

## Impact of Droop and Scarf on the Aerodynamic Performance of Compact Aero-Engine Nacelles

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### Abstract

Future turbofan engines will operate with larger engine bypass-ratios and lower specific thrust than current in-service architectures to reduce the specific fuel consumption. This will be achieved by increasing the fan diameter which will incur in an increment in nacelle size and a concomitant larger nacelle drag, weight and interaction effects with the airframe. Therefore, it is required to design compact nacelles which will not counteract the benefits obtained from the new engine cycles. Nacelle design is based on a set of aero-lines that in combination with droop and scarf result in a 3D design. Traditionally, this process was performed by the design of axisymmetric aero-lines. Nevertheless, there is an emerging need to carry out the design process for full 3D configurations to have a better understanding of the effect of droop and scarf angles on the nacelle drag characteristics. This paper presents a numerical method for the multi-objective optimisation of drooped and scarfed non-axisymmetric nacelle aero-engines. It uses intuitive Class Shape Transformations (iCSTs) for the aero-engine geometry definition, multi-point aerodynamic simulation, a near-field nacelle drag extraction method and the NSGA-II genetic algorithm. The process has been employed to perform independent multi-objective optimisations of compact architectures at selected droop and scarf angle combinations. The multi-objective optimisation framework was successfully demonstrated for the new nacelle de-

sign challenge and the overall system was shown to enable the identification of the effects of droop and scarf on compact aero-engines. The proposed tool complements a set of technologies for the design, analysis and optimisation of future civil turbofans aiming at reduction of specific fuel consumption.

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## 1. Introduction

The Advisory Council for Aviation Research and Innovation in Europe (ACARE) established very challenging aerospace performance targets for 2050 [1]. It aims to reduce by 80% the NO<sub>x</sub> emissions, 75% the fuel-burn and 65% the perceived noise with respect to a year-2000 aircraft. In order to meet these objectives future civil aero-engines are expected to have larger bypass ratio (BPR) [2] and lower fan pressure ratio (FPR) [3] than current architectures to reduce the engine specific fuel consumption (SFC) and improve the propulsive efficiency. These new configurations will present larger fan diameters which will have associated an increase on nacelle drag, overall weight and larger interaction effects with the airframe [4, 5]. Therefore, future civil aero-engines will be mounted in compact nacelles to meet the expected SFC improvements.

One of the main challenges of nacelle design is the requirement for acceptable aerodynamic performance in the broad range of flow conditions that are met throughout the aircraft mission. For future UHBPR nacelle aero-engines and long range applications one key aerodynamic design point is the cruise segment [6]. Traditionally, nacelle design has been tackled by multi-point aerodynamic optimisation in which mid-cruise conditions, sensitivity to flight Mach number and sensitivity to massflow capture ratio (MFCR) are considered. Tejero *et al.*

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[6] developed a nacelle optimisation framework for axisymmetric configurations based on a CFD in-the-loop approach for compact aero-engines in which the sensitivity to the nacelle design parameters of  $L_{nac}/r_{hi}$  and  $r_{te}/r_{hi}$  was quantified. The method was successfully demonstrated for the identification of the viable nacelle design space for future civil aero-engines. Robinson *et al.* [7] carried out a multi-point optimisation for two UHBPR turbofan nacelles with a conventional length of  $L_{nac}/r_{hi} = 4.3$  and a compact architecture with  $L_{nac}/r_{hi} = 3.1$ . A maximum reduction of 16.1% in mid-cruise nacelle drag was achieved on the compact configuration with respect to the long nacelle aero-engine. Albert *et al.* [8] investigated different parametric geometry definitions for the design of axisymmetric nacelles aero-engines. It was concluded that the Class Shape Transformation (CST) outperformed the super-ellipses and B-spline methods.

Although the basic form of nacelle design is based on a set of axisymmetric aero-lines which in combination with droop and scarf result in a 3D design, it is still required to have a better insight of the transonic flow aerodynamics associated to non-axisymmetric configurations. This also includes a better understanding of the impact of droop and scarf on the nacelle drag characteristics for the new nacelle design challenge of UHBPR aero-engines. These angles define the offset required for the highlight plane to re-orient the intake axis. The majority of previous non-axisymmetric nacelle design studies are based on multi-fidelity methods that include RANS simulations, surrogate modelling and genetic algorithms [9, 10, 11]. These investigations do not quantify the impact of the droop and scarf angles on the aerodynamic performance as they were fixed during the design process. Fang *et al.* [9] carried out the optimisation of a non-axisymmetric configuration with  $L_{nac}/r_{hi} = 3.5$  using Class Shape Transformations and 20 design variables to describe the aero-engine. The study was focus on a medium range application at  $M = 0.80$  in which the main objective

