0.99992	0.99983	0.9999	1.0	0.999517	1.000216			

Table K3 - Min DOC Conv Aircraft Design Optimisation History (sample of intermediate results normalised by previous iteration data)