was to minimise the nacelle drag. The proposed method yielded to a configuration with a reduction of 1.5dc with respect to a reference configuration. Peters *et al.* [11] investigated the effects of short intakes on nacelle drag at cruise conditions for a medium range application ( $M = 0.80$ ). It was concluded that the nacelle external drag could be reduced by 15% by employing short-inlet configurations of  $L_{int}/D_{fan} = 0.19$  with respect to  $L_{int}/D_{fan} = 0.5$ . On the other hand, other studies have quantified the impact of droop and scarf on intake performance metrics [12, 13, 14]. The investigations were mainly focused on negative drooped and scarfed configurations. The benefits of these architectures have been demonstrated for take-off conditions to delay the incidence angle at which the intake flow separates [12] as well as for the reduction of the perceived noise at ground level [14]. Nevertheless, these studies do not evaluate the nacelle drag under cruise conditions which is vital for long range applications.

### 1.1. Scope of the present work

This work further develops a computational method for the multi-point multi-objective optimisation of non-axisymmetric nacelle configurations. The tool encompasses an analytical formulation for the parametric definition of the aero-engine with intuitive Class Shape Transformations, multi-point aerodynamic simulations, a near-field nacelle drag extraction method and the NSGA-II genetic algorithm.

The aim of this work is to demonstrate the capabilities of the developed framework for the new nacelle design challenge. The tool is employed for the optimisation of 3D non-axisymmetric configurations for different ranges of droop and scarf angles to assess the trade-off of these two design variables on the nacelle drag characteristics. The method is subsequently employed to derive guidelines for the design of compact nacelles.



## 2. Nacelle design framework

This work is based on the framework for the aerodynamic design of nacelle aero-engines developed by Tejero *et al.* [6, 15]. The method has a set of modules that include a parametric representation of the aero-engine with intuitive Class Shape Transformations (iCST) [16], automatic structured mesh generation [17], computation of the viscous compressible flow-field [18], post-processing to extract the pertinent objective functions [19] as well as a multi-objective optimisation capability with genetic algorithms [20]. A detailed description of each module is presented below.

### 2.1. Geometry definition and mesh generation

The developed tool uses a geometry parameterisation of the nacelle aero-lines based on intuitive Class Shape Transformations (iCST) [16, 21]. This formulation provides sufficient geometric control and is also tractable within an optimisation and design requirement. The parameterisation has been tested for axisymmetric nacelle design applications with success [6] and has been extended to construct 3D nacelles which can accommodate azimuthal aero-line variations as well as the necessary intake droop and scarf requirements (Figure 1). The current fancowl definition employs 7 intuitive design variables to describe a single aero-line:  $r_{hi}$ ,  $r_{te}$ ,  $L_{nac}$ ,  $f_{max}$ ,  $r_{max}$ ,  $f_{if}$ ,  $\beta_{nac}$  (Figure 1a). The method has been extended to non-axisymmetric configurations by employing eight control lines, which are reduced to five as left-right symmetry is considered in this work (Figure 1b). For each design variable CST curves are created in the cylindrical coordinate system and the values at intermediate aero-lines are calculated by interrogating the associated CST curves. Therefore, for fixed end-points ( $L_{nac}/r_{hi}$  and  $r_{te}/r_{hi}$ ) the current non-axisymmetric nacelle definition is based on 5 control aero-lines ( $\psi = 0^\circ, 45^\circ, 90^\circ, 135^\circ$  and  $180^\circ$ ) which are described by 4 nacelle design variables each. Overall, the method uses 20 nacelle variables

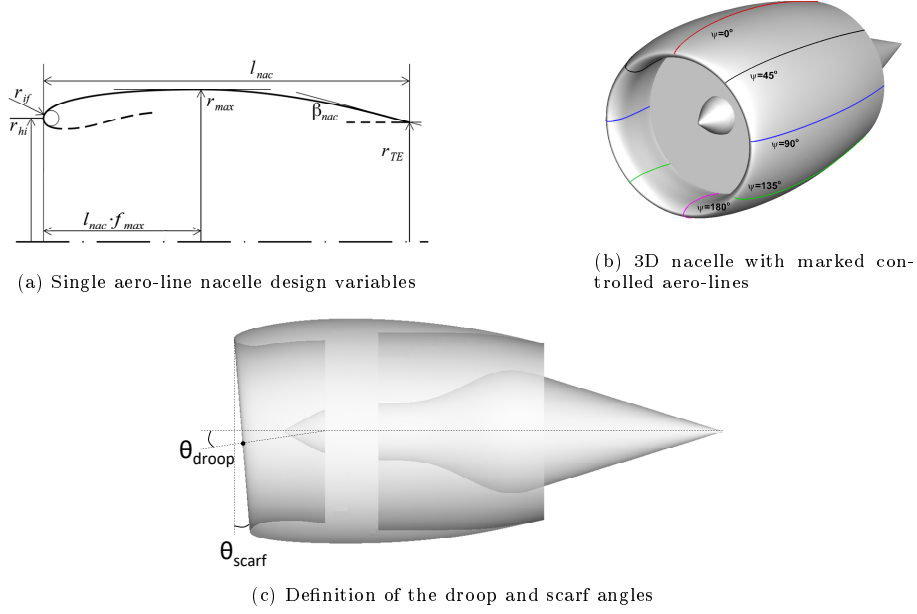


Figure 1: 2D axis-symmetric and 3D non-axisymmetric nacelle definition

and the droop and scarf angles to describe a non-axisymmetric nacelle aero-engine configuration (Figure 1c). The tool uses a generic intake and exhaust system to minimise the interactions with the nacelle drag characteristics. A conical exhaust is employed to generate a representative post-exit streamtube to extract the post-exit force term (Figure 1c).

The framework has an automated meshing capability with a multi-block structured computational domain [17] (Figure 2). The radial discretisation of the boundary layer block around the viscous walls employs  $y^+ \approx 30$ .

## 2.2. Computational method

The compressible Favre-averaged Navier-Stokes equations are solved with a double precision density-based solver and an implicit time integration formulation [18]. A second-order upwind scheme for the spatial discretisation with a Green-Gauss node based scheme and the 2-equations  $k-\omega$  Shear-Stress Trans-

port (SST) turbulence model are employed [22]. The Sutherland's law [23] is used to calculate the dynamic viscosity. The convergence criteria for each numerical simulation throughout the optimisation routine is based on a reduction of five order of magnitude on the normalised residuals and changes lower than 0.05% over the last 300 iterations on the fan massflow and the fancowl force.

The boundary conditions are imposed to fulfill the user prescribed flight conditions of Mach number, MFCR, altitude and incidence angle. The spinner, intake and fan cowl are set with a no-slip and adiabatic wall condition. The inlet fan face uses a pressure-outlet boundary conditions in which a target massflow value is set according to the prescribed MFCR. The fan exit is defined by a pressure-inlet conditions of total pressure and temperature. The freestream conditions are set with the the flight Mach number, angle of attack and the associated static temperature and pressure of the desired user-prescribed altitude (Figure 2b).

Subsequently the framework automatically extracts the nacelle drag by employing the industrial thrust-drag bookkeeping approach from AGARD [19]. The nacelle drag is composed by the contribution of the pressure and viscous forces on the fan cowl ( $\phi_{nac}$ ), the pre-entry force ( $\phi_{pre}$ ) and the post-exit force ( $\phi_{post}$ ). Whilst the contribution of  $\phi_{nac} + \phi_{pre}$  is calculated with a modified near-field method [24], the post-exit force is obtained by the numerical integration of the pressure term along the streamlines from the nacelle trailing edge.

### *2.2.1. Grid convergence study and numerical validation*

The influence of the domain size on the nacelle drag was assessed by locating the farfield boundary conditions at four different location with respect to the nacelle maximum radius:  $60r_{max}$ ,  $80r_{max}$ ,  $100r_{max}$  and  $120r_{max}$ . The study revealed that the nacelle drag increased only by 0.05% between the  $100r_{max}$  and  $120r_{max}$  cases and the  $100r_{max}$  domain size was selected within this investiga-

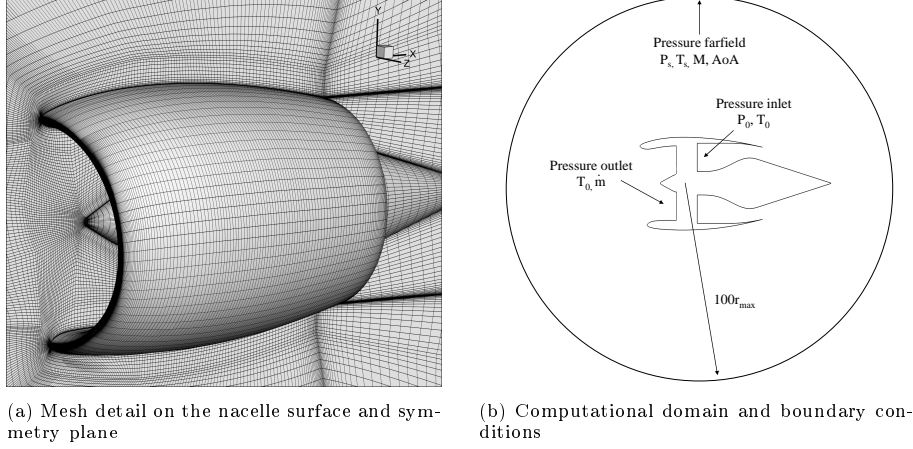


Figure 2: Computational domain and 3D view of the mesh used on the developed tool

tion (Figure 2b). A mesh independence study was calculated for four different mesh sizes (200k, 400k, 800k and 1600k) and the grid convergence index (GCI) was evaluated for the different levels of refinement considered. The 800k mesh size presented a value of  $GCI = 0.5\%$  on mid-cruise nacelle drag and was selected within the optimisation routine.

The numerical method was previously validated for a range of flight conditions across Mach numbers from 0.80 and 0.89 and MFCR from 0.45 and 0.70 [25]. The computational nacelle drag coefficient was underpredicted by approximately 3.0% at mid-cruise type conditions with  $M = 0.85$  and  $MFCR = 0.70$ . The predicted drag rise Mach number was within 0.002 with respect the the measurements [25].

### 2.3. Optimisation routine

The developed nacelle optimisation tool encompasses the capability of Design Space Exploration (DSE) studies as well as an optimisation environment. The design of experiments is started with a Latin Hypercube Sampling (LHS) due to the proven capabilities to efficiently cover high-dimensional design spaces [26]. The optimisation can be performed with three different strategies: (a) higher

fidelity CFD in-the-loop approach, (b) lower fidelity approach from a response surface model obtained with the DSE results and (c) an adaptive method that combines numerical simulations and the construction of RSMs [15]. The tool has a multi-point multi-objective design optimisation capability based on the Non-dominated Sorted Genetic Algorithm II (NSGA-II) genetic algorithm [20].

For this investigation the framework has been employed with the full CFD in-the-loop approach. The multi-point multi-objective optimisation is carried out for three different flight conditions that are encountered within the cruise segment: mid-cruise drag (Eq. 1), sensitivity to flight Mach number (Eq. 2) and sensitivity to changes on massflow capture ratio (Eq. 3).

$$C_{D-cruise} = \frac{D_{nac}}{\frac{1}{2}\rho_{\infty}V_{ref}^2A_{hi}} \quad (1)$$

$$\Delta C_{D-Mach} = \frac{D_{nac,M=M_{ref}+0.02} - D_{nac,M=M_{ref}}}{\frac{1}{2}\rho_{\infty}V_{ref}^2A_{hi}} \quad (2)$$

$$C_{D-spill} = \frac{D_{nac,MFCR_{cruise}} - D_{nac,MFCR_{EOC}}}{\frac{1}{2}\rho_{\infty}V_{ref}^2A_{hi}} \quad (3)$$

### 3. Results and discussions

A compact nacelle architecture of expected future civil aero-engines with  $L_{nac}/r_{hi} = 3.1$  and  $r_{te}/r_{hi} = 0.91$  has been considered. The multi-objective optimisations were carried out for representative flight conditions of long-range applications with mid-cruise conditions of  $M = 0.85$ ,  $MFCR = 0.70$  and  $h = 10668\text{m}$ . The flight Mach number was increased to  $M = 0.87$  at the same massflow capture ratio and altitude to quantify the sensitivity to Mach number. To account for the reduction of ingested massflow across the flight profile, the MFCR was set to 0.65 at the same  $M = 0.85$  and  $h = 10668\text{m}$  of the mid-cruise

conditions.

### 3.1. Demonstration of the tool for 3D nacelle optimisation

The developed numerical method has been employed for the multi-objective optimisation of a compact nacelle aero-engine in which the variables  $f_{max}$ ,  $r_{max}$ ,  $r_{if}$  and  $\beta_{nac}$  of the 5 controlled aero-lines float during the optimisation routine. Therefore, a total of 20 nacelle design variables are considered which highlights the relatively large aerodynamic design space. The capabilities of the framework for non-axisymmetric nacelle design is demonstrated for a configuration in which  $\theta_{droop}$  is aligned with the freestream incidence angle (AoA) and  $\theta_{scarf}/\theta_{droop} = 1.3$ .

The optimisation process starts with a Latin Hypercube Sampling [26] design of experiments. Overall, 400 designs were evaluated by CFD during the design space exploration. The following generations of the evolutionary algorithm are also evaluated with numerical simulations. The multi-objective optimisation is continued until the Pareto optimal set of solution has a hypervolume variation lower than 1.0% in the last three generations.

The optimisation routine resulted in a 3D Pareto front which is presented with a projection into the  $C_{D-cruise}$  -  $\Delta C_{D-Mach}$  space and coloured by  $C_{D-spill}$  (Figure 3a). It demonstrates the non-linearity of compact nacelle aero-engines. Whilst there are nacelle designs with low spillage nacelle drag ( $C_{D-spill}$ ) but a large concomitant sensitivity to Mach number ( $\Delta C_{D-Mach}$ ) and mid-cruise conditions ( $C_{D-cruise}$ ), the optimal solutions for  $\Delta C_{D-Mach}$  have associated large penalties on  $C_{D-spill}$  and  $C_{D-cruise}$ . This is highlighted on the nacelle designs C1, C2 and C3 which are the configurations with the lowest  $C_{D-cruise}$ ,  $\Delta C_{D-Mach}$  and  $C_{D-spill}$ , respectively. Relative to C1, the C2 configuration reduces  $\Delta C_{D-Mach}$  by 0.0029 at the expense of an increment by 8.7% on mid-cruise nacelle drag and a larger sensitivity to changes on MFCR with an incre-

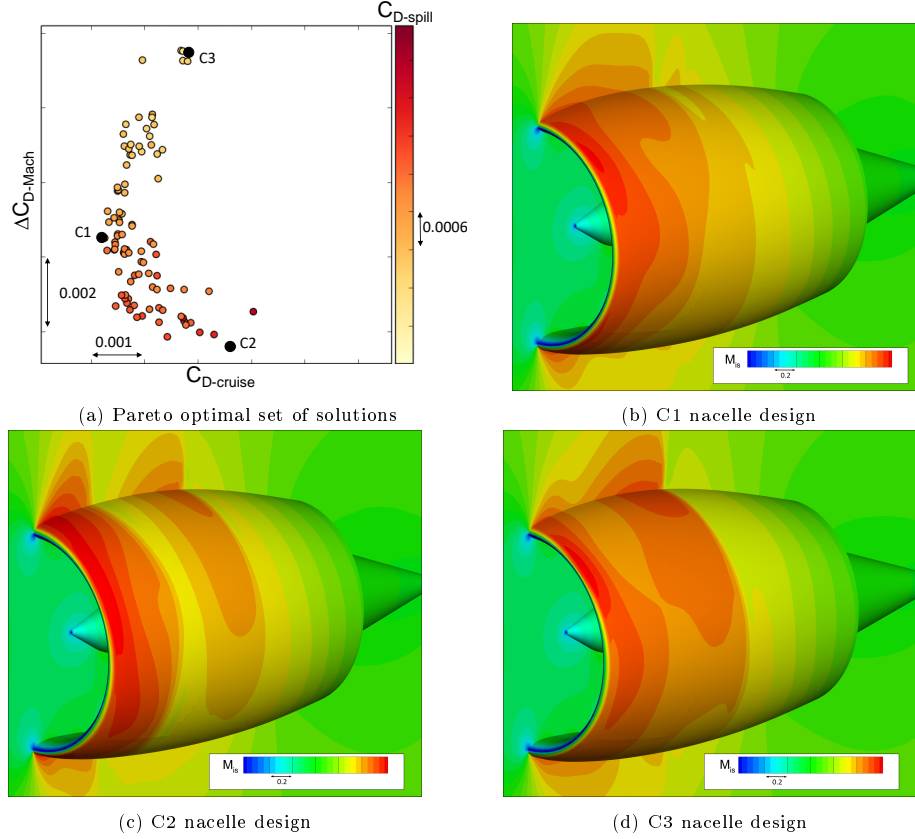


Figure 3: Pareto front and isentropic Mach number distribution of the selected designs with  $L_{nac}/r_{hi} = 3.1$  and  $r_{te}/r_{hi} = 0.91$ ,  $\theta_{droop} = \Lambda oA$ ,  $\theta_{scarf} = 1.3\theta_{droop}$

ment of 0.0016 on  $C_{D-spill}$ . The C3 nacelle has the lowest spillage drag but a concomitant increment on mid-cruise drag by 5.3% and a larger sensitivity to changes on flight Mach number with respect to C1.

The large variation on the nacelle drag characteristics is caused by a fundamental change on the associated nacelle transonic flow aerodynamics (Figure 3). The peak isentropic Mach number at the top aero-line ( $\psi = 0^\circ$ ) is significantly different on the three selected designs and varies by 0.11 (Figure 3). The configuration C1, which has the lowest  $C_{D-cruise}$  found throughout the optimisation process, has a well defined shock-wave at  $X/L_{nac} = 0.40$  on the top aero-line

(Figure 4a). The design C2 has a double shock structure with a first shock located at  $X/L_{nac} = 0.18$  a second shock-wave at  $X/L_{nac} = 0.53$ . Relative to the pre-shock  $M_{is}$  of C1, the strength of the pre-shock  $M_{is}$  for the design C2 increases by 0.04 and 0.03 in the first and second shock-wave, respectively. Conversely, C3 has an initial deceleration after the peak  $M_{is}$  and then the flow accelerates to terminate with a strong shock-wave at  $X/L_{nac} = 0.47$  (Figure 4a). For the azimuthal section  $\psi = 45^\circ$  all three designs have similar peak  $M_{is}$  (Figure 4b). Then, differences in the flow structures start to arise between the configurations. While the C1 design has a monotonic reduction of  $M_{is}$  along the aero-line and C2 depicts a double shock-wave pattern, the C3 configuration has a single strong shock structure. Although similar flow structures appear on the side aero-line ( $\psi = 90^\circ$ ) with respect to the  $\psi = 45^\circ$  aero-line (Figure 4c), there is a noticeable change on the intensity of the associated transonic flow aerodynamics. For example, the C3 design has a peak  $M_{is}$  reduction of 0.09 between  $\psi = 45^\circ$  and  $90^\circ$ . Both aero-lines have a well defined shock at  $X/L_{nac} = 0.49$  but a difference on the pre-shock  $M_{is}$  of 0.05. Lastly, the controlled aero-lines at  $\psi = 135^\circ$  and  $180^\circ$  present relatively benign transonic flow aerodynamics. For instance, the double shock topology of the C2 configuration at  $\psi = 0^\circ$ ,  $45^\circ$  and  $90^\circ$  (Figures 4a, 4b and 4c) is not present at the bottom aero-line (Figure 4d), in which there is single shock structure. The described results highlight the larger flow acceleration around the nacelle lip and the stronger shock-wave at the control lines  $\psi = 0^\circ$  and  $45^\circ$  with respect to  $\psi = 90^\circ$ ,  $135^\circ$  and  $180^\circ$ , which shows the impact that both aero-lines may have on the nacelle drag.

The developed nacelle design framework has been demonstrated for the new nacelle design challenge. The tool has been successfully employed to evaluate drooped and scarfed non-axisymmetric configurations within the context of mid-cruise conditions and sensitivity to changes on flight Mach number and MFCR.



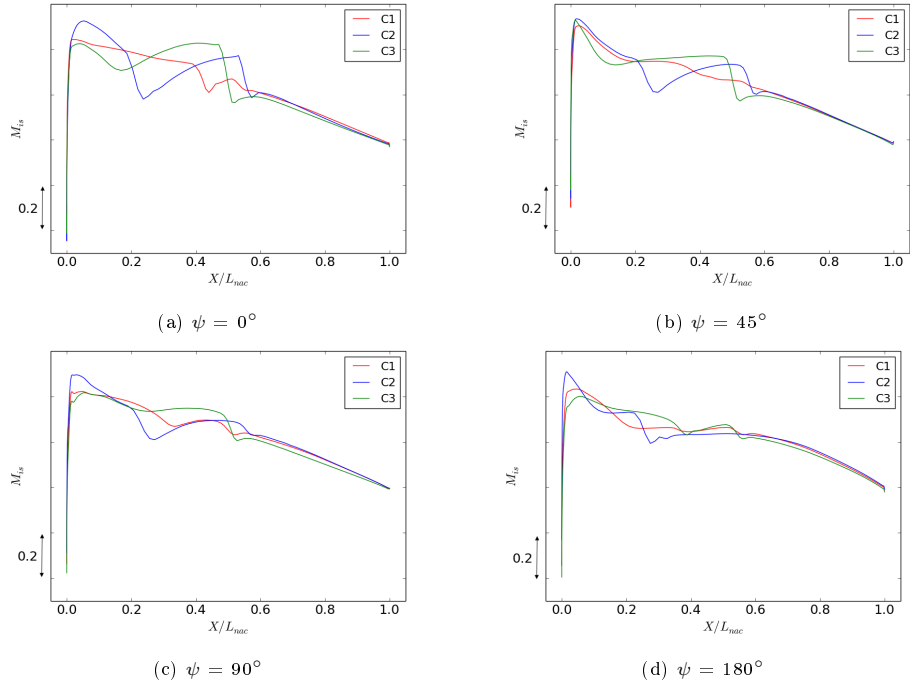


Figure 4: Comparison of  $M_{is}$  for selected designs at different azimuthal sections

Configuration	$\theta_{droop}$	$\theta_{scarf}/\theta_{droop}$
A	AoA-2.0°	1.3
B	AoA-1.0°	1.3
C	AoA	1.3
D	AoA+1°	1.3

Table 1: Summary of cases in which the effects of droop and scarf angles have been studied

As such, the proposed method constitutes an useful tool for the design of future nacelle civil aero-engines and provides the confidence to conduct extensive numerical simulations to assess the impact of the droop and scarf angles on the nacelle drag characteristics.

### 3.2. Aerodynamic impact of droop and scarf

A set of independent MOOs were carried out for a range of different  $\theta_{scarf}$  and  $\theta_{droop}$  angles (Table 1). For each configuration the MOO was performed with the established method of an initial DOE with 400 design evaluations and subsequent generations also evaluated with CFD until reaching convergence to the Pareto front based on the hypervolume value. The configuration C in Table 1 refers to the previously described multi-objective optimisation.

The independent MOOs resulted in 3D optimal sets of solutions upon which the impact of droop and scarf in the nacelle aerodynamic performance can be quantified. The comparison between the different configurations is performed for the nacelle design with minimum drag that has a potential acceptable spillage with  $C_{D-spill} < 0.1C_{D-cruise}$  [6]. Across the range of cases considered the mid-cruise drag vary by 3.5% (Figure 5). Relative to the design selected from configuration C (named C1 in the previous section), a reduction of  $\theta_{droop}$  and  $\theta_{scarf}$  by -1.0° and -1.3° results in an optimal design for the configuration B with a 1.4% penalty on mid-cruise drag. As the droop and scarf angles was reduced by -2.0° and -2.6° on the case A, the optimisation process resulted in a nacelle

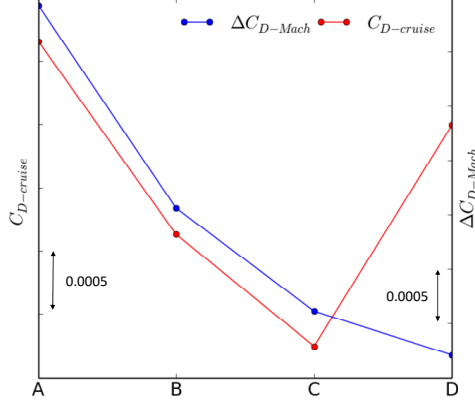


Figure 5: Changes on mid-cruise drag ( $C_{D-cruise}$ ) and sensitivity to Mach number ( $\Delta C_{D-Mach}$ ) for selected designs identified from the independent multi-objective optimisation routines

configuration with a  $C_{D-cruise}$  increment of 3.5% with respect to the design C. The optimisation of the configuration D resulted on a design with a penalty on mid-cruise drag of 2.5%. It is a larger penalty than the one for configuration B at the same variation on the droop and scarf angles but different polarity. This is caused by the larger sensitivity to changes on MFCR ( $C_{D-spill}$ ) of the configuration D which results on the selection of a design with a larger cruise drag to meet the established selection criteria of  $C_{D-spill} < 0.1C_{D-cruise}$  [6]. The compact nacelles have lower sensitivity to changes on flight Mach number ( $\Delta C_{D-Mach}$ ) as the values of droop and scarf angles are increased (Figure 5).

The selected nacelle designs have significant differences on their transonic flow aerodynamics (Figure 6). The designs with the reduced droop and scarf angles, e.g. A and B, have larger peak  $M_{is}$  on the top half ( $0^\circ < \psi < 90^\circ$ ) than the designs with increased droop and scarf values, e.g. design D. This is caused by the reduction of the nacelle aero-line length as the scarf angle reduces, which decreases the curvature of the local aero-lines and increases the acceleration along the nacelle lip. Conversely, on the nacelle bottom half ( $90^\circ < \psi < 180^\circ$ )

the designs A and B have a more benign acceleration along the nacelle lip than the design D due to the larger effective nacelle length. Figure 7 compares the changes on  $M_{is}$  for the selected designs at the azimuthal sections  $\psi = 0^\circ$  and  $180^\circ$ . At the top nacelle aero-line, the maximum value of isentropic Mach number along the nacelle forebody varies by 0.09 for the selected configurations (Figure 7a). All four optimal designs have a well defined shock-wave structure. The shock-wave is located on the nacelle crest at  $X/L_{nac} \approx 0.40$  with similar pre-shock  $M_{is}$  for the configurations A, B and C. The nacelle D has a deceleration after the nacelle lip and then the flow accelerates again to terminate in a normal shock at  $X/L_{nac} = 0.49$ . The selected designs have noticeable changes on the peak  $M_{is}$  at the bottom aero-line ( $\psi = 180^\circ$ ) (Figure 7b). Relative to the design A, which has the largest effective nacelle length on the bottom aero-line, the peak  $M_{is}$  increases by 0.06, 0.12 and 0.16 for the designs B, C and D, respectively. While the nacelles A, B and C have relatively benign flow aerodynamics after the peak  $M_{is}$ , the design D depicts a shock structure after the nacelle crest at  $X/L_{nac} = 0.53$ .

#### 4. Conclusion

A novel framework for the multi-objective optimisation of non-axisymmetric nacelle aero-engines has been further developed. It encompasses a parametric aero-engine definition with intuitive Class Shape Transformations, numerical simulations, a thrust-drag bookkeeping accounting method and a evolutionary algorithm. The tool has been used to investigate the impact of the droop and scarf angles on the nacelle drag characteristics of compact configurations. The optimisation process was carried out with a higher fidelity CFD in-the-loop approach to evaluate the nacelle drag throughout the design process.

A set of independent multi-objective optimizations for different droop and

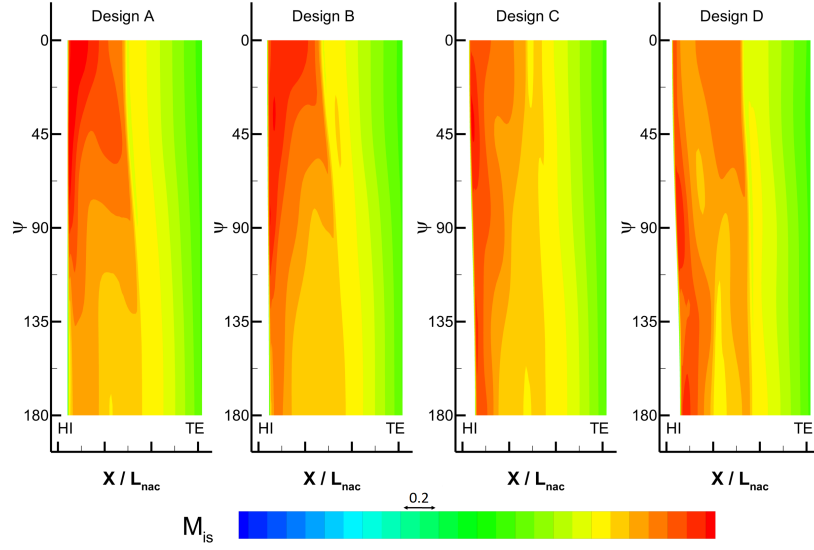


Figure 6: Isentropic Mach number distribution for selected designs identified from the independent multi-objective optimisation routines

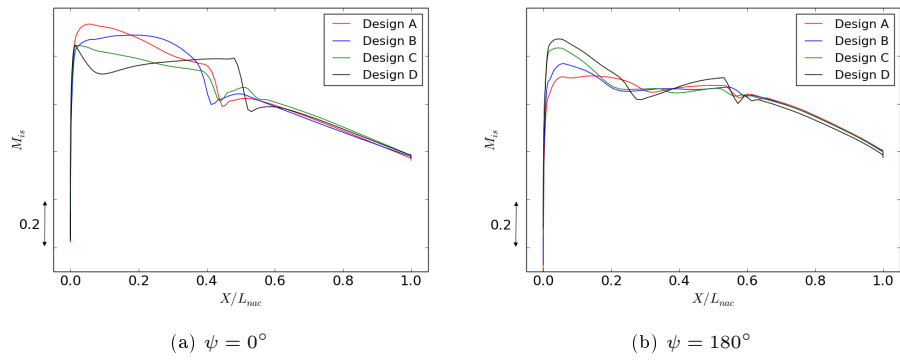


Figure 7: Comparison of  $M_{is}$  at different azimuthal sections for selected designs identified from the independent multi-objective optimisation routines

scarf angles were carried out. Across the ranges considered the nacelle mid-cruise drag varies by 3.5%. The presented results demonstrate the relatively large impact of both design variables on the nacelle drag characteristics. As such, they need to be adequately selected to maximise the expected benefits of future civil aero-engine architectures. The tool has been successfully employed to identity the changes on the transonic flow aerodynamics of the different configurations investigated. The proposed numerical method complements a set of enabling technologies for the design, analysis and optimisation of future civil large turbofans aiming at reduction of specific fuel consumption.

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